ADVANCED TOPICS IN POMP

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Contents

1.	The low-level interface	1
2.	Acceleration using native codes.	3
3.	A more complex example: a seasonal SIR model	5

This document serves to introduce the low-level interface to pomp objects and to give some examples of the use of native (C or FORTRAN) codes in pomp.

1. The low-level interface

There is a low-level interface to pomp objects, primarily designed for package developers. Ordinary users should have little reason to use this interface. In this section, each of the methods that make up this interface will be introduced.

The init.state method is called to initialize the state (unobserved) process. It takes a vector or matrix of parameters and returns a matrix of initial states.

```
data(ou2)
 true.p <- coef(ou2)</pre>
 x0 <- init.state(ou2)
 x0
   [,1]
x1
     -3
x2
       4
new.p <- cbind(true.p,true.p,true.p)</pre>
 new.p["x1.0",] \leftarrow 1:3
 init.state(ou2,params=new.p)
   [,1] [,2] [,3]
x1
      1
            2
                  3
                  4
```

The rprocess method gives access to the process model simulator. It takes initial conditions (which need not correspond to the zero-time to specified when the pomp object was constructed), a set of times, and a set of parameters. The initial states and parameters must be matrices, and they are checked for commensurability. The method returns a rank-3 array containing simulated state trajectories, sampled at the times specified.

1

2 A. A. KING

```
x <- rprocess(ou2,xstart=x0,times=time(ou2,t0=T),params=as.matrix(true.p))
dim(x)

[1] 2 1 101

x[,,1:5]

[,1] [,2] [,3] [,4] [,5]

x1 -3 -3.283357 -0.6275075 6.035261 9.479388
x2 4 7.630037 7.6131727 10.854834 2.597988</pre>
```

Note that the dimensions of x are nvars x nreps x ntimes, where nvars is the number of state variables, nreps is the number of simulated trajectories (which is the number of columns in the params and xstart matrices), and ntimes is the length of the times argument. Note also that x[,,1] is identical to xstart.

The rmeasure method gives access to the measurement model simulator:

The dmeasure and dprocess methods give access to the measurement and process model densities, respectively.

```
fp <- dprocess(ou2, x=x, times=time(ou2), params=as.matrix(true.p))
dim(fp)

[1] 1 99

fp[,36:40]

[1] 0.006356768 0.008230949 0.011165882 0.018466369
[5] 0.015810859

fm <- dmeasure(ou2, y=y[,1,], x=x, times=time(ou2), params=as.matrix(true.p))
dim(fm)

[1] 1 100

fm[,36:40]

[1] 0.118826706 0.065905743 0.016613495 0.118275252
[5] 0.008519114</pre>
```

All of these are to be preferred to direct access to the slots of the pomp object, because they do sanity checks on the inputs and outputs.

2. Acceleration using native codes.

Since many of the methods we will use require us to simulate the process and/or measurement models many times, it is a good idea to use native (compiled) codes for the computational heavy lifting. This can result in many-fold speedup. The pomp package includes some examples that use C codes. Here, we'll have a look at how the discrete-time 2-D Ornstein-Uhlenbeck process with normal measurement error is implemented.

Recall that the unobserved Ornstein-Uhlenbeck (OU) process $X_t \in \mathbb{R}^2$ satisfies

$$X_t = A X_{t-1} + \xi_t.$$

The observation process is

$$Y_t = B X_t + \varepsilon_t.$$

In these equations, A and and B are 2×2 constant matrices; ξ_t and ε_t are mutually-independent families of i.i.d. bivariate normal random variables. We let $\sigma\sigma^T$ be the variance-covariance matrix of ξ_t , where σ is lower-triangular; likewise, we let $\tau\tau^T$ be that of ε_t .

You can load a pomp object for this model with the command

```
data(ou2)
```

Here we'll examine how this object is put together.

