Deep Generative Models

Lecture 2

Roman Isachenko

Moscow Institute of Physics and Technology

2023. Autumn

We are given i.i.d. samples $\{\mathbf{x}_i\}_{i=1}^n \in \mathcal{X}$ (e.g. $\mathcal{X} = \mathbb{R}^m$) from unknown distribution $\pi(\mathbf{x})$.

Goal

We would like to learn a distribution $\pi(\mathbf{x})$ for

- evaluating $\pi(\mathbf{x})$ for new samples (how likely to get object \mathbf{x} ?);
- ▶ sampling from $\pi(\mathbf{x})$ (to get new objects $\mathbf{x} \sim \pi(\mathbf{x})$).

Instead of searching true $\pi(\mathbf{x})$ over all probability distributions, learn function approximation $p(\mathbf{x}|\theta) \approx \pi(\mathbf{x})$.

Divergence

- ▶ $D(\pi||p) \ge 0$ for all $\pi, p \in \mathcal{S}$;
- ▶ $D(\pi||p) = 0$ if and only if $\pi \equiv p$.

Divergence minimization task

$$\min_{\boldsymbol{\theta}} D(\pi||p).$$

Forward KL

$$\mathit{KL}(\pi||p) = \int \pi(\mathbf{x}) \log rac{\pi(\mathbf{x})}{p(\mathbf{x}|m{ heta})} d\mathbf{x}
ightarrow \min_{m{ heta}}$$

Reverse KL

$$\mathit{KL}(p||\pi) = \int p(\mathbf{x}|\boldsymbol{\theta}) \log \frac{p(\mathbf{x}|\boldsymbol{\theta})}{\pi(\mathbf{x})} d\mathbf{x} \to \min_{\boldsymbol{\theta}}$$

Maximum likelihood estimation (MLE)

$$\theta^* = \arg\max_{\theta} p(\mathbf{X}|\theta) = \arg\max_{\theta} \prod_{i=1}^n p(\mathbf{x}_i|\theta) = \arg\max_{\theta} \sum_{i=1}^n \log p(\mathbf{x}_i|\theta).$$

Maximum likelihood estimation is equivalent to minimization of the Monte-Carlo estimate of forward KL.

Likelihood as product of conditionals

Let
$$\mathbf{x} = (x_1, \dots, x_m)$$
, $\mathbf{x}_{1:j} = (x_1, \dots, x_j)$. Then

$$p(\mathbf{x}|\boldsymbol{\theta}) = \prod_{j=1}^{m} p(x_j|\mathbf{x}_{1:j-1}, \boldsymbol{\theta}); \quad \log p(\mathbf{x}|\boldsymbol{\theta}) = \sum_{j=1}^{m} \log p(x_j|\mathbf{x}_{1:j-1}, \boldsymbol{\theta}).$$

MLE problem for autoregressive model

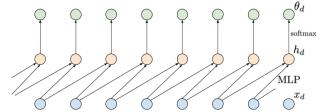
$$oldsymbol{ heta}^* = rg \max_{oldsymbol{ heta}} p(\mathbf{X}|oldsymbol{ heta}) = rg \max_{oldsymbol{ heta}} \sum_{i=1}^n \sum_{j=1}^m \log p(x_{ij}|\mathbf{x}_{i,1:j-1}oldsymbol{ heta}).$$

Sampling

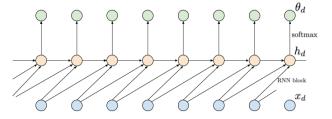
$$\hat{x}_1 \sim p(x_1|\theta), \quad \hat{x}_2 \sim p(x_2|\hat{x}_1,\theta), \ldots, \quad \hat{x}_m \sim p(x_m|\hat{\mathbf{x}}_{1:m-1},\theta)$$

New generated object is $\hat{\mathbf{x}} = (\hat{x}_1, \hat{x}_2, \dots, \hat{x}_m)$.

Autoregressive MLP



Autoregressive RNN



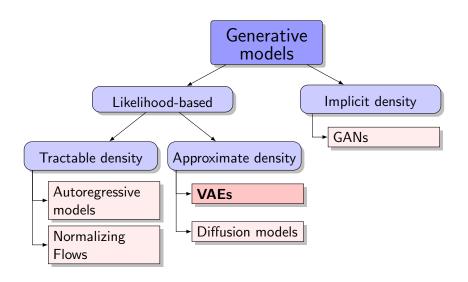
Outline

1. Bayesian framework

2. Latent variable models (LVM)

3. Variational lower bound (ELBO)

Generative models zoo



Outline

1. Bayesian framework

Latent variable models (LVM)

