

USING COMPILED CODE IN POMP

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1. THE LOW-LEVEL INTERFACE

There is a low-level interface to **pomp** objects, primarily designed for package developers. Ordinary users should have little reason to use this interface. In this section, each of the methods that make up this interface will be introduced.

The `init.state` method is called to initialize the state (unobserved) process. It takes a vector or matrix of parameters and returns a matrix of initial states.

```
data(ou2)
true.p <- coef(ou2)
x0 <- init.state(ou2)
x0

      [,1]
x1      50
x2     -50

new.p <- cbind(true.p, true.p, true.p)
new.p["x1.0", ] <- 1:3
init.state(ou2, params = new.p)

      [,1] [,2] [,3]
x1      1    2    3
x2     -50  -50  -50
```

The `rprocess` method gives access to the process model simulator. It takes initial conditions (which need not correspond to the zero-time `t0` specified when the **pomp** object was constructed), a set of times, and a set of parameters. The initial states and parameters must be matrices, and they are checked for commensurability. The method returns a rank-3 array containing simulated state trajectories, sampled at the times specified.

```
x <- rprocess(ou2, xstart = x0, times = time(ou2,
      t0 = T), params = as.matrix(true.p))
dim(x)
```

```
[1] 2 1 101
```

```
x[, , 1:5]
```

```
      [,1]      [,2]      [,3]      [,4]      [,5]
x1  50  44.30555  39.77838  37.21832  33.96139
x2 -50 -47.31719 -47.78786 -42.91187 -46.40403
```

Note that the dimensions of `x` are `nvars x nreps x ntimes`, where `nvars` is the number of state variables, `nreps` is the number of simulated trajectories (which is the number of columns in the `params` and `xstart` matrices), and `ntimes` is the length of the `times` argument. Note also that `x[, ,1]` is identical to `xstart`.

The `rmeasure` method gives access to the measurement model simulator:

```
x <- x[, , -1, drop = F]
y <- rmeasure(ou2, x = x, times = time(ou2), params = as.matrix(true.p))
dim(y)
```

```
[1] 2 1 100
```

```
y[, , 1:5]
```

```
      [,1]      [,2]      [,3]      [,4]      [,5]
y1  46.04027  39.85474  37.20344  34.09994  31.55727
y2 -46.63870 -46.11194 -41.49220 -47.41769 -45.55778
```

The `dmeasure` and `dprocess` methods give access to the measurement and process model densities, respectively.

```
dprocess(ou2, x[, , 36:41, drop = F], times = time(ou2)[35:40],
  params = as.matrix(true.p))
```

```
      [,1]      [,2]      [,3]      [,4]      [,5]
[1,] 0.01907030 0.02469285 0.03349765 0.05539911 0.04743258
```

```
dmeasure(ou2, y = y[, 1, 1:4], x = x[, , 1:4,
  drop = F], times = time(ou2)[1:4], params = as.matrix(true.p))
```

```
      [,1]      [,2]      [,3]      [,4]
[1,] 0.02808023 0.03896308 0.05809258 0.09430426
```

All of these are to be preferred to direct access to the slots of the `pomp` object, because they do sanity checks on the inputs and outputs.

2. ACCELERATION USING NATIVE CODES.

Since many of the methods we will use require us to simulate the process and/or measurement models many times, it is a good idea to use native (compiled) codes for the computational heavy lifting. This can result in many-fold speedup. The `pomp` package includes some examples that use C codes. Here, we'll have a look at how the discrete-time 2-D Ornstein-Uhlenbeck process with normal measurement error is implemented.

Recall that the unobserved Ornstein-Uhlenbeck (OU) process $X_t \in \mathbb{R}^2$ satisfies

$$X_t = A X_{t-1} + \xi_t.$$

The observation process is

$$Y_t = B X_t + \varepsilon_t.$$

In these equations, A and B are 2×2 constant matrices; ξ_t and ε_t are mutually-independent families of i.i.d. bivariate normal random variables. We let $\sigma\sigma^T$ be the variance-covariance matrix of ξ_t , where σ is lower-triangular; likewise, we let $\tau\tau^T$ be that of ε_t .

You can load a `pomp` object for this model with the command

```
data(ou2)
```

Here we'll examine how this object is put together.

