# Deep Generative Models

Lecture 3

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# Recap of previous lecture

## MLE problem for autoregressive model

$$oldsymbol{ heta}^* = rg \max_{oldsymbol{ heta}} p(\mathbf{X}|oldsymbol{ heta}) = rg \max_{oldsymbol{ heta}} \sum_{i=1}^n \sum_{j=1}^m \log p(x_{ij}|\mathbf{x}_{i,1:j-1}oldsymbol{ heta}).$$

## Sampling

$$\hat{x}_1 \sim p(x_1|\boldsymbol{\theta}), \quad \hat{x}_2 \sim p(x_2|\hat{x}_1, \boldsymbol{\theta}), \ldots, \quad \hat{x}_m \sim p(x_m|\hat{\mathbf{x}}_{1:m-1}, \boldsymbol{\theta})$$

New generated object is  $\hat{\mathbf{x}} = (\hat{x}_1, \hat{x}_2, \dots, \hat{x}_m)$ .

Masking helps to make neural network autoregressive.

- ► MADE masked autoencoder (MLP).
- ► WaveNet masked 1D convolutions.
- ▶ PixelCNN masked 2D convolutions.

**PixelCNN++** uses discretized mixture of logistic distribution to make the output distribution more natural.

## Recap of previous lecture

#### Posterior distribution

$$p(\theta|\mathbf{X}) = \frac{p(\mathbf{X}|\theta)p(\theta)}{p(\mathbf{X})} = \frac{p(\mathbf{X}|\theta)p(\theta)}{\int p(\mathbf{X}|\theta)p(\theta)d\theta}$$

Bayesian inference

$$p(\mathbf{x}|\mathbf{X}) = \int p(\mathbf{x}|\boldsymbol{\theta})p(\boldsymbol{\theta}|\mathbf{X})d\boldsymbol{\theta}$$

Maximum a posteriori (MAP) estimation

$$\boldsymbol{\theta}^* = \argmax_{\boldsymbol{\theta}} p(\boldsymbol{\theta}|\mathbf{X}) = \argmax_{\boldsymbol{\theta}} \left(\log p(\mathbf{X}|\boldsymbol{\theta}) + \log p(\boldsymbol{\theta})\right)$$

MAP inference

$$p(\mathbf{x}|\mathbf{X}) = \int p(\mathbf{x}|\theta)p(\theta|\mathbf{X})d\theta \approx p(\mathbf{x}|\theta^*).$$

# Latent variable models (LVM)

## MLE problem

$$m{ heta}^* = rg \max_{m{ heta}} p(\mathbf{X}|m{ heta}) = rg \max_{m{ heta}} \prod_{i=1}^n p(\mathbf{x}_i|m{ heta}) = rg \max_{m{ heta}} \sum_{i=1}^n \log p(\mathbf{x}_i|m{ heta}).$$

The distribution  $p(\mathbf{x}|\theta)$  could be very complex and intractable (as well as real distribution  $\pi(\mathbf{x})$ ).

## Extended probabilistic model

Introduce latent variable z for each sample x

$$p(\mathbf{x}, \mathbf{z}|\theta) = p(\mathbf{x}|\mathbf{z}, \theta)p(\mathbf{z}); \quad \log p(\mathbf{x}, \mathbf{z}|\theta) = \log p(\mathbf{x}|\mathbf{z}, \theta) + \log p(\mathbf{z}).$$

$$p(\mathbf{x}|\theta) = \int p(\mathbf{x}, \mathbf{z}|\theta)d\mathbf{z} = \int p(\mathbf{x}|\mathbf{z}, \theta)p(\mathbf{z})d\mathbf{z}.$$

#### Motivation

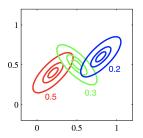
The distributions  $p(\mathbf{x}|\mathbf{z}, \theta)$  and  $p(\mathbf{z})$  could be quite simple.