3. Variational lower bound (ELBO)

Bayes theorem

$$p(\mathbf{t}|\mathbf{x}) = \frac{p(\mathbf{x}|\mathbf{t})p(\mathbf{t})}{p(\mathbf{x})} = \frac{p(\mathbf{x}|\mathbf{t})p(\mathbf{t})}{\int p(\mathbf{x}|\mathbf{t})p(\mathbf{t})d\mathbf{t}}$$

- x observed variables, t unobserved variables (latent variables/parameters);
- $ightharpoonup p(\mathbf{x}|\mathbf{t}) likelihood;$
- $p(\mathbf{x}) = \int p(\mathbf{x}|\mathbf{t})p(\mathbf{t})d\mathbf{t}$ evidence;
- $ightharpoonup p(\mathbf{t})$ prior distribution, $p(\mathbf{t}|\mathbf{x})$ posterior distribution.

Meaning

We have unobserved variables \mathbf{t} and some prior knowledge about them $p(\mathbf{t})$. Then, the data \mathbf{x} has been observed. Posterior distribution $p(\mathbf{t}|\mathbf{x})$ summarizes the knowledge after the observations.

Let consider the case, where the unobserved variables ${\bf t}$ is our model parameters ${\boldsymbol \theta}$.

- $\mathbf{X} = {\mathbf{x}_i}_{i=1}^n$ observed samples;
- $p(\theta)$ prior parameters distribution (we treat model parameters θ as random variables).

Posterior distribution

$$p(\theta|\mathbf{X}) = \frac{p(\mathbf{X}|\theta)p(\theta)}{p(\mathbf{X})} = \frac{p(\mathbf{X}|\theta)p(\theta)}{\int p(\mathbf{X}|\theta)p(\theta)d\theta}$$

Bayesian inference

$$p(\mathbf{x}|\mathbf{X}) = \int p(\mathbf{x}|\theta)p(\theta|\mathbf{X})d\theta$$

Note the difference from

$$p(\mathbf{x}) = \int p(\mathbf{x}|\boldsymbol{\theta})p(\boldsymbol{\theta})d\boldsymbol{\theta}.$$

Posterior distribution

$$p(\boldsymbol{\theta}|\mathbf{X}) = \frac{p(\mathbf{X}|\boldsymbol{\theta})p(\boldsymbol{\theta})}{p(\mathbf{X})} = \frac{p(\mathbf{X}|\boldsymbol{\theta})p(\boldsymbol{\theta})}{\int p(\mathbf{X}|\boldsymbol{\theta})p(\boldsymbol{\theta})d\boldsymbol{\theta}}$$

Bayesian inference

$$p(\mathbf{x}|\mathbf{X}) = \int p(\mathbf{x}|\theta)p(\theta|\mathbf{X})d\theta$$

If evidence $p(\mathbf{X})$ is intractable (due to multidimensional integration), we can't get posterior distribution and perform the precise inference.

Maximum a posteriori (MAP) estimation

$$\boldsymbol{\theta}^* = \argmax_{\boldsymbol{\theta}} p(\boldsymbol{\theta}|\mathbf{X}) = \argmax_{\boldsymbol{\theta}} \left(\log p(\mathbf{X}|\boldsymbol{\theta}) + \log p(\boldsymbol{\theta})\right)$$

MAP estimation

$$\boldsymbol{\theta}^* = \argmax_{\boldsymbol{\theta}} p(\boldsymbol{\theta}|\mathbf{X}) = \argmax_{\boldsymbol{\theta}} \left(\log p(\mathbf{X}|\boldsymbol{\theta}) + \log p(\boldsymbol{\theta})\right)$$

Estimated θ^* is a deterministic variable, but we could treat it as a random variable with density $p(\theta|\mathbf{X}) = \delta(\theta - \theta^*)$.

Dirac delta function

$$\delta(x) = \begin{cases} +\infty, & x = 0; \\ 0, & x \neq 0; \end{cases} \int \delta(x) dx = 1; \int f(x) \delta(x-y) dx = f(y).$$

MAP inference

$$p(\mathbf{x}|\mathbf{X}) = \int p(\mathbf{x}|\theta)p(\theta|\mathbf{X})d\theta \approx p(\mathbf{x}|\theta^*).$$

Outline

1. Bayesian framework

2. Latent variable models (LVM)

3. Variational lower bound (ELBO)

Latent variable models (LVM)

MLE problem

$$m{ heta}^* = rg \max_{m{ heta}} p(\mathbf{X}|m{ heta}) = rg \max_{m{ heta}} \prod_{i=1}^n p(\mathbf{x}_i|m{ heta}) = rg \max_{m{ heta}} \sum_{i=1}^n \log p(\mathbf{x}_i|m{ heta}).$$

The distribution $p(\mathbf{x}|\theta)$ could be very complex and intractable (as well as real distribution $\pi(\mathbf{x})$).

