GloMarGridding

Release 0.3.0

NOC Surface Processes

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CHAPTER

ONE

INTRODUCTION

Global surface temperature datasets - such as those used in the Intergovernmental Panel on Climate Change (IPCC) Assessment Report [IPCC] rely on a range of techniques to generate smoothed, infilled gridded fields from available observations [Lenssen], [Kadow], [RohdeBerkeley], [Morice_2021], [Huang] . The construction of these datasets involves numerous processing decisions, and variations in how each dataset represents the temperature field contribute to what is known as structural uncertainty [Thorne]. This structural uncertainty has two primary sources: (1) differences in the processing of the input temperature measurements, and (2) differences in the spatial interpolation methods applied. Because these steps are often tightly integrated, it is difficult to determine their individual contributions.

glomar_gridding is a software package developed to support the evaluation of structural uncertainty by offering flexible tools for spatial interpolation. The package enables users to spatially interpolate grid-box average observations and their associated uncertainty estimates using Gaussian Process Regression Modelling (GPRM, often called Kriging) [Rasmussen], [Cressie]. This technique builds on established methods for generating surface temperature fields [Karspeck], [Morice_2012]. By decoupling interpolation from earlier processing stages - such as homogenization, quality control, and aggregation to grid-cell averages - glomar_gridding allows users to create spatially complete fields while independently assessing the effects of upstream data processing choices.

CHAPTER

TWO

GETTING STARTED

2.1 Installation

2.1.1 Via Pip

GloMarGridding is not available on PyPI, however it can be installed via pip with the following command:

2.1.2 From Source

Alternatively, you can clone the repository and install using pip (or conda if preferred).

```
git clone git@git.noc.ac.uk/nocsurfaceprocesses/glomar_gridding.git
cd glomar_gridding
python -m venv venv
source venv/bin/activate
pip install -e .
```

CHAPTER

THREE

CREDITS

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6 Chapter 3. Credits

STATIONARY INTERPOLATION COVARIANCE

Outside of the observation values and positions, the spatial covariance structure is the most important component for Kriging. The Kriging classes in this library all require this matrix as the input to the class. This covariance matrix can be provided as a pre-computed matrix, loaded into the environment with <code>glomar_gridding.interpolation_covariance.load_covariance()</code>. Alternatively the covariance structure can be estimated using functions and classes contained within <code>glomar_gridding</code>.

A commonly used approach is to compute a stationary covariance structure, using a *Variogram* with fixed scales. The use of *stationary* here suggests that the range of covariance is constant across all positions - each position has the same influence over a fixed distance.

```
from glomar_gridding.grid import grid_from_resolution, grid_to_distance_matrix
from glomar_gridding.variogram import GaussianVariogram, variogram_to_covariance
# Initialise a grid
grid = grid_from_resolution(
   resolution=5,
   bounds=[(-87.5, 90), (-177.5, 180)],
    coord_names=["latitude", "longitude"],
)
# Compute a distance matrix
dist = grid_to_distance_matrix(
   grid=grid,
   lat_coord="latitude",
    lon_coord="longitude",
)
# Define and compute a Variogram
variogram = GaussianVariogram(
   nugget=0.0,
   psill=1.2,
   range=1300,
).fit(dist)
# Convert to covariance
covariance = variogram_to_covariance(variogram, sill=1.2)
```

4.1 Grid

glomar_gridding.grid.grid_from_resolution(resolution, bounds, coord_names)

Generate a grid from a resolution value, or a list of resolutions for given boundaries and coordinate names.

Note that all list inputs must have the same length, the ordering of values in the lists is assumed align.

Parameters

- **resolution** (*float* | *list[float]*) Resolution of the grid. Can be a single resolution value that will be applied to all coordinates, or a list of values mapping a resolution value to each of the coordinates.
- **bounds** (list[tuple[float, float]]) A list of bounds of the form (lower_bound, upper_bound) indicating the bounding box of the returned grid
- **coord_names** (list[str]) List of coordinate names

Returns

grid – The grid defined by the resolution and bounding box.

Return type

xarray.DataArray:

Calculate a distance matrix between all positions in a grid. Orientation of latitude and longitude will be maintained in the returned distance matrix.

Parameters

- **grid** (*xarray*. *DataArray*) A 2-d grid containing latitude and longitude indexes specified in decimal degrees.
- **dist_func** (*Callable*) Distance function to use to compute pairwise distances. See glomar_gridding.distances.calculate_distance_matrix for more information.
- lat_coord (str) Name of the latitude coordinate in the input grid.
- **lon_coord** (*str*) Name of the longitude coordinate in the input grid.

Returns

dist – A DataArray containing the distance matrix with coordinate system defined with grid cell index ("index_1" and "index_2"). The coordinates of the original grid are also kept as coordinates related to each index (the coordinate names are suffixed with "_1" or "_2" respectively).

Return type

xarray.DataArray

4.2 Variograms

Exponential Model

- **psill** (*float* / *numpy.ndarray*) The variance of the variogram.
- nugget (float | numpy.ndarray)

- effective_range (float | numpy.ndarray | None)
- range (float | numpy.ndarray | None)

fit(distance_matrix)

Fit the Exponential Variogram model to a distance matrix

Parameters

distance_matrix (numpy.ndarray | xarray.DataArray) - The distance matrix indicating the distance between each pair of points in the grid.

Returns

A matrix containing the variogram values at each distance.

Return type

numpy.ndarray | xarray.DataArray

Spherical Model

Parameters

- psill (float / np.ndarray) The variance of the variogram.
- nugget (float | np.ndarray)
- effective_range (float | np.ndarray | None)
- range (float | np.ndarray | None)

fit(distance_matrix)

Fit the Spherical Variogram model to a distance matrix

Return type

ndarray | DataArray

class glomar_gridding.variogram.GaussianVariogram(psill, nugget, effective_range=None, range=None)
 Gaussian Model

Parameters

- **psill** (*float* | *np.ndarray*) The variance of the variogram.
- nugget (float | np.ndarray)
- effective_range (float | np.ndarray | None)
- range (float | np.ndarray | None)

fit(distance_matrix)

Fit the Gaussian Variogram model to a distance matrix

Parameters

distance_matrix (numpy.ndarray | xarray.DataArray) - The distance matrix indicating the distance between each pair of points in the grid.

Returns

A matrix containing the variogram values at each distance.

Return type

numpy.ndarray | xarray.DataArray

4.2. Variograms 9

class glomar_gridding.variogram.MaternVariogram(psill, nugget, effective_range=None, range=None, nu=0.5, method='sklearn')

Matern Models

Same args as the Variogram classes with additional nu (ν), method parameters.

Sklearn

- 1) This is called "sklearn" because if d/range = 1.0 and $\nu = 0.5$, it gives 1/e correlation...
- 2) This is NOT the same formulation as in GSTAT nor in papers about non-stationary anistropic covariance models (aka Karspeck paper).
- 3) It is perhaps the most intitutive (because of (1)) and is used in sklearn GP and HadCRUT5 and other UKMO dataset.
- 4) nu defaults to 0.5 (exponential; used in HADSST4 and our kriging). HadCRUT5 uses 1.5.
- 5) The "2" is inside the square root for middle and right.

GeoStatic:

Similar to Sklearn Matern Variogram model but uses the range scaling in gstat. Note: there are no square root 2 or nu in middle and right

Yields the same answer to sklearn Matern Variogram if $\nu = 0.5$ but are otherwise different.

Karspeck:

Similar to Sklearn Matern Variogram model but uses the form in Karspeck paper Note: Note the 2 is outside the square root for middle and right e-folding distance is now at d/SQRT(2) for $\nu=0.5$

References

see chapter 4.2 of Rasmussen, C. E., & Williams, C. K. I. (2005). Gaussian Processes for Machine Learning. The MIT Press. https://doi.org/10.7551/mitpress/3206.001.0001

- **psill** (*float* / *np.ndarray*) Sill of the variogram where it will flatten out. Values in the variogram will not exceed psill + nugget. This value is the variance.
- nugget (float | np.ndarray) The value of the independent variable at distance 0
- effective_range (float | np.ndarray | None) Effective Range, this is the lag where 95% of the sill are exceeded. This is not the range parameter, which is defined as r/3 if nu < 0.5 or nu > 10, otherwise r/2 (where r is the effective range). One of effective_range and range must be set.
- range (float | ndarray | None) The range parameter. One of range and effective_range must be set. If range is not set, it will be computed from effective_range.
- **nu** (*float* | np.ndarray) ν , smoothing parameter, shapes to a smooth or rough variogram function
- **method** (MaternModel) One of "sklearn", "gstat", or "karspeck":
 - sklearn: https://scikit-learn.org/stable/modules/generated/sklearn.gaussian_process. kernels.Matern.html#sklearn.gaussian_process.kernels.Matern
 - gstat: https://scikit-gstat.readthedocs.io/en/latest/reference/models.html#matern-model
 - karspeck: https://rmets.onlinelibrary.wiley.com/doi/10.1002/qj.900

fit(distance matrix)

Fit the MaternVariogram model to a distance matrix.

Parameters

distance_matrix (numpy.ndarray | xarray.DataArray) – The distance matrix indicating the distance between each pair of points in the grid.

Returns

A matrix containing the variogram values at each distance.

Return type

numpy.ndarray | xarray.DataArray

glomar_gridding.variogram.variogram_to_covariance(variogram, variance)

Convert a variogram matrix to a covariance matrix.

This is given by:

covariance = variance - variogram

Parameters

- variogram (numpy.ndarray | xarray.DataArray) The variogram matrix, output of Variogram.fit.
- variance (numpy.ndarray | float) The variance

Returns

cov – The covariance matrix

Return type

numpy.ndarray | xarray.DataArray

4.3 Covariance

I/O functionality for loading a covariance matrix from disk.

Load a covariance matrix from a netCDF file. Can input a filename or a string to format with keyword arguments.

Parameters

- **path** (*str*) Full filename (including path), or filename with replacements using str.format with named replacements. For example: /path/to/global_covariance_{month:02d}.nc
- cov_var_name (str) Name of the variable for the covariance matrix
- **kwargs Keywords arguments matching the replacements in the input path.

Returns

covariance – A numpy matrix containing the covariance matrix loaded from the netCDF file determined by the input arguments.

Return type

numpy.ndarray

4.3. Covariance

ELLIPSES: NON-STATIONARY INTERPOLATION COVARIANCE

5.1 Ellipse Models

The class that contains variogram/ellipse fitting methods and parameters

This class assumes your input to be a standardised correlation matrix They are easier to handle because stdevs in the covariance function become 1

Parameters

- anisotropic (bool) Should the output be an ellipse? Set to False for circle.
- **rotated** (*boo1*) Can the ellipse be rotated. If anisotropic is False this value cannot be True.
- physical_distance (bool) Use physical distances rather than lat/lon distance.
- \mathbf{v} (float) Matern Shape Parameter. Must be > 0.0.
- **unit_sigma=True** (*bool*) When MLE fitting the Matern parameters, assuming the Matern parameters themselves are normally distributed, there is standard deviation within the log likelihood function.

See Wikipedia entry for Maximum Likelihood under: - Continuous distribution, continuous parameter space

Its actual value is not important to the best (MLE) estimate of the Matern parameters. If one assumes the parameters are normally distributed, the mean (best estimate) is independent of its variance. In fact in Karspeck et al 2012 [Karspeck], it is simply set to 1 Eq B1). This value can however be computed. It serves a similar purpose as the original standard deviation: in this case, how the actual observed semivariance disperses around the fitted variogram.