# Latent variable models (LVM)

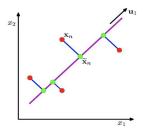
$$\log p(\mathbf{x}|oldsymbol{ heta}) = \log \int p(\mathbf{x}|\mathbf{z},oldsymbol{ heta}) p(\mathbf{z}) d\mathbf{z} 
ightarrow \max_{oldsymbol{ heta}}$$

### Examples

Mixture of gaussians



#### PCA model

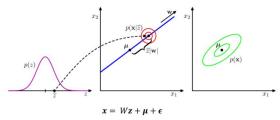


- $ho(\mathbf{x}|z, oldsymbol{ heta}) = \mathcal{N}(\mathbf{x}|oldsymbol{\mu}_z, oldsymbol{\Sigma}_z)$
- $ightharpoonup p(z) = \mathsf{Categorical}(\pi)$
- $p(\mathbf{z}) = \mathcal{N}(\mathbf{z}|0,\mathbf{I})$

# Latent variable models (LVM)

$$\log p(\mathbf{x}|oldsymbol{ heta}) = \log \int p(\mathbf{x}|\mathbf{z},oldsymbol{ heta}) p(\mathbf{z}) d\mathbf{z} 
ightarrow \max_{oldsymbol{ heta}}$$

**PCA** projects original data **X** onto a low dimensional latent space while maximizing the variance of the projected data.



- $p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) = \mathcal{N}(\mathbf{x}|\mathbf{W}\mathbf{z} + \boldsymbol{\mu}, \sigma^2 \mathbf{I})$
- $p(z) = \mathcal{N}(z|0, I)$
- $p(\mathbf{x}) = \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}, \mathbf{W}\mathbf{W}^T + \sigma^2 \mathbf{I})$
- $p(\mathbf{z}|\mathbf{x}) = \mathcal{N}(\mathbf{M}^{-1}\mathbf{W}^T(\mathbf{x} \boldsymbol{\mu}), \sigma^2\mathbf{M}), \text{ where } \mathbf{M} = \mathbf{W}\mathbf{W}^T + \sigma^2\mathbf{I}$

## Maximum likelihood estimation for LVM

## MLE for extended problem

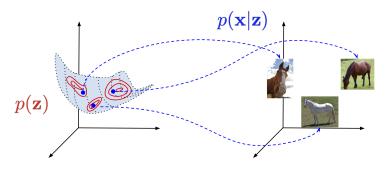
$$egin{aligned} m{ heta}^* &= rg\max_{m{ heta}} p(\mathbf{X}, \mathbf{Z} | m{ heta}) = rg\max_{m{ heta}} \prod_{i=1}^n p(\mathbf{x}_i, \mathbf{z}_i | m{ heta}) = \ &= rg\max_{m{ heta}} \sum_{i=1}^n \log p(\mathbf{x}_i, \mathbf{z}_i | m{ heta}). \end{aligned}$$

However, **Z** is unknown.

## MLE for original problem

$$\begin{aligned} \boldsymbol{\theta}^* &= \arg\max_{\boldsymbol{\theta}} \log p(\mathbf{X}|\boldsymbol{\theta}) = \arg\max_{\boldsymbol{\theta}} \sum_{i=1}^n \log p(\mathbf{x}_i|\boldsymbol{\theta}) = \\ &= \arg\max_{\boldsymbol{\theta}} \sum_{i=1}^n \log \int p(\mathbf{x}_i, \mathbf{z}_i|\boldsymbol{\theta}) d\mathbf{z}_i = \\ &= \arg\max_{\boldsymbol{\theta}} \log \sum_{i=1}^n \int p(\mathbf{x}_i|\mathbf{z}_i, \boldsymbol{\theta}) p(\mathbf{z}_i) d\mathbf{z}_i. \end{aligned}$$

# Naive approach



#### Monte-Carlo estimation

$$p(\mathbf{x}|\boldsymbol{\theta}) = \int p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) p(\mathbf{z}) d\mathbf{z} = \mathbb{E}_{p(\mathbf{z})} p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) pprox rac{1}{K} \sum_{k=1}^{K} p(\mathbf{x}|\mathbf{z}_k, \boldsymbol{\theta})$$

**Challenge:** to cover the space properly, the number of samples grows exponentially with respect to dimensionality of **z**.

