

A Survey on Navier–Stokes Equations

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Abstract

A personal survey on Navier–Stokes equations (NSEs), especially its regularity and turbulence models.

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Quick notes

1. The 4 formulations appearing in the *Clay Millennium Prize* formulation Fefferman, 2006 of NSEs.

1 Incompressible NSEs

1.1 Various concepts of solutions to NSEs

To describe various formulations for NSEs, we must first define properly the concept of a solution to NSEs, including, e.g., *periodic solutions*, *finite energy solutions*, H^1 *solutions*, and *smooth solutions*, etc.

1.1.1 Smooth solutions of NSEs

“Note that even within the category of smooth solutions, there is some choice in what decay hypotheses to place on the initial data and solution; for instance, one can require that the initial velocity \mathbf{u}_0 be Schwartz class, or merely smooth with finite energy. Intermediate between these two will be data which is smooth and in H^1 .”
– Tao, 2013

Recall Tao, 2013, Def. 1.1:

Definition 1.1 (Smooth solutions to NSEs). *A smooth set of data for NSEs up to time T is a triplet $(\mathbf{u}_0, \mathbf{f}, T)$, where $0 < T < \infty$ is a time, the initial velocity vector field $\mathbf{u}_0 : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ and the forcing term $\mathbf{f} : [0, T] \times \mathbb{R}^3 \rightarrow \mathbb{R}^3$ are assumed to be smooth on \mathbb{R}^3 and $[0, T] \times \mathbb{R}^3$, respectively, (thus, \mathbf{u}_0 is infinitely differentiable in space, and \mathbf{f} is infinitely differentiable in spacetime), and \mathbf{u}_0 is furthermore required to be divergence-free:*

$$\nabla \cdot \mathbf{u}_0 = 0, \text{ in } \mathbb{R}^3. \quad (1.1)$$

If $\mathbf{f} = \mathbf{0}$, we say that the data is homogeneous.

The total energy $E(\mathbf{u}_0, \mathbf{f}, T)$ of a smooth set of data $(\mathbf{u}_0, \mathbf{f}, T)$ is defined by the quantity

$$E(\mathbf{u}_0, \mathbf{f}, T) := \frac{1}{2} \left(\|\mathbf{u}_0\|_{L^2_x(\mathbb{R}^3)} + \|\mathbf{f}\|_{L^1_t L^2_x([0, T] \times \mathbb{R}^3)} \right)^2, \quad (\text{iiNS}/E)$$

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and $(\mathbf{u}_0, \mathbf{f}, T)$ is said to have finite energy if $E(\mathbf{u}_0, \mathbf{f}, T) < \infty$. We define the H^1 norm $\mathcal{H}^1(\mathbf{u}_0, \mathbf{f}, T)$ of the data to be the quantity

$$\mathcal{H}^1(\mathbf{u}_0, \mathbf{f}, T) := \|\mathbf{u}_0\|_{H_x^1(\mathbb{R}^3)} + \|\mathbf{f}\|_{L_t^\infty H_x^1(\mathbb{R}^3)} < \infty, \quad (\text{iiNS}/\mathcal{H}^1)$$

and say that $(\mathbf{u}_0, \mathbf{f}, T)$ is H^1 if $\mathcal{H}^1(\mathbf{u}_0, \mathbf{f}, T) < \infty$; note that the H^1 regularity is essentially 1 derivative higher than the energy regularity, which is at the level of L^2 , and instead matches the regularity of the initial enstrophy $\frac{1}{2} \int_{\mathbb{R}^3} \|\boldsymbol{\omega}_0(t, \mathbf{x})\|^2 d\mathbf{x}$, where $\boldsymbol{\omega}_0 := \nabla \times \mathbf{u}_0$ is the initial vorticity. We say that a smooth set of data $(\mathbf{u}_0, \mathbf{f}, T)$ is Schwartz if, for all integers $\alpha, m, k \geq 0$, one has

$$\sup_{\mathbf{x} \in \mathbb{R}^3} (1 + \|\mathbf{x}\|)^k \|\nabla_{\mathbf{x}}^\alpha \mathbf{u}_0(\mathbf{x})\| < \infty \text{ and } \sup_{(t, \mathbf{x}) \in [0, T] \times \mathbb{R}^3} (1 + \|\mathbf{x}\|)^k \|\nabla_{\mathbf{x}}^\alpha \partial_t^m \mathbf{f}(\mathbf{x})\| < \infty. \quad (1.2)$$

Thus, e.g., the Schwartz property implies H^1 , which in turn implies finite energy. We also say that $(\mathbf{u}_0, \mathbf{f}, T)$ is periodic with some period $L > 0$ if one has $\mathbf{u}_0(\mathbf{x} + L\mathbf{k}) = \mathbf{u}_0(\mathbf{x})$ and $\mathbf{f}(t, \mathbf{x} + L\mathbf{k}) = \mathbf{f}(t, \mathbf{x})$ for all $t \in [0, T]$, $\mathbf{x} \in \mathbb{R}^3$, and $\mathbf{k} \in \mathbb{Z}^3$. Of course, periodicity is incompatible with the Schwartz, H^1 , or finite energy properties, unless the data is zero. To emphasize the periodicity, we will sometimes write a periodic set of data $(\mathbf{u}_0, \mathbf{f}, T)$ as $(\mathbf{u}_0, \mathbf{f}, T, L)$.

A smooth solution to the NSEs, or a smooth solution, is a quintuplet $(\mathbf{u}, p, \mathbf{u}_0, \mathbf{f}, T)$, where $(\mathbf{u}_0, \mathbf{f}, T)$ is a smooth set of data, and the velocity vector field $\mathbf{u} : [0, T] \times \mathbb{R}^3 \rightarrow \mathbb{R}^3$ and pressure field $p : [0, T] \times \mathbb{R}^3 \rightarrow \mathbb{R}$ are smooth functions on $[0, T] \times \mathbb{R}^3$ that obey the NSE:¹

$$\partial_t \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} = \Delta \mathbf{u} - \nabla p + \mathbf{f}, \quad (1.3)$$

and the incompressibility property

$$\nabla \cdot \mathbf{u} = 0, \quad (1.4)$$

on all of $[0, T] \times \mathbb{R}^{32}$, and also the initial condition

$$\mathbf{u}(0, \mathbf{x}) = \mathbf{u}_0(\mathbf{x}), \quad \forall \mathbf{x} \in \mathbb{R}^3. \quad (1.5)$$

We say that a smooth solution $(\mathbf{u}, p, \mathbf{u}_0, \mathbf{f}, T)$ has finite energy if the associated data $(\mathbf{u}_0, \mathbf{f}, t)$ has finite energy, and in addition one has

$$\|\mathbf{u}\|_{L_t^\infty L_x^2([0, T] \times \mathbb{R}^3)} < \infty. \quad (1.6)$$

2 Compressible NSEs

References

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¹NQBH: Why no viscosity ν ? Any major differences in their mathematical analysis, especially the case $\nu = \nu(t, \mathbf{x}, \mathbf{u}, p)$ in turbulence models?

²NQBH: NSEs on the whole domain, hence useless for shape and topology optimizations, but useful for applying harmonic and Fourier analysis.