Graph Kernels

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Content s

- ➢ Overview of Graph Kernels.

- ➢ Graph Kernels methods:

  - ➢ Graphlet kernel.

  - ➢ Shortest path kernel

  - ➢ Random walk kernel.

  - ➢ Weisfeiler-Lehman (WL) graph kernel: WL relabelling process.

- ➢ Subgraph Matching Kernel.

- ➢ Sample code of Graph Kernels.

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➢ From an algorithmic perspective, graphs are the most general data structures, as all common data types are simple instances of graphs.

  ➢ E.g. 1, A time series of vectors can be represented as a graph that contains one node per time step, and consecutive steps are linked by an edge.

  ➢ E.g. 2, A string is a graph in which each node represents one character, and consecutive characters are connected by an edge.

➢ Given their generality, the natural question to ask is:

   Why have graphs not been the common data structure in computer science for decades?

➢ The answer is simple:

   Their comparison is computationally expensive.

   Graphs are prisoners of their own their flexibility.

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➢ Graph kernels are one of the most recent approaches to graph comparison.

➢ Interestingly, graph kernels employ concepts from all three traditional branches of graph comparison:

    ➢ Measure similarity in terms of isomorphic substructures of graphs.

    ➢ Allow for inexact matching of nodes, edges, and labels.

    ➢ Treat graphs as vectors in a Hilbert space of graph features.

➤ Given two graphs G and G'. The problem of graph comparison is to find a mapping:

$$s : \mathcal{G} \times \mathcal{G} \to \mathbb{R}$$

➤ Such that $s(G, G')$ quantifies the similarity (dissimilarity) of G and G'

G

G′
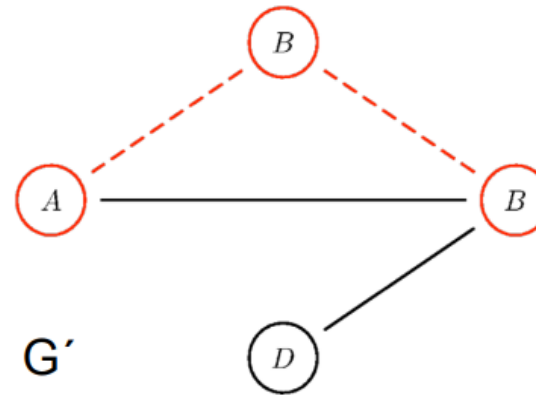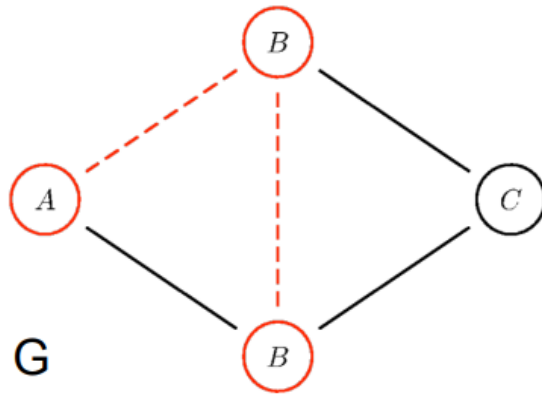
➢ Function prediction of chemical compounds.

➢ Structural comparison and function prediction of protein structures.

➢ Comparison of social networks.

➢ Analysis of semantic structures in Natural Language Processing.

➢ Comparison of UML diagrams.

➤ Graph isomorphism:

    ➤ Find a mapping f of the vertices of G_1 to the vertices of G_2 such that G_1 and G_2 are identical.

    ➤ i.e. (x, y) is an edge of G_1 if $(f(x), f(y))$ is an edge of G_2. Then f is an isomorphism, and G_1 and G_2 are called isomorphic.

    ➤ No polynomial-time algorithm is known for graph isomorphism.

