Deep Generative Models

Lecture 3

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Recap of previous lecture

Posterior distribution

$$p(\theta|\mathbf{X}) = \frac{p(\mathbf{X}|\theta)p(\theta)}{p(\mathbf{X})} = \frac{p(\mathbf{X}|\theta)p(\theta)}{\int p(\mathbf{X}|\theta)p(\theta)d\theta}$$

Bayesian inference

$$p(\mathbf{x}|\mathbf{X}) = \int p(\mathbf{x}|\theta)p(\theta|\mathbf{X})d\theta$$

Maximum a posteriori (MAP) estimation

$$\boldsymbol{\theta}^* = \arg\max_{\boldsymbol{\theta}} p(\boldsymbol{\theta}|\mathbf{X}) = \arg\max_{\boldsymbol{\theta}} \bigl(\log p(\mathbf{X}|\boldsymbol{\theta}) + \log p(\boldsymbol{\theta})\bigr)$$

MAP inference

$$p(\mathbf{x}|\mathbf{X}) = \int p(\mathbf{x}|\theta)p(\theta|\mathbf{X})d\theta \approx p(\mathbf{x}|\theta^*).$$

Recap of previous lecture

Latent variable models (LVM)

$$p(\mathbf{x}|\boldsymbol{\theta}) = \int p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta}) d\mathbf{z} = \int p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) p(\mathbf{z}) d\mathbf{z}.$$

MLE problem for LVM

$$\begin{aligned} \boldsymbol{\theta}^* &= \arg\max_{\boldsymbol{\theta}} \log p(\mathbf{X}|\boldsymbol{\theta}) = \arg\max_{\boldsymbol{\theta}} \sum_{i=1}^n \log p(\mathbf{x}_i|\boldsymbol{\theta}) = \\ &= \arg\max_{\boldsymbol{\theta}} \sum_{i=1}^n \log \int p(\mathbf{x}_i|\mathbf{z}_i,\boldsymbol{\theta}) p(\mathbf{z}_i) d\mathbf{z}_i. \end{aligned}$$

Naive Monte-Carlo estimation

$$p(\mathbf{x}|\boldsymbol{\theta}) = \int p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) p(\mathbf{z}) d\mathbf{z} = \mathbb{E}_{p(\mathbf{z})} p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) \approx \frac{1}{K} \sum_{k=1}^{K} p(\mathbf{x}|\mathbf{z}_k, \boldsymbol{\theta}),$$
 where $\mathbf{z}_k \sim p(\mathbf{z}).$

Recap of previous lecture

ELBO derivation 1 (inequality)

$$\log p(\mathbf{x}|\theta) = \log \int p(\mathbf{x}, \mathbf{z}|\theta) d\mathbf{z} \geq \mathbb{E}_q \log \frac{p(\mathbf{x}, \mathbf{z}|\theta)}{q(\mathbf{z})} = \mathcal{L}(q, \theta)$$

ELBO derivation 2 (equality)

$$\mathcal{L}(q, \theta) = \int q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}|\theta)}{q(\mathbf{z})} d\mathbf{z} = \int q(\mathbf{z}) \log \frac{p(\mathbf{z}|\mathbf{x}, \theta)p(\mathbf{x}|\theta)}{q(\mathbf{z})} d\mathbf{z} = \\ = \log p(\mathbf{x}|\theta) - KL(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x}, \theta))$$

Variational decomposition

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathcal{L}(q, \boldsymbol{\theta}) + KL(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})) \geq \mathcal{L}(q, \boldsymbol{\theta}).$$

Outline

1. ELBO gradients, reparametrization trick

2. Variational autoencoder (VAE)

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1. ELBO gradients, reparametrization trick

2. Variational autoencoder (VAE

ELBO gradients, (M-step, $\nabla_{\theta} \mathcal{L}(\phi, \theta)$)

$$\mathcal{L}(\phi, oldsymbol{ heta}) = \mathbb{E}_{q(\mathbf{z}|\mathbf{x}, oldsymbol{\phi})} \left[\log p(\mathbf{x}|\mathbf{z}, oldsymbol{ heta}) - \log rac{q(\mathbf{z}|\mathbf{x}, oldsymbol{\phi})}{p(\mathbf{z})}
ight]
ightarrow \max_{\phi, oldsymbol{ heta}}.$$

M-step: $\nabla_{\theta} \mathcal{L}(\phi, \theta)$

$$egin{aligned}
abla_{m{ heta}} \mathcal{L}(m{\phi}, m{ heta}) &= \int q(\mathbf{z}|\mathbf{x}, m{\phi})
abla_{m{ heta}} \log p(\mathbf{x}|\mathbf{z}, m{ heta}) d\mathbf{z} pprox \\ &pprox
abla_{m{ heta}} \log p(\mathbf{x}|\mathbf{z}^*, m{ heta}), \quad \mathbf{z}^* \sim q(\mathbf{z}|\mathbf{x}, m{\phi}). \end{aligned}$$

Naive Monte-Carlo estimation

$$p(\mathbf{x}|\boldsymbol{\theta}) = \int p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) p(\mathbf{z}) d\mathbf{z} = \mathbb{E}_{p(\mathbf{z})} p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) \approx \frac{1}{K} \sum_{k=1}^{K} p(\mathbf{x}|\mathbf{z}_k, \boldsymbol{\theta}),$$

where $\mathbf{z}_k \sim p(\mathbf{z})$.

