# geometric-smote: A package for flexible and efficient over-sampling

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#### Abstract

Learning from class-imbalanced data continues to be a frequent and challenging problem in machine learning. Standard classification algorithms are designed under the assumption that the distribution of classes is balanced. To mitigate this problem several approaches have been proposed. The most general and popular approach is the generation of artificial data for the minority classes, known as oversampling. Geometric SMOTE is a state-of-the-art oversampling algorithm that has been shown to outperform other standard oversamplers in a large number of datasets. In order to make available Geometric SMOTE to the machine learning community, in this paper we provide a Python implementation. It is important to note that this implementation integrates seamlessly with the Scikit-Learn ecosystem. Therefore, machine learning researchers and practitioners can benefit from its use in a straightforward manner.

Keywords: Machine learning, Classification, Imbalanced learning, Oversampling

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Code metadata	
Current code version	v0.1.2
Permanent link to code/repository	https://github.com/
used for this code version	georgedouzas/geometric-smote
Legal Code License	MIT
Code versioning system used	git
Software code languages, tools, and	Python, Travis CI, AppVeyor, Read
services used	the Docs, Codecov, CircleCI, zen-
	odo, Anaconda Cloud
Compilation requirements, operat-	Linux, Mac OS, Windows
ing environments & dependencies	
If available Link to developer docu-	https://geometric-smote.
mentation/manual	readthedocs.io/
Support email for questions	georgios.douzas@gmail.com

Table 1: Code metadata

#### 1. Motivation and significance

### 2 1.1. Introduction

The imbalanced learning problem is defined as a machine learning classification task using datasets with binary or multi-class targets where one of the classes, called the majority class, outnumbers significantly the remaining classes, called the minority class(es) [1]. Learning from imbalanced data is a frequent and non-trivial problem for academic researchers and industry practitioners alike. The imbalance learning problem can be found in multiple domains such as chemical and biochemical engineering, financial management, information technology, security, business, agriculture or emergency management [2].

Standard machine learning classification algorithms induce a bias towards the majority class during training. This results in low performance when metrics suitable for imbalanced data are used for the classifier's evaluation. An important characteristic of imbalanced data is the Imbalance Ratio (IR) which is defined as the ratio between the number of samples of the majority class and each of the minority classes. For example, in a fraud detection task with 1% of fraudulent transactions, corresponding to an  $IR = \frac{0.99}{0.01} = 99$ , a trivial classifier that always labels a transaction as legit will score a classification accuracy of 99%. However in this case, all fraud cases remain undetected. IR values between 100 and 100.000 have been observed [3], [4]. Figure 1 shows an example of imbalanced data in two dimensions and the

resulting decision boundary of a typical classifier when they are used as a training set.

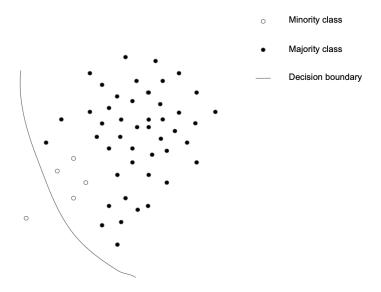


Figure 1: Imbalanced data in two dimensions. The decision boundary of a classifier shows a bias towards the majority class.

#### 1.2. Oversampling algorithms

Various approaches have been proposed to deal with the imbalanced learning problem. The most general approach is the modification at the data level by oversampling the minority class(es) [5]. Synthetic Minority Oversampling Technique (SMOTE) was the first informed oversampling algorithm proposed and continuous to be extensively used [3]. It generates synthetic instances along a line segment that joins minority class samples. Although SMOTE has been shown to be effective for generating artificial data, it also has some weaknesses [6]. In order to improve the quality of the generated data, many variants of SMOTE have been proposed. Nevertheless, all of these variations use the same data generation mechanism, i.e. linear interpolation between minority class samples as shown in figure 2.

A Python implementation of SMOTE and several of its variants is available in the Imbalanced-Learn [7] library, which is fully compatible with the popular machine learning toolbox Scikit-Learn [8].

### 1.3. Geometric SMOTE

Geometric SMOTE (G-SMOTE) [9] uses a different approach compared to existing SMOTE's variations. More specifically, G-SMOTE oversampling

algorithm substitutes the data generation mechanism of SMOTE by defining a flexible geometric region around each minority class instance and generating synthetic instances inside the boundaries of this region. The algorithm requires the selection of the hyperparameters truncation\_factor, deformation\_factor, selection\_strategy and k\_neighbors. The first three of them, called geometric hyperparameters, control the shape of the geometric region while the later adjusts its size. Figure 2 presents a visual comparison between the data generation mechanisms of SMOTE and G-SMOTE.

