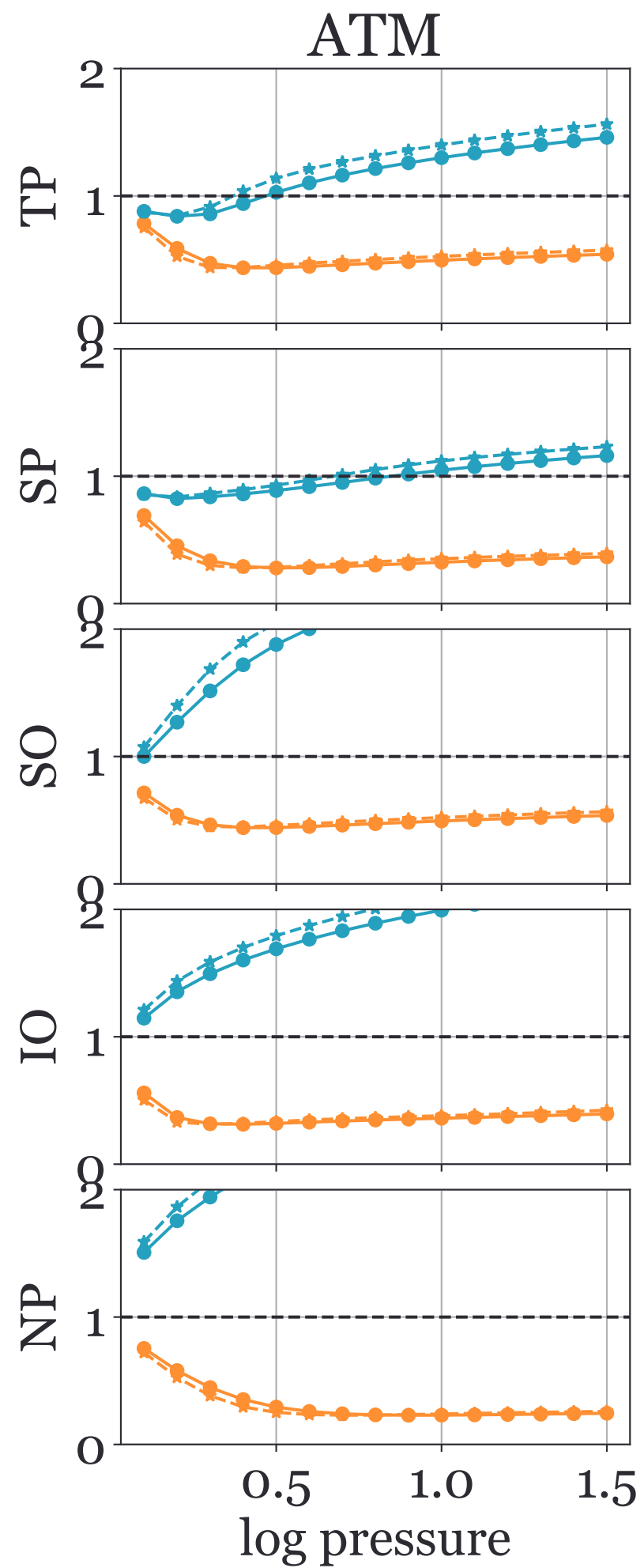


Error in Kalman gain by localization radius

Relative error



Localization radius