## Variational lower bound

#### Derivation 1

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \log \int p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta}) d\mathbf{z} =$$

$$= \log \int \frac{q(\mathbf{z})}{q(\mathbf{z})} p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta}) d\mathbf{z} = \log \mathbb{E}_q \left[ \frac{p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta})}{q(\mathbf{z})} \right] \geq$$

$$\geq \mathbb{E}_q \log \frac{p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta})}{q(\mathbf{z})} = \int q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta})}{q(\mathbf{z})} d\mathbf{z} = \mathcal{L}(q, \boldsymbol{\theta})$$

#### Derivation 2

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \int q(\mathbf{z}) \log p(\mathbf{x}|\boldsymbol{\theta}) d\mathbf{z} =$$

$$= \int q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta})}{p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})} d\mathbf{z} = \int q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta})q(\mathbf{z})}{p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})q(\mathbf{z})} d\mathbf{z} =$$

$$= \int q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta})}{q(\mathbf{z})} d\mathbf{z} + \int q(\mathbf{z}) \log \frac{q(\mathbf{z})}{p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})} d\mathbf{z} =$$

$$= \mathcal{L}(q, \boldsymbol{\theta}) + KL(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})) \ge \mathcal{L}(q, \boldsymbol{\theta}).$$

### Variational lower bound

## Evidence Lower Bound (ELBO)

$$\mathcal{L}(q, \theta) = \int q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}|\theta)}{q(\mathbf{z})} d\mathbf{z} =$$

$$= \int q(\mathbf{z}) \log p(\mathbf{x}|\mathbf{z}, \theta) d\mathbf{z} + \int q(\mathbf{z}) \log \frac{p(\mathbf{z})}{q(\mathbf{z})} d\mathbf{z}$$

$$= \mathbb{E}_q \log p(\mathbf{x}|\mathbf{z}, \theta) - KL(q(\mathbf{z})||p(\mathbf{z}))$$

#### Log-likelihood decomposition

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathbb{E}_q \log p(\mathbf{x}|\mathbf{z},\boldsymbol{\theta}) - KL(q(\mathbf{z})||p(\mathbf{z})) + KL(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x},\boldsymbol{\theta})).$$

Instead of maximizing incomplete likelihood, maximize ELBO (equivalently minimize KL)

$$\max_{m{ heta}} p(\mathbf{x}|m{ heta}) \quad o \quad \max_{m{q},m{ heta}} \mathcal{L}(m{q},m{ heta}) \equiv \min_{m{q},m{ heta}} \mathit{KL}(m{q}(\mathbf{z})||p(\mathbf{z}|\mathbf{x},m{ heta})).$$

# EM-algorithm

$$\mathcal{L}(q, oldsymbol{ heta}) = \int q(\mathbf{z}) \log p(\mathbf{x}|\mathbf{z}, oldsymbol{ heta}) d\mathbf{z} + \int q(\mathbf{z}) \log rac{p(\mathbf{z})}{q(\mathbf{z})} d\mathbf{z}.$$

### Block-coordinate optimization

- lnitialize  $\theta^*$ ;
- ► E-step

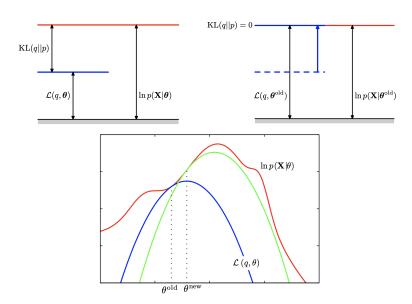
$$egin{aligned} q^*(\mathbf{z}) &= rg \max_q \mathcal{L}(q, oldsymbol{ heta}^*) = \ &= rg \min_q \mathit{KL}(q(\mathbf{z}) || \mathit{p}(\mathbf{z}|\mathbf{x}, oldsymbol{ heta}^*)) = \mathit{p}(\mathbf{z}|\mathbf{x}, oldsymbol{ heta}^*); \end{aligned}$$

M-step

$$\theta^* = \arg\max_{oldsymbol{ heta}} \mathcal{L}(q^*, oldsymbol{ heta});$$

Repeat E-step and M-step until convergence.

