hw09

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1 Homework 09

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```
[1]: # better image quality
import matplotlib as mpl
%matplotlib inline
mpl.rcParams['figure.dpi'] = 300
```

1.1 Problem 1

1.1.1 a.)
$$\{0,1,0,0\} \circledast \{0,0,1,0\}$$

The easiest method is using the circulant matrix method:

$$\{0,1,0,0\} \circledast \{0,0,1,0\} = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

1.1.2 b.) $\{1, 1, 0, 0\} \otimes \{0, 0, 1, 1\}$

$$\{1,1,0,0\} \circledast \{0,0,1,1\} = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 2 \end{bmatrix}$$

1.2 Problem 2

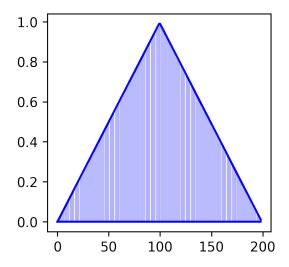
Init the discrete triangle function: ### a.)

```
[2]: import numpy as np
import matplotlib.pyplot as plt

f = np.concatenate((np.arange(0,1,0.01), np.arange(0.99,0,-0.01)))
   _, ax = plt.subplots(figsize=(3,3))
   markerline, stemlines, baseline = ax.stem(
    f,
        linefmt="b-",
```

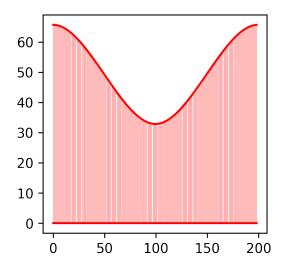
```
markerfmt="b",
  basefmt="b-",
)
plt.setp(stemlines, linewidth=0.2)
```

[2]: [None]



Compute the circular convolution:

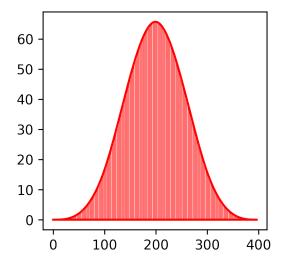
Function total data points: 199 Circular convolution total data points: 199



1.2.1 b.) numpy conv

Using the np.convolve function:

[4]: [None]



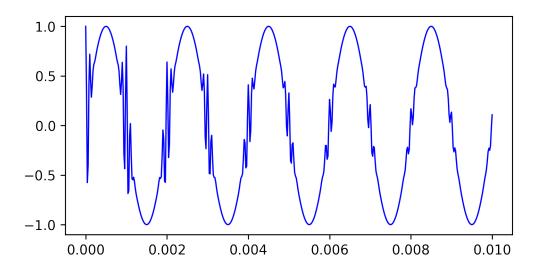
1.3 Problem 4

We can plot the data signal:

```
[5]: from scipy.io import loadmat
  from scipy.signal import firwin
  from helpers import plot_filt

data = loadmat("data/hw9prob4data.mat")
  g = data['g'][0,:]
  t = data['t'][0,:]
  plt.subplots(figsize=(6,3))
  plt.plot(t,g, 'b-', linewidth=1)
```

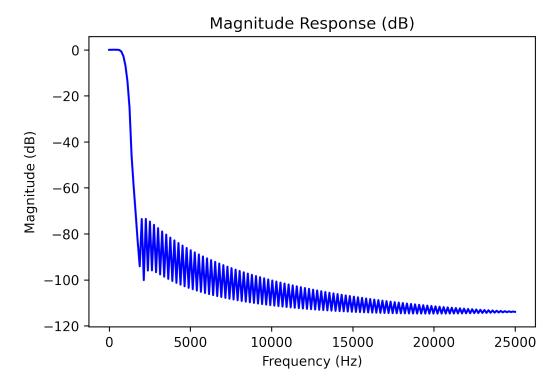
[5]: [<matplotlib.lines.Line2D at 0x13907caf0>]

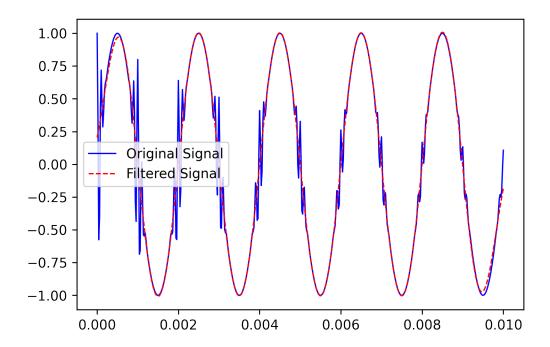


In order to stabilize and smooth out the signal we can apply a lowpass filter with a cutoff frequency (f_c) around twice the frequency of the interference. In this case, that would be ~1000Hz.