    ➤ Neither is it known to be NP-hard.
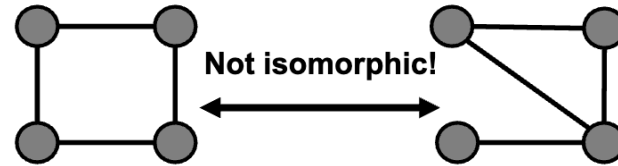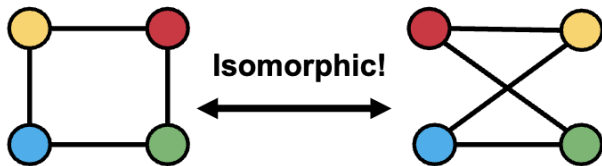
Graph G	Graph H	An isomorphism between G and H
		$f(a) = 1$
		$f(b) = 6$
		$f(c) = 8$
		$f(d) = 3$
		$f(g) = 5$
		$f(h) = 2$
		$f(i) = 4$
		$f(j) = 7$

➢ Subgraph isomorphism:

  ➢ Subgraph isomorphism asks if there is a subset of edges and vertices of G_1 that is isomorphic to a smaller graph G_2.

  ➢ Subgraph isomorphism is **NP-complete**.

Subgraph G'   Graph G   Graph G''

$fsub$: (V_1, V'_3), (V_2, V'_1), (V_3, V'_2)
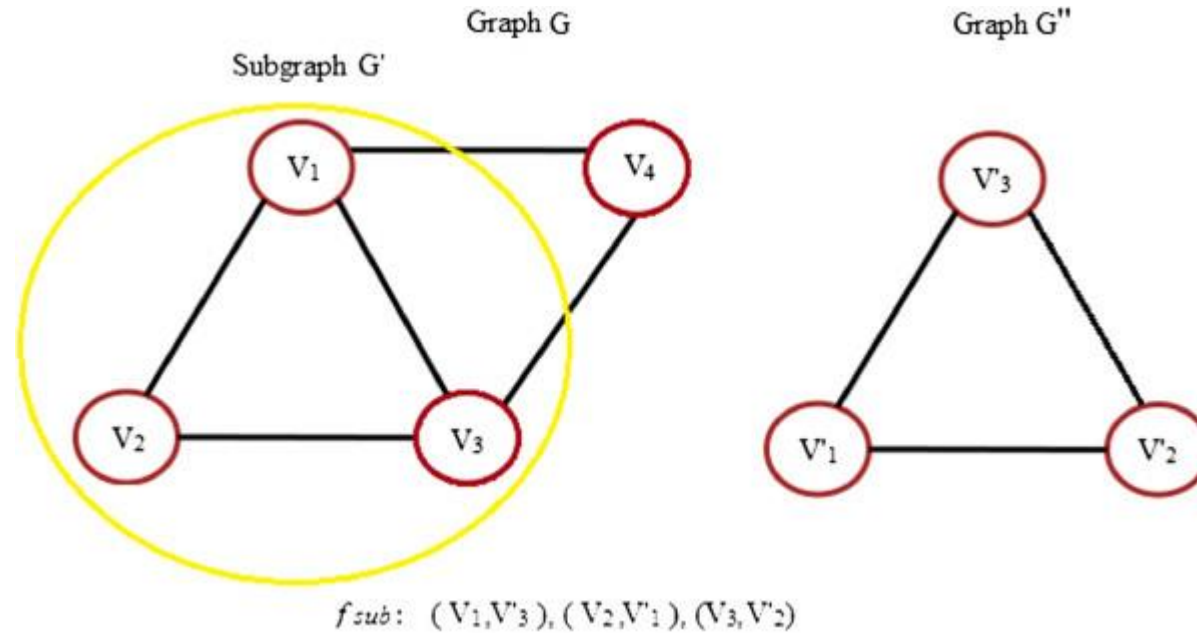
➢ **NP-completeness:**

 ➢ A decision problem C is NP-complete if

  ➢ C is in NP.

  ➢ C is NP-hard, i.e. every other problem in NP is reducible to it.

➢ **Problems for the practitioner:**

 ➢ Excessive runtime in worst case.

 ➢ Runtime may grow exponentially with the number of nodes.

 ➢ For larger graphs with many nodes and for large datasets of graphs, this is an enormous problem.

➡ Wanted: Polynomial-time similarity measure for graphs.

➢ Principle:

    ➢ Count operations that are necessary to transform g_1 into g_2.

