

# Numerical Linear Algebra

## QR and Least Squares

Zahra Lakdawala

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# Outline

1 Projectors

2 QR Factorization

3 Gram-Schmidt Orthogonalization

# Projectors

# Projectors

- A projector satisfies  $\mathbf{P}^2 = \mathbf{P}$ . They are also said to be *idempotent*.
  - Orthogonal projector
  - Oblique projector
- Example

$$\begin{bmatrix} 0 & 0 \\ \alpha & 1 \end{bmatrix}$$

- is an oblique projector if  $\alpha \neq 0$ ,
- is orthogonal projector if  $\alpha = 0$ .

# Complementary Projectors

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- What space does  $\mathbf{I} - \mathbf{P}$  project?

# Complementary Projectors

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- What space does  $\mathbf{I} - \mathbf{P}$  project?
  - Answer:  $\text{null}(\mathbf{P})$
  - $\text{range}(\mathbf{I} - \mathbf{P}) \supseteq \text{null}(\mathbf{P})$  because  $\mathbf{P}\mathbf{v} = 0 \Rightarrow (\mathbf{I} - \mathbf{P})\mathbf{v} = \mathbf{v}$ .
  - $\text{range}(\mathbf{I} - \mathbf{P}) \subseteq \text{null}(\mathbf{P})$  because for any  $\mathbf{v}$

$$(\mathbf{I} - \mathbf{P})\mathbf{v} = \mathbf{v} - \mathbf{P}\mathbf{v} \in \text{null}(\mathbf{P}).$$

- A projector separates  $\mathbb{C}^m$  into two complementary subspaces: range space and null space (i.e.,  $\text{range}(\mathbf{P}) + \text{null}(\mathbf{P}) = \mathbb{C}^m$  and  $\text{range}(\mathbf{P}) \cap \text{null}(\mathbf{P}) = \{0\}$  for projector  $\mathbf{P} \in \mathbb{C}^{m \times m}$ )
- It projects onto range space along null space
  - In other words,  $\mathbf{x} = \mathbf{P}\mathbf{x} + \mathbf{r}$ , where  $\mathbf{r} \in \text{null}(\mathbf{P})$
- Question: Are range space and null space of projector orthogonal to each other?

# Orthogonal Projector

- An orthogonal projector is one that projects onto a subspace  $S_1$  along a space  $S_2$ , where  $S_1$  and  $S_2$  are orthogonal.

## Theorem

A projector  $\mathbf{P}$  is orthogonal if and only if  $\mathbf{P} = \mathbf{P}^*$ .

## Proof

"If" direction: If  $\mathbf{P} = \mathbf{P}^*$ , then  $(\mathbf{P}\mathbf{x})^*(\mathbf{I} - \mathbf{P})\mathbf{y} = \mathbf{x}^*(\mathbf{P} - \mathbf{P}^2)\mathbf{y}$ . "Only if" direction: Use SVD. Suppose  $\mathbf{P}$  projects onto  $S_1$  along  $S_2$  where  $S_1 \perp S_2$ , and  $S_1$  has dimension  $n$ . Let  $\mathbf{q}_1, \dots, \mathbf{q}_n$  be orthonormal basis of  $S_1$  and  $\mathbf{q}_{n+1}, \dots, \mathbf{q}_m$  be a basis for  $S_2$ . Let  $\mathbf{Q}$  be unitary matrix whose  $j$ th column is  $\mathbf{q}_j$ , and we have  $\mathbf{P}\mathbf{Q} = (\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_n, 0, \dots, 0)$ , so  $\mathbf{Q}^*\mathbf{P}\mathbf{Q} = \text{diag}(1, 1, \dots, 1, 0, \dots) = \Sigma$ , and  $\mathbf{P} = \mathbf{Q}\Sigma\mathbf{Q}^*$ .

Question: Are orthogonal projectors orthogonal matrices?

# Basis of Projections

- Projection with orthonormal basis
  - Given any matrix  $\hat{\mathbf{Q}} \in \mathbb{C}^{m \times n}$  whose columns are orthonormal, then  $\mathbf{P} = \hat{\mathbf{Q}}\hat{\mathbf{Q}}^*$  is orthogonal projector, so is  $\mathbf{I} - \mathbf{P}$
  - We write  $\mathbf{I} - \mathbf{P}$  as  $\mathbf{P}_\perp$
  - In particular, if  $\hat{\mathbf{Q}} = \mathbf{q}$ , we write  $\mathbf{P}_\mathbf{q} = \mathbf{q}\mathbf{q}^*$  and  $\mathbf{P}_{\perp\mathbf{q}} = \mathbf{I} - \mathbf{P}_\mathbf{q}$
  - For arbitrary vector  $\mathbf{a}$ , we write  $\mathbf{P}_\mathbf{a} = \frac{\mathbf{a}\mathbf{a}^*}{\mathbf{a}^*\mathbf{a}}$  and  $\mathbf{P}_{\perp\mathbf{a}} = \mathbf{I} - \mathbf{P}_\mathbf{a}$



