



NOAA Atlas 15:

*Updated Present-Day Estimates
of Heavy Rainfall Values*

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PREDICTION

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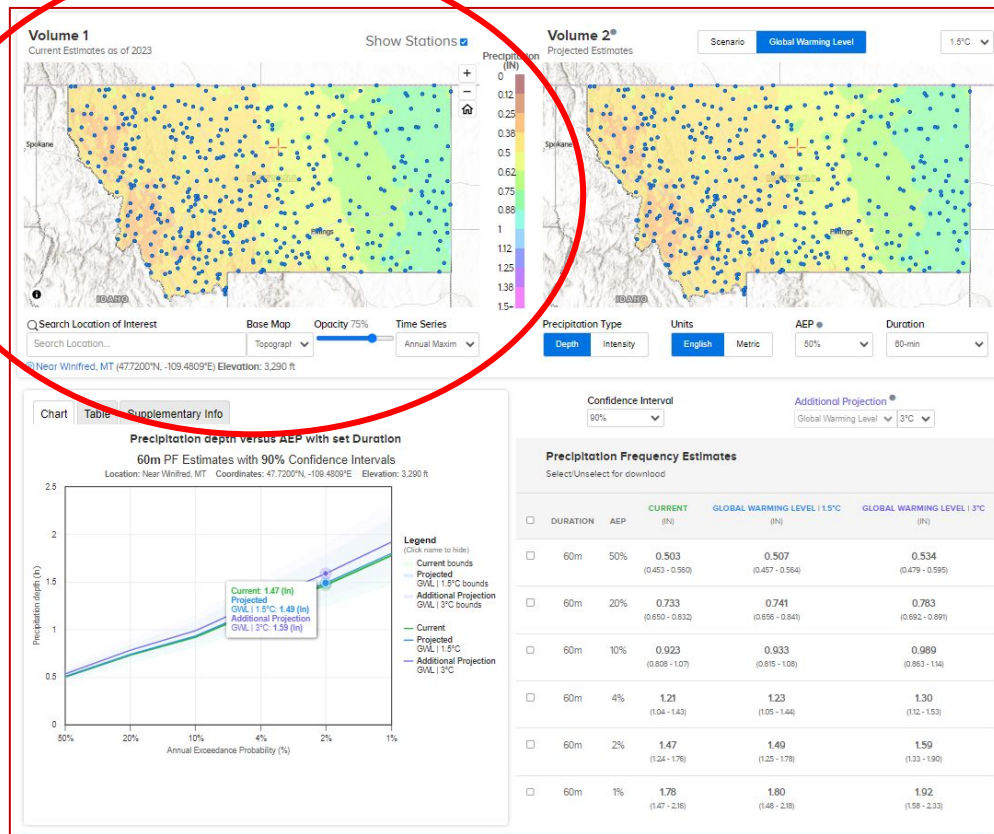
Overview

● Volume 1

- Accounts for temporal trends in historical observations
- 5-minute to 60-day
- 1/2 to 1/1000 probabilities
- Gridded CONUS and OCONUS

● Volume 2

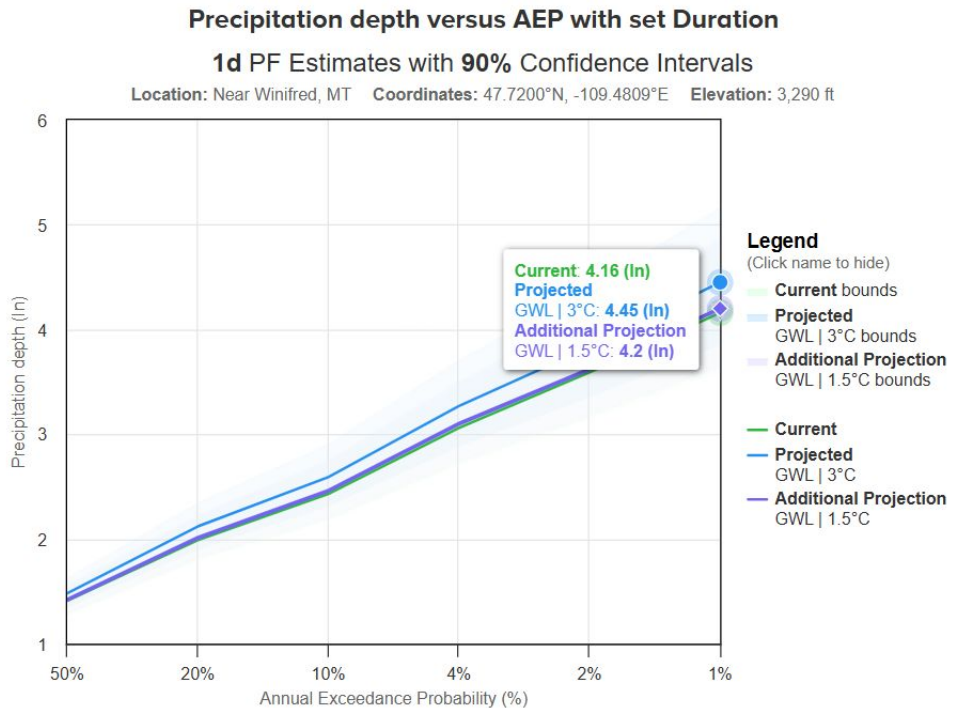
- Future estimates through year 2100 based on future climate model data up to 5°C of warming
 - SSP2-4.5, SSP5-8.5