    ➢ Assign costs to different types of operations (edge/node insertion/deletion, modification of labels).

$$GED(g_1, g_2) = \min_{(e_1,...,e_k) \in \mathcal{P}(g_1, g_2)} \sum_{i=1}^{k} c(e_i)$$

Where $P(g_1, g_2)$ denotes the set of edit paths transforming g_1 into g_2 and $c(e) \geq 0$ is the cost of each graph edit operation e.
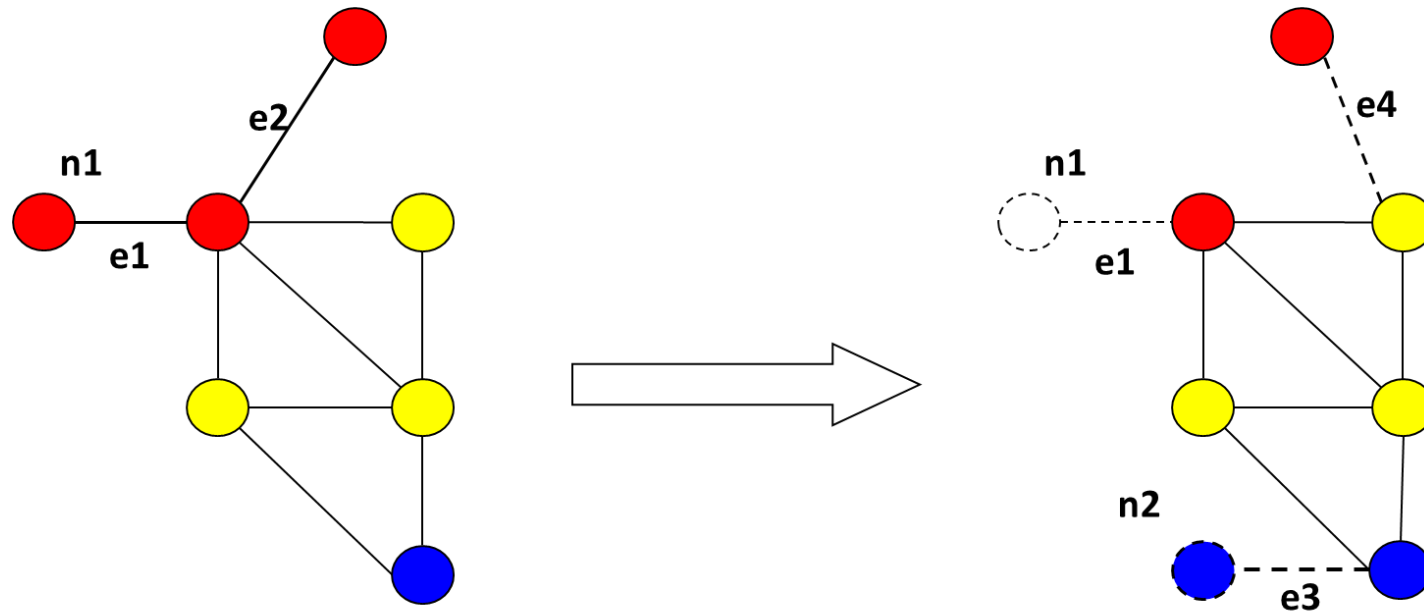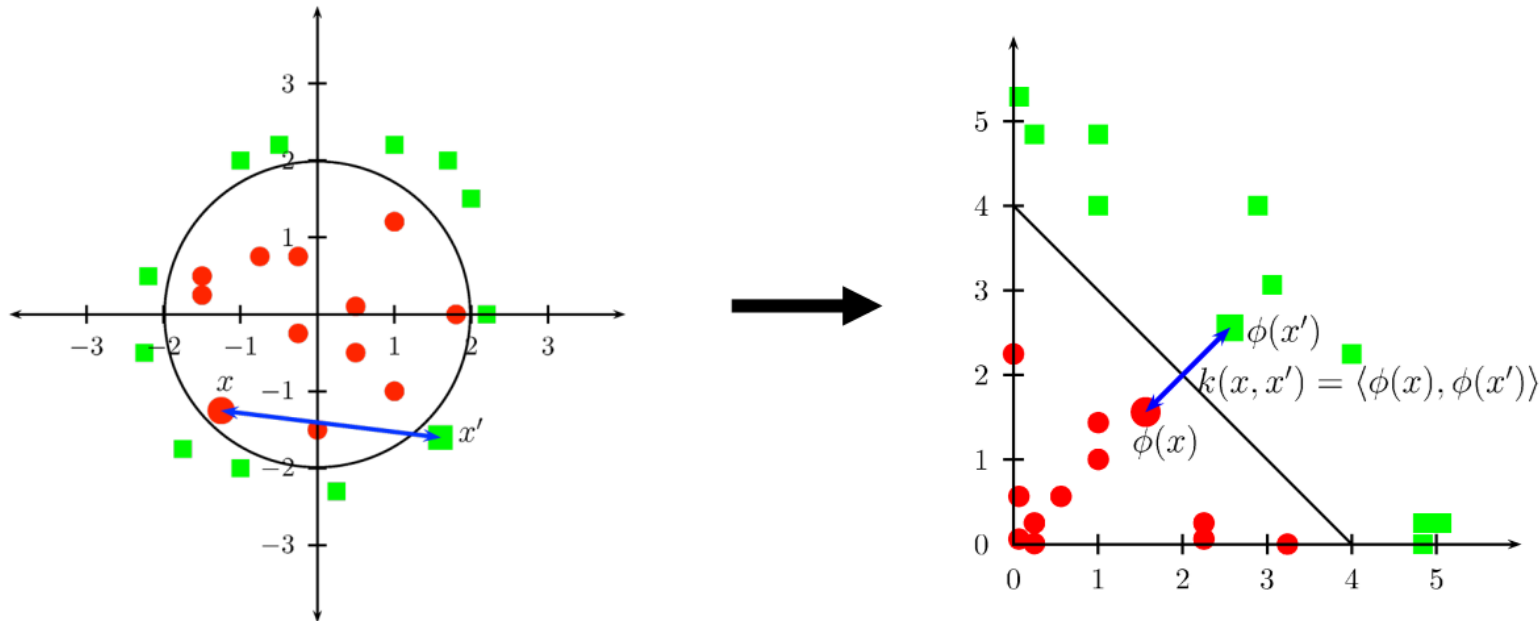
➢ Advantages:

  ➢ Captures partial similarities between graphs.

  ➢ Allows for noise in the nodes, edges and their labels.

  ➢ Flexible way of assigning costs to different operations.

➢ Disadvantages:

  ➢ Contains subgraph isomorphism check as one intermediate step.

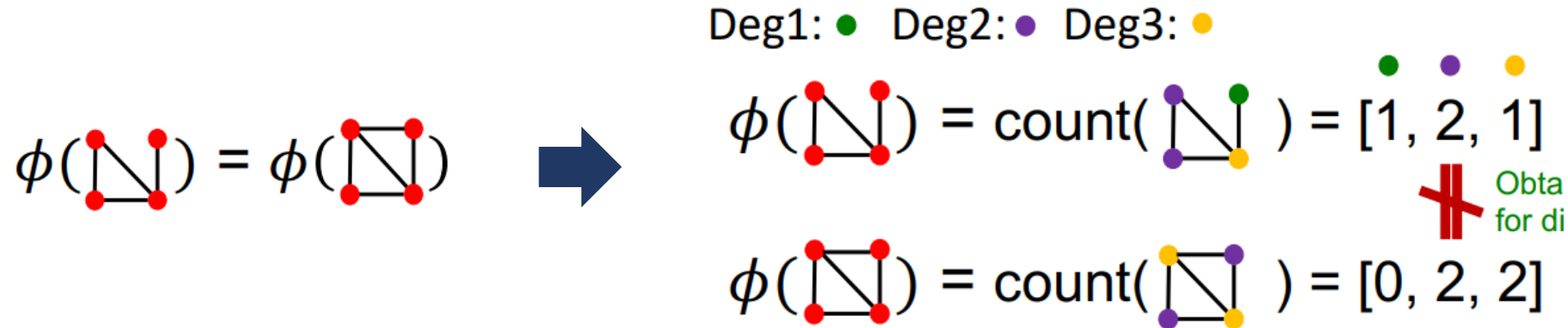 ➢ Choosing cost function for different operations is difficult.