Extended probabilistic model

Introduce latent variable z for each sample x

$$p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta}) = p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta})p(\mathbf{z}); \quad \log p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta}) = \log p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) + \log p(\mathbf{z}).$$

$$p(\mathbf{x}|\boldsymbol{\theta}) = \int p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta}) d\mathbf{z} = \int p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) p(\mathbf{z}) d\mathbf{z}.$$

Motivation

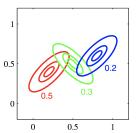
The distributions $p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta})$ and $p(\mathbf{z})$ could be quite simple.

Latent variable models (LVM)

$$\log p(\mathbf{x}|oldsymbol{ heta}) = \log \int p(\mathbf{x}|\mathbf{z},oldsymbol{ heta}) p(\mathbf{z}) d\mathbf{z}
ightarrow \max_{oldsymbol{ heta}}$$

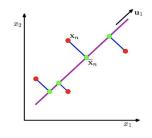
Examples

Mixture of gaussians



- $p(\mathbf{x}|z, \boldsymbol{\theta}) = \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}_z, \boldsymbol{\Sigma}_z)$
- $ightharpoonup p(z) = \mathsf{Categorical}(\pi)$

PCA model

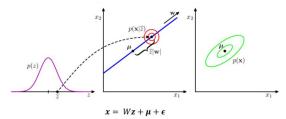


- $p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) = \mathcal{N}(\mathbf{x}|\mathbf{W}\mathbf{z} + \boldsymbol{\mu}, \sigma^2 \mathbf{I})$
- $p(\mathbf{z}) = \mathcal{N}(\mathbf{z}|0,\mathbf{I})$

Latent variable models (LVM)

$$\log p(\mathbf{x}|oldsymbol{ heta}) = \log \int p(\mathbf{x}|\mathbf{z},oldsymbol{ heta}) p(\mathbf{z}) d\mathbf{z}
ightarrow \max_{oldsymbol{ heta}}$$

PCA projects original data **X** onto a low dimensional latent space while maximizing the variance of the projected data.



- $p(\mathbf{x}|\mathbf{z}, \boldsymbol{\theta}) = \mathcal{N}(\mathbf{x}|\mathbf{W}\mathbf{z} + \boldsymbol{\mu}, \sigma^2 \mathbf{I})$
- $p(\mathbf{z}) = \mathcal{N}(\mathbf{z}|0, \mathbf{I})$
- $p(\mathbf{x}) = \mathcal{N}(\mathbf{x}|\boldsymbol{\mu}, \mathbf{W}\mathbf{W}^T + \sigma^2 \mathbf{I})$
- $p(\mathbf{z}|\mathbf{x}) = \mathcal{N}(\mathbf{M}^{-1}\mathbf{W}^T(\mathbf{x} \boldsymbol{\mu}), \sigma^2\mathbf{M}), \text{ where } \mathbf{M} = \mathbf{W}\mathbf{W}^T + \sigma^2\mathbf{I}$

Maximum likelihood estimation for LVM

MLE for extended problem

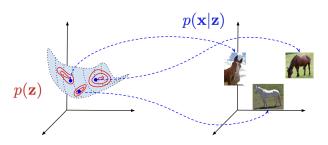
$$egin{aligned} m{ heta}^* &= rg\max_{m{ heta}} p(\mathbf{X}, \mathbf{Z} | m{ heta}) = rg\max_{m{ heta}} \prod_{i=1}^n p(\mathbf{x}_i, \mathbf{z}_i | m{ heta}) = \\ &= rg\max_{m{ heta}} \sum_{i=1}^n \log p(\mathbf{x}_i, \mathbf{z}_i | m{ heta}). \end{aligned}$$

However, **Z** is unknown.