The choice to default to 1 follows Karspeck et al. 2012 [Karspeck]

fit(X, y, guesses=None, bounds=None, opt_method='Nelder-Mead', tol=None, estimate_SE='bootstrap_parallel', n_sim=500, n_jobs=4, backend='loky', random_seed=1234)

Default solver in Nelder-Mead as used in Karspeck et al. 2012 [Karspeck] i.e. https://docs.scipy.org/doc/scipy/reference/optimize.minimize-neldermead.html default max-iter is 200 x (number_of_variables) for 3 variables (Lx, Ly, theta) -> 200x3 = 600 note: unlike variogram fitting, no nugget, no sill, and no residue variance (normalised data but Fisher transform needed?) can be adjusted using "maxiter" within "options" kwargs

Much of the variable names are defined the same way as earlier

- **X** (*numpy.ndarray*) Array of displacements. Expected to be 1-dimensional if the ellipse model is not anisotropic, 2-dimensional otherwise. In units of km if the ellipse uses physical distances, otherwise in degrees. The displacements are from each position within the test region to the centre of the ellipse.
- **y** (*numpy.ndarray*) Vector of observed correlations between the centre of the ellipse and each test point.
- **guesses=None** (list[float] | None) List of initial values to scipy.optimize.minimize, default guesses for the ellipse model are used if not set.
- **bounds=None** (list[tuple[float, float]] / None) Tuples/lists of bounds for fitted parameters. Default bounds for the ellipse model are used if not set.
- **opt_method** (*str*) scipy.optimize.minimize optimisation method. Defaults to "Nelder-Mead". See https://docs.scipy.org/doc/scipy/reference/generated/scipy.optimize. minimize.html for valid values.
- tol=None (float | None) scipy.optimize.minimize convergence tolerance
- **estimate_SE='bootstrap_parallel'** (*str | None*) How to estimate standard error if needed. If not set no standard error is computed.
- **n_sim=500** (*int*) Number of bootstrap to estimate standard error
- **n_jobs=DEFAULT_N_JOBS** (*int*) Number of threads for bootstrapping if *estimate_SE* is set to "bootstrap_parallel".
- **backend=DEFAULT_BACKEND** (*str*) joblib backend for bootstrapping.
- random_seed=1234 (int) Random seed for bootstrap

Return type

tuple[OptimizeResult, float | None, list[tuple[float, float]]]

Returns

- **results** (*OptimizeResult*) Output of scipy.optimize.minimize
- SE (float | None) Standard error of the fitted parameters
- **bounds** (*list[tuple[float*, ...]]) Bounds of fitted parameters

negative_log_likelihood(X, y, params, arctanh transform=True)

Compute the negative log-likelihood given observed X independent observations (displacements) and y dependent variable (the observed correlation), and Matern parameters params. Namely does the Matern covariance function using params, how close it explains the observed displacements and correlations.

log(LL) = SUM (f (y,x|params)) params = Maximise (log(LL)) params = Minimise (-log(LL)) which is how usually the computer solves it assuming errors of params are normally distributed

There is a hidden scale/standard deviation in stats.norm.logpdf(scale, which defaults to 1) but since we have scaled our values to covariance to correlation (and even used Fisher transform) as part of the function, it can be dropped

Otherwise, you need to have stdev as the last value of params, and should be set to the scale parameter

- **X** (np.ndarray) Observed displacements to the centre of the ellipse.
- **y** (*np.ndarray*) Observed correlation against the centre of the ellipse.
- params (list[float]) Ellipse parameters (in the current optimize iteration) or if you want to compute the actual negative log-likelihood.

• **arctanh_transform** (*bool*) – Should the Fisher (arctanh) transform be used This is usually option, but it does make the computation more stable if they are close to 1 (or -1; doesn't apply here)

Returns

nLL - The negative log likelihood

Return type

float

$negative_log_likelihood_function(X, y)$

Creates a function that can be fed into scipy.optimizer.minimize

Return type

Callable[[list[float]], float]

5.2 Ellipse Parameter Estimation

class glomar_gridding.ellipse.EllipseBuilder(data array, coords)

Class to build spatial covariance and correlation matrices used to estimate ellipse parameterss using an instance of EllipseModel which sets up the defaults for a given configuration.

To fit ellipse parameters to the correlation of the input data_array, call self.fit_ellipse_model.

Parameters

- data_array (numpy.ndarray | numpy.ma.MaskedArray) Training data stored within a numpy array. In general, this input should be extracted from an xarray.DataArray, and masked appropriately.
- **coords** (*xarray*. *Coordinates*) The coordinates associated with the data_array value. It is expected that these are ["time", "latitude", "longitude"]

calc_cov(rounding=None)

Calculate covariance and correlation matrices.

Parameters

```
rounding (int | None) – Round the values of the output.
```

Return type

None

```
compute_params (default_value, matern_ellipse, max_distance=20.0, min_distance=0.3, delta_x_method='Modified_Met_Office', guesses=None, bounds=None, opt_method='Nelder-Mead', tol=0.0001, estimate_SE=None, n_jobs=4, n_sim=500)
```

Fit ellipses/covariance models using adhoc local covariances to all unmasked grid points

The form of the covariance model depends on the "fform" attribute of the Ellipse model:

- isotropic (radial distance only)
- anistropic (x and y are different, but not rotated)
- anistropic_rotated (rotated)

If the "fform" attribute ends with _pd then physical distances are used instead of degrees

range is defined max_distance (either in km and degrees) default is in degrees, but needs to be km if fform is from _pd series <— likely to be wrong: max_distance should only be in degrees

there is also a min_distance in which values, matern function is not defined at the origin, so the 0.0 needs to removed

v = matern covariance function shape parameter Karspeck et al. [Karspeck] and Paciorek & Schervish [PaciorekSchervish] but 0.5 and 1.5 are popular 0.5 gives an exponential decay lim v->inf, Gaussian shape delta x method: only meaningful for pd fits:

- "Met_Office": Cylindrical Earth delta_x = 6400km x delta_lon (in radians)
- "Modified_Met_Office": uses the average zonal dist at different lat

Parameters

- **default_value** (*Any*) Default value(s) to fill arrays where parameter estimation is not possible (typically due to masking). Typically, one should set a value that is appropriate to the type of the field. If a single value is provided, this is used for all fields. If not, the length of the list of default values must equal the number of parameters of the *EllipseModel*
- matern_ellipse (EllipseModel) EllipseModel to use for parameter estimation
- max_distance (float) Maximum separation in distance unit that data will be fed into parameter fitting Units depend on fform (it is usually either degrees or km)
- min_distance (float) Minimum separation in distance unit that data will be fed into parameter fitting Units depend on fform (it is usually either degrees or km) Note: Due to the way we compute the Matern function, it is undefined at dist == 0 even if the limit -> zero is obvious.
- **delta_x_method="Modified_Met_Office"** (*str*) How to compute distances between grid points For istropic variogram/covariances, this is a trivial problem; you can just take the haversine or Euclidean ("tunnel") distance as they are non-directional.

But it is non trivial for anistropic cases, you have to define a set of orthogonal space. In HadSST4, Earth is assumed to be cylindrical "tin can" Earth, so you can just define the orthogonal space by lines of constant lat and lon (delta_x_method="Met_Office").

The modified "Modified_Met_Office" is a variation to that, but allow the tin can get squished at the poles. (Sinusoidal projection). This does results in a problem: the zonal displacement now depends in which latitude you compute on (at the beginning latitude or at the end latitude). Here we take the average of the two.

- guesses=None (tuple of floats; None uses default guess values) Initial guess values that get feeds in the optimizer for MLE. In scipy, you are required to do so (but R often doesn't). You should anyway; sometimes they do funny things if you don't (per recommendation of David Stephenson)
- bounds=None (tuple of floats; None uses default bounds values) This is essentially a Bayesian "uniformative prior" that forces convergence if the optimizer hits the bound. For lower resolution fitting, this is rarely a problem. For higher resolution fits, this often interacts with the limit of the data you can put into the fit the optimizer may fail to converge if the input data is very smooth (aka ENSO region, where anomalies are smooth over very large (~10000km) scales).
- opt_method='Nelder-Mead' (str) scipy.optimize method. Nelder-Mead is the one used by [Karspeck]. See https://docs.scipy.org/doc/scipy/tutorial/optimize.html for valid options
- tol=0.001 (float) Set convergence tolerance for scipy optimize. See https://docs.scipy.org/doc/scipy/reference/generated/scipy.optimize.minimize.html# scipy.optimize.minimize

Note on new tol kwarg: For N-M, this sets the value to both xatol and fatol Default is 1E-4 Since it affects accuracy of all values including rotation rotation angle $0.001 \, \text{rad} \sim 0.05 \, \text{deg}$

- **estimate_SE=None** (*str | None*) The code can estimate the standard error if the Matern parameters. This is not usually used or discussed for the purpose of kriging. Certain opt_method (gradient descent) can do this automatically using Fisher Info for certain covariance function, but is not possible for some nasty functions (aka Bessel func) gets involved nor it is possible for some optimisers (such as Nelder-Mead). The code does it using bootstrapping.
- n_jobs=DEFAULT_N_JOBS (int) If parallel processing, number of threads to use.
- **n_sim** (*int*) Number of simulations to bootstrap for SE estimation.

Returns

params – Containing arrays for each parameter in the ellipse model class. Note that one array is likely to be "qc_code", which takes values:

- 0: success
- 2: success but with one parameter reaching upper boundaries
- 3: success with multiple parameters reaching the boundaries (aka both Lx and Ly), can be both at lower or upper boundaries
- 9: fail, probably due to running out of maxiter (see scipy.optimize.minimize kwargs "options)"

Return type

xarray.Dataset

find_nearest_xy_index_in_cov_matrix(lonlat, use_full=False)

Find the nearest column/row index of the covariance that corresponds to a specific lat lon

Return type

tuple[int, ndarray]

```
fit_ellipse_model(xy_point, matern_ellipse, max_distance=20.0, min_distance=0.3, delta_x_method='Modified_Met_Office', guesses=None, bounds=None, opt_method='Nelder-Mead', tol=0.001, estimate_SE=None, n_jobs=4, n_sim=500)
```

Fit ellipses/covariance models using adhoc local covariances

the form of the covariance model depends on the "fform" attribute of the Ellipse model:

isotropic (radial distance only) anistropic (x and y are different, but not rotated) anistropic_rotated (rotated)

If the "fform" attribute ends with _pd then physical distances are used instead of degrees

range is defined max_distance (either in km and degrees) default is in degrees, but needs to be km if fform is from _pd series <— likely to be wrong: max_distance should only be in degrees

there is also a min_distance in which values, matern function is not defined at the origin, so the 0.0 needs to removed

v = matern covariance function shape parameter Karspeck et al. [Karspeck] and Paciorek & Schervish [PaciorekSchervish] use 3 and 4 but 0.5 and 1.5 are popular. 0.5 gives an exponential decay: lim v->inf, Gaussian shape

delta_x_method: only meaningful for _pd fits:

- "Met_Office": Cylindrical Earth delta_x = 6400km x delta_lon (in radians)
- "Modified_Met_Office": uses the average zonal dist at different lat

Parameters

- **xy_point** (*int*) The index point where ellipses will be fitted to
- max_distance (float) Maximum separation in distance unit that data will be fed into parameter fitting Units depend on fform (it is usually either degrees or km)
- min_distance (float) Minimum separation in distance unit that data will be fed into parameter fitting Units depend on fform (it is usually either degrees or km) Note: Due to the way we compute the Matern function, it is undefined at dist == 0 even if the limit -> zero is obvious.
- **delta_x_method="Modified_Met_Office"** (*str*) How to compute distances between grid points For istropic variogram/covariances, this is a trivial problem; you can just take the haversine or Euclidean ("tunnel") distance as they are non-directional.

But it is non trivial for anistropic cases, you have to define a set of orthogonal space. In HadSST4, Earth is assumed to be cylindrical "tin can" Earth, so you can just define the orthogonal space by lines of constant lat and lon (delta_x_method="Met_Office").

The modified "Modified_Met_Office" is a variation to that, but allow the tin can get squished at the poles. (Sinusoidal projection). This does results in a problem: the zonal displacement now depends in which latitude you compute on (at the beginning latitude or at the end latitude). Here we take the average of the two.

- guesses=None (tuple of floats; None uses default guess values) Initial guess values that get feeds in the optimizer for MLE. In scipy, you are required to do so (but R often doesn't). You should anyway; sometimes they do funny things if you don't (per recommendation of David Stephenson)
- bounds=None (tuple of floats; None uses default bounds values) This is essentially a Bayesian "uniformative prior" that forces convergence if the optimizer hits the bound. For lower resolution fitting, this is rarely a problem. For higher resolution fits, this often interacts with the limit of the data you can put into the fit the optimizer may fail to converge if the input data is very smooth (aka ENSO region, where anomalies are smooth over very large (~10000km) scales).
- opt_method='Nelder-Mead' (str) scipy.optimize method. Nelder-Mead is the one used by [Karspeck]. See https://docs.scipy.org/doc/scipy/tutorial/optimize.html for valid options
- tol=0.001 (float) Set convergence tolerance for scipy optimize. See https://docs.scipy.org/doc/scipy/reference/generated/scipy.optimize.minimize.html# scipy.optimize.minimize

Note on new tol kwarg: For N-M, this sets the value to both xatol and fatol Default is 1E-4 (?) Since it affects accuracy of all values including rotation rotation angle 0.001 rad ~ 0.05 deg

- **estimate_SE=None** (*str | None*) The code can estimate the standard error if the Matern parameters. This is not usually used or discussed for the purpose of kriging. Certain opt_method (gradient descent) can do this automatically using Fisher Info for certain covariance function, but is not possible for some nasty functions (aka Bessel func) gets involved nor it is possible for some optimisers (such as Nelder-Mead). The code does it using bootstrapping.
- n_jobs=DEFAULT_N_JOBS (int) If parallel processing, number of threads to use.
- **n_sim** (*int*) Number of simulations to bootstrap for SE estimation.

Returns

Dictionary with results of the fit and the observed correlation matrix.

