Digital Signal Processing

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Chapter 3 Discrete-Time Signals in the Frequency-Domain





Review of DTFT and IDTFT

 $x[n] \leftrightarrow X(e^{j\omega})$

●复数性 ● 周期性

• 连续性 $X(e^{j\omega}) = \sum x[n]e^{-j\omega n}$ $n = -\infty$

 $x[n] = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(e^{j\omega}) e^{j\omega n} d\omega$

What is the relationship between $G_a(j\Omega)$ and $G(e^{j\omega})$?



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• The frequency-domain representation of g_a(t) is given by CTFT:

$$G_a(j\Omega) = \int_{-\infty}^{\infty} g_a(t) e^{-j\Omega t} dt$$

• The frequency-domain representation of *g*[*n*] is given by DTFT:

$$G(e^{j\omega}) = \sum_{n=-\infty}^{\infty} g[n] e^{-j\omega n}$$

Review of Sampling

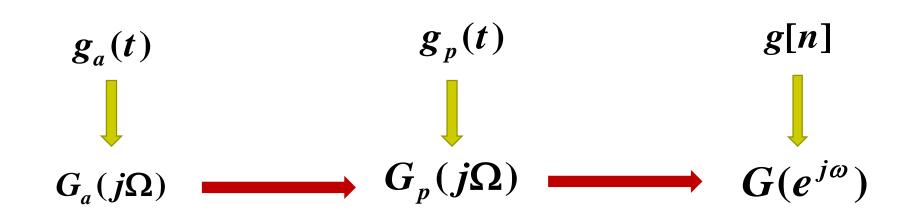


 $g_{a}(t) \longrightarrow g_{p}(t)$ p(t) $g_{p}(t) = g_{a}(t)p(t)$ $p(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT)$

$$g_p(t) = g_a(t)p(t) = \sum_{n=-\infty}^{\infty} g_a(nT)\delta(t-nT)$$







$$g_p(t) = g_a(t)p(t)$$



- There are two different forms of $G_p(j\Omega)$:
- 1) One form is given by the weighted sum of the CTFTs of $\delta(t-nT)$:

 $G_{p}(j\Omega) = \int_{-\infty}^{\infty} g_{p}(t) e^{-j\Omega t} dt$ = $\int_{-\infty}^{\infty} \left[\sum_{n=-\infty}^{\infty} g_{a}(nT) \delta(t-nT) \right] e^{-j\Omega t} dt$ = $\sum_{n=-\infty}^{\infty} g_{a}(nT) e^{-j\Omega nT} \int_{-\infty}^{\infty} \left[\delta(t-nT) \right] dt$ = $\sum_{n=-\infty}^{\infty} g_{a}(nT) e^{-j\Omega nT}$



(2) note that *p*(*t*) can be expressed as a Fourier series:

$$p(t) = \frac{1}{T} \sum_{k=-\infty}^{\infty} e^{j(2\pi/T)kt} = \frac{1}{T} \sum_{k=-\infty}^{\infty} e^{j\Omega_T kt}$$

where
$$\Omega_T = 2\pi/T$$

• The impulse train $g_p(t)$ therefore can be expressed

as

$$g_p(t) = \left(\frac{1}{T} \sum_{k=-\infty}^{\infty} e^{j\Omega_T kt}\right) \cdot g_a(t)$$

调制关系



• From the frequency-shifting property of the CTFT, an alternative form of the CTFT of $g_p(t)$ is given by

$$G_p(j\Omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} G_a(j(\Omega - k\Omega_T))$$

• $G_p(j\Omega)$ is a periodic function of Ω consisting of a sum of shifted and scaled replicas of $G_a(j\Omega)$, shifted by integer multiples of Ω_T and scaled by 1/T