# Basis of Projections

- Projection with arbitrary basis
  - Given any matrix  $\mathbf{A} \in \mathbb{C}^{m \times n}$  that has full rank  $m \geq n$

$$\mathbf{P} = \mathbf{A}(\mathbf{A}^* \mathbf{A})^{-1} \mathbf{A}^*$$

is an orthogonal projection

- What does  $\mathbf{P}$  project onto?
  - $\text{range}(\mathbf{A})$
- $(\mathbf{A}^* \mathbf{A})^{-1} \mathbf{A}^*$  is called the pseudo inverse of  $\mathbf{A}$ , denoted as  $\mathbf{A}^+$

# QR Factorization

# Motivation

- Question: Given a linear system  $\mathbf{Ax} = \mathbf{b}$  where  $\mathbf{A} \in \mathbb{C}^{m \times n} (m \geq n)$  has full rank, how to solve the linear system?
- Answer: One possible solution is to use SVD. How?

$$\mathbf{A} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}^*, \text{ so } \mathbf{x} = \mathbf{V}\mathbf{\Sigma}^{-1}\mathbf{U}^*\mathbf{b}$$

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Another solution is to use QR factorization, which decompose  $\mathbf{A}$  into product of two simple matrices  $\mathbf{Q}$  and  $\mathbf{R}$  where columns of  $\mathbf{Q}$  are orthonormal and  $\mathbf{R}$  is upper triangular.

# Two Different Versions of QR

- Full QR factorization:  $\mathbf{A} \in \mathbb{C}^{m \times n} (m \geq n)$

$$\mathbf{A} = \mathbf{Q}\mathbf{R}$$

where  $\mathbf{Q} \in \mathbb{C}^{m \times m}$  is unitary and  $\mathbf{R} \in \mathbb{C}^{m \times n}$  is upper triangular

- Reduced QR factorization:  $\mathbf{A} \in \mathbb{C}^{m \times n} (m \geq n)$

$$\mathbf{A} = \hat{\mathbf{Q}}\hat{\mathbf{R}}$$

where  $\hat{\mathbf{Q}} \in \mathbb{C}^{m \times n}$  contains orthonormal vectors and  $\hat{\mathbf{R}} \in \mathbb{C}^{n \times n}$  is upper triangular

- What space do  $\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_j, j \leq n$  span?

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- What space do  $\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_j, j \leq n$  span?
  - Answer: For full rank  $\mathbf{A}$ , first  $j$  column vectors of  $\mathbf{A}$ , i.e.  
 $\langle \mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_j \rangle = \langle \mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_j \rangle$

# Gram-Schmidt Orthogonalization

- A method to construct QR factorization is to orthogonalize the column vectors of  $\mathbf{A}$ :
- Basic idea:
  - Take first column  $\mathbf{a}_1$  and normalize it to obtain vector  $\mathbf{q}_1$ ;
  - Take second column  $\mathbf{a}_2$ , subtract its orthogonal projection to  $\mathbf{q}_1$ , and normalize to obtain  $\mathbf{q}_2$ ;
  - ...
  - Take  $j$ -th column of  $\mathbf{a}_j$ , subtract its orthogonal projection to  $\mathbf{q}_1, \dots, \mathbf{q}_{j-1}$  and normalize to obtain  $\mathbf{q}_j$

$$\mathbf{v}_j = \mathbf{a}_j - \sum_{i=1}^{j-1} \mathbf{q}_i^* \mathbf{a}_j \mathbf{q}_i, \quad \mathbf{q}_j = \mathbf{v}_j / \|\mathbf{v}_j\|$$

- This idea is called Gram-Schmidt orthogonalization.