## **EM** illustration



### Amortized variational inference

## E-step

$$q(\mathbf{z}) = rg \max_{q} \mathcal{L}(q, oldsymbol{ heta}^*) = rg \min_{q} \mathit{KL}(q||p) = p(\mathbf{z}|\mathbf{x}, oldsymbol{ heta}^*).$$

- $\triangleright$   $p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta}^*)$  could be intractable;
- $ightharpoonup q(\mathbf{z})$  is different for each object  $\mathbf{x}$ .

#### Idea

Restrict a family of all possible distributions  $q(\mathbf{z})$  to a parametric class  $q(\mathbf{z}|\mathbf{x}, \phi)$  conditioned on samples  $\mathbf{x}$  with parameters  $\phi$ .

#### Variational Bayes

► E-step

$$\phi_k = \phi_{k-1} + \eta \nabla_{\phi} \mathcal{L}(\phi, \theta_{k-1})|_{\phi = \phi_{k-1}}$$

M-step

$$oldsymbol{ heta}_k = oldsymbol{ heta}_{k-1} + \eta 
abla_{oldsymbol{ heta}} \mathcal{L}(oldsymbol{\phi}_k, oldsymbol{ heta})|_{oldsymbol{ heta} = oldsymbol{ heta}_{k-1}}$$

# Variational EM-algorithm

#### **ELBO**

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathcal{L}(\boldsymbol{\phi}, \boldsymbol{\theta}) + \mathit{KL}(q(\mathbf{z}|\mathbf{x}, \boldsymbol{\phi})||p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})) \geq \mathcal{L}(\boldsymbol{\phi}, \boldsymbol{\theta}).$$

E-step

$$\phi_k = \phi_{k-1} + \eta \nabla_{\phi} \mathcal{L}(\phi, \theta_{k-1})|_{\phi = \phi_{k-1}},$$

where  $\phi$  – parameters of variational distribution  $q(\mathbf{z}|\mathbf{x},\phi)$ .

M-step

$$\theta_k = \theta_{k-1} + \eta \nabla_{\theta} \mathcal{L}(\phi_k, \theta)|_{\theta = \theta_{k-1}},$$

where  $\theta$  – parameters of the generative distribution  $p(\mathbf{x}|\mathbf{z},\theta)$ .

Now all we have to do is to obtain two gradients  $\nabla_{\phi} \mathcal{L}(\phi, \theta)$ ,  $\nabla_{\theta} \mathcal{L}(\phi, \theta)$ .

**Challenge:** Number of samples n could be huge (we heed to derive unbiased stochastic gradients).

# **ELBO** gradients

$$\mathcal{L}(\phi, oldsymbol{ heta}) = \mathbb{E}_q \left[ \log p(\mathbf{x}|\mathbf{z}, oldsymbol{ heta}) + \log rac{p(\mathbf{z})}{q(\mathbf{z}|\mathbf{x}, oldsymbol{\phi})} 
ight] 
ightarrow \max_{\phi, oldsymbol{ heta}}.$$

