

Homework 1

1. Consider the following four data points:

Class 1: $\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

Class 2: $\begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

- (a) Are they linearly separable?
- (b) Find the linear decision boundary by applying fixed-increment single-sample perception procedure with initial weight vector $\mathbf{0}$ and plot it in the feature space.
- (c) Repeat (b) by using MSE procedure.
- (d) Implement the Ho-Kashyap algorithm in MATLAB and repeat (b).
- (e) Repeat (a) through (d) with the following data points:
 Class 1: $\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix}$
 Class 2: $\begin{pmatrix} 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix}$
- (f) Comment on the three procedures used.

2. Suppose that the following are a set of points in two classes:

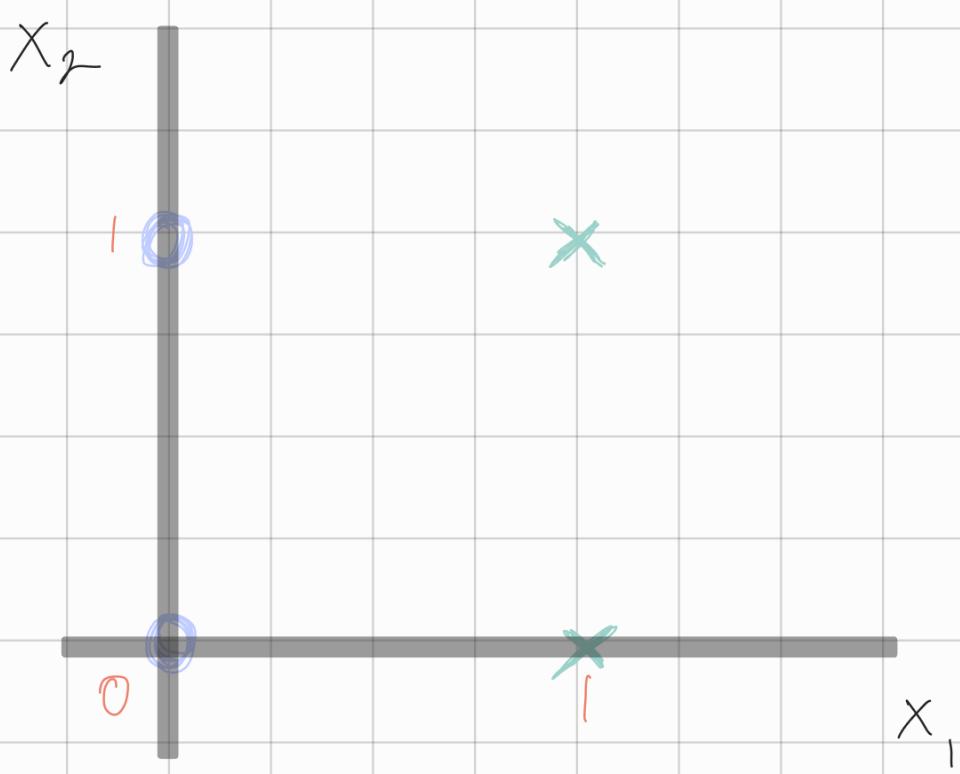
Class 1: $\begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \end{pmatrix}$

Class 2: $\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

Plot them and find the optimal separating line. What are the support vectors and what is the margin?

do c & f

1)



a) They are linearly separable

b)

$$Y = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ -1 & -1 & -1 \\ -1 & -1 & 0 \end{bmatrix} \quad \begin{array}{l} y_1 \\ y_2 \\ y_3 \\ y_4 \end{array} \quad \left. \begin{array}{l} \text{Class 1} \\ \text{Class 2} \end{array} \right\}$$

$$\alpha = [0 \ 0 \ 0]^T$$

$$y_1 \cdot a = 0 > 0 \quad ? \quad No$$

$$a_{\text{new}} = a_{\text{old}} + (y_1)^T$$

$$a_{\text{new}} = [1 \ 0 \ 0]^T$$

$$y_2 \cdot a = 1 \cdot 1 + 0 \cdot 0 + 0 \cdot 0 = 1 > 0 \quad yes$$

$$y_3 \cdot a = -1 \cdot 1 + 0 \cdot 0 + 0 \cdot 0 = -1 > 0 \quad No$$

$$a_{\text{new}} = a_{\text{old}} + (y_3)^T$$

$$a_{\text{new}} = [0 \ -1 \ -1]$$

$$y_4 \cdot a = 0 \cdot 1 + 1 \cdot -1 + 0 \cdot -1 = 1 > 0 \quad yes$$

$$y_1 \cdot a = \begin{matrix} 1 \cdot 0 & 0 \cdot -1 & 0 \cdot -1 \\ 0 + 0 + 0 \end{matrix} = 0 \stackrel{?}{>} 0 \quad \text{No}$$

