

Serial Datalogger

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Installation:

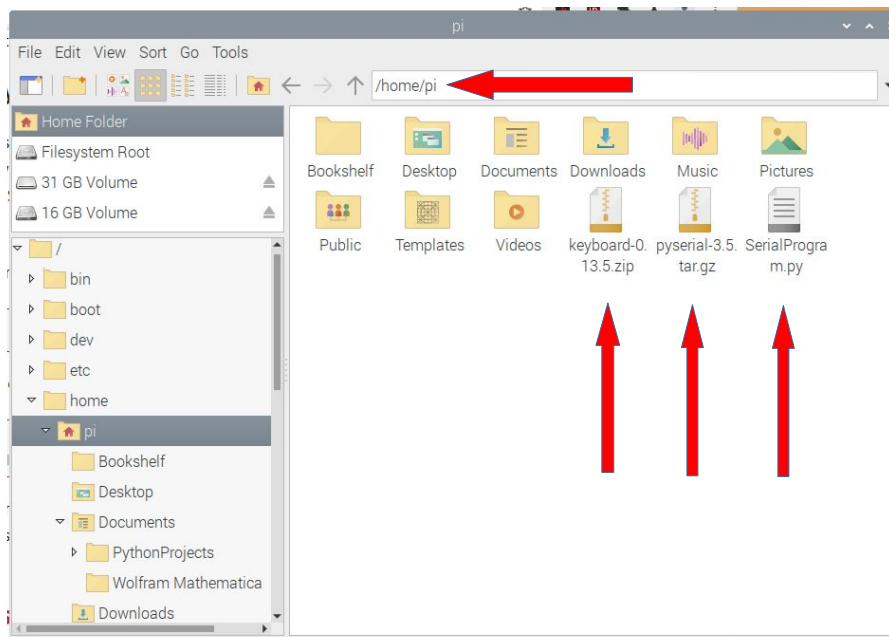
Verify that Python and pip are installed on your system by typing the command “python --version” and “pip --version” in the terminal. This program was written for Python 3.10 but it may also work with different versions like 3.9. The source file of Python 3.10 is included in this .zip file if Python is not already installed or the program does not work with the version that is currently installed on your system.

If pip is not installed, you can try executing “sudo python -m ensurepip --upgrade”. After executing this command, try “pip --version” again.

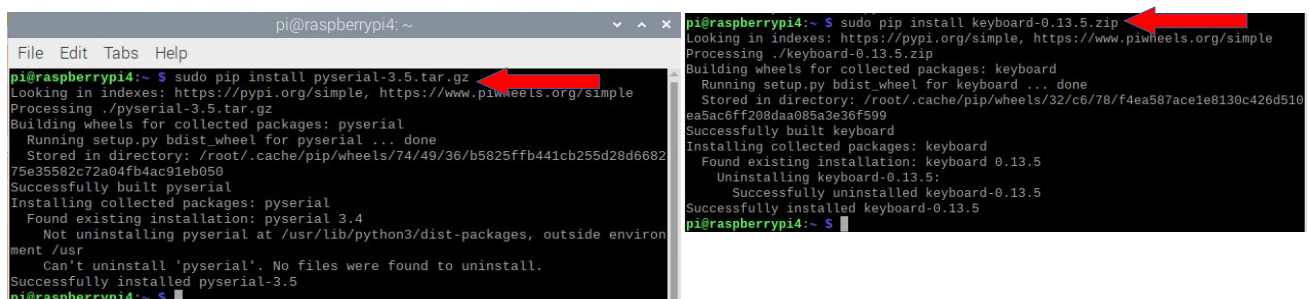
To install the program simply move the program file and the libraries (“SerialProgram.py”, “pyserial-3.5.tar.gz”, “keyboard-0.13.5.zip”) to the home folder of the user that you are currently using.

On “Raspberry Pi OS” this is typically the user “pi” and the home folder therefore is: “/home/pi”. Just move the program file to this folder.