```
plot_filt(DFILT, sample_rate)
g_filtered = np.convolve(DFILT, g, "same")

# view newly filtered signal
_, ax = plt.subplots(figsize=(6,4))
ax.plot(t,g, 'b-', linewidth=1)
ax.plot(t,g_filtered,'r--', linewidth=1)
ax.legend(['Original Signal','Filtered Signal'])
plt.show()
```





We can see after the filter is applied that we get a **much** smoother signal that removes a lot of the aliasing and interference.

1.4 Problem 5

1.4.1 Part a.)

We will plot the raw data with the reconstructed image next to it

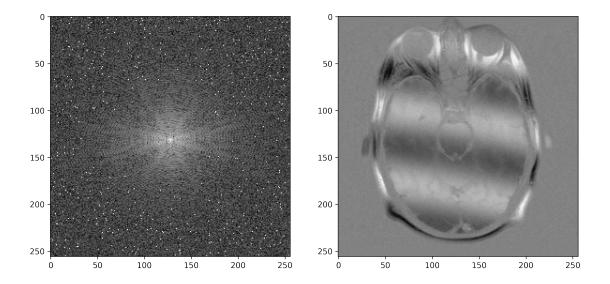
```
[93]: from helpers import ifft2c

# extract data and inverse fft
data = loadmat("data/fse_t1_ax_data.mat")
d = data['d']
d_recons = ifft2c(d)

# plot images
_, ax = plt.subplots(1,2, figsize=(12,6))
ax[0].imshow(np.abs(np.log(d)), cmap="gray")
ax[1].imshow(d_recons.real, cmap="gray")
```

/var/folders/_w/yrr0qqbd52gc6jj0fnqyk8640000gn/T/ipykernel_38912/1892396003.py:1
0: RuntimeWarning: divide by zero encountered in log
 ax[0].imshow(np.abs(np.log(d)), cmap="gray")

[93]: <matplotlib.image.AxesImage at 0x17774fd90>



1.4.2 part b.)

We can simulate reconstructing an image from half the original data (undersampled image):

: ComplexWarning: Casting complex values to real discards the imaginary part
 dhalf[:,::2] = d[:,::2]

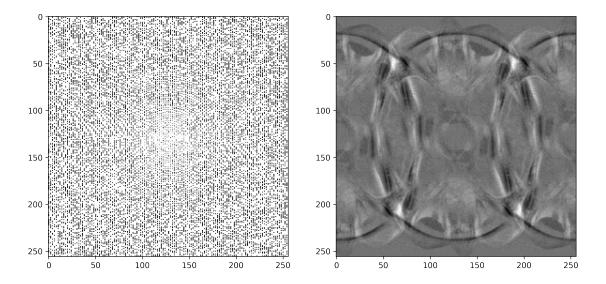
/var/folders/_w/yrr0qqbd52gc6jj0fnqyk8640000gn/T/ipykernel_38912/2291779447.py:8

: RuntimeWarning: divide by zero encountered in log ax[0].imshow(np.abs(np.log(dhalf)), cmap="gray")

/var/folders/_w/yrr0qdbd52gc6jj0fnqyk8640000gn/T/ipykernel_38912/2291779447.py:8

: RuntimeWarning: invalid value encountered in log ax[0].imshow(np.abs(np.log(dhalf)), cmap="gray")

[92]: <matplotlib.image.AxesImage at 0x1776324f0>

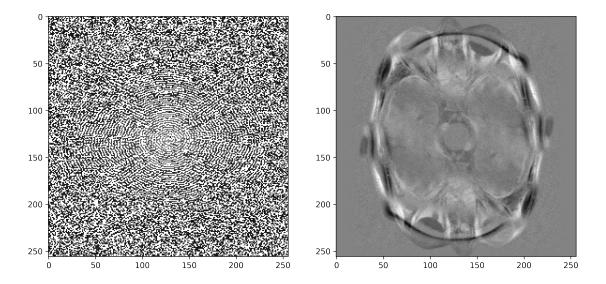


1.4.3 part c.)

Lets build and apply a filter to the MRI data using the scipy.signals.firwin package.