M-step:  $\nabla_{\theta} \mathcal{L}(\phi, \theta)$ 

$$egin{aligned} 
abla_{m{ heta}} \mathcal{L}(m{\phi}, m{ heta}) &= \int q(\mathbf{z}|\mathbf{x}, m{\phi}) 
abla_{m{ heta}} \log p(\mathbf{x}|\mathbf{z}, m{ heta}) d\mathbf{z} pprox \\ &pprox 
abla_{m{ heta}} \log p(\mathbf{x}|\mathbf{z}^*, m{ heta}), \quad \mathbf{z}^* \sim q(\mathbf{z}|\mathbf{x}, m{\phi}). \end{aligned}$$

# E-step: $\nabla_{\phi} \mathcal{L}(\phi, \theta)$

Difference from M-step: density function  $q(\mathbf{z}|\mathbf{x}, \phi)$  depends on the parameters  $\phi$ , it is impossible to use the Monte-Carlo estimation:

$$egin{aligned} 
abla_{\phi} \mathcal{L}(\phi, oldsymbol{ heta}) &= 
abla_{\phi} \int q(\mathbf{z}|\mathbf{x}, \phi) \left[ \log p(\mathbf{x}|\mathbf{z}, oldsymbol{ heta}) + \log rac{p(\mathbf{z})}{q(\mathbf{z}|\mathbf{x}, \phi)} 
ight] d\mathbf{z} \ &
eq \int q(\mathbf{z}|\mathbf{x}, \phi) 
abla_{\phi} \left[ \log p(\mathbf{x}|\mathbf{z}, oldsymbol{ heta}) + \log rac{p(\mathbf{z})}{q(\mathbf{z}|\mathbf{x}, \phi)} 
ight] d\mathbf{z} \end{aligned}$$

# Reparametrization trick

## Law of the unconscious statistician (LOTUS)

Let X be a random variable and let Y = g(X). Then

$$\mathbb{E}_{p_Y}Y = \mathbb{E}_{p_X}g(X) = \int g(\mathbf{x})p(\mathbf{x})d\mathbf{x}.$$

### **Examples**

- $r(x) = \mathcal{N}(x|0,1), y = \sigma \cdot x + \mu, p_Y(y|\theta) = \mathcal{N}(y|\mu,\sigma^2), \\ \theta = [\mu,\sigma].$
- $ightharpoonup \epsilon^* \sim r(\epsilon), \quad \mathbf{z} = g(\mathbf{x}, \epsilon, \phi), \quad \mathbf{z} \sim q(\mathbf{z}|\mathbf{x}, \phi)$

$$\nabla_{\phi} \int q(\mathbf{z}|\mathbf{x}, \phi) f(\mathbf{z}) d\mathbf{z} = \nabla_{\phi} \int r(\epsilon) f(\mathbf{z}) d\epsilon$$
$$= \int r(\epsilon) \nabla_{\phi} f(g(\mathbf{x}, \epsilon, \phi)) d\epsilon \approx \nabla_{\phi} f(g(\mathbf{x}, \epsilon^*, \phi))$$

# ELBO gradient (E-step, $\nabla_{\phi} \mathcal{L}(\phi, \theta)$ )

$$\nabla_{\phi} \mathcal{L}(\phi, \theta) = \nabla_{\phi} \int q(\mathbf{z}|\mathbf{x}, \phi) \log p(\mathbf{x}|\mathbf{z}, \theta) d\mathbf{z} - \nabla_{\phi} \mathsf{KL}(q(\mathbf{z}|\mathbf{x}, \phi)||p(\mathbf{z}))$$

$$= \int r(\epsilon) \nabla_{\phi} \log p(\mathbf{x}|g(\mathbf{x}, \epsilon, \phi), \theta) d\epsilon - \nabla_{\phi} \mathsf{KL}(q(\mathbf{z}|\mathbf{x}, \phi)||p(\mathbf{z}))$$

$$\approx \nabla_{\phi} \log p(\mathbf{x}|g(\mathbf{x}, \epsilon^*, \phi), \theta) - \nabla_{\phi} \mathsf{KL}(q(\mathbf{z}|\mathbf{x}, \phi)||p(\mathbf{z}))$$

