ADVANCED TOPICS IN POMP

AARON A. KING

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This document serves to give some examples of the use of native (C or FORTRAN) codes in pomp and to introduce the low-level interface to pomp objects.

1. Acceleration using native codes.

Since many of the methods we will use require us to simulate the process and/or measurement models many times, it is a good idea to use native (compiled) codes for the computational heavy lifting. This can result in many-fold speedup. The pomp package includes some examples that use C codes. First we'll have a look at how the discrete-time bivariate AR(1) process with normal measurement error is implemented. You can load a pomp object for this model and have a look at its structure with the commands

```
require(pomp)
data(ou2)
show(ou2)
```

Here we'll examine how this object is put together. The process model simulator and density functions are as follows:

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```
xstart = as.double(xstart),
              par = as.double(params),
              times = as.double(times),
              n = as.integer(c(nvar,npar,nrep,ntimes)),
              parindex = as.integer(parindex),
              DUP = FALSE,
              NAOK = TRUE,
              PACKAGE = "pomp"
               )$X,
           dim=c(nvar,nrep,ntimes),
           dimnames=list(rownames(xstart), NULL, NULL)
   }
   ou2.dprocess <- function (x, times, params, log, paramnames, ...) {
     nvar <- nrow(x)</pre>
     npar <- nrow(params)</pre>
     nrep <- ncol(x)</pre>
     ntimes <- length(times)</pre>
     parindex <- match(paramnames,rownames(params))-1</pre>
     array(
            .C("ou2_pdf",
              d = double(nrep*(ntimes-1)),
              X = as.double(x),
              par = as.double(params),
              times = as.double(times),
              n = as.integer(c(nvar,npar,nrep,ntimes)),
              parindex = as.integer(parindex),
              give_log=as.integer(log),
              DUP = FALSE,
              NAOK = TRUE,
              PACKAGE = "pomp"
               )$d,
           dim=c(nrep,ntimes-1)
   }
The call that constructs the pomp object is:
 ou2 <- pomp(
             data=data.frame(
                time=seq(1,100),
               y1=NA,
               y2=NA
               ),
              times="time",
             t0=0,
             rprocess = ou2.rprocess,
             dprocess = ou2.dprocess,
             dmeasure = "normal_dmeasure",
             rmeasure = "normal_rmeasure",
             paramnames=c(
                "alpha.1", "alpha.2", "alpha.3", "alpha.4",
```

```
"sigma.1","sigma.2","sigma.3",
   "tau"
),
statenames = c("x1","x2"),
PACKAGE="pomp"
)
```

Notice that the process model is implemented using using .C, while the measurement model is specified by giving the names of native C routines. Read the source to see the definitions of these functions. For convenience, the source codes are provided with the package in the examples directory. Do

```
edit(file=system.file("examples/ou2.c",package="pomp"))
```

to view the source code.

We'll specify some parameters:

Time difference of 1.417655 secs

In this example, we've written our simulators and density functions "from scratch". pomp provides "plug-in" facilities to make it easier to define certain kinds of models. These plug-ins can be used with native codes as well, as we'll see in the next example.

2. The seasonal SIR model implemented using compiled native routines

In the "intro_to_pomp" vignette, we looked at the SIR model, which we implemented using an Euler-multinomial approximation to the continuous-time Markov process. Here is the same model implemented using native C codes:

```
pomp(
    data=data.frame(
        time=seq(from=1/52, to=4, by=1/52),
        reports=NA
    ),
    times="time",
    t0=0,
    ## native routine for the process simulator:
    rprocess=euler.sim(
        step.fun="sir_euler_simulator",
        delta.t=1/52/20
    ),
    ## native routine for the skeleton:
```

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```
skeleton.vectorfield="sir_ODE",
## binomial measurement model:
rmeasure="binom_rmeasure",
## binomial measurement model:
dmeasure="binom_dmeasure",
PACKAGE="pomp", ## name of the shared-object library
## the order of the state variables assumed in the native routines:
statenames=c("S","I","R","cases","W"),
## the order of the parameters assumed in the native routines:
paramnames=c(
  "gamma", "mu", "iota", "beta1", "beta.sd",
  "pop", "rho", "nbasis", "degree", "period"
  ),
## reset cases to zero at each new observation:
zeronames=c("cases"),
initializer=function(params, t0,...){
 p <- exp(params)</pre>
  with(
       as.list(p),
       {
         fracs \leftarrow c(S.0, I.0, R.0)
         x0 <- round(c(pop*fracs/sum(fracs),0,0))</pre>
         names(x0) <- c("S","I","R","cases","W")</pre>
       }
       )
) -> sir
```