The folder should now look something like this:

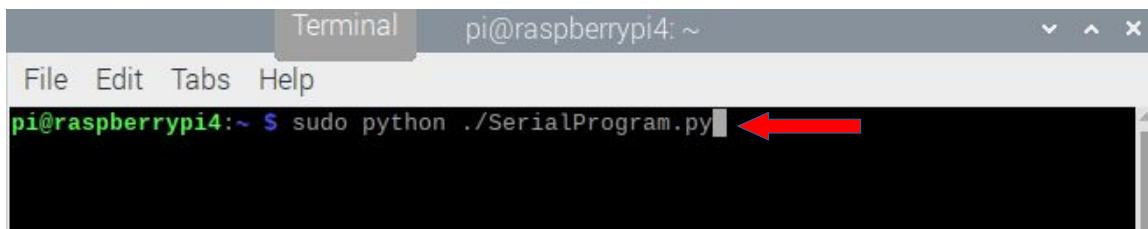


Then open the terminal and install the libraries via “sudo pip install pyserial-3.5.tar.gz” and “sudo pip install keyboard-0.13.5.zip”. After installing the libraries, you can delete the library installation files.



Start the program:

To start the program **first connect** the device to a USB port
and then open the terminal and type:
“sudo python ./SerialProgram.py” and hit enter.



```
Terminal pi@raspberrypi4: ~
File Edit Tabs Help
pi@raspberrypi4:~ $ sudo python ./SerialProgram.py
```

Note: If the program file is located in a different location than the home folder, specify the exact location. e.g.: “sudo python /home/pi/Desktop/SerialProgram.py” if the program is located on the Desktop.

After hitting enter, the program starts in the same terminal.

Setup

Once the program is started, it asks the user to give information on the device that is connected.

1.) Select the device from the list of available COM Ports.

To select the device you want to log data from, you have to specify the COM Port that is going to be used. To specify the COM Port, you simply type in the name of the COM Port of the device you want to use and press enter. (The names of available COM Ports are listed)

e.g.: `"/dev/ttyUSB0"`



```
pi@raspberrypi4: ~  
File Edit Tabs Help  
pi@raspberrypi4:~ $ sudo python ./SerialProgram.py  
Starting Program...  
Available COM Ports:  
/dev/ttyUSB0 - CP2102 USB to UART Bridge Controller - CP2102 USB to UART Bridge Controller  
/dev/ttyAMA0 - ttyAMA0  
Input name of COM Port of Serial Device (e.g. 'COM4')  
>>> /dev/ttyUSB0
```


Note: You can identify the name of the device by first starting the program when the device is not connected, and then restarting the program when the device is connected. The device should only be listed when the device is actually connected via USB.

2.) Specify the baudrate of the connected device.

After the COM Port was specified, the program asks for the baudrate that is used.

To specify the baudrate, you simply type in the baudrate and press enter.

(for an ESP32 the default baudrate is 115200; for an Arduino Uno the default baudrate is 9600)



```
pi@raspberrypi4: ~  
File Edit Tabs Help  
pi@raspberrypi4:~ $ sudo python ./SerialProgram.py  
Starting Program...  
Available COM Ports:  
/dev/ttyUSB0 - CP2102 USB to UART Bridge Controller - CP2102 USB to UART Bridge Controller  
/dev/ttyAMA0 - ttyAMA0  
Input name of COM Port of Serial Device (e.g. 'COM4')  
>>> /dev/ttyUSB0  
  
Default Baudrate of ESP32: 115200  
Default Baudrate of Arduino: 9600  
Enter baudrate of Serial Connection  
>>> 115200
```

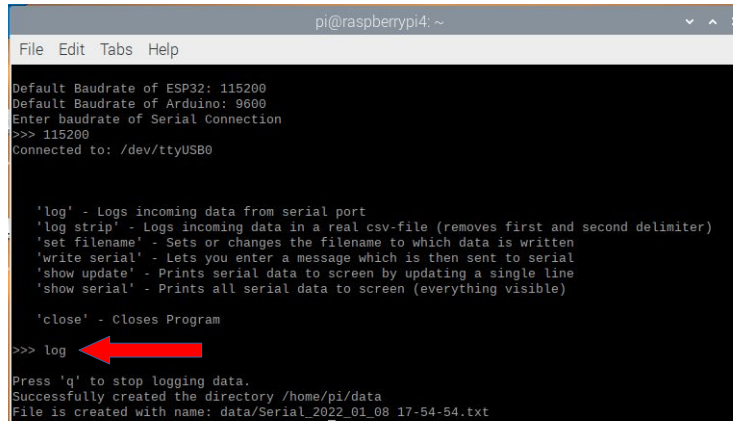
Note: It is crucial that you DO NOT use the NumPad to type in the numbers, otherwise the COM Port will not be opened!!!

Now you are in the main menu of the program!

