

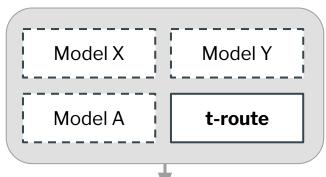
# River routing capability in the Next Generation Water Resources Model Framework

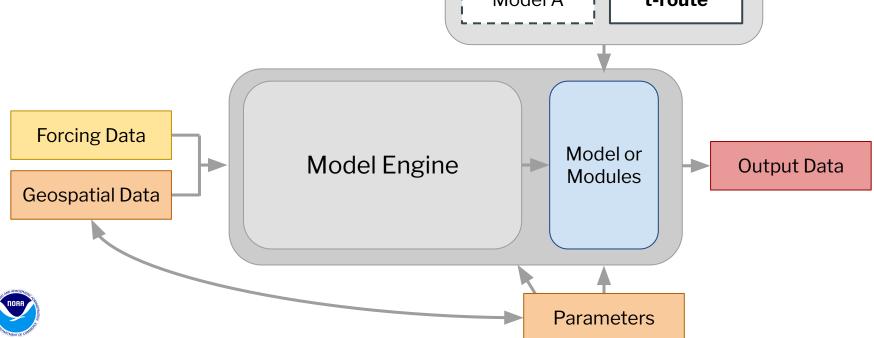


Naoki Mizukami, Adam Wlostowski, Andy W. Wood, Keith S. Jennings, Wanru Wu, Luciana Kindl da Cunha, Nels Frazier, Fred L. Ogden, Trey C. Flowers

## **Next Generation Water Resources Model Framework (Nextgen)**

**t-route:** a post-processor to compute discharge, velocity, river stage at river channel as well as perform data assimilation

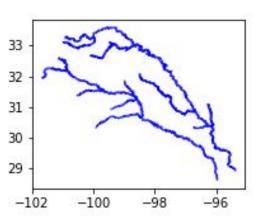




#### t-route

- Open source, community wide development
- Python-Fortran based codes.
- River network topological-based routing model.
- Shared memory parallel computing.
- Muskingum-Cunge (MC) and Diffusive wave routing.
- Level-pool lake routing.
- Heterogeneous routing domain (work in progress).

#### Parallel routing

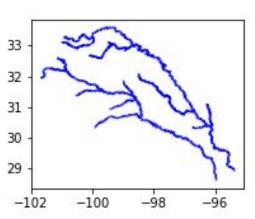




### t-route

- Open source, community wide development
- Python-Fortran based codes.
- River network topological-based routing model.
- Shared memory parallel computing.
- Muskingum-Cunge (MC) and Diffusive wave routing.
- Level-pool lake routing.
- Heterogeneous routing domain (work in progress).

#### Parallel routing





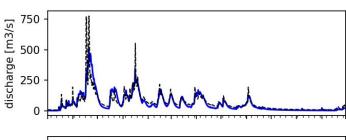
## **Current simulation example**

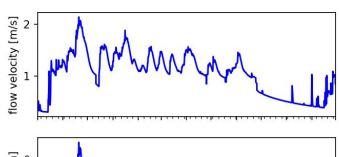
#### Nextgen model chain

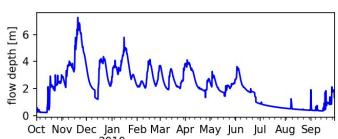
- Noah-OWP Modular (hydrology above ground)
- 2. CFE (soil hydrology)
- 3. t-route (river routing)

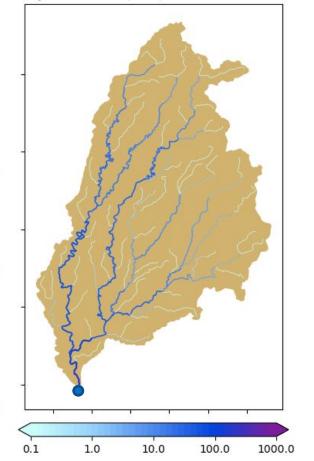
uniform routing: use a single routing method everywhere

12035000- SATSOP RIVER NEAR SATSOP, WA









Hourly Streamflow [cms] 2009-11-10 00:00:00



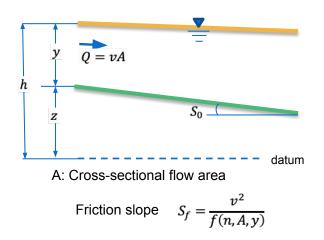
#### St. Venant equation (1-D shallow wave equation)

Continuity equation

$$\frac{\partial A}{\partial t} = -\frac{\partial Q}{\partial x}$$

· Momentum equation

$$\frac{1}{A}\frac{\partial Q}{\partial t} + \frac{1}{A}\frac{\partial}{\partial x}\left(\frac{Q^2}{A}\right) + g\frac{\partial y}{\partial x} - g(S_0 - S_f) = 0$$
Local Advective acceleration
Pressure Gravity Friction
Inertia term





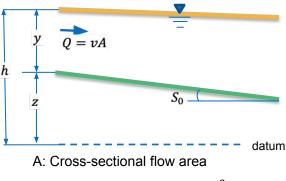
#### St. Venant equation (1-D shallow wave equation)

· Continuity equation

$$\frac{\partial A}{\partial t} = -\frac{\partial Q}{\partial x}$$

· Momentum equation

$$\frac{1}{A}\frac{\partial Q}{\partial t} + \frac{1}{A}\frac{\partial}{\partial x} \left(\frac{Q^2}{A}\right) + g\frac{\partial y}{\partial x} - g(S_0 - S_f) = 0$$
Local Advective acceleration
Pressure Gravity Friction
Inertia term