The variational posterior $q(\mathbf{z}|\mathbf{x},\phi)$ assigns typically more probability mass in a smaller region than the prior $p(\mathbf{z})$. image credit: https://jmtomczak.github.io/blog/4/4_VAE.html

ELBO gradients, (E-step, $\nabla_{\phi}\mathcal{L}(\phi, \boldsymbol{\theta})$)

E-step: $\nabla_{\phi} \mathcal{L}(\phi, \theta)$

Difference from M-step: density function $q(\mathbf{z}|\mathbf{x}, \phi)$ depends on the parameters ϕ , it is impossible to use the Monte-Carlo estimation:

$$\nabla_{\phi} \mathcal{L}(\phi, \theta) = \nabla_{\phi} \int q(\mathbf{z}|\mathbf{x}, \phi) \left[\log p(\mathbf{x}|\mathbf{z}, \theta) - \log \frac{q(\mathbf{z}|\mathbf{x}, \phi)}{p(\mathbf{z})} \right] d\mathbf{z}$$

$$\neq \int q(\mathbf{z}|\mathbf{x}, \phi) \nabla_{\phi} \left[\log p(\mathbf{x}|\mathbf{z}, \theta) - \log \frac{q(\mathbf{z}|\mathbf{x}, \phi)}{p(\mathbf{z})} \right] d\mathbf{z}$$

Reparametrization trick (LOTUS trick)

$$r(x) = \mathcal{N}(x|0,1), y = \sigma \cdot x + \mu, p_Y(y|\theta) = \mathcal{N}(y|\mu,\sigma^2), \theta = [\mu,\sigma].$$

$$\begin{array}{c} \bullet \ \epsilon^* \sim r(\epsilon), \quad \mathsf{z} = g(\mathsf{x}, \epsilon, \phi), \quad \mathsf{z} \sim q(\mathsf{z}|\mathsf{x}, \phi) \\ \\ \nabla_\phi \int q(\mathsf{z}|\mathsf{x}, \phi) f(\mathsf{z}) d\mathsf{z} = \nabla_\phi \int r(\epsilon) f(\mathsf{z}) d\epsilon \end{array}$$

$$= \int r(\epsilon) \nabla_{\phi} f(g(\mathbf{x}, \epsilon, \phi)) d\epsilon \approx \nabla_{\phi} f(g(\mathbf{x}, \epsilon^*, \phi))$$

ELBO gradient (E-step, $\nabla_{\phi} \mathcal{L}(\phi, \theta)$)

$$\nabla_{\phi} \mathcal{L}(\phi, \theta) = \nabla_{\phi} \int q(\mathbf{z}|\mathbf{x}, \phi) \log p(\mathbf{x}|\mathbf{z}, \theta) d\mathbf{z} - \nabla_{\phi} \mathsf{KL}(q(\mathbf{z}|\mathbf{x}, \phi)||p(\mathbf{z}))$$

$$= \int r(\epsilon) \nabla_{\phi} \log p(\mathbf{x}|g(\mathbf{x}, \epsilon, \phi), \theta) d\epsilon - \nabla_{\phi} \mathsf{KL}(q(\mathbf{z}|\mathbf{x}, \phi)||p(\mathbf{z}))$$

$$\approx \nabla_{\phi} \log p(\mathbf{x}|g(\mathbf{x}, \epsilon^*, \phi), \theta) - \nabla_{\phi} \mathsf{KL}(q(\mathbf{z}|\mathbf{x}, \phi)||p(\mathbf{z}))$$

Variational assumption

$$egin{aligned} r(\epsilon) &= \mathcal{N}(0, \mathbf{I}); \quad q(\mathbf{z}|\mathbf{x}, \phi) = \mathcal{N}(\mu_{\phi}(\mathbf{x}), \sigma_{\phi}^2(\mathbf{x})). \ \mathbf{z} &= g(\mathbf{x}, \epsilon, \phi) = \sigma_{\phi}(\mathbf{x}) \cdot \epsilon + \mu_{\phi}(\mathbf{x}). \end{aligned}$$

Here $\mu_{\phi}(\cdot)$, $\sigma_{\phi}(\cdot)$ are parameterized functions (outputs of neural network).