Return type

dict

5.3 Ellipse-based Covariance Estimation

Compute covariance from Ellipse parameters and positions.

v = Matern covariance shape parameter

Lx - an numpy array of horizontal length scales (Ly - an numpy array of meridonal length scales theta - an numpy array of rotation angles (RADIANS ONLY)

sdev - standard deviation - right now it just takes a numeric array if you have multiple contribution to sdev (uncertainties derived from different sources), you need to put them into one array

Rules: Valid (ocean) point: 1) cov_ns and cor_ns are computed out to max_dist; out of range = 0.0 2) Masked points are ignored

Invalid (masked) points: 1) Skipped over

max_dist: float (km) or (degrees if you want to work in degrees), default 6000km if you want infinite distance, just set it to a large number, some fun numbers to use:

- 1.5E8 (i.e. ~1 astronomical unit (Earth-Sun distance))
- 5.0E9 (average distance between Earth and not-a-planet-anymore Pluto)

- Lx (numpy.ndarray) Arrays with non-stationary parameters
- Ly (numpy.ndarray) Arrays with non-stationary parameters
- theta (numpy.ndarray) Arrays with non-stationary parameters
- **stdev** (*numpy.ndarray*) Arrays with non-stationary parameters
- lats (numpy.ndarray) Arrays containing the latitude and longitude values
- lons (numpy.ndarray) Arrays containing the latitude and longitude values
- v(float) Matern shape parameter
- **delta_x_method** (str) How are displacements computed between points
- max_dist (float) If the Haversine distance between 2 points exceed max_dist, covariance is set to 0
- **precision** (*type*) Floating point precision of the output covariance numpy defaults to np.float32.
- **covariance_method** (*CovarianceMethod*) Set the covariance method used:

- array (default): faster but uses significantly more memory as more pre-computation is performed. Values are computed in a vectorised method.
- loop: slower iterative process, computes each value individually
- batched: combines the above approaches.

If the number of grid-points exceeds 10_000 and "array" method is used, the method will be overwritten to "loop".

• **batch_size** (*int | None*) – Size of the batch to use for the "batched" method. Must be set if the covariance_method is set to "batched".

c_ij_anisotropic_array(i_s, j_s)

Compute the covariances between pairs of ellipses, at displacements.

Each ellipse is defined by values from Lxs, Lys, and thetas, with standard deviation in stdevs.

The displacements between each pair of ellipses are x_is and x_js.

For N ellipses, the number of displacements should be 1/2 * N * (N - 1), i.e. the displacement between each pair combination of ellipses. This function will return the upper triangular values of the covariance matrix (excluding the diagonal).

itertools.combinations is used to handle ordering, so the displacements must be ordered in the same way.

Parameters

- i_s (numpy.ndarray) The row indices for the covariance matrix.
- **j_s** (*numpy.ndarray*) The column indices for the covariance matrix.

Returns

 $\mathbf{c_{ij}}$ – A vector containing the covariance values between each pair of ellipses. This will return the components of the upper triangle of the covariance matrix as a vector (excluding the diagonal).

Return type

numpy.ndarray

References

- 1. Paciorek and Schevrish 2006 [PaciorekSchervish] Equation 8
- 2. Karspeck et al. 2012 [Karspeck] Equation 17

calculate_cor()

Calculate correlation matrix from the covariance matrix

Return type

None

calculate_covariance_array()

Calculate the covariance matrix from the ellipse parameters

Return type

None

calculate_covariance_batched()

Compute the covariance matrix from ellipse parameters, using a batched approach. This approach is more memory safe and appropriate for low-memory operations, but is slower than self.calculate_covariance

which pre-computes values at all upper triangle points. This approach performs pre-computation at all points within the current batch.

Each ellipse is defined by values from Lxs, Lys, and thetas, with standard deviation in stdevs.

Requires a batch_size parameter.

Return type

None

References

- 1. Paciorek and Schevrish 2006 [PaciorekSchervish] Equation 8
- 2. Karspeck et al. 2012 [Karspeck] Equation 17

calculate_covariance_loop()

Compute the covariance matrix from ellipse parameters, using a loop. This approach is more memory safe and appropriate for low-memory operations, but is significantly slower than self.calculate_covariance which uses a lot of pre-computation and a vectorised approach.

Each ellipse is defined by values from Lxs, Lys, and thetas, with standard deviation in stdevs.

Return type

None

References

- 1. Paciorek and Schevrish 2006 [PaciorekSchervish] Equation 8
- 2. Karspeck et al. 2012 [Karspeck] Equation 17

uncompress_cov(diag_fill_value=nan, fill_value=nan)

Convert the covariance matrix to full grid size.

Optionally, fill the array with along the diagonal with a *diag_fill_value* and off the diagonal with a *fill_value*, which both default to *np.nan*.

Overwrites the *cov_ns* attribute.

Parameters

- diag_fill_value (Any) Value to assign to diagonal masked values. Defaults to np.nan
- fill_value (Any) Value to assign to off-diagonal masked values. Defaults to np.nan

Return type

None

ERROR COVARIANCE

Functions for computing correlated and uncorrelated components of the error covariance. These values are determined from standard deviation (sigma) values assigned to groupings within the observational data.

The correlated components will form a matrix that is permutationally equivalent to a block diagonal matrix (i.e. the matrix will be block diagonal if the observational data is sorted by the group).

The uncorrelated components will form a diagonal matrix.

Further a distance-based component can be constructed, where distances between records within the same grid box are evaluated.

The functions in this module are valid for observational data where there could be more than 1 observation in a gridbox.

Returns measurements covariance matrix updated by adding bias uncertainty to the measurements based on a grouping within the observational data.

The result is equivalent to a block diagonal matrix via permutation. If the input observational data is sorted by the group column then the resulting matrix is block diagonal, where the blocks are the size of each grouping. The values in each block are the square of the sigma value associated with the grouping.

Note that in most cases the output is not a block-diagonal, as the input is not usually sorted by the group column. In most processing cases, the input dataframe will be sorted by the gridbox index.

The values can either be pre-defined in the observational dataframe, and can be indicated by the "bias_val_col" argument. Alternatively, a mapping can be passed, the values will be then assigned by this mapping of group to sigma.

- **df** (*polars.DataFrame*) Observational DataFrame including group information and bias uncertainty values for each grouping. It is assumed that a single bias uncertainty value applies to the whole group, and is applied as cross terms in the covariance matrix (plus to the diagonal).
- **group_col** (*str*) Name of the column that can be used to partition the observational DataFrame.
- bias_sig_col (str | None) Name of the column containing bias uncertainty values for each of the groups identified by 'group_col'. It is assumed that a single bias uncertainty value applies to the whole group, and is applied as cross terms in the covariance matrix (plus to the diagonal).
- bias_sig_map (dict[str, float] | None) Mapping between values in the group_col and bias uncertainty values, if bias_val_col is not in the DataFrame.

Return type

The correlated components of the error covariance.

glomar_gridding.error_covariance.dist_weight(df, dist_fn, grid_idx='grid_idx', **dist_kwargs)

Compute the distance and weight matrices over gridboxes for an input Frame.

This function acts as a wrapper for a distance function, allowing for computation of the distances between positions in the same gridbox using any distance metric.

The weightings from this function are for the gridbox mean of the observations within a gridbox.

Parameters

- df (polars.DataFrame) The observation DataFrame, containing the columns required
 for computation of the distance matrix. Contains the "grid_idx" column which indicates
 the gridbox for a given observation. The index of the DataFrame should match the index
 ordering for the output distance matrix/weights.
- **dist_fn** (*Callable*) The function used to compute a distance matrix for all points in a given grid-cell. Takes as input a polars.DataFrame as first argument. Any other arguments should be constant over all gridboxes, or can be a look-up table that can use values in the DataFrame to specify values specific to a gridbox. The function should return a numpy matrix, which is the distance matrix for the gridbox only. This wrapper function will correctly apply this matrix to the larger distance matrix using the index from the DataFrame.

If dist_fn is None, then no distances are computed and None is returned for the dist value.

• **dist_kwargs - Arguments to be passed to dist_fn. In general these should be constant across all gridboxes. It is possible to pass a look-up table that contains pre-computed values that are gridbox specific, if the keys can be matched to a column in df.

Return type

tuple[ndarray, ndarray]

Returns

• **dist** (*numpy.matrix*) – The distance matrix, which contains the same number of rows and columns as rows in the input DataFrame df. The values in the matrix are 0 if the indices of the row/column are for observations from different gridboxes, and non-zero if the row/column indices fall within the same gridbox. Consequently, with appropriate re-arrangement of rows and columns this matrix can be transformed into a block-diagonal matrix. If the DataFrame input is pre-sorted by the gridbox column, then the result is a block-diagonal matrix.

If dist fn is None, then this value will be None.

• weights (numpy.matrix) – A matrix of weights. This has dimensions n x p where n is the number of unique gridboxes and p is the number of observations (the number of rows in df). The values are 0 if the row and column do not correspond to the same gridbox and equal to the inverse of the number of observations in a gridbox if the row and column indices fall within the same gridbox. The rows of weights are in a sorted order of the gridbox. Should this be incorrect, one should re-arrange the rows after calling this function.

glomar_gridding.error_covariance.get_weights(df, grid_idx='grid_idx')

Get just the weight matrices over gridboxes for an input Frame.

The weightings from this function are for the gridbox mean of the observations within a gridbox.

Parameters

• **df** (*polars.DataFrame*) – The observation DataFrame, containing the columns required for computation of the distance matrix. Contains the "grid idx" column which indicates

the gridbox for a given observation. The index of the DataFrame should match the index ordering for the output weights.

• grid_idx (str) – Name of the column containing the gridbox index from the output grid.

Returns

 $\mathbf{weights} - \mathbf{A}$ matrix of weights. This has dimensions n x p where n is the number of unique gridboxes and p is the number of observations (the number of rows in df). The values are 0 if the row and column do not correspond to the same gridbox and equal to the inverse of the number of observations in a gridbox if the row and column indices fall within the same gridbox. The rows of weights are in a sorted order of the gridbox. Should this be incorrect, one should re-arrange the rows after calling this function.

Return type

numpy.matrix

```
\label{local_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_global_g
```

Calculates the covariance matrix of the measurements (observations). This is the uncorrelated component of the covariance.

The result is a diagonal matrix. The diagonal is formed by the square of the sigma values associated with the values in the grouping.

The values can either be pre-defined in the observational dataframe, and can be indicated by the "bias_val_col" argument. Alternatively, a mapping can be passed, the values will be then assigned by this mapping of group to sigma.

Parameters

- **df** (polars.DataFrame) The observational DataFrame containing values to group by.
- group_col (str) Name of the group column to use to set observational sigma values.
- **obs_sig_col** (*str | None*) Name of the column containing observational sigma values. If set and present in the DataFrame, then this column is used as the diagonal of the returned covariance matrix.
- **obs_sig_map** (*dict[str*, *float] | None*)—Mapping between group and observational sigma values used to define the diagonal of the returned covariance matrix.

Return type

ndarray

Returns

- A diagonal matrix representing the uncorrelated components of the error
- covariance matrix.

KRIGING

The *glomar_gridding.kriging* module contains classes and functions for interpolation via Kriging. Two methods of Kriging are supported by *glomar gridding*:

- · Simple Kriging
- · Ordinary Kriging

For each Kriging method there is a class and a function. The recommended approach is to use the classes, the functions will be deprecated in a future version of *glomar_gridding*. The classes require the full grid spatial covariance structure as an input. Each class contains a *solve* method that requires the observation values and the 1-dimensional grid index of each observation, optionally an error covariance matrix can be provided. The grid index values are used to index into the covariance matrix to obtain the inputs for the Kriging equations.

7.1 Preparation

glomar_gridding provides functionality for preparing your data for the interpolation. The grid module has functionality for defining the output grid (glomar_gridding.grid.grid_from_resolution()) which allows the user to create a coordinate system for the output, that can easily be mapped to a covariance matrix. The grid object is an xarray.DataArray object, with a coordinate system. Once the grid is defined, the observations can be mapped to the grid. This creates a 1-dimensional index value that should match to the covariance matrices used in the interpolation.

glomar_gridding.grid.map_to_grid(obs, grid, obs_coords=['lat', 'lon'], grid_coords=['latitude', 'longitude'], sort=True, bounds=None, add_grid_pts=True, grid_prefix='grid_')

Align an observation dataframe to a grid defined by an xarray DataArray.

Maps observations to the nearest grid-point, and sorts the data by the 1d index of the DataArray in a row-major format.

The grid defined by the latitude and longitude coordinates of the input DataArray is then used as the output grid of the Gridding process.

- **obs** (*polars.DataFrame*) The observational DataFrame containing positional data with latitude, longitude values within the *obs_latname* and *obs_lonname* columns respectively. Observations are mapped to the nearest grid-point in the grid.
- **grid** (xarray. DataArray) Contains the grid coordinates to map observations to.
- **obs_coords** (*list[str]*) Names of the column containing positional values in the input observational DataFrame.
- **grid_coords** (*list[str]*) Names of the coordinates in the input grid DataArray used to define the grid.
- **sort** (*bool*) Sort the observational DataFrame by the grid index

- **bounds** (list[tuple[float, float]] | None) Optionally filter the grid and DataFrame to fall within spatial bounds. This list must have the same size and ordering as obs_coords and grid_coords arguments.
- add_grid_pts (bool) Add the grid positional information to the observational DataFrame.
- grid_prefix(str) Prefix to use for the new grid columns in the observational DataFrame.

Returns

obs – Containing additional *grid_**, and *grid_idx* values indicating the positions and grid index of the observation respectively. The DataFrame is also sorted (ascendingly) by the *grid_idx* columns for consistency with the gridding functions.