Atlas 15 Pilot Info
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A15 Volume 1 Approach



- **Computation of precipitation frequency estimates at station locations**
 - **Nonstationary** - incorporates temporal covariate
 - **Regional** - automated scheme for regionalization, spatial covariates
 - **Precipitation frequency analysis** - Maximum Likelihood Estimation (MLE) to estimate distribution parameters
- **Spatial mapping of precipitation frequency estimates to high-resolution grids**

A15 Volume 1 - Nonstationary PF analysis method

- Regional Nonstationary Maximum Likelihood Estimation (MLE) method used to estimate **GEV distribution parameters (location, scale, and shape)** at each target station
- Spatial covariate: **Mean Annual Maximum (MAM)** precipitation
- Temporal covariate: **Global Warming Level (GWL)**

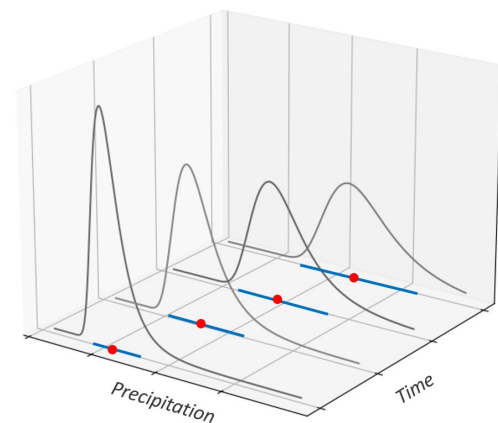
Probability density function of the GEV distribution:

$$f(x, t) = \frac{1}{\sigma} \left\{ 1 - \xi \frac{x - \mu}{\sigma} \right\}^{\left(\frac{1}{\xi} - 1 \right)} \exp \left(- \left\{ 1 - \xi \frac{x - \mu}{\sigma} \right\}^{\frac{1}{\xi}} \right)$$

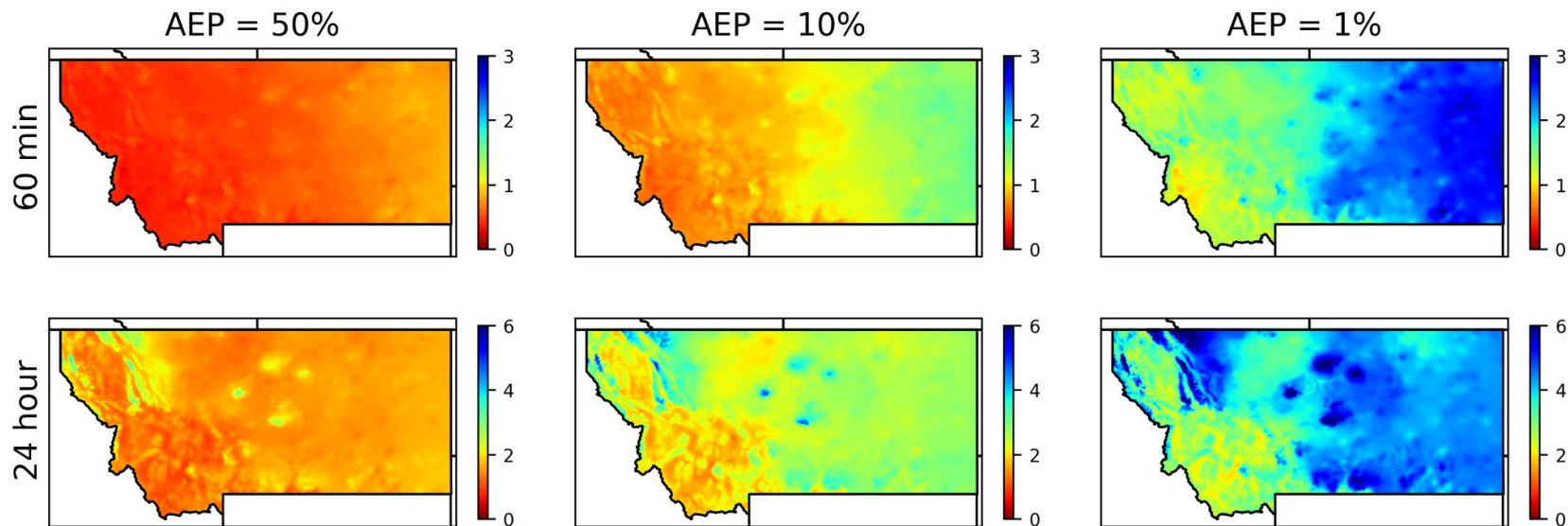
Location: $\mu(x, t) = a_1 \times MAM(x)[1 + a_2 \times GWL(t)]$