Start datalogging

Logging without specifying a filename first:

You can directly start logging by typing “log” and pressing enter, a file with the current date and time as the filename will be created. All data that is read by the serial port will be automatically be saved in this file, which is located in the folder “/data” which is created in the home folder.



```
pi@raspberrypi4: ~
File Edit Tabs Help

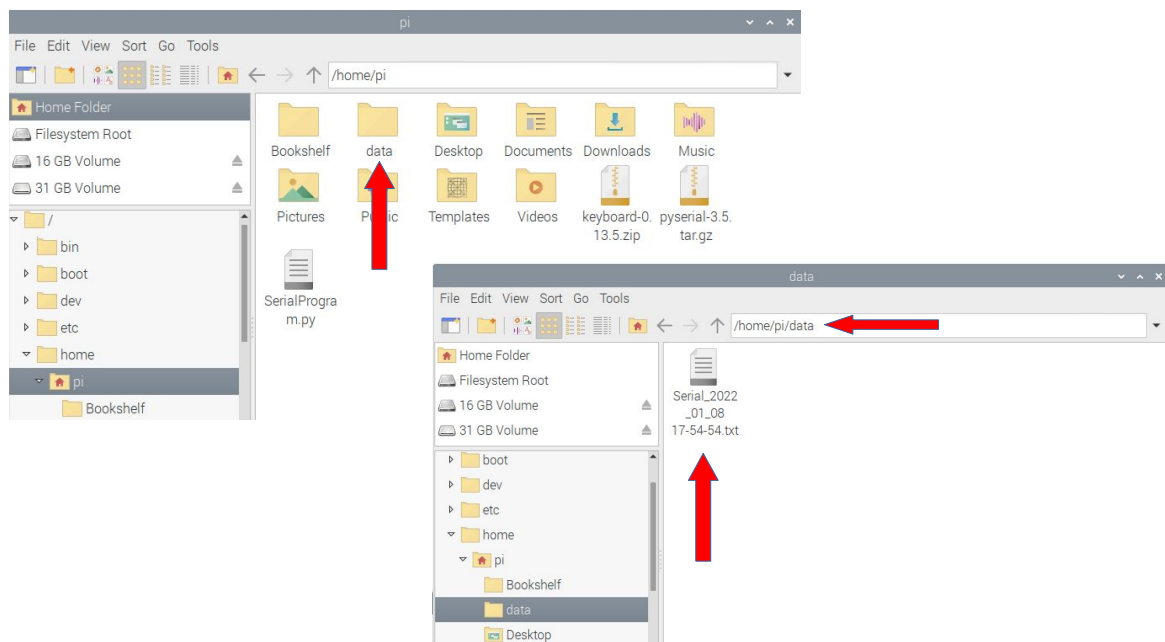
Default Baudrate of ESP32: 115200
Default Baudrate of Arduino: 9600
Enter baudrate of Serial Connection
>>> 115200
Connected to: /dev/ttyUSB0

'log' - Logs incoming data from serial port
'log strip' - Logs incoming data in a real csv-file (removes first and second delimiter)
'set filename' - Sets or changes the filename to which data is written
'write serial' - Lets you enter a message which is then sent to serial
'show update' - Prints serial data to screen by updating a single line
'show serial' - Prints all serial data to screen (everything visible)

'close' - Closes Program
>>> log
Press 'q' to stop logging data.
Successfully created the directory /home/pi/data
File is created with name: data/Serial_2022_01_08 17-54-54.txt
```

This command automatically creates the folder “/data” and logs all incoming data to a .txt file that created in the “/data” folder with the current date and time as the filename.

To stop datalogging you have to press “q” until the program shows “>>>” again, followed by Enter. This will bring you back to the main menu.



Logging with specifying a filename:

When you set a filename by the command “set filename” first and then start logging, the filename of the logfile will be the one you specified. The file will be located in the same folder “/data”.

During this you will also be asked if you want to include a timestamp in the logfile. This is useful to later see, when the data was logged.

After those two inputs, you get back to the main menu.

Now to actually START datalogging, you type “log” and press enter. All incoming data will now be logged in the logfile with your custom filename which is located in the “/data” folder.

Show the serial data without logging

To just show what is read on the serial connection, you can type either “show update” or “show serial”.

“show update” will only show the latest line of serial data that was received.

“show serial” will show everything that has been received.

To get back to the main menu, you have to press “q” until the program shows “>>>” again, followed by Enter.