Return type

pandas.DataFrame

For Kriging, the interpolation requires at most a single observation value in each grid box. If the data contains multiple values in a single grid cell then these need to be combined.

```
glomar_gridding.kriging.prep_obs_for_kriging(unmask_idx, unique_obs_idx, weights, obs, remove_obs_mean=0, obs_bias=None, error_cov=None)
```

Prep masked observations for Kriging. Combines observations in the same grid box to a single averaged observation using a weighted average.

Parameters

- unmask_idx (np.ndarray[int]) Indices of all un-masked points for chosen date.
- unique_obs_idx (np.ndarray[int]) Unique indices of all measurement points for a chosen date, representative of the indices of gridboxes, which have => 1 measurement.
- weights (np.ndarray[float]) Weight matrix (inverse of counts of observations).
- **obs** (*np.ndarray* [*float*]) All point observations/measurements for the chosen date.
- **remove_obs_mean** (*int*) Should the mean or median from obs be removed and added back onto obs?
 - -0 = No (default action)
 - -1 = the mean is removed
 - -2 = the median is removed
 - -3 = the spatial meam os removed

Note that the mean will need to be reapplied to the Kriging result.

• **obs_bias** (*np.ndarray[float] | None*) – Bias of all measurement points for a chosen date (corresponds to x obs).

Return type

tuple[ndarray, ndarray]

Returns

- obs_idx (numpy.ndarray[int]) Subset of grid-box indices containing observations that are unmasked.
- **grid_obs** (numpy.ndarray[float]) Unmasked and combined observations

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7.2 Simple Kriging

class glomar_gridding.kriging.SimpleKriging(covariance)

Class for SimpleKriging.

The equation for simple Kriging is:

$$(C_{obs} + E)^{-1} \times C_{cross} \times y + \mu$$

Where μ is a constant known mean, typically this is 0.

Parameters

covariance (*numpy.ndarray*) – The spatial covariance matrix. This can be a pre-computed matrix loaded into the environment, or computed from a Variogram class or using Ellipse methods.

constraint_mask(idx)

Compute the observational constraint mask (A14 in [Morice_2021]) to determine if a grid point should be masked/weights modified by how far it is to its near observed point

Note: typo in Section A4 in [Morice_2021] (confirmed by authors).

Equation to use is A14 is incorrect. Easily noticeable because dimensionally incorrect is wrong, but the correct answer is easy to figure out.

Correct Equation (extra matrix inverse for $C_{obs} + E$):

$$\frac{1 - diag(C - C_{cross}^T \times (C_{obs} + E)^{-1} \times C_{cross})}{diag(C)} < \alpha$$

This can be re-written as:

$$\frac{diag(C_{cross}^{T} \times (C_{obs} + E)^{-1} \times C_{cross})}{diag(C)} < \alpha$$

 α is chosen to be 0.25 in the UKMO paper

Written by S. Chan, modified by J. Siddons.

This requires that the kriging_weights attribute is set.

Parameters

idx (numpy.ndarray) – The 1d indices of observation grid points. These values should be between 0 and (N * M) - 1 where N, M are the number of longitudes and latitudes respectively. Note that these values should also be computed using "C" ordering in numpy reshaping. They can be computed from a grid using glomar_gridding.grid.map_to_grid. Each value should only appear once. Points that contain more than 1 observation should be averaged. Used to compute the Kriging weights.

Returns

constraint_mask – Constraint mask values, the left-hand-side of equation A14 from Morice et al. (2021). This is a vector of length *k_obs.size[0]*.

Return type

numpy.ndarray

References

[Morice_2021]: https://agupubs.onlinelibrary.wiley.com/doi/pdf/10.1029/2019JD032361

get_kriging_weights(idx, error_cov=None)

Compute the Kriging weights from the flattened grid indices where there is an observation. Optionally add an error covariance to the covariance between observation grid points.

The Kriging weights are calculated as:

$$(C_{obs} + E)^{-1} \times C_{cross}$$

Where C_{obs} is the spatial covariance between grid-points with observations, E is the error covariance between grid-points with observations, and C_{cross} is the covariance between grid-points with observations and all grid-points (including observation grid-points).

Sets the *kriging_weights* attribute.

Parameters

- idx (numpy.ndarray[int] / list[int]) The 1d indices of observation grid points. These values should be between 0 and (N * M) 1 where N, M are the number of longitudes and latitudes respectively. Note that these values should also be computed using "C" ordering in numpy reshaping. They can be computed from a grid using glomar_gridding.grid.map_to_grid. Each value should only appear once. Points that contain more than 1 observation should be averaged
- error_cov (numpy.ndarray | None) Optionally add error covariance values to the covariance between observation grid points.

Return type

None

get_uncertainty(idx)

Compute the kriging uncertainty. This requires the attribute kriging_weights to be computed.

Returns

uncert - The Kriging uncertainty.

Return type

numpy.ndarray

kriging_weights_from_inverse(inv, idx)

Compute the Kriging weights from the flattened grid indices where there is an observation, using a precomputed inverse of the covariance between grid-points with observations.

The Kriging weights are calculated as:

$$(C_{obs} + E)^{-1} \times C_{cross}$$

Where C_{obs} is the spatial covariance between grid-points with observations, E is the error covariance between grid-points with observations, and C_{cross} is the covariance between grid-points with observations and all grid-points (including observation grid-points).

Sets the *kriging_weights* attribute.

Parameters

- inv (numpy.ndarray) The pre-computed inverse of the covariance between grid-points with observations. $(C_{obs} + E)^{-1}$
- idx (numpy.ndarray[int] / list[int]) The 1d indices of observation grid points. These values should be between 0 and (N * M) 1 where N, M are the number of longitudes and latitudes respectively. Note that these values should also be computed using "C" ordering in numpy reshaping. They can be computed from a grid using glomar_gridding.grid.map_to_grid. Each value should only appear once. Points that contain more than 1 observation should be averaged

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Return type

None

solve(*grid_obs*, *idx*, *error_cov=None*, *mean=0.0*)

Solves the simple Kriging problem. Computes the Kriging weights if the *kriging_weights* attribute is not already set. The solution to Kriging is:

$$(C_{obs} + E)^{-1} \times C_{cross} \times y$$

Where C_{obs} is the spatial covariance between grid-points with observations, E is the error covariance between grid-points with observations, C_{cross} is the covariance between grid-points with observations and all grid-points (including observation grid-points), and y are the observation values.

Parameters

- **grid_obs** (*numpy.ndarray*) The observation values. If there are multiple observations in any grid box then these values need to be averaged into one value per grid box.
- idx (numpy.ndarray) The 1d indices of observation grid points. These values should be between 0 and (N * M) 1 where N, M are the number of longitudes and latitudes respectively. Note that these values should also be computed using "C" ordering in numpy reshaping. They can be computed from a grid using glomar_gridding.grid.map_to_grid. Each value should only appear once. Points that contain more than 1 observation should be averaged. Used to compute the Kriging weights.
- **error_cov** (*numpy.ndarray | None*) Optionally add error covariance values to the covariance between observation grid points. Used to compute Kriging weights.
- **mean** (numpy.ndarray | float) Constant, known, mean value of the system. Defaults to 0.0.

Returns

The solution to the simple Kriging problem (as a Vector, this may need to be re-shaped appropriately as a post-processing step).

Return type

numpy.ndarray

glomar_gridding.kriging.kriging_simple(obs_obs_cov, obs_grid_cov, grid_obs, interp_cov, mean=0.0)

Perform Simple Kriging assuming a constant known mean.

This function is deprecated in favour of SimpleKriging class. It will be removed in version 1.0.0.

Parameters

- **obs_obs_cov** (*np.ndarray[float]*) Covariance between all measured grid points plus the covariance due to measurements (i.e. measurement noise, bias noise, and sampling noise). Can include error covariance terms.
- **obs_grid_cov** (*np.ndarray[float]*) Covariance between the all (predicted) grid points and measured points. Does not contain error covarance.
- **grid_obs** (*np.ndarray[float]*) Gridded measurements (all measurement points averaged onto the output gridboxes).
- **interp_cov** (*np.ndarray*[*float*]) interpolation covariance of all output grid points (each point in time and all points against each other).
- **mean** (*float*) The constant mean of the output field.

Return type

tuple[ndarray, ndarray]

Returns

- **z_obs** (*np.ndarray[float]*) Full set of values for the whole domain derived from the observation points using simple kriging.
- **dz** (np.ndarray[float]) Uncertainty associated with the simple kriging.

7.3 Ordinary Kriging

class glomar_gridding.kriging.OrdinaryKriging(covariance)

Class for OrdinaryKriging.

The equation for ordinary Kriging is:

$$(C_{obs} + E)^{-1} \times C_{cross} \times y$$

with a constant but unknown mean.

In this case, the C_{obs} , C_{cross} and y values are extended with a Lagrange multiplier term, ensuring that the Kriging weights are constrained to sum to 1.

The matrix C_{obs} is extended by one row and one column, each containing the value 1, except at the diagonal point, which is 0. The C_{cross} matrix is extended by an extra row containing values of 1. Finally, the grid observations y is extended by a single value of 0 at the end of the vector.

Parameters

covariance (*numpy.ndarray*) – The spatial covariance matrix. This can be a pre-computed matrix loaded into the environment, or computed from a Variogram class or using Ellipse methods.

constraint_mask(idx, simple_kriging_weights=None, error_cov=None)

Compute the observational constraint mask (A14 in [Morice_2021]) to determine if a grid point should be masked/weights modified by how far it is to its near observed point

Note: typo in Section A4 in [Morice 2021] (confirmed by authors).

Equation to use is A14 is incorrect. Easily noticeable because dimensionally incorrect is wrong, but the correct answer is easy to figure out.

Correct Equation (extra matrix inverse for $C_{obs} + E$):

$$\frac{1 - diag(C - C_{cross}^{T} \times (C_{obs} + E)^{-1} \times C_{cross})}{diag(C)} < \alpha$$

This can be re-written as:

$$\frac{diag(C_{cross}^{T} \times (C_{obs} + E)^{-1} \times C_{cross})}{diag(C)} < \alpha$$

 α is chosen to be 0.25 in the UKMO paper

Written by S. Chan, modified by J. Siddons.

This requires the Kriging weights from simple Kriging. If these are not provided as an input, then they are calculated.

Parameters

• idx (numpy.ndarray) – The 1d indices of observation grid points. These values should be between 0 and (N * M) - 1 where N, M are the number of longitudes and latitudes respectively. Note that these values should also be computed using "C" ordering in numpy

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reshaping. They can be computed from a grid using glomar_gridding.grid.map_to_grid. Each value should only appear once. Points that contain more than 1 observation should be averaged. Used to compute the Kriging weights.

- **simple_kriging_weights** (*numpy.ndarray | None*,) The Kriging weights for the equivalent simple Kriging system.
- **error_cov** (*numpy.ndarray | None*,) The error covariance matrix. Used to compute the simple Kriging weights if not provided. Can be excluded if not Kriging with an error covariance.

Returns

constraint_mask – Constraint mask values, the left-hand-side of equation A14 from Morice et al. (2021). This is a vector of length $k_obs.size[0]$.

Return type

numpy.ndarray

References

[Morice_2021]: https://agupubs.onlinelibrary.wiley.com/doi/pdf/10.1029/2019JD032361

extended_inverse(simple_inv)

Compute the inverse of a covariance matrix $S = C_{obs} + E$, and use that to compute the inverse of the extended version of the covariance matrix with Lagrange multipliers, used by Ordinary Kriging.

This is useful when one needs to perform BOTH simple and ordinary Kriging, or when one wishes to compute the constraint mask for ordinary Kriging which requires the Kriging weights for the equivalent simple Kriging problem.

The extended form of S is given by:

$$\begin{pmatrix} & & 1 \\ S & \vdots \\ & & 1 \\ 1 & \dots & 1 & 0 \end{pmatrix}$$

This approach follows Guttman 1946 10.1214/aoms/1177730946

Parameters

simple_inv (numpy.matrix) – Inverse of the covariance between observation grid-points

Returns

Inverse of the extended covariance matrix between observation grid-points including the Lagrange multiplier factors.

Return type

numpy.matrix

get_kriging_weights(idx, error_cov=None)

Compute the Kriging weights from the flattened grid indices where there is an observation. Optionally add an error covariance to the covariance between observation grid points.

The Kriging weights are calculated as:

$$(C_{obs} + E)^{-1} \times C_{cross}$$

Where C_{obs} is the spatial covariance between grid-points with observations, E is the error covariance between grid-points with observations, and C_{cross} is the covariance between grid-points with observations and all grid-points (including observation grid-points).

In this case, the C_{obs} , C_{cross} and are extended with a Lagrange multiplier term, ensuring that the Kriging weights are constrained to sum to 1.

The matrix C_{obs} is extended by one row and one column, each containing the value 1, except at the diagonal point, which is 0. The C_{cross} matrix is extended by an extra row containing values of 1.

Sets the *kriging_weights* attribute.

Parameters

- idx (numpy.ndarray[int] | list[int]) The 1d indices of observation grid points. These values should be between 0 and (N * M) 1 where N, M are the number of longitudes and latitudes respectively. Note that these values should also be computed using "C" ordering in numpy reshaping. They can be computed from a grid using glomar_gridding.grid.map_to_grid. Each value should only appear once. Points that contain more than 1 observation should be averaged
- **error_cov** (*numpy.ndarray | None*) Optionally add error covariance values to the covariance between observation grid points.