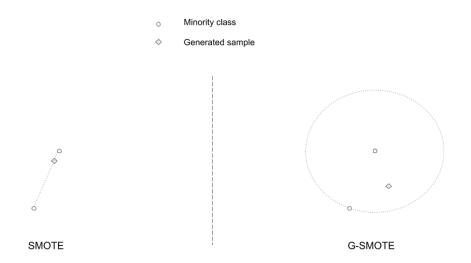


Figure 2: Comparison between the data generation mechanisms of SMOTE and G-SMOTE. SMOTE uses linear interpolation, while G-SMOTE defines a circle as the permissible data generation area.

G-SMOTE algorithm has been shown to outperform SMOTE and its variants across 69 imbalanced datasets for various classifiers and evaluation metrics [9]. In this paper, we present a Python implementation of G-SMOTE. In section 2, the software description is given while section 3 provides a demonstrative example of its functionalities.

## 56 2. Software description

The geometric-smote software project is written in Python 3.7. It contains an object-oriented implementation of the G-SMOTE algorithm as well as an extensive online documentation. The implementation provides an API

that is compatible with Imbalanced-Learn and Scikit-Learn libraries, therefore it makes full use of various features that support standard machine learning functionalities.

## 2.1. Software Architecture

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The geometric-smote project contains the Python package gsmote. The 64 main module of gsmote is called geometric-smote.py. It contains the class 65 GeometricSMOTE that implements the G-SMOTE algorithm. The initializa-66 tion of a GeometricSMOTE instance includes G-SMOTE's hyperparameters 67 that control the generation of synthetic data. Additionally, GeometricSMOTE inherits from the BaseOverSampler class of Imbalanced-Learn library. Therefore, an instance of GeometricSMOTE class provides the fit and fit\_resample 70 methods, the two main methods for resampling as explained in subsection 2.2. 71 This is achieved by implementing the \_fit\_resample abstract method of the 72 parent class BaseOverSampler. More specifically, the function \_make\_geometric\_sample 73 implements the data generation mechanism of G-SMOTE as shortly de-74 scribed in section 1.3. This function is called in the \_make\_geometric\_samples 75 method of the GeometricSMOTE class in order to generate the appropriate number of synthetic data for a particular minority class. Finally, the method 77 \_make\_geometric\_samples is called in \_fit\_resample method to generate 78 synthetic data for all minority classes. Figure 3 provides a visual represen-79 tation of the above classes and functions hierarchy. 80

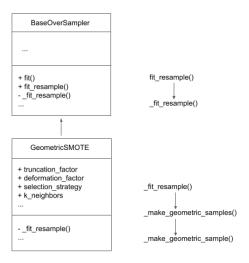


Figure 3: UML class diagrams and callgraphs of main classes and methods.

## 2.2. Software Functionalities

As it was mentioned in subsection 2.1, the class GeometricSMOTE repre-82 sents the G-SMOTE oversampler. The intializer of GeometricSMOTE includes 83 the following G-SMOTE's hyperparameters: truncation\_factor, deformation\_factor, 84 selection\_strategy and k\_neighbors as explained in subsection 1.3. Once 85 the GeometricSMOTE object is initialized with a specific parametrization, it 86 can be used to resample the imbalanced data represented by the input ma-87 trix X and the target labels y. Following the Scikit-Learn API, both X, y are 88 array-like objects of appropriate shape. 89

Resampling is achieved by using the two main methods of fit and fit\_resample of the GeometricSMOTE object. More specifically, both of them take as input parameters the X and y. The first method computes various statistics which are used to resample X while the second method does the same but additionally returns a resampled version of X and y.

The geometric-smote project has been designed to integrate with the
Imbalanced-Learn toolbox and Scikit-Learn ecosystem. Therefore the GeometricSMOTE
object can be used in a machine learning pipeline, through ImbalancedLearn's class Pipeline, that automatically combines samplers, transformers
and estimators. The next section provides examples of the above functionalities.