Scale: $\sigma(x, t) = b_1 \times MAM(x)[1 + b_2 \times GWL(t)]$

Shape: $\xi = c_0$



A15 Pilot Volume 1 - Estimates – Under Peer Review Now



Atlas 15 Pilot Volume 1 present-day precipitation frequency estimates (inches)

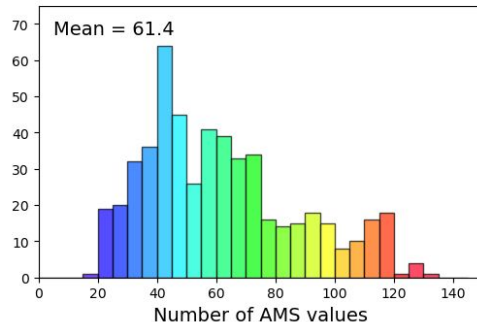
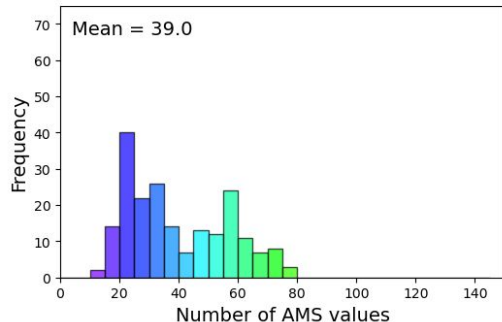
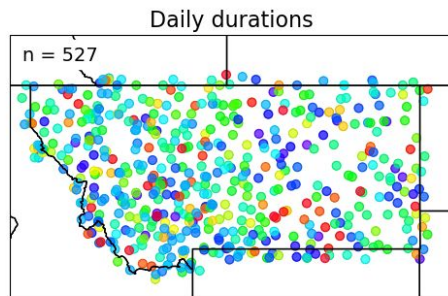
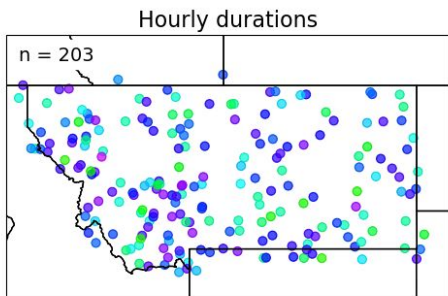
Available for Atlas 15 prototype

| | |
|-----------|---|
| Durations | 60-min, 2-hr, 3-hr, 6-hr, 12-hr, 24-hr , 2-day, 3-day, 4-day, 7-day, 10-day |
| AEPs | 1/2 (50%) , 1/5 (20%), 1/10 (10%) , 1/25 (4%), 1/50 (2%), 1/100 (1%) |

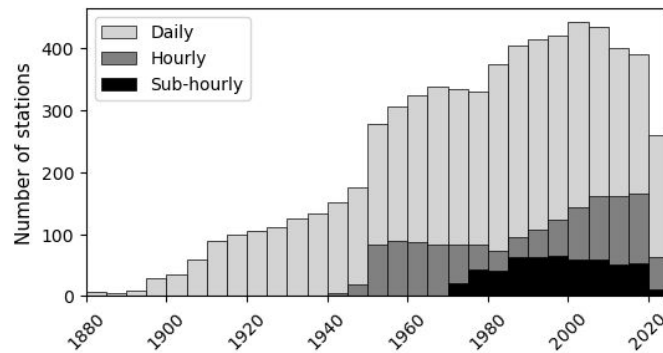
Atlas 15 Pilot
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A15 Volume 1 - Pilot Data