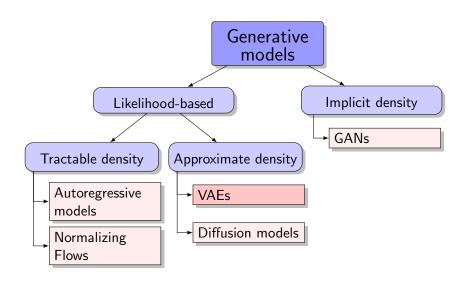
- p(z) prior distribution on latent variables z. We could specify any distribution that we want. Let say $p(z) = \mathcal{N}(0, \mathbf{I})$.
- $p(\mathbf{x}|\mathbf{z}, \theta)$ generative distibution. Since it is a parameterized function let it be neural network with parameters θ .

Outline

1. ELBO gradients, reparametrization trick

2. Variational autoencoder (VAE)

Generative models zoo



Variational autoencoder (VAE)

Final EM-algorithm

- ightharpoonup pick random sample \mathbf{x}_i , $i \sim U[1, n]$.
- compute the objective:

$$\epsilon^* \sim r(\epsilon); \quad \mathbf{z}^* = g(\mathbf{x}, \epsilon^*, \phi);$$

$$\mathcal{L}(\phi, \theta) pprox \log p(\mathbf{x}|\mathbf{z}^*, \theta) - \mathit{KL}(q(\mathbf{z}^*|\mathbf{x}, \phi)||p(\mathbf{z}^*)).$$

lacktriangle compute a stochastic gradients w.r.t. ϕ and heta

$$abla_{\phi} \mathcal{L}(\phi, \theta) pprox
abla_{\phi} \log p(\mathbf{x}|g(\mathbf{x}, \epsilon^*, \phi), \theta) -
abla_{\phi} \mathsf{KL}(q(\mathbf{z}|\mathbf{x}, \phi)||p(\mathbf{z})); \\
\nabla_{\theta} \mathcal{L}(\phi, \theta) pprox
abla_{\theta} \log p(\mathbf{x}|\mathbf{z}^*, \theta).$$

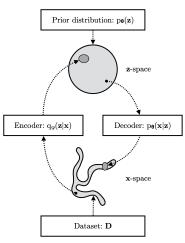
• update θ , ϕ according to the selected optimization method (SGD, Adam, RMSProp):

$$\phi := \phi + \eta \nabla_{\phi} \mathcal{L}(\phi, \theta),$$

$$\theta := \theta + \eta \nabla_{\theta} \mathcal{L}(\phi, \theta).$$

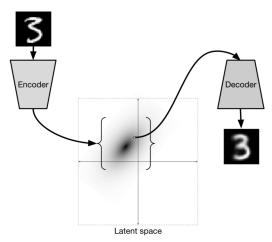
Variational autoencoder (VAE)

- VAE learns stochastic mapping between x-space, from complicated distribution π(x), and a latent z-space, with simple distribution.
- The generative model learns a joint distribution $p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta}) = p(\mathbf{z})p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta})$, with a prior distribution $p(\mathbf{z})$, and a stochastic decoder $p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta})$.
- The stochastic encoder $q(\mathbf{z}|\mathbf{x}, \phi)$ (inference model), approximates the true but intractable posterior $p(\mathbf{z}|\mathbf{x}, \theta)$ of the generative model.



Variational Autoencoder

$$\mathcal{L}(\phi, oldsymbol{ heta}) = \mathbb{E}_{q(\mathbf{z}|\mathbf{x}, \phi)} \left[\log p(\mathbf{x}|\mathbf{z}, oldsymbol{ heta}) - \log rac{q(\mathbf{z}|\mathbf{x}, \phi)}{p(\mathbf{z})}
ight]
ightarrow \max_{\phi, heta}.$$



Variational autoencoder (VAE)

- lacksquare Encoder $q(\mathbf{z}|\mathbf{x},\phi) = \mathsf{NN}_e(\mathbf{x},\phi)$ outputs $\mu_\phi(\mathbf{x})$ and $\sigma_\phi(\mathbf{x})$.
- ▶ Decoder $p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) = \mathsf{NN}_d(\mathbf{z}, \boldsymbol{\theta})$ outputs parameters of the sample distribution.

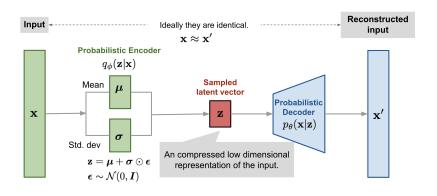


image credit:

Summary

- The general variational EM algorithm maximizes ELBO objective for LVM model to find MLE for parameters θ.
- Amortized variational inference allows to efficiently compute the stochastic gradients for ELBO using Monte-Carlo estimation.
- The reparametrization trick gets unbiased gradients w.r.t to the variational posterior distribution $q(\mathbf{z}|\mathbf{x}, \phi)$.
- The VAE model is an LVM with two neural network: stochastic encoder $q(\mathbf{z}|\mathbf{x}, \phi)$ and stochastic decoder $p(\mathbf{x}|\mathbf{z}, \theta)$.