view frames Result Recorded at time: 1706400514.126213 map Broadcaster: /static transform publisher Average rate: $10000.\overline{0}$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 t265 odom frame Broadcaster: /t265/realsense2 camera manager Average rate: 200.096 Buffer length: 4.998 Most recent transform: 1706400514.107 Oldest transform: 1706400509.109 t265_pose_frame Broadcaster: /t265/realsense2 camera manager Average rate: $10\overline{0}0.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 t265 link Broadcaster: /t265/realsense2_camera_manager Broadcaster: /t265/realsense2 camera manager Broadcaster: /state publisher Broadcaster: /state publisher Average rate: $10\overline{0}0.0$ Average rate: $1\overline{00000.0}$ Average rate: $1\overline{00000.0}$ Buffer length: 0.0 Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 d455_link t265 accel frame base_link Broadcaster: /t265/realsense2 camera manager Broadcaster: /t265/realsense2 camera manager Average rate: $100\overline{0}0.0$ Average rate: $100\overline{0}0.0$ Buffer length: 0.0 Buffer length: 0.0 Most recent transform: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 Oldest transform: 0.0 t265 accel optical frame

Average rate: $10\overline{0}0.0$

Buffer length: 0.0

Most recent transform: 0.0

Oldest transform: 0.0

Average rate: 10000.0

Buffer length: 0.0

Most recent transform: 0.0

Oldest transform: 0.0

t265_gyro_frame

t265 gyro optical frame

Broadcaster: /d455/realsense2 camera manager $d455_depth_frame$ Broadcaster: /d455/realsense2 camera manager Average rate: $100\overline{0}0.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 d455 depth optical frame