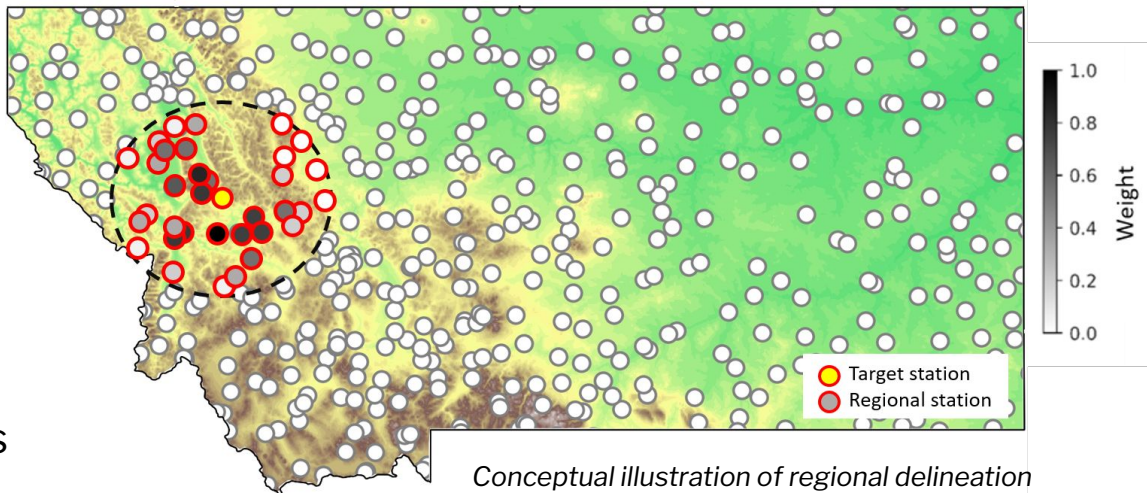


- Atlas 14 Vol. 12 quality controlled metadata and AMS data
- Gridded PRISM mean annual maximum (MAM) and mean annual precipitation (MAP)
- Annual near-surface temperature anomalies from NCEI
- NASA's SRTM90 DEM grids



A15 Volume 1 - Regionalization approach

- Regional stations around target stations are identified
- Stations weighted based on:
 - geographical features
 - meteorological attributes
 - statistical testing
- Weights determine extent of contribution by regional stations
- PF estimates are computed for each station location within the domain



Conceptual illustration of regional delineation and weighting within Pilot domain

Regionalization (Pilot)

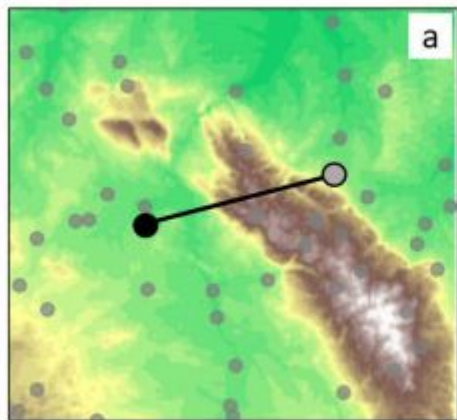


Table 2. Attribute parameters used in weighting of regional stations.

| Attribute | $W = 1$ | $1 > W > 0$ | $W = 0$ |
|---|-------------------------|-----------------------------|-------------------------|
| Distance | $x \leq 70 \text{ km}$ | $70 < x < 160 \text{ km}$ | $x \geq 160 \text{ km}$ |
| MAP difference | $x \leq 70\%$ | $70 < x < 100\%$ | $x \geq 100\%$ |
| MAM difference | $x \leq 40\%$ | $40 < x < 75\%$ | $x \geq 75\%$ |
| Elevation difference | $x \leq 700 \text{ m}$ | $700 < x < 1200 \text{ m}$ | $x \geq 1200 \text{ m}$ |
| Obstacle height | $x \leq 600 \text{ m}$ | $600 < x < 1100 \text{ m}$ | $x \geq 1100 \text{ m}$ |
| Elevation range | $x \leq 1200 \text{ m}$ | $1200 < x < 1700 \text{ m}$ | $x \geq 1700 \text{ m}$ |
| P-value based on two-sample statistical tests | $x \geq 0.2$ | $0.2 > x > 0.05$ | $x \leq 0.05$ |