Return type

None

get_uncertainty(idx)

Compute the kriging uncertainty. This requires the attribute kriging weights to be computed.

Returns

uncert - The Kriging uncertainty.

Return type

numpy.ndarray

kriging_weights_from_inverse(inv, idx)

Compute the Kriging weights from the flattened grid indices where there is an observation, using a precomputed inverse of the covariance between grid-points with observations.

The Kriging weights are calculated as:

$$(C_{obs} + E)^{-1} \times C_{cross}$$

Where C_{obs} is the spatial covariance between grid-points with observations, E is the error covariance between grid-points with observations, and C_{cross} is the covariance between grid-points with observations and all grid-points (including observation grid-points).

In this case, the inverse matrix must be computed from the covariance between observation grid-points with the Lagrange multiplier applied.

This method is appropriate if one wants to compute the constraint mask which requires simple Kriging weights, which can be computed from the unextended covariance inverse. The extended inverse can then be calculated from that inverse.

Sets the *kriging_weights* attribute.

Parameters

- inv (numpy.ndarray) The pre-computed inverse of the covariance between grid-points with observations. $(C_{obs} + E)^{-1}$
- idx (numpy.ndarray[int] / list[int]) The 1d indices of observation grid points. These values should be between 0 and (N * M) 1 where N, M are the number of longitudes and latitudes respectively. Note that these values should also be computed using "C" ordering in numpy reshaping. They can be computed from a grid using glo-

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mar_gridding.grid.map_to_grid. Each value should only appear once. Points that contain more than 1 observation should be averaged

Return type

None

solve(grid_obs, idx, error_cov=None)

Solves the ordinary Kriging problem. Computes the Kriging weights if the *kriging_weights* attribute is not already set. The solution to Kriging is:

$$(C_{obs} + E)^{-1} \times C_{cross} \times y$$

Where C_{obs} is the spatial covariance between grid-points with observations, E is the error covariance between grid-points with observations, C_{cross} is the covariance between grid-points with observations and all grid-points (including observation grid-points), and y are the observation values.

In this case, the C_{obs} , C_{cross} and are extended with a Lagrange multiplier term, ensuring that the Kriging weights are constrained to sum to 1.

The matrix C_{obs} is extended by one row and one column, each containing the value 1, except at the diagonal point, which is 0. The C_{cross} matrix is extended by an extra row containing values of 1.

Parameters

- **grid_obs** (*numpy.ndarray*) The observation values. If there are multiple observations in any grid box then these values need to be averaged into one value per grid box.
- idx (numpy.ndarray) The 1d indices of observation grid points. These values should be between 0 and (N * M) 1 where N, M are the number of longitudes and latitudes respectively. Note that these values should also be computed using "C" ordering in numpy reshaping. They can be computed from a grid using glomar_gridding.grid.map_to_grid. Each value should only appear once. Points that contain more than 1 observation should be averaged. Used to compute the Kriging weights.
- **error_cov** (*numpy.ndarray | None*) Optionally add error covariance values to the covariance between observation grid points. Used to compute Kriging weights.

Returns

The solution to the ordinary Kriging problem (as a Vector, this may need to be re-shaped appropriately as a post-processing step).

Return type

numpy.ndarray

glomar_gridding.kriging.kriging_ordinary(obs_obs_cov, obs_grid_cov, grid_obs, interp_cov)

Perform Ordinary Kriging with unknown but constant mean.

This function is deprecated in favour of OrdinaryKriging class. It will be removed in version 1.0.0.

Parameters

- **obs_obs_cov** (*np.ndarray[float]*) Covariance between all measured grid points plus the covariance due to measurements (i.e. measurement noise, bias noise, and sampling noise). Can include error covariance terms, if these are being used.
- **obs_grid_cov** (*np.ndarray[float]*) Covariance between the all (predicted) grid points and measured points. Does not contain error covarance.
- grid_obs (np.ndarray[float]) Gridded measurements (all measurement points averaged onto the output gridboxes).
- **interp_cov** (*np.ndarray[float]*) Interpolation covariance of all output grid points (each point in time and all points against each other).

Return type

tuple[ndarray, ndarray]

Returns

- **z_obs** (*np.ndarray[float]*) Full set of values for the whole domain derived from the observation points using ordinary kriging.
- **dz** (*np.ndarray*[*float*]) Uncertainty associated with the ordinary kriging.

7.4 Perturbed Gridded Fields

An additional two-stage combined Kriging class is provided in the *stochastic* module.

class glomar_gridding.stochastic.StochasticKriging(covariance)

Class for the combined two-stage Kriging approach following [Morice_2021] The first stage is to produce a gridded field from the observations using Ordinary Kriging. The second stage is to apply a perturbation.

The perturbation is constructed by first generating a simulated state from the covariance matrix. A set of simulated observations is drawn from the error covariance matrix. A simulated gridded field is then computed using Simple Kriging with the simulated observations as input. Finally, the perturbation is then the difference between the simulated gridded field and the simulated state. This perturbation is added to the gridded field from the first stage.

The equation for ordinary Kriging is:

$$(C_{obs} + E)^{-1} \times C_{cross} \times y$$

with a constant but unknown mean.

In this case, the C_{obs} , C_{cross} and y values are extended with a Lagrange multiplier term for the first stage, ensuring that the Kriging weights are constrained to sum to 1.

Additionally, the matrix C_{obs} is extended by one row and one column, each containing the value 1, except at the diagonal point, which is 0 for the first Ordinary Kriging stage. The C_{cross} matrix is extended by an extra row containing values of 1. Finally, the grid observations y is extended by a single value of 0 at the end of the vector.

Parameters

covariance (*numpy.ndarray*) – The spatial covariance matrix. This can be a pre-computed matrix loaded into the environment, or computed from a Variogram class or using Ellipse methods.

constraint_mask(idx)

Compute the observational constraint mask (A14 in [Morice_2021]) to determine if a grid point should be masked/weights modified by how far it is to its near observed point

Note: typo in Section A4 in [Morice_2021] (confirmed by authors).

Equation to use is A14 is incorrect. Easily noticeable because dimensionally incorrect is wrong, but the correct answer is easy to figure out.

Correct Equation (extra matrix inverse for $C_{obs} + E$):

$$\frac{1 - diag(C - C_{cross}^T \times (C_{obs} + E)^{-1} \times C_{cross})}{diag(C)} < \alpha$$

This can be re-written as:

$$\frac{diag(C_{cross}^{T} \times (C_{obs} + E)^{-1} \times C_{cross})}{diag(C)} < \alpha$$

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 α is chosen to be 0.25 in the UKMO paper

Written by S. Chan, modified by J. Siddons.

This requires the Kriging weights from simple Kriging, set as the *simple_kriging_weights* attribute.

Parameters

idx (numpy.ndarray) – The 1d indices of observation grid points. These values should be between 0 and (N * M) - 1 where N, M are the number of longitudes and latitudes respectively. Note that these values should also be computed using "C" ordering in numpy reshaping. They can be computed from a grid using glomar_gridding.grid.map_to_grid. Each value should only appear once. Points that contain more than 1 observation should be averaged. Used to compute the Kriging weights.

Return type

ndarray

Returns

- **constraint_mask** (*numpy.ndarray*) Constraint mask values, the left-hand-side of equation A14 from [Morice_2021]. This is a vector of length *k_obs.size[0]*.
- Reference
- ____
- [Morice_2021]_ (https://agupubs.onlinelibrary.wiley.com/doi/pdf/10.1029/2019JD032361)

get_kriging_weights(idx, error_cov=None)

Compute the Kriging weights from the flattened grid indices where there is an observation. Optionally add an error covariance to the covariance between observation grid points.

The Kriging weights are calculated as:

$$(C_{obs} + E)^{-1} \times C_{cross}$$

Where C_{obs} is the spatial covariance between grid-points with observations, E is the error covariance between grid-points with observations, and C_{cross} is the covariance between grid-points with observations and all grid-points (including observation grid-points).

In this case, the C_{obs} , C_{cross} and are extended with a Lagrange multiplier term, ensuring that the Kriging weights are constrained to sum to 1, for the first stage of the StochasticKriging process.

The matrix C_{obs} is extended by one row and one column, each containing the value 1, except at the diagonal point, which is 0. The C_{cross} matrix is extended by an extra row containing values of 1.

Sets the *kriging_weights* and *simple_kriging_weights* attributes.

Parameters

- idx (numpy.ndarray[int] / list[int]) The 1d indices of observation grid points. These values should be between 0 and (N * M) 1 where N, M are the number of longitudes and latitudes respectively. Note that these values should also be computed using "C" ordering in numpy reshaping. They can be computed from a grid using glomar_gridding.grid.map_to_grid. Each value should only appear once. Points that contain more than 1 observation should be averaged
- **error_cov** (*numpy.ndarray | None*) Optionally add error covariance values to the covariance between observation grid points.

Return type

None

get_uncertainty(idx)

Compute the kriging uncertainty. This requires the attribute kriging_weights to be computed.

Returns

uncert – The Kriging uncertainty.

Return type

numpy.ndarray

kriging_weights_from_inverse(inv, idx)

Compute the Kriging weights from the flattened grid indices where there is an observation, using a precomputed inverse of the covariance between grid-points with observations.

The Kriging weights are calculated as:

$$(C_{obs} + E)^{-1} \times C_{cross}$$

Where C_{obs} is the spatial covariance between grid-points with observations, E is the error covariance between grid-points with observations, and C_{cross} is the covariance between grid-points with observations and all grid-points (including observation grid-points).

This method is appropriate if one wants to compute the constraint mask which requires simple Kriging weights, which can be computed from the unextended covariance inverse. The extended inverse can then be calculated from that inverse.

The inverse matrix is used to compute the inverse of the extended covariance matrix used for the first Ordinary Kriging stage.

Sets the *kriging_weights* and *simple_kriging_weights* attributes.

Parameters

- inv (numpy.ndarray) The pre-computed inverse of the covariance between grid-points with observations. $(C_{obs}+E)^{-1}$
- idx (numpy.ndarray[int] | list[int]) The 1d indices of observation grid points. These values should be between 0 and (N * M) 1 where N, M are the number of longitudes and latitudes respectively. Note that these values should also be computed using "C" ordering in numpy reshaping. They can be computed from a grid using glomar_gridding.grid.map_to_grid. Each value should only appear once. Points that contain more than 1 observation should be averaged

Return type

None

set_simple_kriging_weights(simple_kriging_weights)

Set Simple Kriging Weights. For use in the second Simple Kriging stage for computing the simulated gridded field.

Sets the *simple_kriging_weights* attribute.

Parameters

simple_kriging_weights (numpy.ndarray) – The pre-computed simple_kriging_weights to use.

Return type

None

solve(*grid obs, idx, error cov=None, simulated state=None*)

Solves the combined Stochastic Kriging problem. Computes the Kriging weights if the *kriging_weights* attribute is not already set.

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Stochastic Kriging is a combined Ordinary and Simple Kriging approach. First a gridded field is generated for the observations using Ordinary Kriging. Secondly, a simulated gridded field is generated using Simple Kriging from a simulated state and simulated observations. The simulated state can be pre-computed or computed by this method. The simulated observations are drawn from the error covariance and located at the simulated state. The difference between the simulated gridded field and the simulated state is added to the gridded field.

The solution to Kriging is:

$$(C_{obs} + E)^{-1} \times C_{cross} \times y$$

Where C_{obs} is the spatial covariance between grid-points with observations, E is the error covariance between grid-points with observations, C_{cross} is the covariance between grid-points with observations and all grid-points (including observation grid-points), and y are the observation values.

In this case, the C_{obs} , C_{cross} and are extended with a Lagrange multiplier term, ensuring that the Kriging weights are constrained to sum to 1. For the Ordinary Kriging component.

The matrix C_{obs} is extended by one row and one column, each containing the value 1, except at the diagonal point, which is 0. The C_{cross} matrix is extended by an extra row containing values of 1. For the Ordinary Kriging component.

This additionally sets the following attributes:

- gridded_field The unperturbed gridded field
- simulated_grid The simulated gridded field
- epsilon The perturbation

Parameters

- **grid_obs** (*numpy.ndarray*) The observation values. If there are multiple observations in any grid box then these values need to be averaged into one value per grid box.
- idx (numpy.ndarray) The 1d indices of observation grid points. These values should be between 0 and (N * M) 1 where N, M are the number of longitudes and latitudes respectively. Note that these values should also be computed using "C" ordering in numpy reshaping. They can be computed from a grid using glomar_gridding.grid.map_to_grid. Each value should only appear once. Points that contain more than 1 observation should be averaged. Used to compute the Kriging weights.
- **error_cov** (*numpy.ndarray | None*) Optionally add error covariance values to the covariance between observation grid points. Used to compute Kriging weights.
- **simulated_state** (*numpy.ndarray* | *None*) Flattened simulated state, used as the location basis for the simulated observation draw. If this is not provided it will be calculated. Often it is better to pre-compute a series of states in advance, since this can be a time consuming step (drawing a single state takes approximately the same time as drawing 200).

Returns

The solution to the stochastic Kriging problem (as a Vector, this may need to be re-shaped appropriately as a post-processing step).

