Assignment 3

WOKWI PROGRAM

Assignment Date	MAY 8 2023
Student Name	N.PURUSHOTHAMAN
Student Roll Number	310520104088
Maximum Marks	2 MARKS

Team ID : NM2023TMID08027

PROGRAM

IOT BASED WEATHER ADAPTIVE STREET LIGHTING SYSTEM

ASSIGNMENT 03:
Write code and connections in wokwi for ultrasonic sensors.
Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.
Upload document with wokwi share link and images of ibm cloud

CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "4yi0vc"
#define DEVICE_TYPE "nodeMcu"
#define DEVICE_ID "Assignment4"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}
 void loop() {
  bool isNearby = dist < 100;
  digitalWrite(led, isNearby);

  publishData();
  delay(500);

  if (!client.loop()) {
   mqttConnect();
  }
}
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
   delay(500);
   Serial.print(".");
  }
```

```
  Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
  }
}

void initManagedDevice() {
  if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
void publishData()
{
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin,HIGH);
  dist=duration*speed/2;
  if(dist<100){
    String payload = "{\"Normal Distance\":";
    payload += dist;
    payload += "}";

    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
      Serial.println("Publish OK");
    }

  }
    if(dist>101 && dist<111){
    String payload = "{\"Alert distance\":";
    payload += dist;
    payload += "}";

    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
     if(client.publish(publishTopic, (char*) payload.c_str())) {
      Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
      digitalWrite(led,HIGH);
    }else {
      Serial.println("Publish FAILED");
    }

  }


  }
  void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
  Serial.print("callback invoked for topic:");
  Serial.println(subscribeTopic);
  for(int i=0; i<payloadLength; i++){
    dist += (char)payload[i];
  }
  Serial.println("data:"+ data3);
  if(data3=="lighton"){
    Serial.println(data3);
    digitalWrite(led,HIGH);
  }
  data3="";
}
```
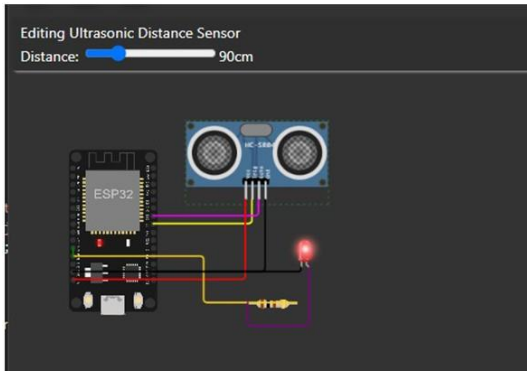
Output

Editing Ultrasonic Distance Sensor
Distance: ▬▬▬ 90cm


```
Sending payload: {"Normal Distance":89.95}
Publish OK

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Publish OK

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Publish OK

Sending payload: {"Normal Distance":89.98}
Publish OK

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Publish OK
```
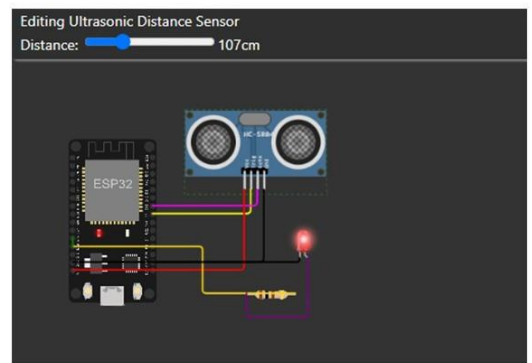
**1) when distance under 100 cm
it wil show normal distance**

Editing Ultrasonic Distance Sensor
Distance: ▬▬▬ 107cm


```
Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automaticaly of the loop

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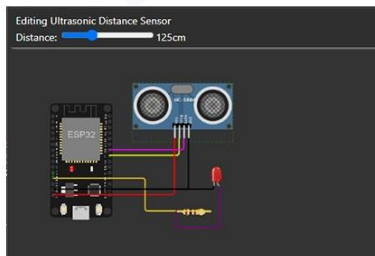
**2) when distance cross 100 cm
it wil show ALERT with warning message
distance**