$$a_{\text{new}} = a_{\text{old}} + (y_1)^T$$

$$a_{\text{new}} = [1 \ -1 \ -1]^T$$

$$y_2 \cdot a = \begin{matrix} 1 \cdot 1 & 0 \cdot -1 & 1 \cdot -1 \\ 1 + 0 + -1 \\ 0 \stackrel{?}{>} 0 \end{matrix} \quad \text{No}$$

$$a_{\text{new}} = a_{\text{old}} + (y_2)^T$$

$$a_{\text{new}} = [2 \ -1 \ 0]$$

$$y_3 \cdot a = \begin{matrix} -1 \cdot 2 & -1 \cdot -1 & -1 \cdot 0 \\ -2 + 1 + 0 \\ -1 \stackrel{?}{>} 0 \end{matrix} \quad \text{No}$$

$$a_{\text{new}} = a_{\text{old}} + (y_3)^T$$

$$a_{\text{new}} = [1 \ -2 \ -1]$$

$$y_4 \cdot a = \begin{matrix} -1 \cdot 1 & -1 \cdot -2 & 0 \cdot -1 \\ -1 & 2 & 0 \end{matrix} = 1 \stackrel{?}{>} 0 \quad \text{Yes}$$

$$y_1 \cdot a = 1 \cdot 1 + 0 \cdot -2 + 0 \cdot -1 = 1 \stackrel{?}{>} 0 \quad \text{Yes}$$