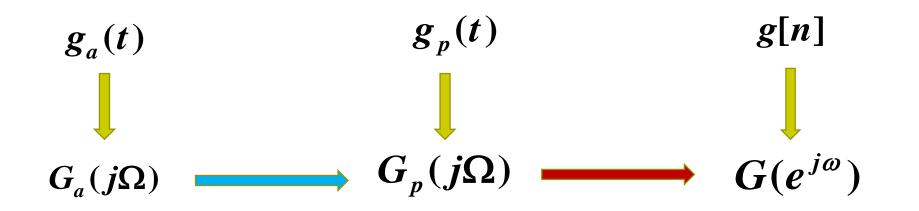
- The term on the RHS of the previous equation for k = 0 is the baseband portion(基带部分) of G_p(jΩ), and each of the remaining terms are the frequency translated portions (频移部分)
- The frequency range

$$-\frac{\Omega_T}{2} \le \Omega \le \frac{\Omega_T}{2}$$

is called the baseband or Nyquist band





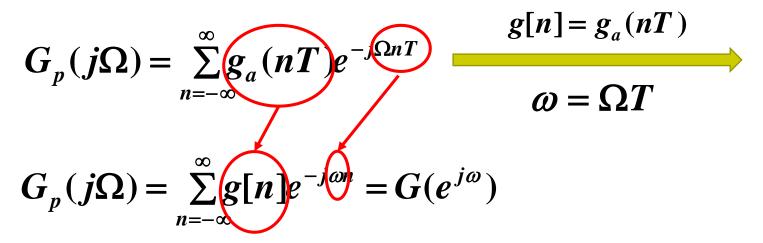


采样的频域分析

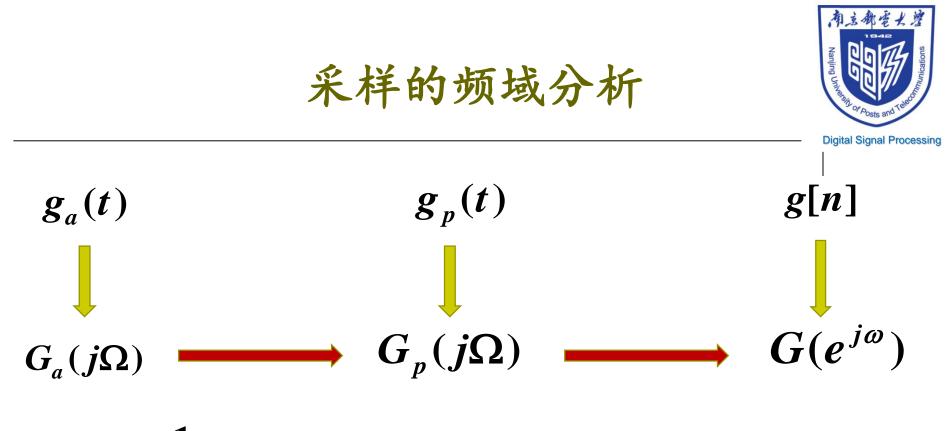


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 $G_n(j\Omega)$ 与 $G(e^{j\omega})$ 之间的关系



所以 $G_p(j\Omega) = G(e^{j\omega})|_{\omega=\Omega T}$ 或 $G(e^{j\omega}) = G_p(j\Omega)|_{\Omega=\omega/T}$ 对频率轴 Ω 进行尺度缩放,可从 $G_p(j\Omega)$ 得到 $G(e^{j\omega})$

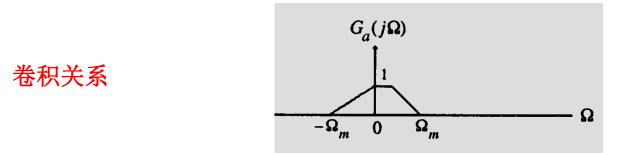


$$G_p(j\Omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} G_a(j(\Omega - k\Omega_T)) \qquad G(e^{j\omega}) = G_p(j\Omega) \Big|_{\Omega = \omega/T}$$

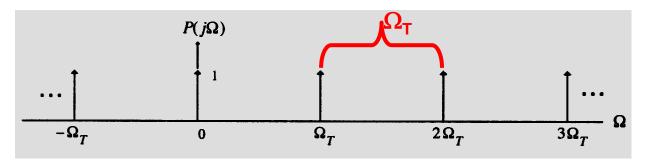
时域采样带来了频谱的周期复制以采样频率为周期进行周期延拓



• Assume $g_a(t)$ is a band-limited signal with a CTFT $G_a(j\Omega)$ as shown below



