

view\_frames Result

Recorded at time: 640.139

map

Broadcaster: /slam\_gmapping  
Average rate: 20.233 Hz  
Most recent transform: 640.170 ( -0.031 sec old)  
Buffer length: 4.300 sec

odom

Broadcaster: /gazebo  
Average rate: 20.233 Hz  
Most recent transform: 640.112 ( 0.027 sec old)  
Buffer length: 4.300 sec

link\_chassis

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 640.139 sec old)  
Buffer length: 0.000 sec

sensor\_laser

Broadcaster: /robot\_state\_publisher  
Average rate: 40.465 Hz  
Most recent transform: 640.113 ( 0.026 sec old)  
Buffer length: 4.300 sec

link\_left\_wheel

Broadcaster: /robot\_state\_publisher  
Average rate: 40.465 Hz  
Most recent transform: 640.113 ( 0.026 sec old)  
Buffer length: 4.300 sec

link\_right\_wheel