$$y_2 \cdot a = 1 \cdot 1 + 0 \cdot -2 + 1 \cdot -1 = 0 > 0 \text{ No}$$

$$a_{\text{new}} = a_{\text{old}} + (y_2)^T$$

$$a_{\text{new}} = [2 \ -2 \ 0]$$

$$y_3 \cdot a = -1 \cdot 2 + -1 \cdot -2 + -1 \cdot 0 = 0 > 0 \text{ No}$$

$$a_{\text{new}} = a_{\text{old}} + (y_3)^T$$

$$a_{\text{new}} = [1 \ -3 \ -1]$$

$$y_4 \cdot a = -1 \cdot 1 + -1 \cdot -3 + 0 \cdot -1 = 2 > 0 \text{ Yes}$$

$$y_1 \cdot a = 1 \cdot 1 + 0 \cdot -3 + 0 \cdot -1 = 1 > 0 \text{ Yes}$$

$$y_2 \cdot a = 1 \cdot 1 + 0 \cdot -3 + 1 \cdot -1 = 0 > 0 \text{ No}$$

$$a_{\text{new}} = a_{\text{old}} + (y_2)^T$$

$$a_{\text{new}} = [2 \ -3 \ 0]$$

$$y_3 \cdot a = -1 \cdot 2 + -1 \cdot -3 + -1 \cdot 0 = 1 > 0 \text{ Yes}$$

$$y_4 \cdot a = -1 \cdot 2 + -1 \cdot -3 + 0 \cdot -1 = 1 > 0 \text{ Yes}$$

$$y_1 \cdot a = 1 \cdot 2 + 0 \cdot -3 + 0 \cdot -1 = 2 > 0 \text{ Yes}$$

$$y_2 \cdot a = 1 \cdot 2 + 0 \cdot -3 + 1 \cdot 0 = 2 > 0 \text{ Yes}$$

Final : $a = [2 \ -3 \ 0]^T$

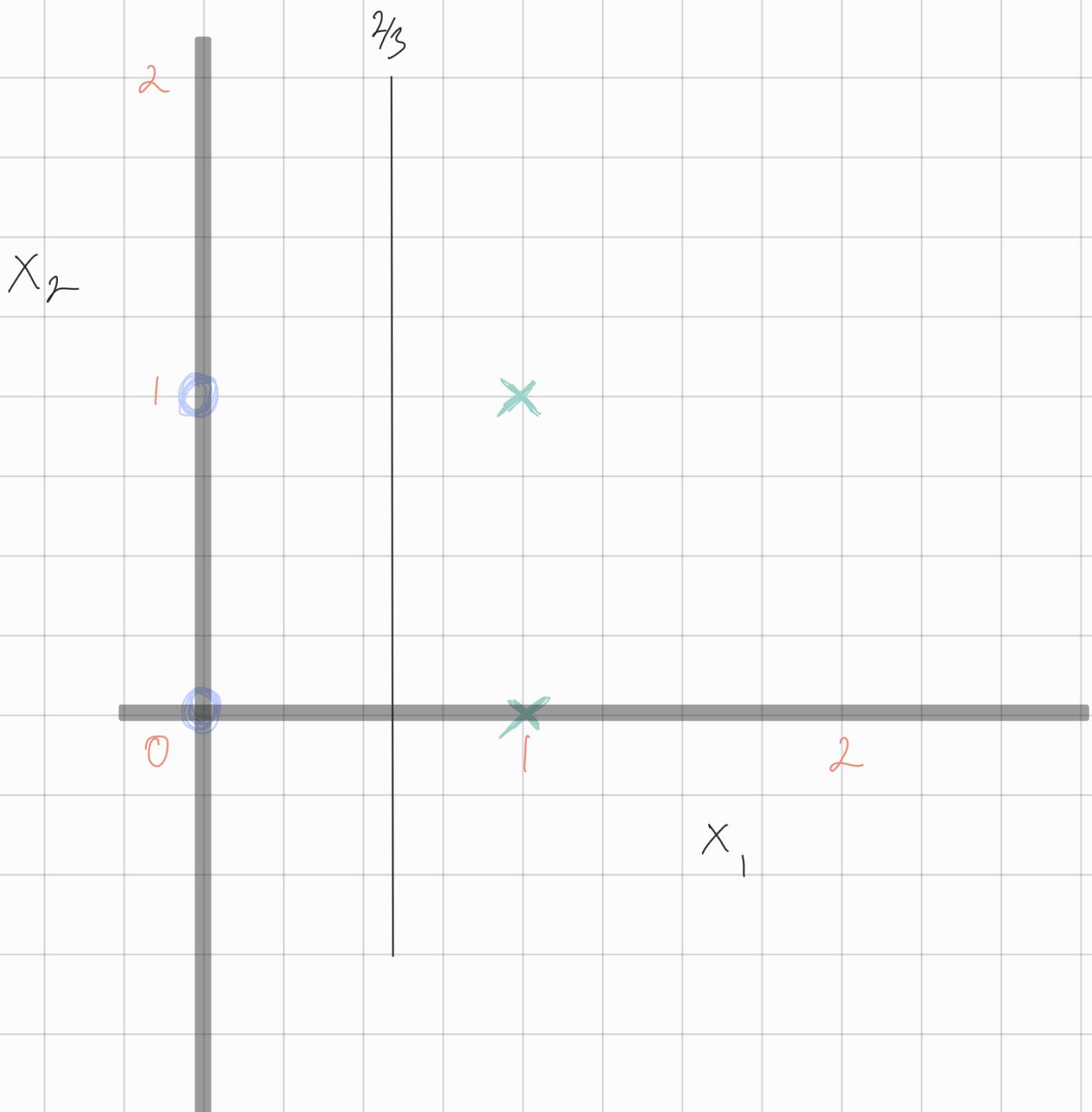
when $g(x) = 0$

$$0 = \omega_0 + \omega_1 x_1 + \omega_2 x_2$$

$$2 + -3x_1 + 0x_2$$

$$-2 = -3x_1$$

$$\frac{2}{3} = x_1$$



c) MSE

$$Y \cdot a = b$$

$$J_s(a) = \| Ya - b \|^2$$

$$= \sum_{i=1}^n (a^T y_i - b_i)^2$$

$$b = [1 \ 1 \ 1 \ 1]^T \quad \nabla J_s(a) = 2 Y^T (Ya - b) = 0$$

$$\rightarrow a = (Y^T Y)^{-1} Y^T b$$

$$Y = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ -1 & -1 & -1 \\ -1 & -1 & 0 \end{bmatrix}$$

$$Y^T = \begin{bmatrix} 1 & 1 & -1 & -1 \\ 0 & 0 & -1 & -1 \\ 0 & 1 & -1 & 0 \end{bmatrix}$$

$$Y^T Y = \begin{bmatrix} 4 & 2 & 2 \\ 2 & 2 & 1 \\ 2 & 1 & 2 \end{bmatrix} \rightarrow$$

$$(Y^T Y)^{-1} = \begin{bmatrix} 0.75 & -0.5 & -0.5 \\ -0.5 & 1 & 0 \\ -0.5 & 0 & 1 \end{bmatrix}$$