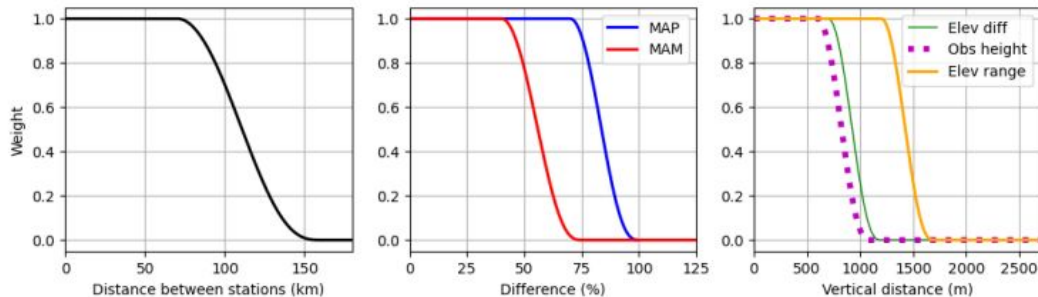
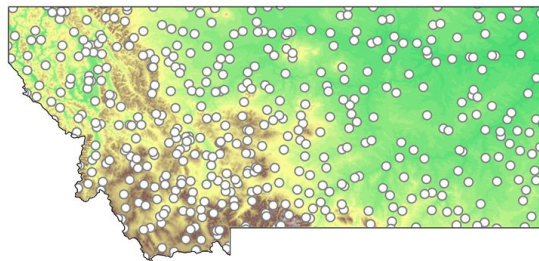
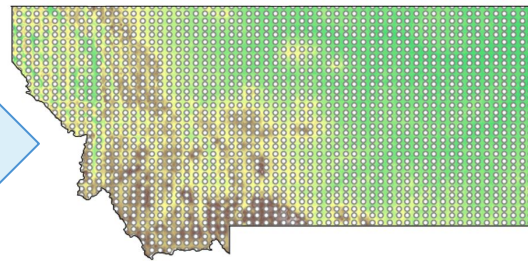
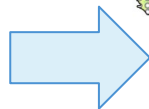


Figure 5. Depiction of weights based on selected attributes from Table 2.

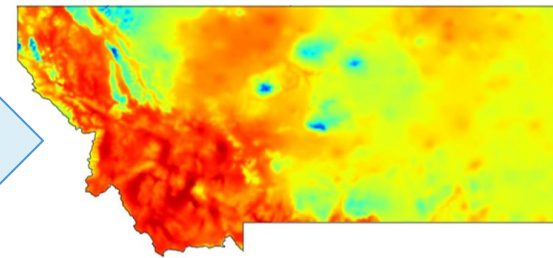
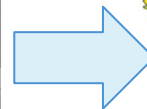
A15 Volume 1 - Interpolation to a grid



PF estimates
computed at
station locations



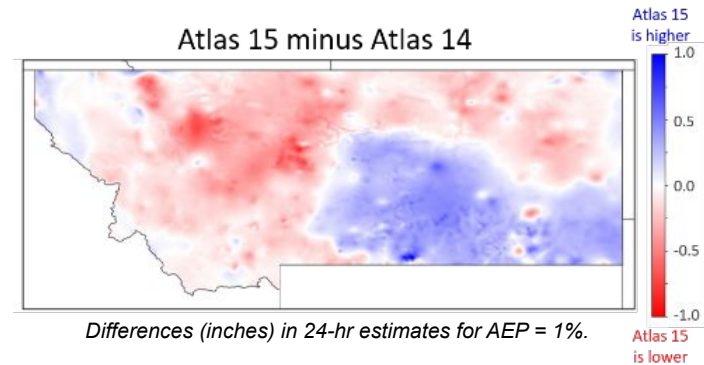
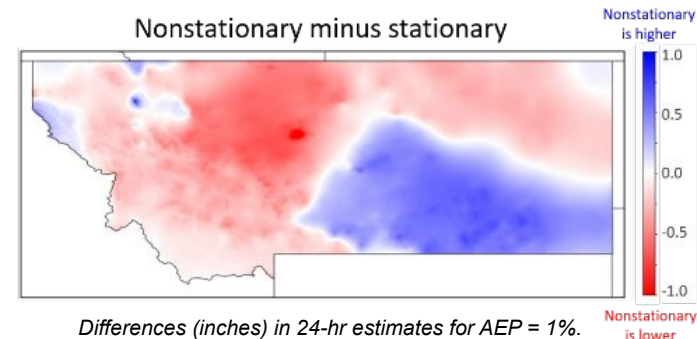
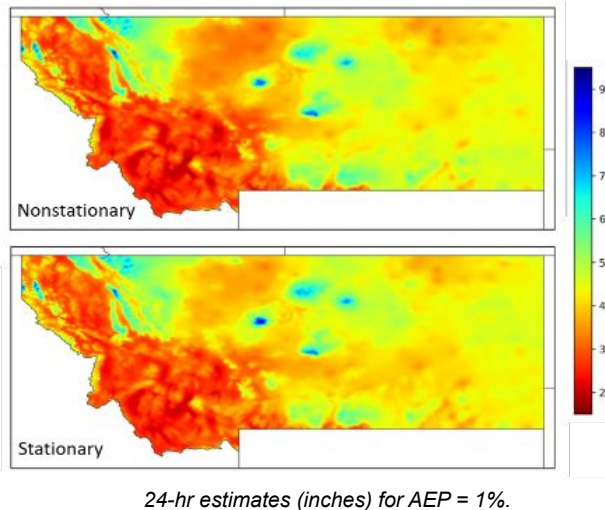
Gridded MAM
values used to
compute gridded
ratios