MLE for original problem

$$\begin{aligned} \boldsymbol{\theta}^* &= \arg\max_{\boldsymbol{\theta}} \log p(\mathbf{X}|\boldsymbol{\theta}) = \arg\max_{\boldsymbol{\theta}} \sum_{i=1}^n \log p(\mathbf{x}_i|\boldsymbol{\theta}) = \\ &= \arg\max_{\boldsymbol{\theta}} \sum_{i=1}^n \log \int p(\mathbf{x}_i, \mathbf{z}_i|\boldsymbol{\theta}) d\mathbf{z}_i = \\ &= \arg\max_{\boldsymbol{\theta}} \log \sum_{i=1}^n \int p(\mathbf{x}_i|\mathbf{z}_i, \boldsymbol{\theta}) p(\mathbf{z}_i) d\mathbf{z}_i. \end{aligned}$$

Naive approach



Monte-Carlo estimation

$$p(\mathbf{x}|\boldsymbol{\theta}) = \int p(\mathbf{x}|\mathbf{z},\boldsymbol{\theta})p(\mathbf{z})d\mathbf{z} = \mathbb{E}_{p(\mathbf{z})}p(\mathbf{x}|\mathbf{z},\boldsymbol{\theta}) \approx \frac{1}{K} \sum_{k=1}^{K} p(\mathbf{x}|\mathbf{z}_k,\boldsymbol{\theta}),$$

where $\mathbf{z}_k \sim p(\mathbf{z})$.

Challenge: to cover the space properly, the number of samples grows exponentially with respect to dimensionality of **z**.

Outline

1. Bayesian framework

2. Latent variable models (LVM)

3. Variational lower bound (ELBO)

Variational lower bound (ELBO)

Derivation 1 (inequality)

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \log \int p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta}) d\mathbf{z} = \log \int \frac{q(\mathbf{z})}{q(\mathbf{z})} p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta}) d\mathbf{z} =$$

$$= \log \mathbb{E}_q \left[\frac{p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta})}{q(\mathbf{z})} \right] \ge \mathbb{E}_q \log \frac{p(\mathbf{x}, \mathbf{z}|\boldsymbol{\theta})}{q(\mathbf{z})} = \mathcal{L}(q, \boldsymbol{\theta})$$

Derivation 2 (equality)

$$\mathcal{L}(q, \theta) = \int q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}|\theta)}{q(\mathbf{z})} d\mathbf{z} = \int q(\mathbf{z}) \log \frac{p(\mathbf{z}|\mathbf{x}, \theta)p(\mathbf{x}|\theta)}{q(\mathbf{z})} d\mathbf{z} =$$

$$= \int q(\mathbf{z}) \log p(\mathbf{x}|\theta) d\mathbf{z} + \int q(\mathbf{z}) \log \frac{p(\mathbf{z}|\mathbf{x}, \theta)}{q(\mathbf{z})} d\mathbf{z} =$$

$$= \log p(\mathbf{x}|\theta) - KL(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x}, \theta))$$

Variational decomposition

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathcal{L}(q, \boldsymbol{\theta}) + KL(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})) \geq \mathcal{L}(q, \boldsymbol{\theta}).$$

Variational lower bound (ELBO)

$$\mathcal{L}(q, \theta) = \int q(\mathbf{z}) \log \frac{p(\mathbf{x}, \mathbf{z}|\theta)}{q(\mathbf{z})} d\mathbf{z} =$$

$$= \int q(\mathbf{z}) \log p(\mathbf{x}|\mathbf{z}, \theta) d\mathbf{z} + \int q(\mathbf{z}) \log \frac{p(\mathbf{z})}{q(\mathbf{z})} d\mathbf{z}$$

$$= \mathbb{E}_q \log p(\mathbf{x}|\mathbf{z}, \theta) - KL(q(\mathbf{z})||p(\mathbf{z}))$$

Log-likelihood decomposition

$$\log p(\mathbf{x}|\boldsymbol{\theta}) = \mathbb{E}_q \log p(\mathbf{x}|\mathbf{z},\boldsymbol{\theta}) - KL(q(\mathbf{z})||p(\mathbf{z})) + KL(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x},\boldsymbol{\theta})).$$

▶ Instead of maximizing incomplete likelihood, maximize ELBO

$$\max_{oldsymbol{ heta}} p(\mathbf{x}|oldsymbol{ heta}) \quad o \quad \max_{oldsymbol{q},oldsymbol{ heta}} \mathcal{L}(oldsymbol{q},oldsymbol{ heta})$$

 Maximization of ELBO by variational distribution q is equivalent to minimization of KL

$$\max_{q} \mathcal{L}(q, \boldsymbol{\theta}) \equiv \min_{q} KL(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x}, \boldsymbol{\theta})).$$

Summary

- WaveNet and PixelCNN models use masked causal convolutions (1D or 2D) to get autoregressive model.
- Bayesian inference is a generalization of most common machine learning tasks. It allows to construct MLE, MAP and bayesian inference, to compare models complexity and many-many more cool stuff.
- ► LVM introduces latent representation of observed samples to make model more interpretable.
- ► LVM maximizes variational evidence lower bound (ELBO) to find MLE for the parameters.