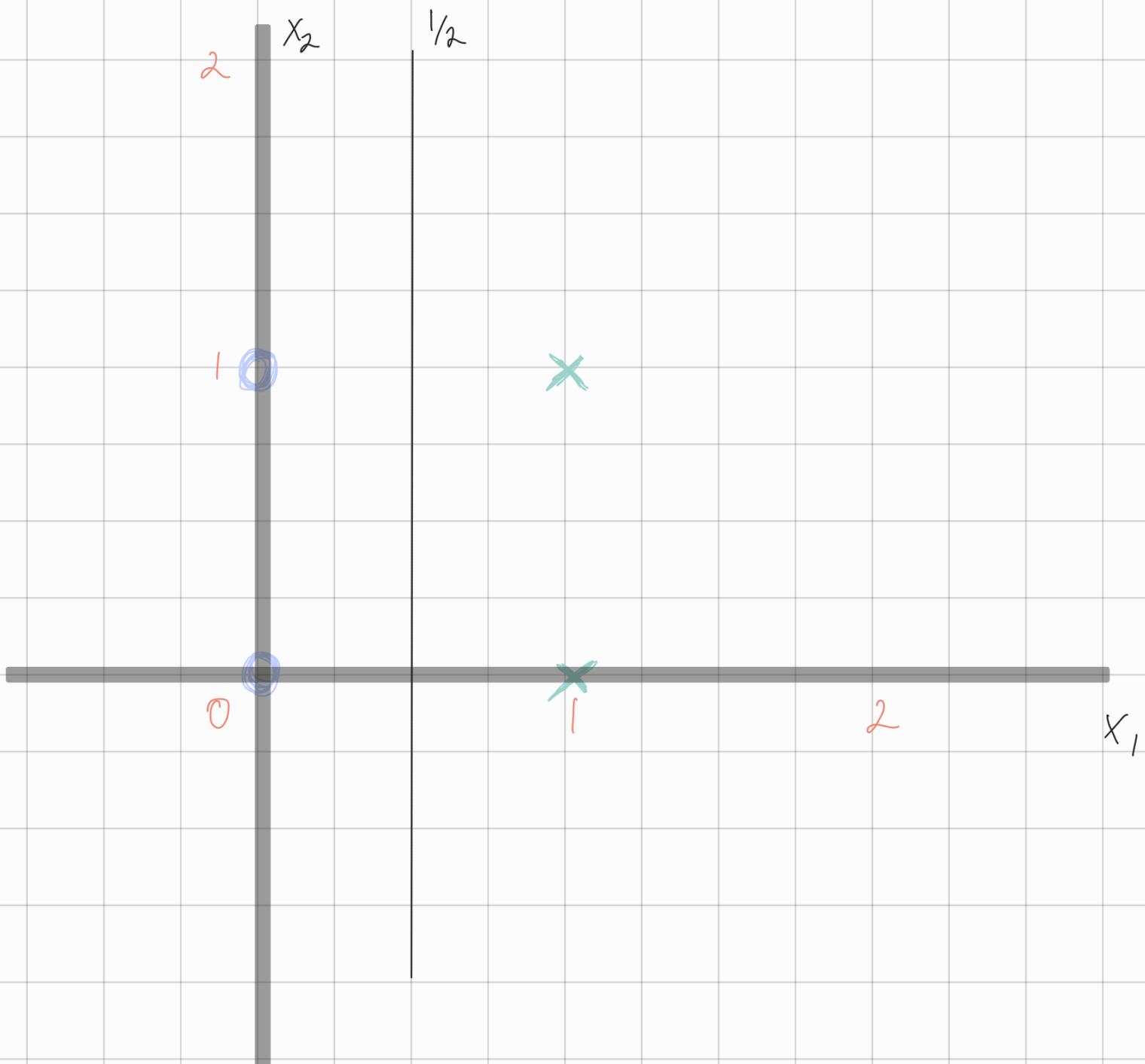
$$(Y^T Y)^{-1} Y^T = \begin{bmatrix} 0.75 & 0.25 & 0.25 & -0.25 \\ -0.5 & -0.5 & -0.5 & -0.5 \\ -0.5 & 0.5 & -0.5 & 0.5 \end{bmatrix}$$