```
[95]: cutoff = 650 # Empirically set this to a number less than 750.
      FILTER = firwin(numtaps=33, cutoff=cutoff, pass_zero="lowpass", fs=1500)
      dfilt = np.zeros(d.shape)
      for n in range(d.shape[0]):
          dfilt[n,:] = np.convolve(FILTER, d[n,:], "same")
      dfilt_recons = ifft2c(dfilt)
      # plot images
      _, ax = plt.subplots(1,2, figsize=(12,6))
      ax[0].imshow(np.abs(np.log(dfilt)), cmap="gray")
      ax[1].imshow(dfilt_recons.real, cmap="gray")
     /var/folders/_w/yrr0qdbd52gc6jj0fnqyk8640000gn/T/ipykernel_38912/3908254211.py:6
     : ComplexWarning: Casting complex values to real discards the imaginary part
       dfilt[n,:] = np.convolve(FILTER, d[n,:], "same")
     /var/folders/_w/yrr0qdbd52gc6jj0fnqyk8640000gn/T/ipykernel_38912/3908254211.py:1
     2: RuntimeWarning: invalid value encountered in log
       ax[0].imshow(np.abs(np.log(dfilt)), cmap="gray")
```

[95]: <matplotlib.image.AxesImage at 0x28fe4c940>



1.4.4 part d.)

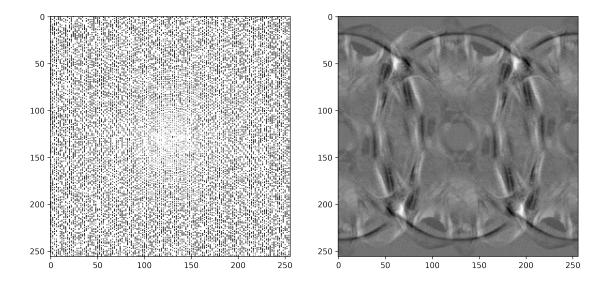
We can again simulate a subsample of the filtered data:

```
[91]: # reconstruct image from half the original data
dfilt_half = np.zeros(dfilt.shape)
dfilt_half[:,::2] = dfilt[:,::2]
dfilt_half_recons = ifft2c(dfilt_half)

# plot images
_, ax = plt.subplots(1,2, figsize=(12,6))
ax[0].imshow(np.abs(np.log(dfilt_half)), cmap="gray")
ax[1].imshow(dfilt_half_recons.real, cmap="gray")

/var/folders/_w/yrr0qqbd52gc6jj0fnqyk8640000gn/T/ipykernel_38912/2220414860.py:8
: RuntimeWarning: divide by zero encountered in log
    ax[0].imshow(np.abs(np.log(dfilt_half)), cmap="gray")
/var/folders/_w/yrr0qqbd52gc6jj0fnqyk8640000gn/T/ipykernel_38912/2220414860.py:8
: RuntimeWarning: invalid value encountered in log
    ax[0].imshow(np.abs(np.log(dfilt_half)), cmap="gray")
```

[91]: <matplotlib.image.AxesImage at 0x17756dd00>



1.4.5 part e.)