## 3. Illustrative Examples

#### 3.1. Basic example

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An example of resampling multi-class imbalanced data using the fit\_resample 103 method is presented in Listing 1. Initially, a 3-class imbalanced dataset is 104 generated. Next, GeometricSMOTE object is initialized with default values for 105 the hyperparameters, i.e. truncation\_factor = 1.0, deformation\_factor = 106 0.0, selection\_strategy = combined. Finally, the object's fit\_resample method is used to resample the data. Printing the class distribution before 108 and after resampling confirms that the resampled data X\_res, y\_res are per-109 fectly balanced. X\_res, y\_res can be used as training data for any classifier 110 in the place of X, y. 111

Listing 1: Resampling of imbalanced data using the fit\_resample method.

```
# Import classes and functions.

from collections import Counter
from gsmote import GeometricSMOTE
from sklearn.datasets import make_classification

# Generate an imbalanced 3-class dataset.
```

```
X, y = make\_classification
        random_state=23,
119
        n_{c} classes = 3,
120
        n_{informative} = 5,
121
        n_{samples} = 500,
        weights = [0.8, 0.15, 0.05]
123
124
125
   \# Create a Geometric SMOTE object with default hyperparameters.
126
   gsmote = GeometricSMOTE(random_state=10)
127
128
   # Resample the imbalanced dataset.
129
   X_{res}, y_{res} = gsmote.fit_{resample}(X, y)
130
131
   # Print number of samples per class for initial and resampled data.
132
   init_count = list(Counter(y).values())
133
   resampled_count = list(Counter(y_res).values())
134
135
   print(f'Initial_class_distribution:_{init_count}.')
136
   \# Initial class distribution: [400, 75, 25].
137
138
   print(f'Resampled_class_distribution:_{resampled_count}.')
139
   \# Resampled class distribution: [400, 400, 400].
140
   3.2. Machine learning pipeline
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      As mentioned before, the GeometricSMOTE object can be used as a part
142
   of a machine learning pipeline. Listing 2 presents a pipeline composed by a
143
   G-SMOTE oversampler, a PCA tranformation and a decision tree classifier.
144
   The pipeline is trained on imbalanced binary-class data and evaluated on a
   hold-out set. The user applies the process in a simple way while the internal
   details of the calculations are hidden.
   Listing 2: Training and evaluation of a machine learning pipeline that contains the
   GeometricSMOTE object.
   # Import classes and functions.
   from gsmote import GeometricSMOTE
149
   from sklearn.datasets import make_classification
   from sklearn.decomposition import PCA
151
```

from sklearn.tree import DecisionTreeClassifier

from sklearn.metrics import fl\_score

153

from sklearn.model\_selection import train\_test\_split

```
from imblearn.pipeline import make_pipeline
155
156
   \# Generate an imbalanced binary-class dataset.
157
   X, y = make\_classification
158
            random_state=23,
159
            n_c c l a s s e s = 2,
160
            n_samples=500,
161
            weights = [0.8, 0.2]
162
163
164
   # Split the data to training and hold-out sets.
165
   X_train, X_test, y_train, y_test = train_test_split(X, y, random_state
166
167
   # Create the pipeline's objects with default hyperparameters.
168
   gsmote = GeometricSMOTE(random_state=11)
169
   pca = PCA()
170
   clf = DecisionTreeClassifier(random_state=3)
171
172
   # Create the pipeline.
173
   pip = make_pipeline(gsmote, pca, clf)
174
175
   # Fit the pipeline to the training set.
176
   pip.fit (X_train, y_train)
177
178
   \# Evaluate the pipeline on the hold-out set using the F-score.
179
   test_score = f1_score(y_test, pip.predict(X_test))
180
181
   print(f'F-score_on_hold-out_set:_{test_score}.')
182
   \# F-score on hold-out set: 0.7.
183
```

## 4. Impact and conclusions

Classification of imbalanced datasets is a challenging task for standard machine learning algorithms. G-SMOTE, as a enhancement of the SMOTE data generation mechanism, provides a flexible and effective way for resampling the imbalanced data. G-SMOTE's emprical results prove that it outperforms SMOTE and its variants. Machine learning researchers and industry practitioners can benefit from using G-SMOTE in their work since the imbalanced learning problem is a common characteristic of many real-world applications.

The geometric-smote project provides the only Python implementation, 193 to the best of our knowledge, of the state-of-the-art oversampling algorithm 194 G-SMOTE. A significant advantage of this implementation is that it is built 195 on top of the Scikit-Learn's ecosystem. Therefore, using the G-SMOTE 196 oversampler in typical machine learning workflows is an effortless task for the 197 user. Also, the public API of the main class GeometricSMOTE is identical to 198 the one implemented in Imbalanced-Learn for all oversamplers. This means 199 that users of Imbalanced-Learn and Scikit-Learn, that apply oversampling 200 on imbalanced data, can integrate the gsmote package in their existing work 201 in a straightforward manner or even replace directly any Imbalanced-Learn's 202 oversampler with GeometricSMOTE.

#### 5. Conflict of Interest

We wish to confirm that there are no known conflicts of interest associated with this publication and there has been no significant financial support for this work that could have influenced its outcome.

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