$$a = (Y^T Y)^{-1} Y^T b = \begin{bmatrix} 1 & -2 & 0 \end{bmatrix}^T$$

$$0 = 1 - 2x_1 + 0x_2$$

$$-1 = 2x_1$$

$$\frac{1}{2} = x_1$$

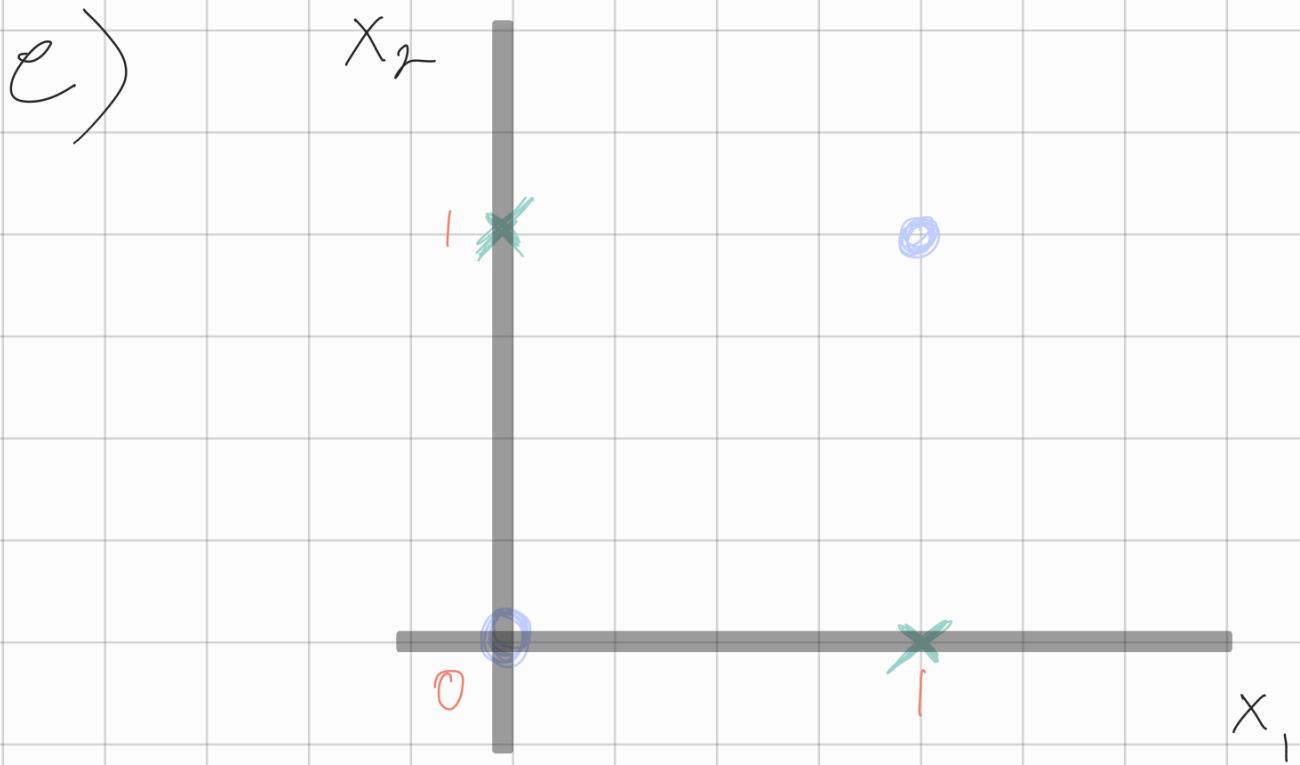


d) done in matlab

final a vector was the

Same as in MSE

$$a = [1 \ -2 \ 0]^T$$



a) they are not linearly separable

b)

$$Y = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ -1 & 0 & -1 \\ -1 & -1 & 0 \end{bmatrix} \quad \begin{array}{l} y_1 \\ y_2 \\ y_3 \\ y_4 \end{array} \quad \left. \begin{array}{l} \text{class 1} \\ \text{class 2} \end{array} \right\}$$