Editing Ultrasonic Distance Sensor
Distance: ▬▬▬ 125cm


```
Sending payload: {"Alert distance":106.96}
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```

**when it cross above 110 cm it totaly
move to iff state once it reduce to 110 it on again**

IBM CLOUD OUPUT

Recent Events

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	{"Normal Distance":89.95}	json	a few seconds ago
Data	{"Normal Distance":89.95}	json	a few seconds ago
Data	{"Normal Distance":89.95}	json	a few seconds ago
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Data	{"Normal Distance":89.95}	json	a few seconds ago

Recent Events

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Event	Value	Format	Last Received
Data	{"Alert distance":106.98}	json	a few seconds ago
Data	{"Alert distance":107.03}	json	a few seconds ago
Data	{"Alert distance":106.98}	json	a few seconds ago
Data	{"Alert distance":106.98}	json	a few seconds ago
Data	{"Alert distance":106.98}	json	a few seconds ago
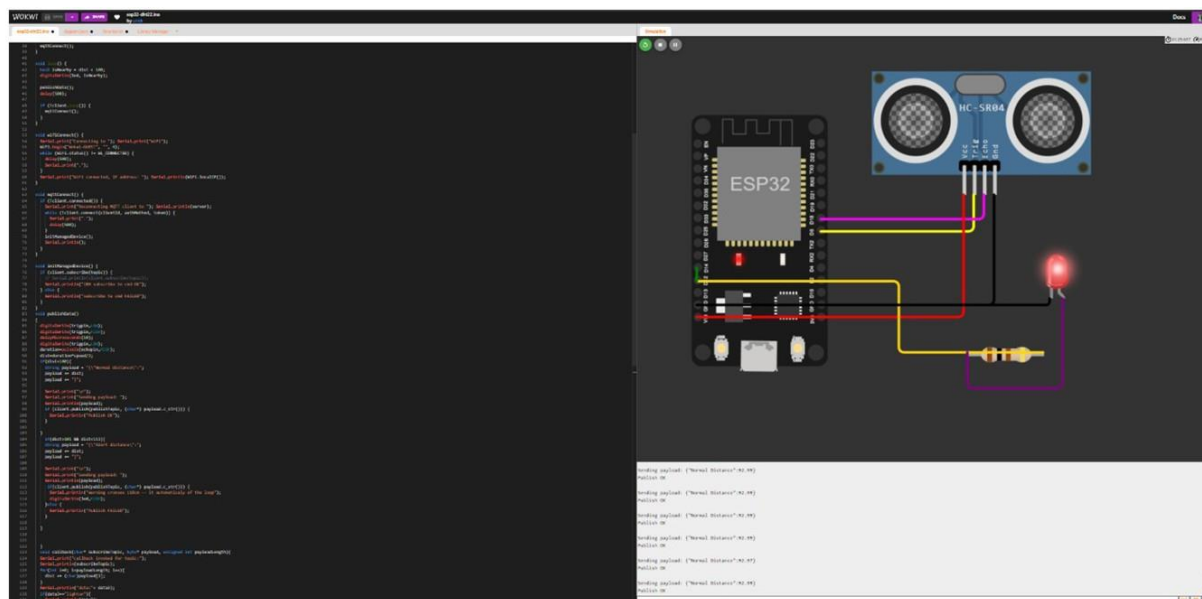
Connection Information

Basic connection information about this device.

Device ID	Assignment 03
Device Type	nodeMcu
Date Added	may 8 2023
Added By	N.Purushothaman
Connection Status	**Disconnected**

Last Connected: may 8 2023
Client Address: 145.40.94.93 Insecure
Duration: 3 minutes
Data Transferred: 14.4 KB

Recent Events

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago

WORK FLOW LIKE IN description