Yahboom Superbit MicroPython API

Import superbit_micropython library
`import super:bit`

`superbit.motor_control(a, b, 0)`
Function:
　　Control the motor on the expansion board to send PWM
Parameter:
　　a: Select the corresponding motor port (superbit.M1-M4)
　　b: PWM duty cycle (-255~255, negative value is reverse, positive value is positive)

`superbit.motor_control_dual(a, b, c, d, 0)`
Function:
　　Control two motors on the expansion board to send PWM at the same time
Parameter:
　　a: Select the corresponding motor1 port (superbit.M1-M4)
　　b: Select the corresponding motor2 port (superbit.M1-M4)
　　c: PWM duty cycle of motor1(-255~255, negative value is reverse, positive value is positive)
　　d: PWM duty cycle of motor2(-255~255, negative value is reverse, positive value is positive)

`superbit.servo270(a, b)`
Function:
　　Control the control the 270 ° servo on servo interface on the expansion board
Parameter:
　　a: Select the servo port number (superbit.S1-8)
　　b: Set the control angle (0-270)

`superbit.stepper_control(a, b)`
Function:
　　Controlling stepper motors on expansion boards
Parameter:
　　a: Select the servo port number（superbit.B1-2）
　　b: Set the control angle (0-360)

Note:
The superbit-micropython library is a driver for the superbit expansion board added to the official microbit-microPython library. Other APIs can be found on the microbit-microPython website.
URL: https://microbit-micropython.readthedocs.io/en/latest/