Return type

numpy.ndarray

glomar_gridding.stochastic.scipy_mv_normal_draw(loc, cov, ndraws=1, eigen_rtol=1e-06, eigen_fudge=1e-08)

Do a random multivariate normal draw using scipy.stats.multivariate_normal.rvs

numpy.random.multivariate_normal can also, but fixing seeds are more difficult using numpy

This function has similar API as GP_draw with less kwargs.

Warning/possible future scipy version may change this: It seems if one uses stats. Covariance, you have to have add [0] from rvs function. The above behavior applies to scipy v1.14.0

Parameters

- **loc** (*float*) the location for the normal dry
- cov (numpy.ndarray) not a xarray/iris cube! Some of our covariances are saved in numpy format and not netCDF files
- n_draws (int) number of simulations, this is usually set to 1 except during
- testing (unit)
- **eigen_rtol** (*float*) relative tolerance to negative eigenvalues
- eigen_fudge (float) forced minimum value of eigenvalues if negative values are detected

Returns

draw – The draw(s) from the multivariate random normal distribution defined by the loc and cov parameters. If the cov parameter is not positive-definite then a new covariance will be determined by adjusting the eigen decomposition such that the modified covariance should be positive-definite.

Return type

np.ndarray

7.5 Outputs

The outputs to the solvers, glomar_gridding.SimpleKriging.solve() for example will be vectors, they should be re-shaped to the grid.

Outputs can also be re-mapped to the grid

glomar_gridding.grid.assign_to_grid(values, grid_idx, grid, mask_grid=False, mask_value=nan)

Assign a vector of values to a grid, using a list of grid index values. The default value for grid values is 0.0.

Optionally, if the grid is a mask, apply the mask to the output grid.

Parameters

- values (polars. Series) The values to map onto the output grid.
- grid_idx (polars. Series) The 1d index of the grid (assuming "C" style ravelling) for each value.
- grid (xarray.DataArray) The grid used to define the output grid.
- mask_grid (bool) Optionally use values in the grid to mask the output grid.
- mask_value (Any) The value in the grid to use for masking the output grid.

Returns

out_grid - A new grid containing the values mapped onto the grid.

Return type

xarray.DataArray

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CHAPTER

EIGHT

MISCALLANEOUS MODULES

8.1 Climatologies

Functions for mapping climatologies and computing anomalies

```
\label{eq:glomar_gridding_glomar_gridding} \begin{split} \text{glomar\_gridding.climatology\_by\_doy}(obs\_df, climatology\_365, lat\_col='lat', \\ lon\_col='lon', date\_col='date', var\_col='sst', \\ clim\_lat='latitude', clim\_lon='longitude', \\ clim\_doy='doy', clim\_var='climatology', \\ temp\_from\_kelvin=True) \end{split}
```

Merge a climatology from an xarray.DataArray into a polars.DataFrame using the day of year value and position.

This function accounts for leap years by taking the average of the climatology values for 28th Feb and 1st March for observations that were made on the 29th of Feb.

The climatology is merged into the DataFrame and anomaly values are computed.

Parameters

- **obs_df** (*polars.DataFrame*) Observational DataFrame.
- **climatology_365** (*xarray.DataArray*) DataArray containing daily climatology values (for 365 days).
- lat_col (str) Name of the latitude column in the observational DataFrame.
- **lon_col** (*str*) Name of the longitude column in the observational DataFrame.
- **date_col** (*str*) Name of the datetime column in the observational DataFrame. Day of year values are computed from this value.
- var_col (str) Name of the variable column in the observational DataFrame. The merged climatology names will have this name prefixed to "_climatology", the anomaly values will have this name prefixed to "_anomaly".
- **clim_lat** (*str*) Name of the latitude coordinate in the climatology DataArray.
- ${\tt clim_lon}\,({\tt str})$ Name of the longitude coordinate in the climatology DataArray.
- clim_doy (str) Name of the day of year coordinate in the climatology DataArray.
- **clim_var** (*str*) Name of the climatology variable in the climatology DataArray.
- **temp_from_kelvin** (*bool*) Optionally adjust the climatology from Kelvin to Celsius if the variable is a temperature.

Returns

obs_df – With the climatology merged and anomaly computed. The new columns are "_climatology" and "_anomaly" prefixed by the *var_col* value respectively.

Return type

polars.DataFrame

glomar_gridding.climatology.read_climatology(clim_path, min_lat=-90, max_lat=90, min_lon=-180, max_lon=180, lat_var='lat', lon_var='lon', **kwargs)

Load a climatology dataset from a netCDF file.

Parameters

- **clim_path** (*str*) Path to the climatology file. Can contain format blocks to be replaced by the values passed to kwargs.
- min_lat (float) Minimum latitude to load.
- max_lat (float) Maximum latitude to load.
- min_lon (float) Minimum longitude to load.
- max_lon (float) Maximum longitude to load.
- lat_var (str) Name of the latitude variable.
- **lon_var** (*str*) Name of the longitude variable.
- ****kwargs** Replacement values for the climatology path.

Returns

clim_ds - Containing the climatology bounded by the min/max arguments provided.

Return type

xarray.Dataset

8.2 Masking

Functions for applying masks to grids and DataFrames

glomar_gridding.mask.get_mask_idx(mask, mask_val=nan, masked=True)

Get the 1d indices of masked values from a mask array.

Parameters

- mask (xarray. DataArray) The mask array, containing values indicated a masked value.
- mask_val (Any) The value that indicates the position should be masked.
- masked (bool) Return indices where values in the mask array equal this value. If set to False it will return indices where values are not equal to the mask value. Can be used to get unmasked indices if this value is set to False.

Return type

An array of integers indicating the indices which are masked.

glomar_gridding.mask.mask_array(grid, mask, varname, masked_value=nan, mask_value=True)

Apply a mask to a DataArray.

The grid and mask must already align for this function to work. An error will be raised if the coordinate systems cannot be aligned.

Parameters

• **grid** (*xarray.DataArray*) – Observational DataArray to be masked by positions in the mask DataArray.

- mask (xarray.DataArray) Array containing values used to mask the observational DataFrame.
- **varname** (*str*) Name of the variable in the observational DataArray to apply the mask to.
- masked_value (Any) Value indicating masked values in the DataArray.
- mask_value (Any) Value to set masked values to in the observational DataFrame.

Returns

grid – Input xarray. Data Array with the variable masked by the mask Data Array.

Return type

xarray.DataArray

glomar_gridding.mask.mask_dataset(dataset, mask, varnames, masked_value=nan, mask_value=True)
Apply a mask to a DataSet.

The grid and mask must already align for this function to work. An error will be raised if the coordinate systems cannot be aligned.

Parameters

- **dataset** (*xarray.Dataset*) Observational Dataset to be masked by positions in the mask DataArray.
- mask (xarray.DataArray) Array containing values used to mask the observational DataFrame.
- **varnames** (*str* / *list[str]*) A list containing the names of variables in the observational Dataser to apply the mask to.
- **masked_value** (*Any*) Value indicating masked values in the DataArray.
- mask_value (Any) Value to set masked values to in the observational DataFrame.

Returns

grid – Input xarray. Dataset with the variables masked by the mask DataArray.

Return type

xarray.Dataset

glomar_gridding.mask.mask_from_obs_array(obs, datetime_idx)

Infer a mask from an input array. Mask values are those where all values are NaN along the time dimension.

An example use-case would be to infer land-points from a SST data array.

Parameters

- **obs** (*numpy.ndarray*) Array containing the observation values. Records that are numpy.nan will count towards the mask, if all values in the datetime dimension are numpy.nan.
- **datetime_idx** (*int*) The index of the datetime, or grouping, dimension. If all records at a point along this dimension are NaN then this point will be masked.

Returns

mask – A boolean array with dimension reduced along the datetime dimension. A True value indicates that all values along the datetime dimension for this index are numpy.nan and are masked.

Return type

numpy.ndarray

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glomar_gridding.mask.mask_from_obs_frame(obs, coords, datetime_col, value_col)

Compute a mask from observations.

Positions defined by the "coords" values that do not have any observations, at any datetime value in the "date-time_col", for the "value_col" field are masked.

An example use-case would be to identify land positions from sst records.

Parameters

- **obs** (*polars.DataFrame*) DataFrame containing observations over space and time. The values in the "value_col" field will be used to define the mask.
- **coords** (*str* / *list[str]*) A list of columns containing the coordinates used to define the mask. For example ["lat", "lon"].
- **datetime_col** (*str*) Name of the datetime column. Any positions that contain no records at any datetime value are masked.
- value_col (str) Name of the column containing values from which the mask will be defined.

Return type

DataFrame

Returns

- polars.DataFrame containing coordinate columns and a Boolean "mask" column
- indicating positions that contain no observations and would be a mask value.

Mask observations in a DataFrame subject to a mask DataArray.

Parameters

- **obs** (*polars.DataFrame*) Observational DataFrame to be masked by positions in the mask DataArray.
- mask (xarray.DataArray) Array containing values used to mask the observational DataFrame.
- **varnames** (*str* / *list[str]*) Columns in the observational DataFrame to apply the mask to.
- mask_varname (str) Name of the mask variable in the mask DataArray.
- **masked_value** (*Any*) Value indicating masked values in the DataArray.
- mask_value (Any) Value to set masked values to in the observational DataFrame.
- **obs_coords** (*list[str]*) A list of coordinate names in the observational DataFrame. Used to map the mask DataArray to the observational DataFrame. The order must align with the coordinates of the mask DataArray.
- mask_coords (list[str]) A list of coordinate names in the mask DataArray. These coordinates are mapped onto the observational DataFrame in order to apply the mask. The ordering of the coordinate names in this list must match those in the obs_coords list.
- align_to_mask (bool) Optionally align the observational DataFrame to the mask DataArray. This essentially sets the mask's grid as the output grid for interpolation.

- **drop** (*boo1*) Drop masked values in the observational DataFrame.
- mask_grid_prefix (str) Prefix to use for the mask gridbox index column in the observational DataFrame.

Returns

obs – Input polars.DataFrame containing additional column named by the mask_varname argument, indicating records that are masked. Masked values are dropped if the drop argument is set to True.

Return type

polars.DataFrame

8.3 Distances and Distance Matrices

Functions for calculating distances or distance-based covariance components.

Some functions can be used for computing pairwise-distances, for example via squareform. Some functions can be used as a distance function for glomar_gridding.error_covariance.dist_weights, accounting for the distance component to an error covariance matrix.

Functions for computing covariance using Matern Tau by Steven Chan (@stchan).

```
\label{local_collision} glomar\_gridding.distances. \textbf{calculate\_distance\_matrix}(df, dist\_func = < function \\ haversine\_distance\_from\_frame >, lat\_col = 'lat', \\ lon \ col = 'lon')
```

Create a distance matrix from a DataFrame containing positional information, typically latitude and longitude, using a distance function.

Available functions are *haversine_distance*, *euclidean_distance*. A custom function can be used, requiring that the function takes the form: (tuple[float, float]) -> float

Parameters

- **df** (*polars.DataFrame*) DataFrame containing latitude and longitude columns indicating the positions between which distances are computed to form the distance matrix
- **dist_func** (*Callable*) The function used to calculate the pairwise distances. Functions available for this function are *haversine_distance* and *euclidean_distance*. A custom function can be based, that takes as input two tuples of positions (computing a single distance value between the pair of positions). (tuple[float, float], tuple[float, float]) -> float
- lat_col (str) Name of the column in the input DataFrame containing latitude values.
- lon_col (str) Name of the column in the input DataFrame containing longitude values.

Returns

dist – A matrix of pairwise distances.

Return type

np.ndarray[float]

 $\verb|glomar_gridding.distances.displacements|| lats, lons, lats 2 = None, lons 2 = None, delta_x_method = None)|| lats, lons, lats 2 = None, lons 2 = None, delta_x_method = None)|| lats, lons, lats 2 = None, lons 2 = None, delta_x_method = None)|| lats, lons, lats 2 = None, lons 2 = None, delta_x_method = None)|| lats, lons, lats 2 = None, lons 2 = None, delta_x_method = None)|| lats, lons, lats 2 = None, lons 2 = None, delta_x_method = None)|| lats, lons, lats 2 = None, lons 2 = None, delta_x_method = None)|| lats, lons, lats 2 = None, lons 2 = None, delta_x_method = None)|| lats, lons, lats 2 = None, lons 2 = None, delta_x_method = None)|| lats, lons, lats 2 = None, lons 2 = None, delta_x_method = None)|| lats, lons, lats 2 = None, lons 2 = None, delta_x_method = None)|| lats, lons, long 2 = None, lons 2 = None, long 2$

Calculate east-west and north-south displacement matrices for all pairs of input positions.

The results are not scaled by any radius, this should be performed outside of this function.

Parameters

- lats (numpy.ndarray) The latitudes of the positions, should be provided in degrees.
- lons (numpy.ndarray) The longitudes of the positions, should be provided in degrees.