Ratios used to
compute gridded
PF estimates

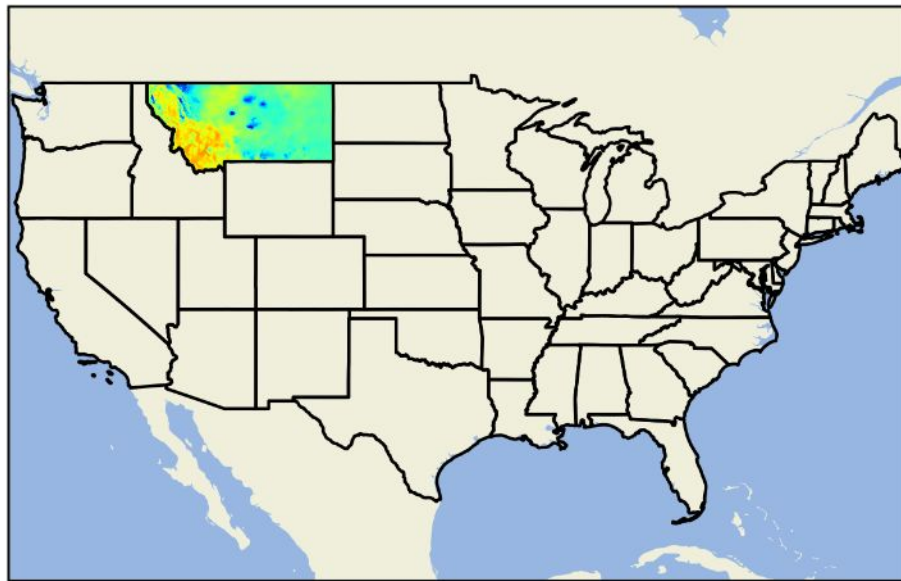
A15 Volume 1 - Nonstationary vs. Stationary Estimates

- A15 nonstationary and stationary estimates are similar
- Present-day differences are within ~15% and reflect trends in gauge data
- Large-scale differences between A15 Nonstationary and A14 (stationary) are largely due to the implementation of a nonstationary framework



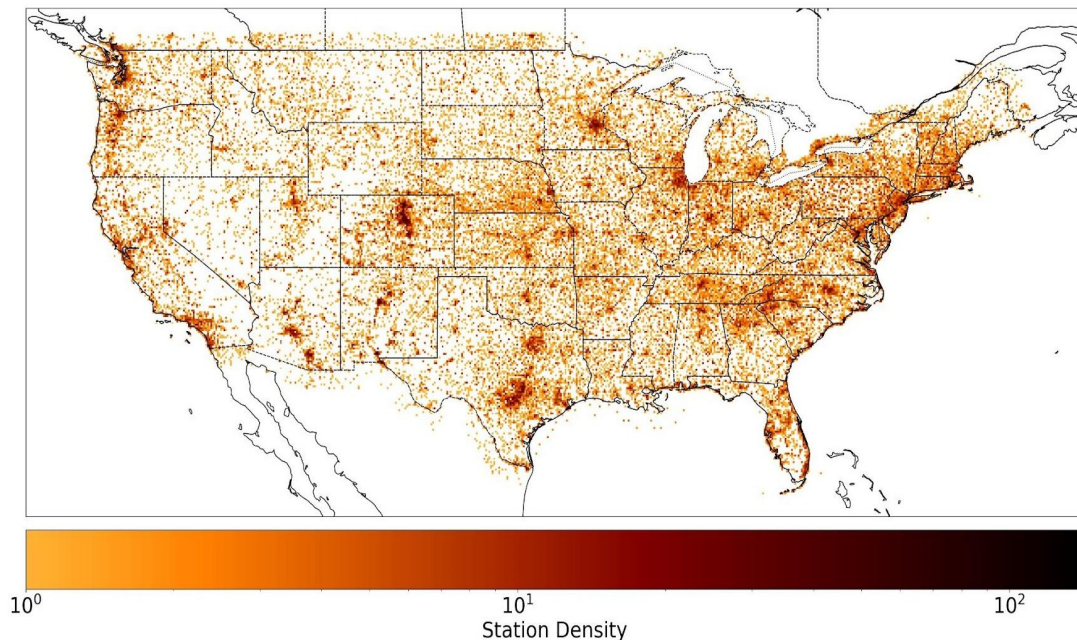
A15 development - Moving on to CONUS (then oCONUS)