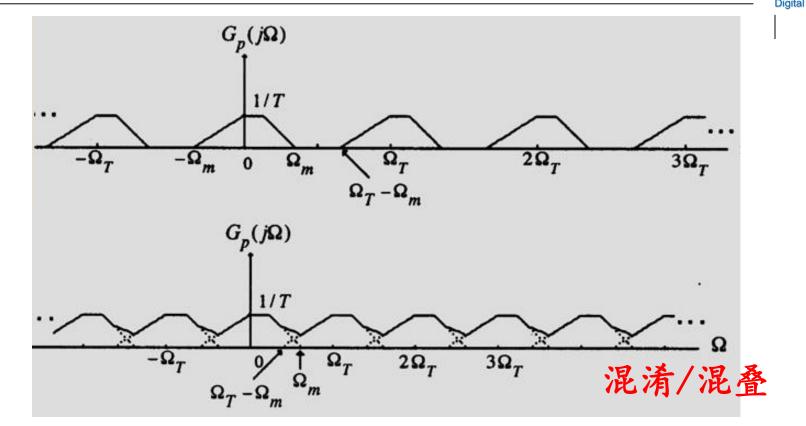
• The spectrum P(j Ω) of p(t) having a sampling period T=2 π/Ω_T is indicated below



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采样的频域分析





从频域看不产生混叠的条件: $\Omega_T \geq 2\Omega_m$



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Let $g_a(t)$ be a band-limited signal with CTFT $G_a(j\Omega)=0$ for $|\Omega| > \Omega_m$

Then $g_a(t)$ is uniquely determined by its samples $g_a(nT)$, $-\infty \le n \le \infty$, if $\Omega_T \ge 2 \Omega_m$

where $\Omega_T = 2\pi/T$



• The condition $\Omega_T \ge 2 \ \Omega_m$ is often referred to as the Nyquist condition

• The frequency $\Omega_T/2$ is usually referred to as the folding frequency



- The highest frequency Ω_m contained in $g_a(t)$ is usually called the Nyquist frequency since it determines the minimum sampling frequency $\Omega_T = 2\Omega_m$ that must be used to fully recover $g_a(t)$ from its sampled version
- The frequency $2\Omega_m$ is called the Nyquist rate



- Oversampling The sampling frequency is higher than the Nyquist rate
- Undersampling-The sampling frequency is lower than the Nyquist rate
- Critical sampling (临界采样) The sampling frequency is equal to the Nyquist rate
- Note: A pure sinusoid may not be recoverable from its critically sampled version

3.8.1 Aliasing in the Frequency Domain



• <u>Example</u> - Consider the three continuoustime sinusoidal signals:

$$g_1(t) = \cos(6\pi t)$$

$$g_2(t) = \cos(14\pi t)$$

$$g_3(t) = \cos(26\pi t)$$

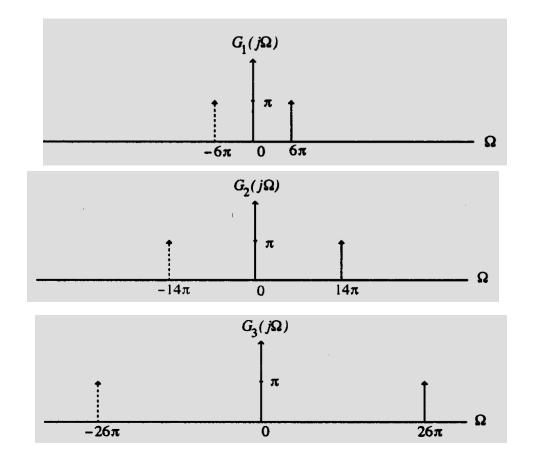
• Their corresponding CTFTs are:

$$\begin{split} G_1(j\Omega) &= \pi [\delta(\Omega - 6\pi) + \delta(\Omega + 6\pi)] \\ G_2(j\Omega) &= \pi [\delta(\Omega - 14\pi) + \delta(\Omega + 14\pi)] \\ G_3(j\Omega) &= \pi [\delta(\Omega - 26\pi) + \delta(\Omega + 26\pi)] \end{split}$$