#### Variational assumption

$$egin{aligned} r(\epsilon) &= \mathcal{N}(0, \mathbf{I}); \quad q(\mathbf{z}|\mathbf{x}, \phi) = \mathcal{N}(\mu_{\phi}(\mathbf{x}), \sigma_{\phi}^2(\mathbf{x})). \ \mathbf{z} &= g(\mathbf{x}, \epsilon, \phi) = \sigma_{\phi}(\mathbf{x}) \cdot \epsilon + \mu_{\phi}(\mathbf{x}). \end{aligned}$$

Here  $\mu_{\phi}(\cdot)$ ,  $\sigma_{\phi}(\cdot)$  are parameterized functions (outputs of neural network).

- p(z) prior distribution on latent variables z. We could specify any distribution that we want. Let say  $p(z) = \mathcal{N}(0, \mathbf{I})$ .
- $p(\mathbf{x}|\mathbf{z}, \theta)$  generative distibution. Since it is a parameterized function let it be neural network with parameters  $\theta$ .

# Variational autoencoder (VAE)

## Final algorithm

- ▶ pick random sample  $\mathbf{x}_i$ ,  $i \sim U[1, n]$ .
- compute the objective:

$$oldsymbol{\epsilon}^* \sim r(oldsymbol{\epsilon}); \quad \mathbf{z}^* = g(\mathbf{x}, oldsymbol{\epsilon}^*, oldsymbol{\phi});$$
  $\mathcal{L}(oldsymbol{\phi}, oldsymbol{ heta}) pprox \log p(\mathbf{x}|\mathbf{z}^*, oldsymbol{ heta}) - \mathit{KL}(q(\mathbf{z}^*|\mathbf{x}, oldsymbol{\phi})||p(\mathbf{z}^*)).$ 

lacktriangle compute a stochastic gradients w.r.t.  $\phi$  and heta

$$abla_{\phi} \mathcal{L}(\phi, \theta) pprox 
abla_{\phi} \log p(\mathbf{x}|g(\mathbf{x}, \epsilon^*, \phi), \theta) - 
abla_{\phi} \mathsf{KL}(q(\mathbf{z}|\mathbf{x}, \phi)||p(\mathbf{z}));$$

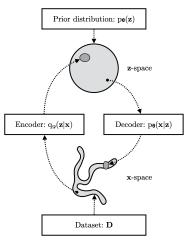
$$abla_{\theta} \mathcal{L}(\phi, \theta) pprox 
abla_{\theta} \log p(\mathbf{x}|\mathbf{z}^*, \theta).$$

• update  $\theta$ ,  $\phi$  according to the selected optimization method (SGD, Adam, RMSProp):

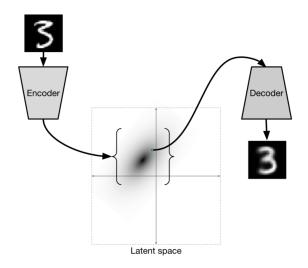
$$\phi := \phi + \eta \nabla_{\phi} \mathcal{L}(\phi, \theta),$$
  
$$\theta := \theta + \eta \nabla_{\theta} \mathcal{L}(\phi, \theta).$$

# Variational autoencoder (VAE)

- VAE learns stochastic mapping between x-space, from complicated distribution π(x), and a latent z-space, with simple distribution.
- The generative model learns a joint distribution  $p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta}) = p(\mathbf{z})p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta})$ , with a prior distribution  $p(\mathbf{z})$ , and a stochastic decoder  $p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta})$ .
- The stochastic encoder  $q(\mathbf{z}|\mathbf{x}, \phi)$  (inference model), approximates the true but intractable posterior  $p(\mathbf{z}|\mathbf{x}, \theta)$  of the generative model.



