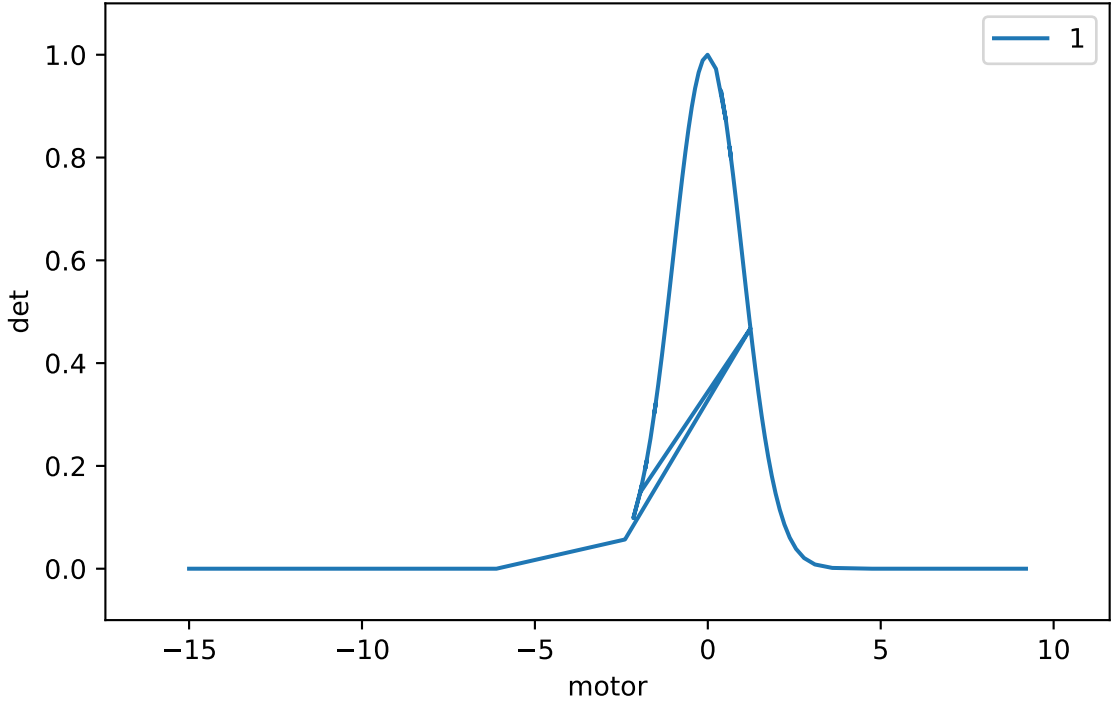
1
1.0
0.8
0.6
0.4
0.2
0.0
det
−15
−10
−5
0
5
10
motor