§ 3.8.1 Aliasing in the Frequency Domain



• These three transforms are plotted below



§ 3.8.1 Aliasing in the Frequency Domain



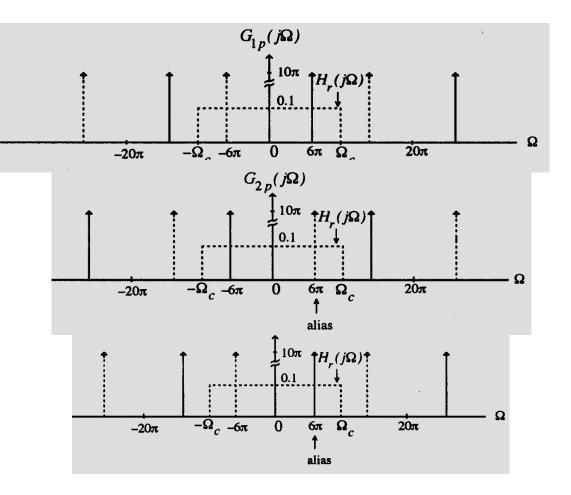
- These continuous-time signals sampled at a rate of T = 0.1 sec, i.e., with a sampling frequency $\Omega_T = 20\pi$ rad/sec
- The sampling process generates the continuous-time impulse trains, $g_{1p}(t)$, $g_{2p}(t)$, and $g_{3p}(t)$
- Their corresponding CTFTs are given by

$$G_{\ell p}(j\Omega) = 10 \sum_{k=-\infty}^{\infty} G_{\ell}(j(\Omega - k\Omega_T)), \quad 1 \le \ell \le 3$$

§ 3.8.1 Aliasing in the Frequency Domain



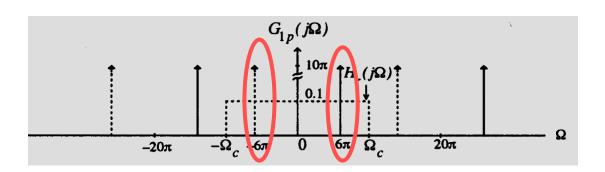
• Plots of the 3 CTFTs are shown below



§ 3.8.1 Aliasing in the Frequency Domain

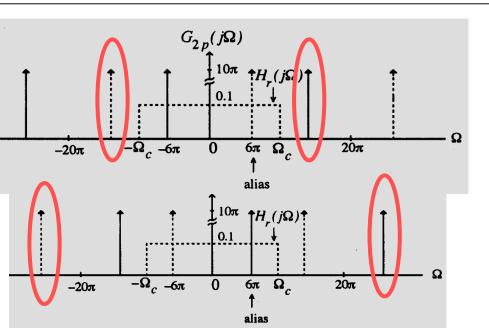






- Dotted lines indicate the frequency response of an ideal lowpass filter with a cutoff at $\Omega_c = \Omega_T/2 = 10\pi$ and a gain T=0.1
- In the case of g₁(t), the sampling rate satisfies the Nyquist condition, hence no aliasing. Moreover, the reconstructed output is precisely the original continuous-time signal

§ 3.8.1 Aliasing in the Frequency Domain

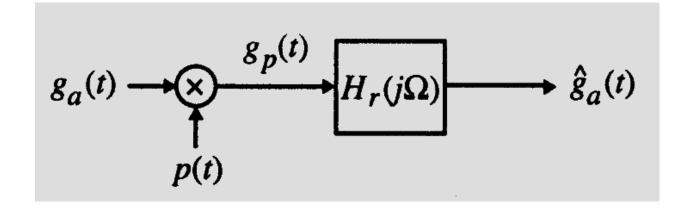


• In the other two cases, the sampling rate does not satisfy the Nyquist condition, resulting in aliasing and the filter outputs are all equal to cos(6pt)