Friction slope  $S_f = \frac{v^2}{f(n, A, y)}$ 

Dynamic Wave (inertia, pressure, & bed friction)

Computationally expensive



### St. Venant equation (1-D shallow wave equation)

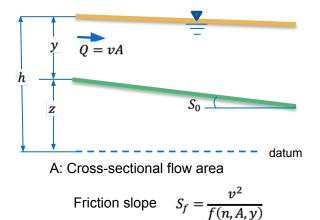
Continuity equation

$$\frac{\partial A}{\partial t} = -\frac{\partial Q}{\partial x}$$

Momentum equation

$$g\frac{\partial y}{\partial x} - g(S_0 - S_f) = 0$$

Pressure Gravity Friction



Diffusive Wave (pressure and bed friction)

Faster than Dynamic wave routing



#### St. Venant equation (1-D shallow wave equation)

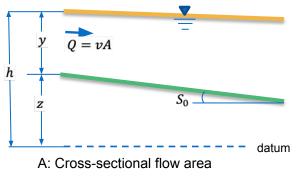
Continuity equation

$$\frac{\partial A}{\partial t} = -\frac{\partial Q}{\partial x}$$

Momentum equation

$$g(S_0 - S_f) = 0$$

Gravity Friction



Friction slope 
$$S_f = \frac{v^2}{f(n, A, y)}$$

Kinematic Wave (Muskingum-Cunge) (Bed friction)

Similar computational cost to diffusive wave routing



## Heterogeneous river routing

## High-resolution, large-domain routing for short-term flood forecasting:

## Meselhe et al., JAWRA (2021)

- Computational efficiency: Time-space dependent wave approximation to avoid expensive routing method (dynamic wave routing) everywhere.
- ~25 % of spatial-temporal hydraulic conditions may require dynamic wave routing.
- ~97 % of spatial-temporal hydraulic conditions may require diffusive wave routing.
- Appropriate wave approximations may be detected using "dimensionless hydraulic parameters" computed at each river reach and time.



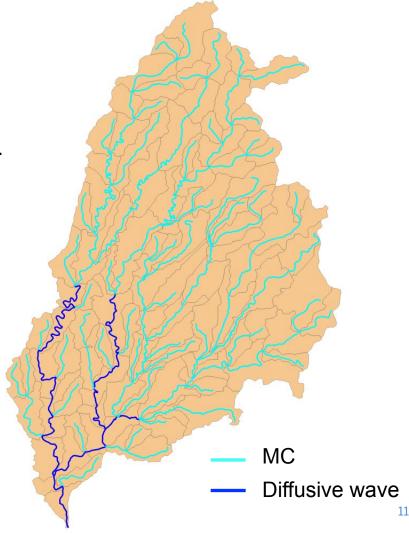




# Heterogeneous river routing

Routing methods depend on reaches and time.

(See illustration (this is not real setup)

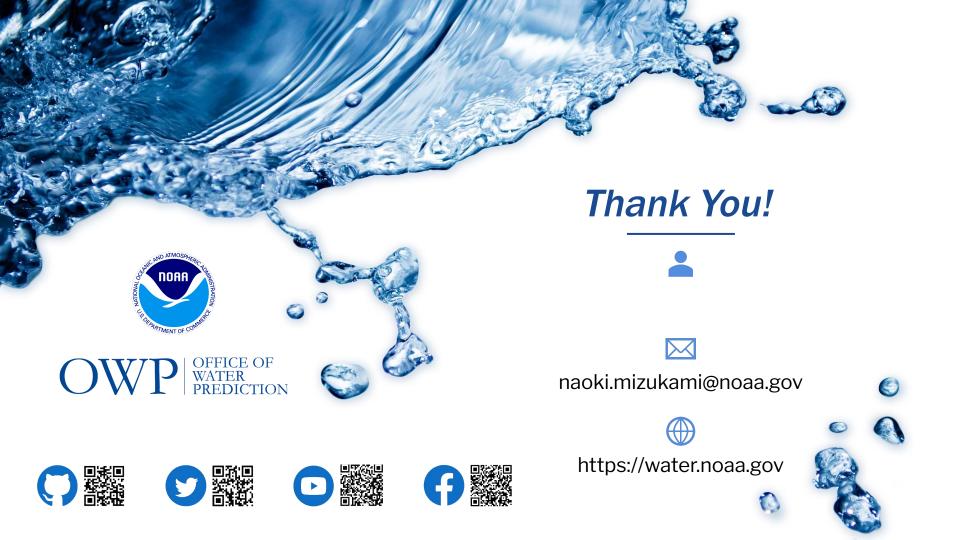






## **On-going and Future work**

- User-input wave domain.
- Run-time, automated wave domain identification at given time and reach.
- Dynamic wave routing
- DA capability (beyond nudging).





# **Back up slides**

### St. Venant equation (1-D shallow wave equation)

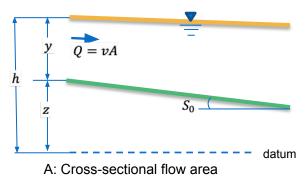
Continuity equation

$$\frac{\partial A}{\partial t} = -\frac{\partial Q}{\partial x}$$

Momentum equation

$$g(S_0 - S_f) = 0$$

Gravity Friction



Friction slope 
$$S_f = \frac{v^2}{f(n, A, y)}$$

Dynamic Wave (inertia, pressure, & bed friction)

Diffusive Wave (pressure and bed friction)

Kinematic Wave (Muskingum-Cunge) (Bed friction)