The process model simulator and density functions are as follows:

```
ou2.rprocess <- function(xstart, times, params,
  paramnames, ...) {
  nvar <- nrow(xstart)
  npar <- nrow(params)
  nrep <- ncol(xstart)
  ntimes <- length(times)
  parindex <- match(paramnames, rownames(params)) -
    1
  array(.C("ou2_adv", X = double(nvar * nrep *
    ntimes), xstart = as.double(xstart), par = as.double(params),
    times = as.double(times), n = as.integer(c(nvar,
      npar, nrep, ntimes)), parindex = as.integer(parindex),
    DUP = FALSE, NAOK = TRUE, PACKAGE = "pomp")$X,
    dim = c(nvar, nrep, ntimes), dimnames = list(rownames(xstart),
      NULL, NULL))
}

ou2.dprocess <- function(x, times, params, log,
  paramnames, ...) {
  nvar <- nrow(x)
  npar <- nrow(params)
  nrep <- ncol(x)
  ntimes <- length(times)
  parindex <- match(paramnames, rownames(params)) -
    1
  array(.C("ou2_pdf", d = double(nrep * (ntimes -
    1)), X = as.double(x), par = as.double(params),
    times = as.double(times), n = as.integer(c(nvar,
      npar, nrep, ntimes)), parindex = as.integer(parindex),
    give_log = as.integer(log), DUP = FALSE,
    NAOK = TRUE, PACKAGE = "pomp")$d, dim = c(nrep,
    ntimes - 1))
}
```

The call that constructs the `pomp` object is:

```
ou2 <- pomp(times = seq(1, 100), data = rbind(y1 = rep(0,
  100), y2 = rep(0, 100)), t0 = 0, rprocess = ou2.rprocess,
  dprocess = ou2.dprocess, dmeasure = "normal_dmeasure",
  rmeasure = "normal_rmeasure", paramnames = c("alpha.1",
    "alpha.2", "alpha.3", "alpha.4", "sigma.1",
```

```
"sigma.2", "sigma.3", "tau"), statenames = c("x1",
"x2"))
```

Notice that the process model is implemented using using `.C`, while the measurement model is specified by giving the names of native C routines. Read the source (file ‘ou2.c’) to see the definitions of these functions.

We’ll specify some parameters:

```
p <- c(alpha.1 = 0.9, alpha.2 = 0, alpha.3 = 0,
      alpha.4 = 0.99, sigma.1 = 1, sigma.2 = 0,
      sigma.3 = 2, tau = 1, x1.0 = 50, x2.0 = -50)

tic <- Sys.time()
x <- simulate(ou2, params = p, nsim = 500, seed = 800733088)
toc <- Sys.time()
print(toc - tic)
```

Time difference of 1.944228 secs

In this example, we’ve written our simulators and density functions “from scratch”. `pomp` provides “plug-in” facilities to make it easier to define certain kinds of models. These plug-ins can be used with native codes as well, as we’ll see in the next example.

3. A MORE COMPLEX EXAMPLE: A SEASONAL SIR MODEL

```
euler.sir <- pomp(times = seq(1/52, 4, by = 1/52),
  data = rbind(measles = numeric(52 * 4)), t0 = 0,
  tcovar = seq(0, 25, by = 1/52), covar = matrix(periodic.bspline.basis(seq(0,
    25, by = 1/52), nbasis = 3, period = 1,
    degree = 3), ncol = 3, dimnames = list(NULL,
    paste("seas", 1:3, sep = ""))), delta.t = 1/52/20,
  statenames = c("S", "I", "R", "cases", "W",
    "B", "dW"), paramnames = c("gamma", "mu",
    "iota", "beta1", "beta.sd", "pop", "rho"),
  covarnames = c("seas1"), zeronames = c("cases"),
  comp.names = c("S", "I", "R"), step.fun = "sir_euler_simulator",
  rprocess = euler.simulate, dens.fun = "sir_euler_density",
  dprocess = onestep.density, skeleton.vectorfield = "sir_ODE",
  rmeasure = "binom_rmeasure", dmeasure = "binom_dmeasure",
  PACKAGE = "pomp", initializer = function(params,
    t0, comp.names, ...) {
    p <- exp(params)
    snames <- c("S", "I", "R", "cases", "W",
      "B", "SI", "SD", "IR", "ID", "RD",
      "dW")
    fracs <- p[paste(comp.names, "0", sep = ".")]
    x0 <- numeric(length(snames))
    names(x0) <- snames
    x0[comp.names] <- round(p["pop"] * fracs/sum(fracs))
    x0
  })
```

```
coef(euler.sir) <- log(c(gamma = 26, mu = 0.02,  
  iota = 0.01, beta1 = 1200, beta2 = 1800, beta3 = 600,  
  beta.sd = 0.001, pop = 2100000, rho = 0.6,  
  S.0 = 26/1200, I.0 = 0.001, R.0 = 1 - 0.001 -  
    26/1200))  
  
euler.sir <- simulate(euler.sir, nsim = 1, seed = 329348545L)
```

This example can be loaded via

```
data(euler.sir)
```

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