- lats2 (numpy.ndarray) The latitudes of the optional second positions, should be provided in degrees.
- **lons2** (*numpy.ndarray*) The longitudes of the optional second positions, should be provided in degrees.
- delta_x_method (str / None) One of "Met_Office" or "Modified_Met_Office". If set to None, the displacements will be returned in degrees, rather than actual distance values. Set to "Met_Office" to use a cylindrical approximation, set to "Modified_Met_Office" to use an approximation that uses the average of the latitudes to set the horizontal displacement scale.

Return type

tuple[ndarray, ndarray]

Returns

- **disp_y** (*numpy.ndarray*) The north-south displacements.
- **disp_x** (*numpy.ndarray*) The east-west displacements.

glomar_gridding.distances.euclidean_distance(df, radius=6371.0)

Calculate the Euclidean distance in kilometers between pairs of lat, lon points on the earth (specified in decimal degrees).

See: https://math.stackexchange.com/questions/29157/how-do-i-convert-the-distance-between-two-lat-long-points-into-feet-methods://cesar.esa.int/upload/201709/Earth Coordinates Booklet.pdf

$$d = SQRT((x_2-x_1)**2 + (y_2-y_1)**2 + (z_2-z_1)**2)$$

where

 $(x_n y_n z_n) = (R\cos(at)\cos(lon)R\cos(lat)\sin(lon)R\sin(lat))$

Parameters

- **df** (*polars.DataFrame*) DataFrame containing latitude and longitude columns indicating the positions between which distances are computed to form the distance matrix
- radius (float) The radius of the sphere used for the calculation. Defaults to the radius of the earth in km (6371.0 km).

Returns

dist – The direct pairwise distance between the positions in the input DataFrame through the sphere defined by the radius parameter.

Return type

float

glomar_gridding.distances.haversine_distance_from_frame(df, radius=6371)

Calculate the great circle distance in kilometers between pairs of lat, lon points on the earth (specified in decimal degrees).

Parameters

- **df** (*polars.DataFrame*) DataFrame containing latitude and longitude columns indicating the positions between which distances are computed to form the distance matrix
- **radius** (*float*) The radius of the sphere used for the calculation. Defaults to the radius of the earth in km (6371.0 km).

Returns

dist – The pairwise haversine distances between the inputs in the DataFrame, on the sphere defined by the radius parameter.

Return type

numpy.ndarray

glomar_gridding.distances.haversine_gaussian(df, R=6371.0, r=40, s=0.6)

Gaussian Haversine Model

Parameters

- **df** (*polars.DataFrame*) Observations, required columns are "lat" and "lon" representing latitude and longitude respectively.
- **R** (*float*) Radius of the sphere on which Haversine distance is computed. Defaults to radius of earth in km.
- **r** (*float*) Gaussian model range parameter
- **s** (*float*) Gaussian model scale parameter

Returns

C – Distance matrix for the input positions. Result has been modified using the Gaussian model.

Return type

np.ndarray

glomar_gridding.distances.inv_2d(mat)

Compute the inverse of a 2 x 2 matrix

Return type

ndarray

glomar_gridding.distances.mahal_dist_func(delta_x, delta_y, Lx, Ly, theta=None)

Calculate tau from displacements, Lx, Ly, and theta (if it is known). For an array of displacements, for a set of scalar ellipse parameters, Lx, Ly, and theta.

Parameters

- delta_x (numpy.ndarray) displacement to remote point as in: (delta_x) i + (delta_y) j
 in old school vector notation
- **delta_y** (*numpy.ndarray*) displacement to remote point as in: (delta_x) i + (delta_y) j in old school vector notation
- Lx (float) Lx, Ly scale (km or degrees)
- Ly (float) Lx, Ly scale (km or degrees)
- theta (float | None) rotation angle in radians

Returns

tau - Mahalanobis distance

Return type

float

 ${\tt glomar_gridding.distances.radial_dist}({\it lat1}, {\it lon1}, {\it lat2}, {\it lon2})$

Computes a distance matrix of the coordinates using a spherical metric.

Parameters

- lat1 (float) latitude of point A
- lon1 (float) longitude of point A
- lat2 (float) latitude of point B

• lon2 (float) – longitude of point B

Return type

Radial distance between point A and point B

glomar_gridding.distances.rot_mat(angle)

Compute a 2d rotation matrix from an angle.

The input angle must be in radians

Return type

ndarray

glomar_gridding.distances.sigma_rot_func(Lx, Ly, theta)

Equation 15 in Karspeck et al 2011 and Equation 6 in Paciorek and Schervish 2006, assuming Sigma(Lx, Ly, theta) locally/moving-window invariant or we have already taken the mean (Sigma overbar, PP06 3.1.1)

Lx, Ly - anistropic variogram length scales theta - angle relative to lines of constant latitude theta should be radians, and the fitting code outputs radians by default

Returns

 $sigma - 2 \times 2 \text{ matrix}$

Return type

np.ndarray

glomar_gridding.distances.tau_dist(dE, dN, sigma)

Eq.15 in Karspeck paper but it is standard formulation to the Mahalanobis distance https://en.wikipedia.org/wiki/Mahalanobis_distance 10.1002/qj.900

Return type

ndarray

glomar_gridding.distances.tau_dist_from_frame(df)

Compute the tau/Mahalanobis matrix for all records within a gridbox

Can be used as an input function for observations.dist_weight.

Eq.15 in Karspeck paper but it is standard formulation to the Mahalanobis distance https://en.wikipedia.org/wiki/Mahalanobis_distance 10.1002/qj.900

By Steven Chan - @stchan

Parameters

df (*polars.DataFrame*) – The observational DataFrame, containing positional information for each observation ("lat", "lon"), gridbox specific positional information ("grid_lat", "grid_lon"), and ellipse length-scale parameters used for computation of *sigma* ("grid_lx", "grid_ly", "grid_theta").

Returns

 \mathbf{tau} – A matrix of dimension n x n where n is the number of rows in df and is the tau/Mahalanobis distance.

Return type

numpy.matrix

8.4 Covariance Tools and Eigenvalue Clipping

When estimating covariance matrices, using ellipse-based methods for example, the results may not be positive-definite. This can be problematic, for instance the Kriging equations may not be solvable as the inverse matrix cannot be computed, or simulated states cannot be constructed using <code>glomar_gridding.stochastic</code>.

scipy_mv_normal_draw(). To account for this, glomar_gridding includes a few tools for fixing these covariance matrices. In general, these methods attempt to coerce the input matrix to be positive-definite by updating the eigenvalues and re-computing the matrix from these updated eigenvalues and the original eigenvectors. The indicators of an invalid covariance matrix include

- 1. Un-invertible covariance matrices with 0 eigenvalues
- 2. Covariance matrices with eigenvalues less than zero

This can typically be a consequence of

- 1. Multicollinearity: but nearly all very large cov matrices will have rounding errors to have this occur
- 2. Number of spatial points >> length of time series (for ESA monthly pentads: this ratio is about 150)
- 3. Covariance is estimated using partial data

In most cases, the most likely causes are 2 and 3.

There are a number of methods included in this module. In general, the approach is to adjust the eigenvalues to ensure small or negative eigenvalues are increased to some minimum threshold. The covariance matrix is then re-calculated using these modified eigenvalues and the original eigenvectors.

In general, the recommended approach is Original Clipping, see *glomar_gridding.covariance_tools.eigenvalue_clip()*.

Fixes:

1. Simple clipping - glomar_gridding.covariance_tools.simple_clipping():

Cut off the negative, zero, and small positive eigenvalues; this is method used in statsmodels.stats.correlation_tools but the version here has better thresholds based on the accuracy of the eigenvalues, plus a iterative version which is slower but more stable with big matrices. The iterative version is recommended for SST/MAT covariances.

This is used for SST covariance matrices which have less dominant modes than MAT; it also preserves more noise.

Trace (aka total variance) of the covariance matrix is not conserved, but it is less disruptive than EOF chop off (method 3).

It is more difficult to use for covariance matrices with one large dominant mode because that raises the bar of accuracy of the eigenvalues, which requires clipping off a lot more eigenvectors.

Note, this will adjust all negative eigenvalues to be positive.

2. Original clipping - glomar_gridding.covariance_tools.eigenvalue_clip():

Determine a noise eigenvalue threshold and replace all eigenvalues below using the average of them, preserving the original trace (aka total variance) of the covariance matrix, but this will require a full computation of all eigenvectors, which may be slow and cause memory problems

Note, this will adjust all negative eigenvalues to be positive.

3. EOF chop-off - glomar_gridding.covariance_tools.eof_chop():

Set a target explained variance (say 95%) for the empirical orthogonal functions, compute the eigenvalues and eigenvectors up to that explained variance. Reconstruct the covariance keeping only EOFs up to the target. This is very close to 2, but it reduces the total variance of the covariance matrix. The original method requires solving for ALL eigenvectors which may not be possible for massive matrices (40000x40000 square matrices). This is currently done for the MAT covariance matrices which have very large dominant modes.

Note, this may not adjust negative eigenvalues to be positive.

- 4. Other methods not implemented here
 - a. shrinkage methods

https://scikit-learn.org/stable/modules/covariance.html

b. reprojection (aka Higham's method) [Higham]

https://github.com/mikecroucher/nearest_correlation

https://nhigham.com/2013/02/13/the-nearest-correlation-matrix/

Author S Chan.

Modified by J. Siddons.

glomar_gridding.covariance_tools.check_symmetric(a, rtol=1e-05, atol=1e-08)

Helper function for perturb_sym_matrix_2_positive_definite

Return type

bool

glomar_gridding.covariance_tools.clean_small(matrix, atol=1e-05)

Set small values (abs(x) < atol) in an matrix to 0

Return type

ndarray

glomar_gridding.covariance_tools.csum_up_to_val(vals, target, reverse=True, niter=0, csum=0.0)

Find csum and sample index that target is surpassed. Displays a warning if the target is not exceeded or the input *vals* is empty.

Can provide an initial *niter* and/or *csum* value(s), if working with multiple arrays in an iterative process.

If *reverse* is set, the returned index will be negative and will correspond to the index required for the non-reversed array. Reverse is the default.

Parameters

- vals (numpy.ndarray) Vector of values to sum cumulatively.
- target (float) Value for which the cumulative sum must exceed.
- **reverse** (*bool*) Reverse the array. The index will be negative.
- **niter** (*int*) Initial number of iterations.
- csum (float) Initial cumulative sum value.

Return type

tuple[float, int]

Returns

- csum (float) The cumulative sum at the index when the target has been exceeded.
- **niter** (*int*) The index of the value that results in the cumulative sum exceeding the target.



It is actually faster to compute a full cumulative sum with *np.cumsum* and then look for the value that exceeds the target. This is not performed in this function.

Examples

```
>>> vals = np.random.rand(1000)
>>> target = 301.1
>>> csum_up_to_val(vals, target)
```

Denoise symmetric damaged covariance/correlation matrix cov by clipping eigenvalues

Explained variance or aspect ratio based threshold Aspect ratios is based on dimensionless parameters (number of independent variable and observation size)

```
q = N/T = (numofindependent variable)/(numofobservation perindependent variable)
```

Does not give the same results as in eig clip

explained_variance here does not have the same meaning. The trace of a correlation, by definition, equals the number of diagonal elements, which isn't intituatively linked to actual explained variance in climate science sense

This is done by KEEPING the largest explained variance in which (number of basis vectors to be kept) >> (number of rows) In ESA data, keeping 95% variance means keeping top ~15% of the eigenvalues

Parameters

- cov (numpy.ndarray) Input covariance matrix to be adjusted to positive definite.
- **method** ("explained_variance" | "Laloux_2000") Method used to identify the index of the eigenvalues to clip. If set to "explained_variance" then the sorted eigenvalues below the target variance are *clipped*. If "Laloux_2000" is set, then the method of [Laloux] is used.

Returns

cov_adj – Adjusted covariance matrix.

Return type

numpy.ndarray

```
glomar_gridding.covariance_tools.eof_chop(cov, target_explained_variance=0.95)
```

Re-compute the covariance using only eigenvectors associated with the largest eigenvalues such that the explained variance achieves a target value.

This method is similar to a standard eigenvalue clipping method, however only the eigenvectors associated with the largest eigenvalues are computed, saving on memory and improves time execution. This method is best suited to larger covariance matrices, for example those for a 1-degree resolution grid (approx 40_000 x 40_000). This is also appropriate for covariance matrices with very large dominant modes.

This method does not preserve the total variance, i.e. the trace of the output covariance matrix may not match the input.

Parameters

- **cov** (*numpy.ndarray*) Input covariance matrix to be adjusted to positive definite.
- target_explained_variance (float) Select only the largest eigenvalues such that the explained variance of these eigenvalues is <= this value. The eigenvalues are first sorted in descending order, then cumulatively summed. Eigenvalues that correspond to values in the cumulative sum above this explained variance are dropped.

Return type

tuple[ndarray, dict[str, Any]]

Returns

- cov adj (numpy.ndarray) Adjusted covariance matrix
- **summary_dict** (*dict[str*, *Any]*) A dictionary containing a summary of the input and results with the following keys:
 - "target_explained_variance%"
 - "num of retained eofs"
 - "threshold"
 - "smallest_eigv"
 - "largest_eigv"
 - "determinant"
 - "total_variance"

glomar_gridding.covariance_tools.perturb_cov_to_positive_definite(cov, threshold=le-15)

Force an estimated covariance matrix to be positive definite using the eigenvalue clipping with statsmodels.stats.correlation_tools.cov_nearest function.