$$\alpha = [0 \ 0 \ 0]^T$$

$$y_1 \cdot a = 1 \cdot 0 + 0 \cdot 0 + 0 \cdot 0 = 0 > 0 \quad \text{NO}$$

$$a_{\text{new}} = a_{\text{old}} + (y_1)^T = [1 \ 0 \ 0]$$

$$y_2 \cdot a = 1 \cdot 1 + 1 \cdot 0 + 1 \cdot 0 = 1 > 0 \quad \text{YES}$$

$$y_3 \cdot a = -1 \cdot 1 + 0 \cdot 0 + -1 \cdot 0 = -1 > 0 \quad \text{NO}$$

$$a_{\text{new}} = a_{\text{old}} + (y_3)^T = [0 \ 0 \ -1]$$

$$y_4 \cdot a = -1 \cdot 0 + 0 \cdot 0 + 0 \cdot -1 = 0 > 0 \quad \text{NO}$$

$$a_{\text{new}} = a_{\text{old}} + (y_4)^T = [-1 \ -1 \ -1]$$

$$y_1 \cdot a = 1 \cdot -1 + 0 \cdot -1 + 0 \cdot -1 = 0 > 0 \quad \text{NO}$$

$$a_{\text{new}} = a_{\text{old}} + (y_1)^T = [0 \ -1 \ -1]$$

$$y_2 \cdot a = 1 \cdot 0 + 1 \cdot -1 + 1 \cdot -1 = -2 > 0 \quad \text{NO}$$

$$a_{\text{new}} = a_{\text{old}} + (y_2)^T = [1 \ 0 \ 0]$$

Loop found, will not terminate
without iteration cap or decreasing learning rate.

MSE

$$Y \cdot a = b$$

$$J_s(a) = \| Ya - b \|^2$$

$$= \sum_{i=1}^n (a^T y_i - b_i)^2$$

$$b = [1 \ 1 \ 1 \ 1]^T \quad \nabla J_s(a) = 2 Y^T (Ya - b) = 0$$

$$\rightarrow a = (Y^T Y)^{-1} Y^T b$$

$$Y = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ -1 & 0 & -1 \\ -1 & -1 & 0 \end{bmatrix}$$

$$Y^T = \begin{bmatrix} 1 & 1 & -1 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 1 & -1 & 0 \end{bmatrix}$$

$$Y^T Y = \begin{bmatrix} 4 & 2 & 2 \\ 2 & 2 & 1 \\ 2 & 1 & 2 \end{bmatrix} \rightarrow (Y^T Y)^{-1} = \begin{bmatrix} 0.75 & -0.5 & -0.5 \\ -0.5 & 1 & 0 \\ -0.5 & 0 & 1 \end{bmatrix}$$

$$(Y^T Y)^{-1} Y^T = \begin{bmatrix} 0.75 & -0.25 & -0.25 & -0.25 \\ -0.5 & 0.5 & 0.5 & -0.5 \\ -0.5 & 0.5 & -0.5 & 0.5 \end{bmatrix}$$

$$a = (Y^T Y)^{-1} Y^T b = [0 \ 0 \ 0]^T$$

d) done in matlab

final a vector was the

same as in MSE

$$a = [0 \ 0 \ 0]^T$$

f) single-sample perceptron was most labor by hand & on matlab. Gave acceptable solution when possible

MSE was quicker because it was an analytical solution rather than iterative method. If all computation for pseudo inverse had to be done by hand, might be a different story.