# Gram Schmidt Projections

- Orthogonal vectors produced by Gram-Schmidt can be written in terms of projectors

$$\mathbf{q}_j = \frac{\mathbf{P}_j \mathbf{a}_j}{\|\mathbf{P}_j \mathbf{a}_j\|}$$

where

$$\mathbf{P}_j = \mathbf{I} - \hat{\mathbf{Q}}_{j-1} \hat{\mathbf{Q}}_{j-1}^* \text{ with } \hat{\mathbf{Q}}_{j-1} = [\mathbf{q}_1 \quad \mathbf{q}_2 \quad \cdots \mathbf{q}_{j-1}]$$

- $\mathbf{P}_j$  projects orthogonally onto space orthogonal to  $\langle \mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_{j-1} \rangle$  and rank of  $\mathbf{P}_j$  is  $m - (j - 1)$



# Algorithm of Gram Schmidt Orthogonalization

Classical Gram-Schmidt method

```
for  $j = 1$  to  $n$   
   $\mathbf{v}_j = \mathbf{a}_j$ ;  
  for  $i = 1$  to  $j - 1$   
     $r_{ij} = \mathbf{q}_i^* \mathbf{a}_j$   
     $\mathbf{v}_j = \mathbf{v}_j - r_{ij} \mathbf{q}_i$   
   $r_{jj} = \|\mathbf{v}_j\|_2$   
   $\mathbf{q}_j = \frac{\mathbf{v}_j}{r_{jj}}$ 
```

- Classical Gram-Schmidt (CGS) is unstable, which means that its solution is sensitive to perturbation

# Existence of QR

## Theorem

Every  $\mathbf{A} \in \mathbb{C}^{m \times n}$  ( $m \geq n$ ) has full QR factorization, hence also a reduced QR factorization.

Key idea of proof:

- If  $\mathbf{A}$  has full rank, Gram-Schmidt algorithm provides a proof itself for having reduced QR.
- If  $\mathbf{A}$  does not have full rank, at some step  $\mathbf{v}_j = 0$ . We can set  $\mathbf{q}_j$  to be a vector orthogonal to  $\mathbf{q}_i, i < j$ .
- To construct full QR from reduced QR, just continue Gram-Schmidt an additional  $m - n$  steps.

# Uniqueness of QR

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Every  $\mathbf{A} \in \mathbb{C}^{m \times n}$  ( $m \geq n$ ) has full rank has a unique reduced QR factorization  $\mathbf{A} = \hat{\mathbf{Q}}\hat{\mathbf{R}}$  with  $r_{jj} > 0$ .

Proof is provided by Gram-Schmidt iteration itself. If the signs of  $r_{jj}$  are determined, then  $r_{ij}$  and  $\mathbf{q}_j$  are determined.

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# Alternative view to Gram-Schmidt Projection

- Orthogonal vectors produced by Gram-Schmidt can be written in terms of projectors

$$\mathbf{q}_j = \frac{\mathbf{P}_j \mathbf{a}_j}{\|\mathbf{P}_j \mathbf{a}_j\|},$$

where  $\mathbf{P}_j = \mathbf{I} - \hat{\mathbf{Q}}_{j-1} \hat{\mathbf{Q}}_{j-1}^*$  with  $\hat{\mathbf{Q}}_{j-1} = [\mathbf{q}_1 \ \mathbf{q}_2 \ \dots \ \mathbf{q}_{j-1}]$

- We may view  $\mathbf{P}_j$  as product of a sequence of projections

$$\mathbf{P}_j = \mathbf{P}_{\perp_{q_{j-1}}} \mathbf{P}_{\perp_{q_{j-2}}} \dots \mathbf{P}_{\perp_{q_1}}$$

where  $\mathbf{P}_{\perp_q} = \mathbf{I} - \mathbf{q}\mathbf{q}^*$

- Instead of computing  $\mathbf{v}_j = \mathbf{P}_j \mathbf{a}_j$ , one could compute  $\mathbf{v}_j = \mathbf{P}_{\perp_{q_{j-1}}} \mathbf{P}_{\perp_{q_{j-2}}} \dots \mathbf{P}_{\perp_{q_1}} \mathbf{a}_j$  instead, resulting in modified Gram-Schmidt algorithm



# Modified Gram-Schmidt Orthogonalization

Classical Gram-Schmidt method:

**for**  $j = 1$  **to**  $n$

$\mathbf{v}_j = \mathbf{a}_j$ ;

**for**  $i = 1$  **to**  $j - 1$

$r_{ij} = \mathbf{q}_i^* \mathbf{a}_j$

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Modified Gram-Schmidt method:

**for**  $j = 1$  **to**  $n$

$\mathbf{v}_j = \mathbf{a}_j$

**for**  $i = 1$  **to**  $n$

$r_{ii} = \|\mathbf{v}_i\|_2$

$\mathbf{q}_i = \mathbf{v}_i / r_{ii}$

**for**  $j = i + 1$  **to**  $n$

$r_{ij} = \mathbf{q}_i^* \mathbf{v}_j$

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# Modified Gram-Schmidt Orthogonalization