➢ Kernel is a type of measures of similarity.

➢ Mapping two objects x and x' via mapping $\boxed{\phi}$ into feature space *H.*

➢ Measure their similarity in *H* as $\langle \phi(x), \phi(x') \rangle.$

➢ **Kernel Trick**: Compute inner product in *H* as kernel in input space

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$$\boxed{k(x, x') = \langle \phi(x), \phi(x') \rangle.}$$

Deg1: ● Deg2: ● Deg3: ●

$\phi(\Box) = \phi(\Box)$ ➡

$\phi(\Box) = \text{count}(\Box) = [1, 2, 1]$

Obta
for di

$\phi(\Box) = \text{count}(\Box) = [0, 2, 2]$

- ➢ Instance of R-convolution kernels by Haussler (1999):

  - ➢ R-convolution kernels compare decompositions of two structured objects.

$$k_{convolution}(x, x') = \sum_{(x_d, x) \in \mathrm{R}} \sum_{(x'_d, x') \in \mathrm{R}} k_{parts}(x_d, x'_d)$$

  - ➢ Decompose graphs into their substructures and add up the pairwise similarities between these substructures.

- ➢ Concept:

  - ➢ Kernel function to measure the similarity of pairs of graphs by computing an inner product on graphs.

  - ➢ Compare substructures of graphs that are computable in polynomial time.

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➢ **Graph kernels based on bags of patterns:**

  ➢ Extraction of a set of patterns from graphs.

  ➢ Comparison between patterns.

  ➢ Comparison between bags of patterns.
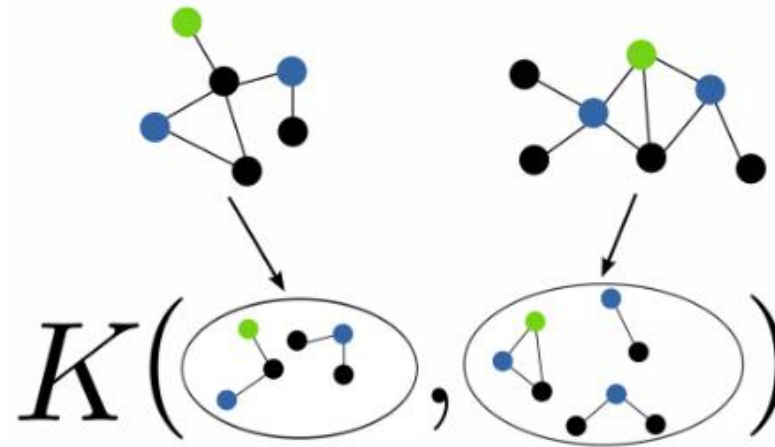
- ➢ Link to graph isomorphism
  - ➢ Let $k(G, G') = <\phi(G), \phi(G')>$ be a graph kernel
  - ➢ If ϕ is injective (one-to-one), *k* is called a complete graph kernel

Proposition 1.

- ➢ Computing any complete graph kernel is at least as hard as deciding whether two graphs are isomorphic.

- ➢ Criteria for a good graph kernel:
  - ➢ Expressive
  - ➢ Efficient to compute
  - ➢ Positive definite
  - ➢ Applicable to wide range of graphs

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Example 17

➢ Let X represent the alphabet where each element of X is a set.

➢ Define the intersection kernel to be $K(X_1, X_2) = |X_1 \cap X_2|$.

➢ Given a graph G, obtain the set of all its subgraphs, denoted by $X(G)$.

➢ Then the following is a graph kernel

$$K(G_1, G_2) = K(X(G_1), X(G_2)) = |X(G_1) \cap X(G_2)|$$

➢ This kernel looks for all overlapping substructures between two graphs.

➢ High complexity.

➢ Graph kernels inspired by concepts from chemoinformatics:

  ➢ Define three new kernels (Tanimoto, MinMax, Hybrid) for function prediction of chemical compounds,

  ➢ Based on the idea of molecular fingerprints and

  ➢ Counting labeled paths of depth up to d using depth-first search from each possible vertex.

➢ **Properties**:

  ➢ Tailored for applications in chemical informatics,

  ➢ Exploit the small size and low average degree of these molecular graphs.