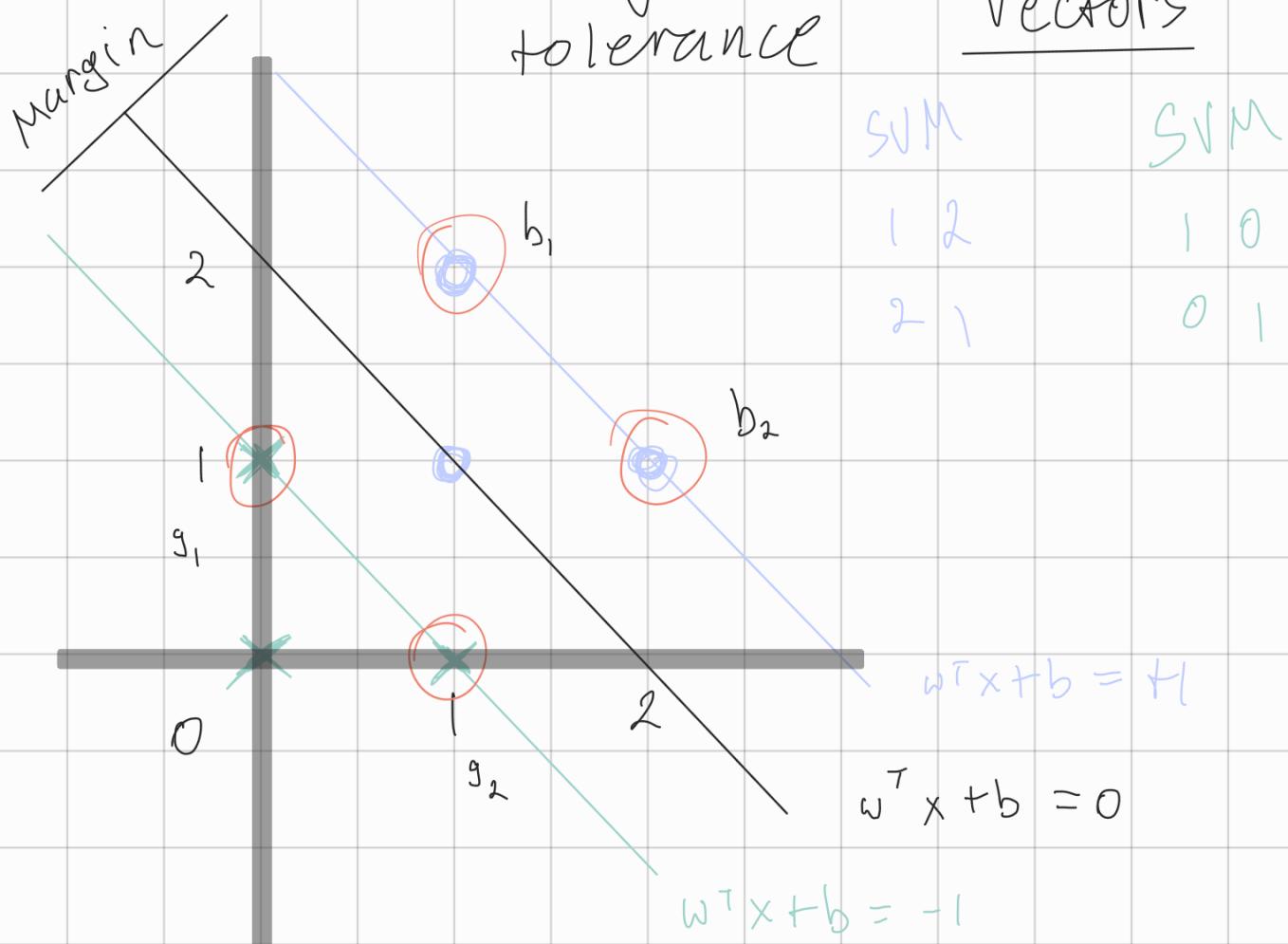
Ho-Kashyap was least effort & simplest in understanding after getting through previous two. don't have to worry about selecting b values because it will get optimized

2)

Class 1: $\begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ Class 2: $\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$$Y = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 2 \\ 1 & 2 & 1 \\ -1 & 0 & 0 \\ -1 & -1 & 0 \\ -1 & 0 & -1 \end{bmatrix}$$

Assuming some tolerance Vectors



distance(b1, g2)

$$d = 2 - 0 = 2$$

$$y_2 - y_1 = m (x_2 - x_1)$$

$$m = \frac{1 - 2}{2 - 1} = \frac{-1}{1} = -1$$

$$y = -(x - 1) + 2$$
$$-x + 1 + 2$$

$$y = -x + 3$$

$$0 = w^T x + b$$

$$\frac{2}{\|w\|} = 2 = \text{margin}$$

No tolerance

Margin

2

1

0

b_1

g_1

g_2

2

1

Vectors

SVM

1 1

SVM

1 0
0 1

$$w^T x + b = +1$$

$$w^T x + b = 0$$

$$w^T x + b = -1$$