The process model simulator and density functions are as follows:

```
ou2.rprocess <- function (xstart, times, params, paramnames, ...) {
  nvar <- nrow(xstart)</pre>
  npar <- nrow(params)</pre>
  nrep <- ncol(xstart)</pre>
  ntimes <- length(times)</pre>
  ## get indices of the various parameters in the 'params' matrix
  ## C uses zero-based indexing!
  parindex <- match(paramnames,rownames(params))-1</pre>
  array(
        .C("ou2_adv",
           X = double(nvar*nrep*ntimes),
           xstart = as.double(xstart),
           par = as.double(params),
           times = as.double(times),
           n = as.integer(c(nvar,npar,nrep,ntimes)),
           parindex = as.integer(parindex),
           DUP = FALSE,
           NAOK = TRUE,
           PACKAGE = "pomp"
           )$X.
        dim=c(nvar,nrep,ntimes),
        dimnames=list(rownames(xstart), NULL, NULL)
        )
ou2.dprocess <- function (x, times, params, log, paramnames, ...) {
 nvar <- nrow(x)
 npar <- nrow(params)</pre>
 nrep <- ncol(x)</pre>
  ntimes <- length(times)</pre>
```

4 A. A. KING

```
parindex <- match(paramnames,rownames(params))-1</pre>
     array(
            .C("ou2_pdf",
               d = double(nrep*(ntimes-1)),
              X = as.double(x),
              par = as.double(params),
               times = as.double(times),
              n = as.integer(c(nvar,npar,nrep,ntimes)),
              parindex = as.integer(parindex),
              give_log=as.integer(log),
              DUP = FALSE,
              NAOK = TRUE,
              PACKAGE = "pomp"
               )$d,
           dim=c(nrep,ntimes-1)
           )
   }
The call that constructs the pomp object is:
 ou2 <- pomp(
              times=seq(1,100),
             data=rbind(
               y1=rep(0,100),
               y2=rep(0,100)
             t0=0,
             rprocess = ou2.rprocess,
             dprocess = ou2.dprocess,
             dmeasure = "normal_dmeasure",
             rmeasure = "normal_rmeasure",
             paramnames=c(
                "alpha.1", "alpha.2", "alpha.3", "alpha.4",
                "sigma.1", "sigma.2", "sigma.3",
                "tau"
               ),
             statenames = c("x1", "x2"),
             PACKAGE="pomp"
             )
```

Notice that the process model is implemented using using .C, while the measurement model is specified by giving the names of native C routines. Read the source (file 'ou2.c') to see the definitions of these functions.

We'll specify some parameters:

```
toc <- Sys.time()
print(toc-tic)</pre>
```

Time difference of 0.943369 secs

In this example, we've written our simulators and density functions "from scratch". pomp provides "plug-in" facilities to make it easier to define certain kinds of models. These plug-ins can be used with native codes as well, as we'll see in the next example.

3. A MORE COMPLEX EXAMPLE: A SEASONAL SIR MODEL

The SIR model is a mainstay of theoretical epidemiology. It has the deterministic skeleton

$$\frac{dS}{dt} = \mu (N - S) + \beta(t) \frac{I}{N} S$$

$$\frac{dI}{dt} = \beta(t) \frac{I}{N} S - \gamma I - \mu I$$

$$\frac{dR}{dt} = \gamma I - \mu R$$

Here N=S+I+R is the (constant) population size and β is a time-dependent contact rate. We'll assume that the contact rate is periodic and implement it as a covariate. We'll implement a stochastic version of this model using an Euler-multinomial approximation to the continuous-time Markov process. As an additional wrinkle, we'll assume that the rate of the infection process $\beta I/N$ is perturbed by white noise.

```
pomp(
      times=seq(1/52, 4, by=1/52),
     data=rbind(measles=numeric(52*4)),
      t0=0.
     statenames=c("S", "I", "R", "cases", "W"),
     paramnames=c("gamma", "mu", "iota", "beta1", "beta.sd", "pop", "rho", "nbasis", "degree", "period"),
     zeronames=c("cases"),
      comp.names=c("S","I","R"),
     rprocess=euler.sim(
        step.fun="sir_euler_simulator",
        delta.t=1/52/20
        ),
      skeleton.vectorfield="sir_ODE",
     rmeasure="binom_rmeasure",
      dmeasure="binom_dmeasure",
     PACKAGE="pomp",
      initializer=function(params, t0, comp.names, ...){
       p <- exp(params)</pre>
        snames <- c("S","I","R","cases","W")</pre>
        fracs <- p[paste(comp.names, "0", sep=".")]</pre>
        x0 <- numeric(length(snames))</pre>
        names(x0) \leftarrow snames
       x0[comp.names] <- round(p['pop']*fracs/sum(fracs))</pre>
     7
     ) -> euler.sir
```

6 A. A. KING

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