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**for**  $j = i + 1$  **to**  $n$

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$\mathbf{v}_j = \mathbf{v}_j - r_{ij} \mathbf{q}_i$

- Key difference between CGS and MGS is how  $r_{ij}$  is computed
- CGS above is column-oriented (in the sense that  $R$  is computed column by column) and MGS above is row-oriented, but this is NOT the main difference between CGS and MGS. There are also column-oriented MGS and row-oriented CGS.
- MGS is numerically more stable than CGS (less sensitive to round-off errors)

# Example: CGS vs. MGS

- Consider matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 \\ \varepsilon & 0 & 0 \\ 0 & \varepsilon & 0 \\ 0 & 0 & \varepsilon \end{bmatrix}$$

where  $\varepsilon$  is small such that  $1 + \varepsilon^2 = 1$  with round-off error

- For both CGS and MGS

$$\begin{aligned} \mathbf{v}_1 &\leftarrow (1, \varepsilon, 0, 0)^T, r_{11} = \sqrt{1 + \varepsilon^2} \approx 1, \mathbf{q}_1 = \mathbf{v}_1 / r_{11} = (1, \varepsilon, 0, 0)^T, \\ \mathbf{v}_2 &\leftarrow (1, 0, \varepsilon, 0)^T, r_{12} = \mathbf{q}_1^T \mathbf{a}_2 (\text{or } = \mathbf{q}_1^T \mathbf{v}_2) = 1 \\ \mathbf{v}_2 &\leftarrow \mathbf{v}_2 - r_{12} \mathbf{q}_1 = (0, -\varepsilon, \varepsilon, 0)^T \\ r_{22} &= \sqrt{2} \varepsilon, \mathbf{q}_2 = (0, -1, 1, 0) / \sqrt{2}, \\ \mathbf{v}_3 &\leftarrow (1, 0, 0, \varepsilon)^T, r_{13} = \mathbf{q}_1^T \mathbf{a}_3 (\text{or } = \mathbf{q}_1^T \mathbf{v}_3) = 1 \\ \mathbf{v}_3 &\leftarrow \mathbf{v}_3 - r_{13} \mathbf{q}_1 = (0, -\varepsilon, 0, \varepsilon)^T \end{aligned}$$

## Example: CGS vs. MGS Cont'd

- For CGS:

$$\begin{aligned}r_{23} &= \mathbf{q}_2^T \mathbf{a}_3 = 0, \mathbf{v}_3 \leftarrow \mathbf{v}_3 - r_{23} \mathbf{q}_2 = (0, -\varepsilon, 0, \varepsilon)^T \\ r_{33} &= \sqrt{2}\varepsilon, \mathbf{q}_3 = \mathbf{v}_3 / r_{33} = (0, -1, 0, 1)^T / \sqrt{2}\end{aligned}$$

- Note that  $\mathbf{q}_2^T \mathbf{q}_3 = (0, -1, 1, 0)(0, -1, 0, 1)^T / 2 = 1/2$

- For MGS:

$$\begin{aligned}r_{23} &= \mathbf{q}_2^T \mathbf{a}_3 = \varepsilon / \sqrt{2}, \mathbf{v}_3 \leftarrow \mathbf{v}_3 - r_{23} \mathbf{q}_2 = (0, -\varepsilon/2, -\varepsilon/2, \varepsilon)^T \\ r_{33} &= \sqrt{6}\varepsilon/2, \mathbf{q}_3 = \mathbf{v}_3 / r_{33} = (0, -1, -1, 2)^T / \sqrt{6}\end{aligned}$$

- Note that  $\mathbf{q}_2^T \mathbf{q}_3 = (0, -1, 1, 0)(0, -1, -1, 2)^T / \sqrt{12} = 0$

# Operation Count

- It is important to assess the efficiency of algorithms. But how?
  - We could implement different algorithms and do head-to-head comparison, but implementation details might affect true performance
  - We could estimate cost of all operations, but it is very tedious
  - Relatively simple and effective approach is to estimate amount of floating-point operations, or 'flops', and focus on asymptotic analysis as sizes of matrices approach infinity
- Count each operation  $+$ ,  $-$ ,  $*$ ,  $/$ , and  $\sqrt{\phantom{x}}$  as one flop, and make no distinction of real and complex numbers

## Theorem

CGS and MGS require  $\sim 2mn^2$  flops to compute a QR factorization of an  $m \times n$  matrix.