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3.8.2 Recovery of the Analog Signal



$$\hat{G}_a(j\Omega) = G_p(j\Omega)H_r(j\Omega)$$
$$g_a(t) = g_p(t) * h_r(t)$$



$$H_r(j\Omega) = \begin{cases} T, & |\Omega| \le \Omega_c \\ 0, & |\Omega| > \Omega_c \end{cases}$$

• The impulse response $h_r(t)$ of the lowpass reconstruction filter is obtained by taking the inverse DTFT of $H_r(j\Omega)$

$$h_{r}(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} H_{r}(j\Omega) e^{j\Omega t} d\Omega = \frac{T}{2\pi} \int_{-\Omega_{c}}^{\Omega_{c}} e^{j\Omega t} d\Omega$$
$$= \frac{\sin(\Omega_{c}t)}{\Omega_{T}t/2}, \quad -\infty \le t \le \infty$$

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• The input to the lowpass filter is the impulse train $g_p(t)$:

$$g_{p}(t) = \sum_{n=-\infty}^{\infty} g[n]\delta(t-nT)$$

$$\hat{g}_a(t) = h_r(t) \circledast g_p(t) = \sum_{n = -\infty}^{\infty} g[n] h_r(t - nT)$$

Substituting $h_r(t)=\sin(\Omega_c t)/(\Omega_T t/2)$ in the above and assuming for simplicity $\Omega_c = \Omega_T/2 = \pi/T$,



3.8.2 Recovery of the Analog Signal

we get

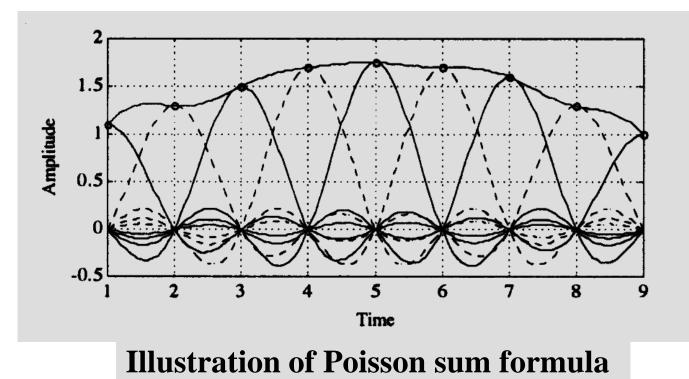
$$\hat{g}_a(t) = \sum_{n=-\infty}^{\infty} g[n] \frac{\sin[\pi(t-nT)/T]}{\pi(t-nT)/T}$$

which is called Poisson sum formula

3.8.2 Recovery of the Analog Signal



• The ideal bandlimited interpolation process is illustrated below



§ 3.8 Digital Processing of Continuous-Time Signals



Digital processing of a continuous-time signal involves the following basic steps:

- (1) Conversion of the continuous-time signal into a discrete-time signal (A/D converter)
- (2) Processing of the discrete-time signal
- (3) Conversion of the processed discrete-time signal back into a continuous-time signal (D/A converter)

§ 3.8 Digital Processing of Continuous-Time Signals



Complete block-diagram



- Both the anti-aliasing filter and the reconstruction filter are analog lowpass filters
- Also, the most widely used IIR digital filter design method is based on the conversion of an analog lowpass prototype



本章重点

1.DTFT定义:正反变换公式

2.会用定义式计算序列的DTFT

3. $X(e^{j\omega})$ 的周期性、复数性、存在性条件

4. DTFT的对称性

5. DTFT的运算性质

6. 采样定理



Homework

• Read textbook from p.81 to 107

• Problems

- 3.16 (b)(c) , 3.21(a)(b)(d), 3.23(a), 3.29, 3.30, 3.31(c), 3.46, 3.48(a)(b)(c)(d), 3.60, 3.61
- MATLAB Exercise M 3.3
- 课后自学并练习《实验指导书》p26 to 35