- Adapt framework for implementation across CONUS, pending completion of repository and MAM grid development

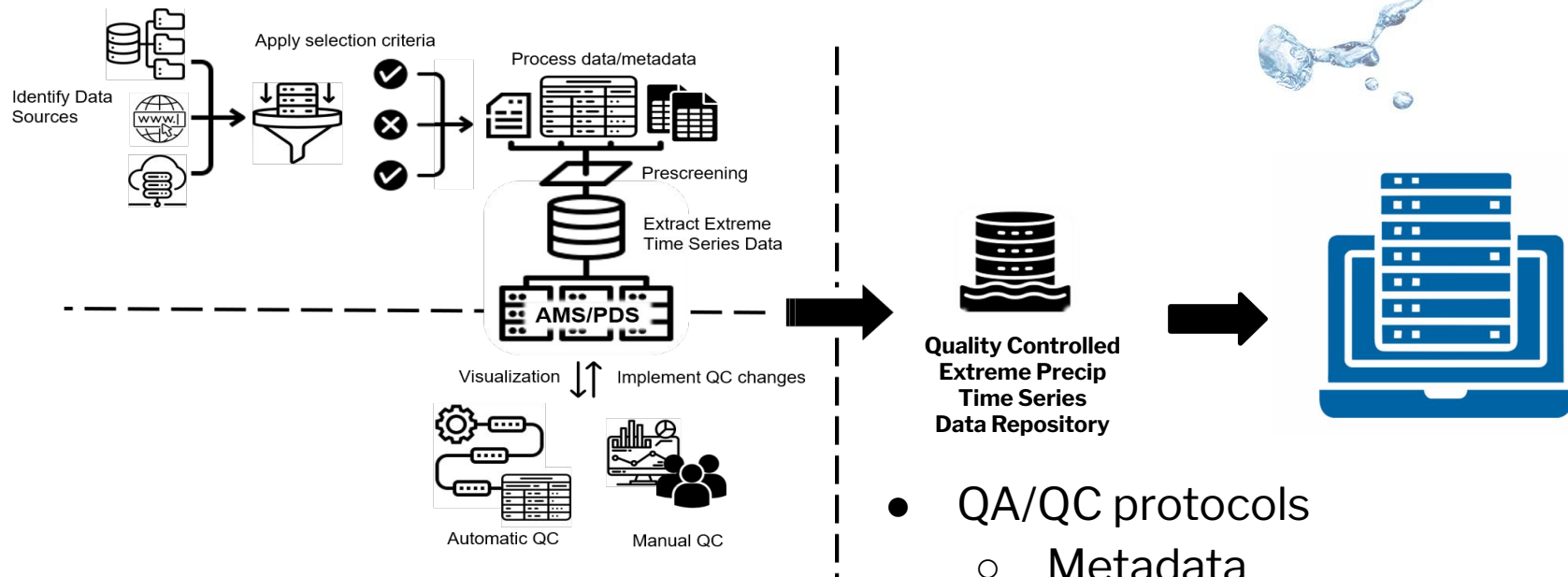


A15 development - Moving on to CONUS (then oCONUS)

- Adapt framework for implementation across CONUS, pending completion of repository and MAM grid development