The source code for the native routines sir_euler_simulator, sir_ODE, binom_rmeasure, and binom_dmeasure is provided with the package (in the examples directory). To see the source code, do

```
edit(file=system.file("examples/sir.c",package="pomp"))
```

Also in the examples directory is an R script that shows how to compile sir.c into a shared-object library and link it with R.

Let's specify some parameters and simulate:

Time difference of 0.6144068 secs

```
tic <- Sys.time()
traj <- trajectory(sir,hmax=1/52)
toc <- Sys.time()
print(toc-tic)</pre>
```

Time difference of 0.2375131 secs

3. The low-level interface

There is a low-level interface to pomp objects, primarily designed for package developers. Ordinary users should have little reason to use this interface. In this section, each of the methods that make up this interface will be introduced.

Getting initial states. The init.state method is called to initialize the state (unobserved) process. It takes a vector or matrix of parameters and returns a matrix of initial states.

```
data(ou2)
true.p <- coef(ou2)
x0 <- init.state(ou2)
x0

[,1]
x1   -3
x2   4

new.p <- cbind(true.p,true.p,true.p)
new.p["x1.0",] <- 1:3
init.state(ou2,params=new.p)

[,1] [,2] [,3]
x1   1   2   3
x2   4   4   4</pre>
```

Simulating the process model. The rprocess method gives access to the process model simulator. It takes initial conditions (which need not correspond to the zero-time t0 specified when the pomp object was constructed), a set of times, and a set of parameters. The initial states and parameters must be matrices, and they are checked for commensurability. The method returns a rank-3 array containing simulated state trajectories, sampled at the times specified.

```
x <- rprocess(ou2,xstart=x0,times=time(ou2,t0=T),params=as.matrix(true.p))
dim(x)

[1] 2 1 101

x[,,1:5]

[,1] [,2] [,3] [,4] [,5]

x1 -3 0.4818917 1.414307 2.430473 4.298055
x2 4 3.1569381 2.435648 1.652435 2.384673</pre>
```

Note that the dimensions of x are nvars x nreps x ntimes, where nvars is the number of state variables, nreps is the number of simulated trajectories (which is the number of columns in the params and xstart matrices), and ntimes is the length of the times argument. Note also that x[,,1] is identical to xstart.

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Simulating the measurement model. The rmeasure method gives access to the measurement model simulator:

Process and measurement model densities. The dmeasure and dprocess methods give access to the measurement and process model densities, respectively.

```
fp <- dprocess(ou2, x=x, times=time(ou2), params=as.matrix(true.p))
dim(fp)

[1] 1 99

fp[,36:40]

[1] 0.003988565 0.023216103 0.008546941 0.001208048

[5] 0.004726450

fm <- dmeasure(ou2, y=y[,1,], x=x, times=time(ou2), params=as.matrix(true.p))
dim(fm)

[1] 1 100

fm[,36:40]</pre>
```

[1] 0.08650342 0.07017731 0.08825893 0.01986403 0.03125561

All of these are to be preferred to direct access to the slots of the pomp object, because they do error checking on the inputs and outputs.

4. Other examples

There are a number of example pomp objects included with the package. These can be found by running

```
data(package="pomp")
```

The R scripts that generated these are included in the data-R directory of the installed package. The majority of these use compiled code, which can be found in the package source.

A. A. King, Departments of Ecology & Evolutionary Biology and Mathematics, University of Michigan, Ann Arbor, Michigan 48109-1048 USA

```
E	ext{-}mail\ address: kingaa at umich dot edu URL: http:pomp.r-forge.r-project.org
```