Graph Algorithms and Related Data Structures

Project 2

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Problem 1: Single-source Shortest Path Algorithm

Dijkstra Algorithm:

```
In [1]:
            import heapq
            import collections
            def shortestpath(edges, startnode, destnode, graph check):
                graph = collections.defaultdict(set)
                if graph check == 'D':
                    for l,r,c in edges:
                         graph[1].add((c,r))
                else:
                    for 1,r,c in edges:
                         graph[1].add((c,r))
                         graph[r].add((c,1))
                queue, visited = [(0, startnode, [])], set()
                heapq.heapify(queue)
                while queue:
                     (cost, node, path) = heapq.heappop(queue)
                    if node not in visited:
                         visited.add(node)
                         path = path + [node]
                         if node == destnode:
                             return (cost, path)
                         for c, neighbour in graph[node]:
                             if neighbour not in visited:
                                 heapq.heappush(queue, (cost+int(c), neighbour, path))
                return float("inf")
            def main():
                edges = []
                nodes=[]
                file=open("Dijkstra Undirected Graph/Input4.txt", "r+")
                lines=file.readlines()
                for line in lines:
                    edges.append(line.split())
                first = list(edges[0])
                last= list(edges[-1])
                vertices = first[0]
                numofedges=first[1]
                g check= first[2]
                edges.pop(0)
                if(len(last)==1):
                     startnode=last[0]
                    edges.pop()
                else:
                    firstnode=list(edges[0])
                     startnode=firstnode[0]
```

```
print('\nSource vertex: '+str(startnode)+'\n')
    print('Nodes: '+str(vertices)+'\n')
    print('Edges: '+str(numofedges)+'\n')
    if g_check == 'U':
        print('Undirected Graph')
    else:
        print('Directed Graph')
    for i in edges:
        nodes.append(i[0])
    nodes.extend(y[1] for y in edges)
    destnode=list(set(nodes))
    for i in destnode:
        print ("\n"+str(startnode)+" -> "+str(i)+":")
        result = shortestpath(edges, startnode, i,g check)
        print('Path Cost: '+str(result[0]))
        print('Path: '+str(result[1]))
if __name__== "__main__":
    main()
```

```
Source vertex: 0
Nodes: 9
Edges: 14
Undirected Graph
0 -> 1:
Path Cost: 4
Path: ['0', '1']
0 -> 8:
Path Cost: 14
Path: ['0', '1', '2', '8']
0 -> 4:
Path Cost: 21
Path: ['0', '7', '6', '5', '4']
0 -> 2:
Path Cost: 12
Path: ['0', '1', '2']
0 -> 3:
Path Cost: 19
Path: ['0', '1', '2', '3']
0 -> 0:
Path Cost: 0
Path: ['0']
0 -> 6:
```

```
Path Cost: 9
Path: ['0', '7', '6']

0 -> 7:
Path Cost: 8
Path: ['0', '7']

0 -> 5:
Path Cost: 11
Path: ['0', '7', '6', '5']
```

Problem 2: Minimum Spanning Tree Algorithm

Prim's Algorithm:

```
In [4]:
         #Program to find the Minimum Spanning Tree using Prim's Algorithm and Heap Da
            import sys
            #Implementation of Heap
            class Heap:
                 s = 0
                 a = []
                 p = \{\}
                 key = \{\}
                 def __init__(self):
                     self.s = -1
                 def heapify_up(self, i):
                     while i>0:
                         j = i//2
                         if self.key[self.a[i]] < self.key[self.a[j]]:</pre>
                             temp = self.a[i]
                             self.a[i] = self.a[j]
                             self.a[j] = temp
                             self.p[self.a[i]] = i
                             self.p[self.a[j]] = j
                             i = j
                         else:
                             break
                 def heapify_down(self,i):
                     j=-1
                     while 2*i <= self.s:
                         if 2*i == self.s or self.key[self.a[2*i]] <= self.key[self.a[2*i</pre>
                             j = 2*i
                         else:
                             j = 2*i + 1
                         if self.key[self.a[j]] < self.key[self.a[i]]:</pre>
                             temp = self.a[i]
                             self.a[i] = self.a[j]
                             self.a[j] = temp
                             self.p[self.a[i]] = i
                             self.p[self.a[j]] = j
                             i = j
                         else:
                             break
                 def decrease key(self, v, key value):
                     self.key[v] = key_value
                     self.heapify_up(self.p[v])
                 def extract min(self):
                     ret = self.a[0]
                     self.a[0]=self.a[self.s]
                     self.p[self.a[0]] = 0
                     self.s-=1
                     if self.s>=0:
                         self.heapify down(0)
                     return ret
```

```
def insert(self, v, key_value):
        self.a.append(v)
        self.s +=1
        self.p[v] = self.s
        self.key[v] = key_value
        self.heapify_up(self.s)
    def printdata(self):
        print("Value of array a: ", self.a)
        print("Value of p: ", self.p)
        print("Value of key: ", self.key)
#Reading data from file
f = open("MST/input2_MST.txt")
lines = f.readlines()
f.close()
#Global variables for the Minimum Spanning Tree
Q = Heap()
n,m = map(int,lines[0].strip().split(" "))
edges = [[-1 \text{ for } x \text{ in } range(0,n+1)] \text{ for } y \text{ in } range(0,n+1)]
d = \{\}
pi = {}
S = []
V = []
total_weight = 0
edges mst = [None]*(n-1)
#Add all nodes to the list V
for i in range(1,n+1):
    V.append(i)
#Add all edges to the edges matrix
for i in range(0,m):
    p,q,r = map(int,lines[i+1].strip().split(" "))
    edges[p][q] = r
    edges[q][p] = r #Adding the edges for both because it is an undirected gr
#Choosing the Arbitrary vertex as "Vertex 1"
d[1] = 0
Q.insert(1,d[1])
#Inserting the Infinity value for all other vertices
for i in range(1,n+1):
    d[i] = sys.maxsize
    Q.insert(i,d[i])
#Finding the Minimum Spanning Tree
while set(S)!=set(V):
    u = Q.extract min()
    S.append(u)
    left = list(set(V) - set(S))
    for v in left:
        if edges[u][v] != -1:
            if edges[u][v] < d[v]:
```

```
d[v] = edges[u][v]
                Q.decrease_key(v,d[v])
                pi[v] = u
#Adding the list of edges into a string array and calculating total weight
i = 0
for v in list(set(V) - set({1})):
   total_weight+=edges[v][pi[v]]
    if v < pi[v]:</pre>
        edges_mst[i] = " " +str(v) + " - " + str(pi[v]) + " \t^* + str(ed
    else:
        edges_mst[i] = " " +str(pi[v]) + " - " + str(v) + " \t^* + str(ed
    i+=1
print("Total cost of Minimum Spanning Tree (MST):",str(total_weight)+"\n")
print("Tree Edges Cost \n")
for i in range(0, n-1):
    print(edges_mst[i])
```

Total cost of Minimum Spanning Tree (MST): 37

Tree	Ed	ges	Cost
1	- 2	2	4
3	- (5	4
3	- 4	4	7
4	- !	5	9
6	- 7	7	2
7	- 8	3	1
1	- 8	3	8
3	- 9	9	2