Developing Precipitation Extreme Time Series Data Repository

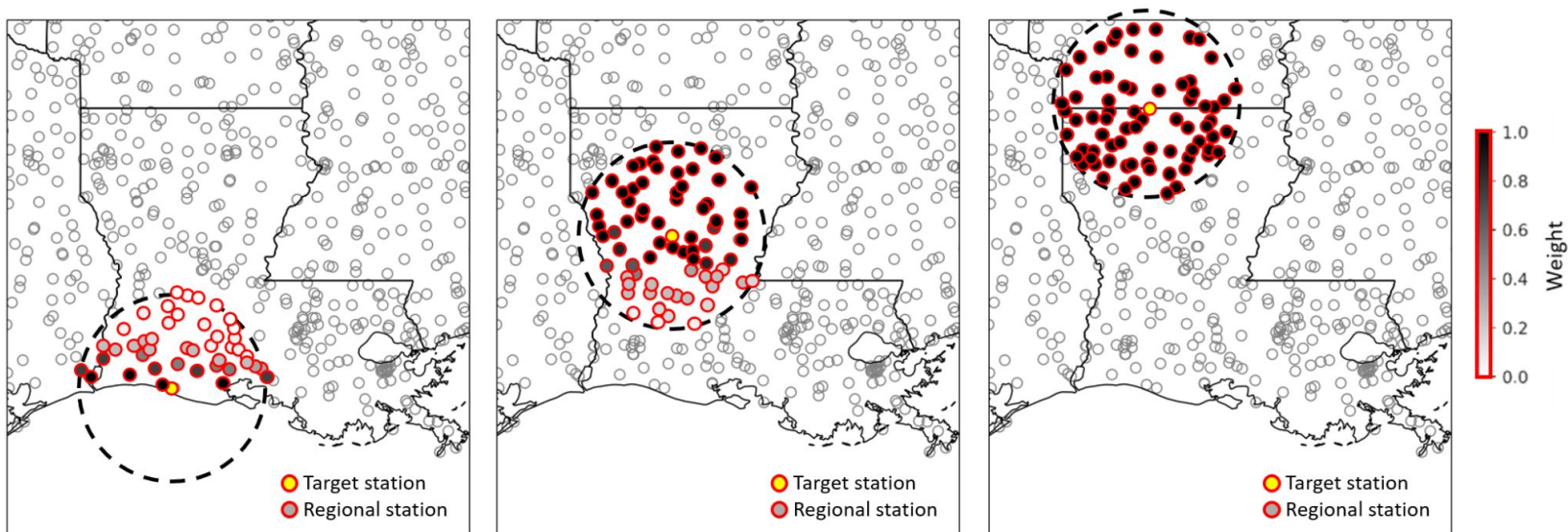


- QA/QC protocols
 - Metadata
 - Station cleanup
 - Annual maximum series (AMS)

CONUS: Evolve Framework - Current Work Example

Expanding Framework to CONUS

- Updated regionalization now includes distance to coast
- Currently investigating bounds on other attribute weights

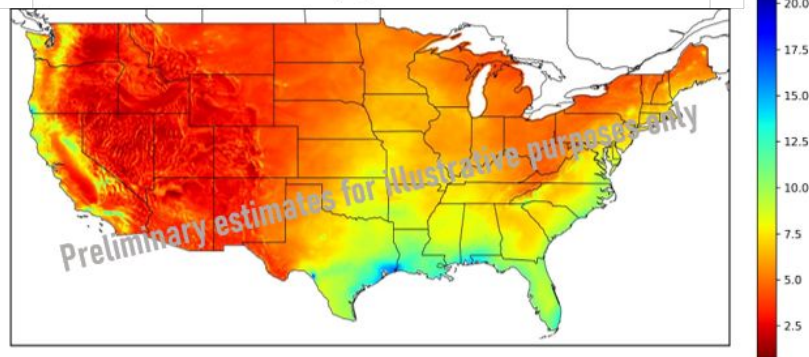


Conceptual illustration of weighting based on distance to coast

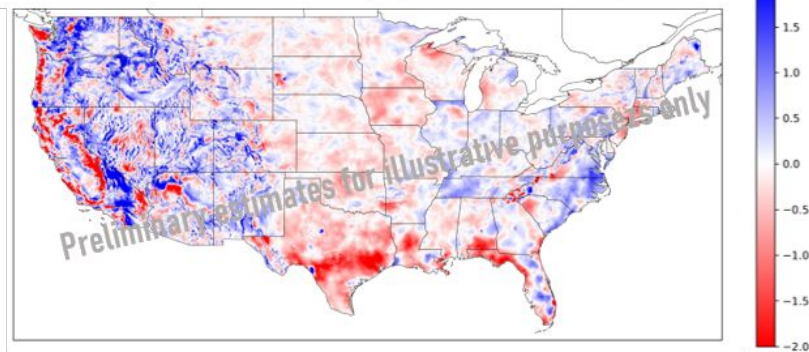
CONUS: Evolve Framework - Next Steps

- Continue investigating MAM grid development approaches
- Revisit regionalization framework
- As repository data are updated, produce new MAM grids and CONUS-wide PF estimates
- Continue alignment of V1 and V2 frameworks
- Incorporate peer-review feedback

Atlas 15 estimates (in) for 24-hr AEP = 1/100



Atlas 15 minus Atlas 14 (in) for 24-hr AEP = 1/100





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Thank You!



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