Deprecated in favour of glomar_gridding.covariance_tools.simple_clipping().

Parameters

- **cov** (*numpy.ndarray*) The estimated covariance matrix that is not positive definite.
- **threshold** (*float | 'auto'*) Eigenvalues below this value are set to 0. If the input is 'auto' then the value is determined using the floating-point precision and magnitude of the largest eigenvalues.

Returns

cov_adj - Adjusted covariance matrix

Return type

numpy.ndarray



Use

Notes

Other methods:

https://nhigham.com/2021/02/16/diagonally-perturbing-a-symmetric-matrix-to-make-it-positive-definite/https://nhigham.com/2013/02/13/the-nearest-correlation-matrix/https://academic.oup.com/imajna/article/22/3/329/708688

glomar_gridding.covariance_tools.simple_clipping(cov, threshold='auto', method='iterative')

A modified version of: https://www.statsmodels.org/dev/generated/statsmodels.stats.correlation_tools.corr_nearest.html

Force an estimated covariance matrix to be positive definite using the eigenvalue clipping with statsmodels.stats.correlation_tools.cov_nearest function.

This is appropriate for covariance matrices which have less dominant modes; it also preserves more noise.

Trace (aka total variance) of the covariance matrix is not conserved, but it is less disruptive than EOF chop off.

Parameters

- **cov** (*numpy.ndarray*) The estimated covariance matrix that is not positive definite.
- **threshold** (*float | 'auto'*) Eigenvalues below this value are set to 0. If the input is 'auto' then the value is determined using the floating-point precision and magnitude of the largest eigenvalues.

Return type

```
tuple[ndarray, dict[str, Any]]
```

Returns

- **cov_adj** (*numpy.ndarray*) Adjusted covariance matrix
- **summary_dict** (*dict[str*, *Any]*) A dictionary containing a summary of the input and results with the following keys:
 - "threshold"
 - "smallest_eigv"
 - "determinant"
 - "total variance"



statsmodels.stats.correlation_tools.cov_nearest

Notes

Other methods:

- https://nhigham.com/2021/02/16/diagonally-perturbing-a-symmetric-matrix-to-make-it-positive-definite/
- https://nhigham.com/2013/02/13/the-nearest-correlation-matrix/
- https://academic.oup.com/imajna/article/22/3/329/708688

8.5 IO

glomar_gridding includes functionality for loading datasets or arrays from netCDF files using python format strings. This can be useful for loading pre-computed inputs for the Kriging process, for example covariance matrices or observations. The allowance for passing a string containing format components (e.g. python t-string) allows for dynamic configuration if processing a series of monthly inputs for example.

Also included is a function for recursively getting sub-keys from a python *dict* style object. This can be useful for working with *yaml* formatting configuration files for instance.

```
glomar_gridding.io.get_recurse(config, *keys, default=None)
```

Recursively get sub keys from a python dict object.

If a dictionary object contains keys whose values are themselves dictionaries, get a value from a sub dictionary by specifying the key-path to get to the desired value.

Equivalent to:

```
> config[keys[0]][keys[1]]...[keys[n]]
```

Or:

> config.get(keys[0]).get(keys[1])...get(keys[n])

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Parameters

- **config** (*dict*) The layered dictionary containing sub dictionaries.
- *keys The sequence of keys to recurse through to get the final value. If any key in the sequence is not found, or is not a dictionary (and is not the final key), then the default value is returned.
- **default** (*Any*) The default value, returned if the sequence of keys cannot be completed or the final key is not present.

Return type

Any

Returns

- The value associated with the final key, or the default value if the final
- key cannot be reached.

glomar_gridding.io.load_array(path, var='covariance', **kwargs)

Load an xarray.DataArray from a netCDF file. Can input a filename or a string to format with keyword arguments.

Parameters

• **path** (*str*) – Full filename (including path), or filename with replacements using str.format with named replacements. For example:

/path/to/global_covariance_{month:02d}.nc

- **var** (*str*) Name of the variable to select from the input file
- **kwargs Keywords arguments matching the replacements in the input path.

Returns

arr – An array containing the values of the variable specified by var

Return type

xarray.DataArray

glomar_gridding.io.load_dataset(path, **kwargs)

Load an xarray.Dataset from a netCDF file. Can input a filename or a string to format with keyword arguments.

Parameters

• **path** (*str*) – Full filename (including path), or filename with replacements using str.format with named replacements. For example:

```
/path/to/global_covariance_{month:02d}.nc
```

• **kwargs – Keywords arguments matching the replacements in the input path.

Returns

arr - The netcdf dataset as an xarray.Dataset.

Return type

xarray.Dataset

8.6 Utilities

Utility functions for glomar gridding

exception glomar_gridding.utils.ColumnNotFoundError

Error class for Column Not Being Found

class glomar_gridding.utils.ConfigParserMultiValues

Internal Helper Class

class glomar_gridding.utils.MonthName(value)

Name of month from int

glomar_gridding.utils.add_empty_layers(nc_variables, timestamps, shape)

Add empty layers to a netcdf file. This adds a layer of zeros to the netCDF file.

Parameters

- nc_variables (Iterable[nc.Variable] | nc.Variable) Name(s) of the variables to add empty layers to
- timestamps (Iterable[int] / int) Indices to add empty layers
- **shape** (tuple[int, int]) Shape of the layer to add

Return type

None

glomar_gridding.utils.adjust_small_negative(mat)

Adjusts small negative values (with absolute value < 1e-8) in matrix to 0 in-place.

Raises a warning if any small negative values are detected.

Parameters

mat (np.ndarray[float]) - Squared uncertainty associated with chosen kriging method Derived from the diagonal of the matrix

Return type

ndarray

glomar_gridding.utils.batched(iterable, n, * (Keyword-only parameters separator ($PEP\ 3102$)), strict=False)
Implementation of itertools.batched for use if python version is < 3.12.

Examples

```
>>> list(batched("ABCDEFG", 3))
[("A", "B", "C"), ("D", "E", "F"), ("G", )]
```

glomar_gridding.utils.check_cols(df, cols)

Check that all columns in a list of columns are in a DataFrame

Return type

None

glomar_gridding.utils.cor_2_cov(cor, variances, rounding=None)

Compute covariance matrix from correlation matrix and variances

Parameters

- **cor** (*numpy.ndarray*) Correlation Matrix
- variances (numpy.ndarray) Variances to scale the correlation matrix.
- rounding (int) round the values of the output

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Return type

ndarray

```
glomar_gridding.utils.cov_2_cor(cov, rounding=None)
```

Normalises the covariance matrices within the class instance and return correlation matrices https://gist.github.com/wiso/ce2a9919ded228838703c1c7c7dad13b

Parameters

- **cov** (*numpy.ndarray*) Covariance matrix
- **rounding** (*int*) round the values of the output

Return type

ndarray

```
glomar_gridding.utils.days_since_by_month(year, day)
```

Get the number of days since *year-01-day* for each month. This is used to set the time values in a netCDF file where temporal resolution is monthly and the units are days since some date.

Return type

ndarray

```
glomar_gridding.utils.deg_to_km(deg)
```

deg: float (degrees) Convert degree latitude change to km

Return type

float

glomar_gridding.utils.deg_to_nm(deg)

deg: float (degrees) Convert degree latitude change to nautical miles

Return type

float

glomar_gridding.utils.filter_bounds(df, bounds, bound_cols, closed='left')

Filter a polars DataFrame based on a set of lower and upper bounds.

Parameters

- **df** (polars.DataFrame) The data to be filtered by the bounds
- bounds (list[tuple[float, float]]) A list of tuples containing lower and upper bounds for a column
- **bound_cols** (*list[str]*) A list of column names to be filtered by the bounds, the length of the bounds list must equal the length of the bound_cols list.
- **closed** (str | list[str]) One of "both", "left", "right", "none" indicating the closedness of the bounds. If the input is a single instance then all bounds will have that closedness. If it is a list of closed values then its length must match the length of the bounds list.

Return type

DataFrame

glomar_gridding.utils.find_nearest(array, values)

Get the indices and values from an array that are closest to the input values.

A single index, value pair is returned for each look-up value in the values list.

Parameters

• array (Iterable) – The array to search for nearest values.

• **values** (*Iterable*) – The values to look-up in the array.

Return type

tuple[list[int], ndarray]

Returns

- idx_list (list[int]) The indices of nearest values
- array_values_list (*list*) The list of values in array that are closest to the input values.

```
glomar_gridding.utils.get_date_index(year, month, start_year)
```

Get the index of a given year-month in a monthly sequence of dates starting from month 1 in a specific start year

Parameters

- **year** (*int*) The year for the date to find the index of.
- **month** (*int*) The month for the date to find the index of.
- **start_year** (*int*) The start year of the date series, the result assumes that the date time series starts in the first month of this year.

Returns

index – The index of the input date in the monthly datetime series starting from the first month of year *start_year*.

Return type

int

glomar_gridding.utils.get_month_midpoint(dates)

Get the month midpoint for a series of datetimes.

The midpoint of a month is the exact half-way point between the start and end of the month.

For example, the midpoint of January 1990 is 1990-01-16 12:00.

Return type

Series

glomar_gridding.utils.get_pentad_range(centre_date)

Get the start and date of a pentad centred at a centre date. If the pentad includes the leap date of 29th Feb then the pentad will include 6 days. This follows the * pentad convention.

The start and end date are first calculated from a non-leap year.

If the centre date value is 29th Feb then the pentad will be a pentad starting on 27th Feb and ending on 2nd March.

Parameters

centre_date (*datetime.date*) – The centre date of the pentad. The start date will be 2 days before this date, and the end date will be 2 days after.

Return type

tuple[date, date]

Returns

- start_date (datetime.date) Two days before centre_date
- end_date (datetime.date) Two days after centre_date

glomar_gridding.utils.get_spatial_mean(grid_obs, covx)

Compute the spatial mean accounting for auto-correlation. See [Cornell]

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Parameters

- **grid_obs** (*np.ndarray*) Vector containing observations
- covx (np.ndarray) Observation covariance matrix

Returns

```
spatial_mean – The spatial mean defined as (1^T \times C^{-1} \times 1)^{-1} \times (1^T \times C^{-1} \times z)
```

Return type

float

References

[Cornell] https://www.css.cornell.edu/faculty/dgr2/_static/files/distance_ed_geostats/ov5.pdf

```
glomar_gridding.utils.init_logging(file=None, level='DEBUG')
```

Initialise the logger

Parameters

- file (str) File to send log messages to. If set to None (default) then print log messages to STDout
- level (str) Level of logging, one of: "debug", "info", "warn", "error", "critical".

Return type

None

```
glomar_gridding.utils.intersect_mtlb(a, b)
```

Returns data common between two arrays, a and b, in a sorted order and index vectors for a and b arrays Reproduces behaviour of Matlab's intersect function.

Parameters

- array (b (array) 1-D)
- array

Returns

- 1-D array, c, of common values found in two arrays, a and b, sorted in order
- List of indices, where the common values are located, for array a
- List of indices, where the common values are located, for array b

```
glomar_gridding.utils.is_iter(val)
```

Determine if a value is an iterable

Return type

bool

```
glomar_gridding.utils.km_to_deg(km)
```

km: float (km) Convert meridonal km change to degree latitude

Return type

float

```
glomar_gridding.utils.mask_array(arr)
```

Forces numpy array to be an instance of np.ma.MaskedArray

Parameters

arr (np.ndarray) - Can be masked or not masked

Returns

arr – array is now an instance of np.ma.MaskedArray

Return type

np.ndarray

glomar_gridding.utils.select_bounds(x, bounds=[(-90, 90), (-180, 180)], variables=['lat', 'lon']) Filter an xarray.DataArray or xarray.Dataset by a set of bounds.

Parameters

- **x** (xarray.DataArray | xarray.Dataset) The data to filter
- **bounds** (list[tuple[float, float]]) A list of tuples containing the lower and upper bounds for each dimension.
- variables (list[str]) Names of the dimensions (the order must match the bounds).

Returns

x – The input data filtered by the bounds.

Return type

xarray.DataArray | xarray.Dataset

glomar_gridding.utils.sizeof_fmt(num, suffix='B')

Convert numbers to kilo/mega... bytes, for interactive printing of code progress.

Return type

str

Un-compress a compressed array using a mask.

Parameters

- **compressed_array** (*numpy.ndarray*) The compressed array, originally compressed by the mask
- mask (numpy.ndarray) The mask a boolean numpy array
- **fill_value** (*Any*) The value to fill masked points. If *apply_mask* is set, then this will be removed in the output.
- apply_mask (bool) Apply the mask to the result, returning a MaskedArray rather than a ndarray.
- **dtype** (*type | None*) Optionally set a dtype for the returned array, if not set then the dtype of the compressed_array is used.

Returns

uncompressed - The uncompressed array, masked points are filled with the fill_value
if apply_mask is False. If apply_mask is True, then the result is an instance of
numpy.ma.MaskedArray with the mask applied to the uncompressed result.

Return type

numpy.ndarray | numpy.ma.MaskedArray

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