## Variational Autoencoder



# Variational autoencoder (VAE)

- lacksquare Encoder  $q(\mathbf{z}|\mathbf{x},\phi)=\mathsf{NN}_e(\mathbf{x},\phi)$  outputs  $\mu_\phi(\mathbf{x})$  and  $\sigma_\phi(\mathbf{x})$ .
- ▶ Decoder  $p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) = \mathsf{NN}_d(\mathbf{z}, \boldsymbol{\theta})$  outputs parameters of the sample distribution.

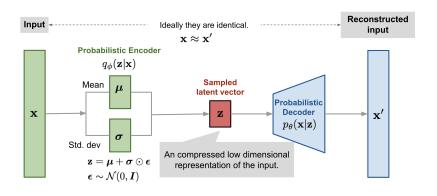


image credit:

# Bayesian framework

Posterior distribution

$$p(\theta|\mathbf{X}) = \frac{p(\mathbf{X}|\theta)p(\theta)}{p(\mathbf{X})} = \frac{p(\mathbf{X}|\theta)p(\theta)}{\int p(\mathbf{X}|\theta)p(\theta)d\theta}$$

Bayesian inference

$$p(\mathbf{x}|\mathbf{X}) = \int p(\mathbf{x}|\theta)p(\theta|\mathbf{X})d\theta$$

Maximum a posteriori (MAP) estimation

$$\boldsymbol{\theta}^* = \argmax_{\boldsymbol{\theta}} \log p(\boldsymbol{\theta}|\mathbf{X}) = \argmax_{\boldsymbol{\theta}} \bigl(\log p(\mathbf{X}|\boldsymbol{\theta}) + \log p(\boldsymbol{\theta})\bigr)$$

#### MAP inference

$$p(\mathbf{x}|\mathbf{X}) = \int p(\mathbf{x}|\theta)p(\theta|\mathbf{X})d\theta = \int p(\mathbf{x}|\theta)\delta(\theta - \theta^*)d\theta \approx p(\mathbf{x}|\theta^*).$$

# VAE as Bayesian model

#### Posterior distribution

$$p(\theta|\mathbf{X}) = \frac{p(\mathbf{X}|\theta)p(\theta)}{p(\mathbf{X})}$$

#### **ELBO**

$$\begin{aligned} \log p(\boldsymbol{\theta}|\mathbf{X}) &= \log p(\mathbf{X}|\boldsymbol{\theta}) + \log p(\boldsymbol{\theta}) - \log p(\mathbf{X}) \\ &= \mathcal{L}(q,\boldsymbol{\theta}) + \mathcal{K}L(q||p) + \log p(\boldsymbol{\theta}) - \log p(\mathbf{X}) \\ &\geq \left[\mathcal{L}(q,\boldsymbol{\theta}) + \log p(\boldsymbol{\theta})\right] - \log p(\mathbf{X}). \end{aligned}$$

#### EM-algorithm

► E-step

$$q(\mathbf{z}) = rg \max_{q} \mathcal{L}(q, oldsymbol{ heta}^*) = rg \min_{q} \mathit{KL}(q||p) = p(\mathbf{z}|\mathbf{x}, oldsymbol{ heta}^*);$$

M-step

$$oldsymbol{ heta}^* = rg \max_{oldsymbol{ heta}} \left[ \mathcal{L}(q, oldsymbol{ heta}) + \log p(oldsymbol{ heta}) 
ight].$$

## Summary

- ► LVM introduces latent representation of observed samples to make model more interpretable.
- ► LVM maximizes variational evidence lower bound (ELBO) to find MLE of model parameters.
- The general variational EM algorithm maximizes ELBO objective.
- Amortized inference allows to efficiently compute stochastic gradients for ELBO using Monte-Carlo estimation.
- ► The reparametrization trick gets unbiased gradients w.r.t to a variational posterior distribution.
- The VAE model is an LVM with two neural network: for stochastic encoder  $q(\mathbf{z}|\mathbf{x}, \phi)$  and for stochastic decoder  $p(\mathbf{x}|\mathbf{z}, \theta)$ .
- ightharpoonup VAE is not a "true" bayesian model since parameters heta do not have a prior distribution.