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➢ **Properties**:

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➢ New kernels and experimental comparison of existing techniques:

  ➢ Define a kernel that considers *graph fragments*: Subgraphs with a maximum of l edges

  ➢ Fragment-based kernels outperform kernels using frequent subgraphs and walk-based kernels.

➢ **Four choices in kernel design for chemical compound**:

  ➢ Generation of patterns (learnt from dataset versus defined by expert).

  ➢ 'Preciseness' of the patterns (whether subgraph features map to the same dimension in feature space).

  ➢ Complete coverage (whether the patterns occur in all of the instances of the dataset).

  ➢ Complexity of patterns (walks and cycles versus frequent subgraphs).

➢ Predict the function of a protein from its structure.

➢ Model protein structure as graph.

➢ Use graph kernels to measure structural similarity and SVM to predict functional class.

➢ Reaches competitive results on benchmark datasets.

protein data → secondary structure elements → sequence → structure
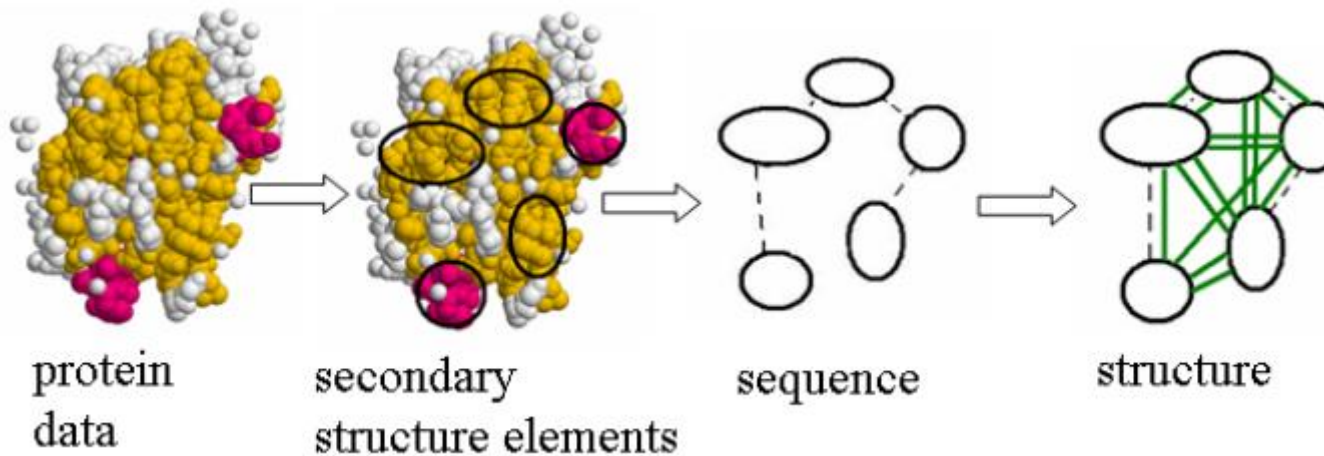
➢ **Graphlet kernel** [Shervashidze et al., 2009]:

  ➢ Counts identical pairs of graphlets.
    (i.e., subgraphs with k nodes where k = 3, 4, 5) in two graphs.

➢ **Shortest path kernel** [Borgwardt and Kriegel, 2005]:

  ➢ Counts pairs of shortest paths in two graphs having the same source and sink labels and identical length.

➢ **Random walk kernel** [Kashima et al.,2003; Gärtner et al., 2003]:

  ➢ Counts pairs of random walks and compare walks in two input graphs.

➢ **Weisfeiler-Lehman** [Weisfeiler-Lehman isomorphic testing, 1968]:

  ➢ WL relabelling process.

➢ **Pyramid match graph kernel** [Nikolentzos et al.,2017b]:

  ➢ Embeds the vertices of the input graphs in a vector space.

  ➢ It then partitions the feature space into regions of increasingly larger size and takes a weighted sum of the matches that occur at each level.

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> ➤ Principle:

>> ➤ Count subgraphs of limited size k in G and G'.

>> ➤ These subgraphs are referred to as graphlets (Przulj, Bioinformatics 2007).

>> ➤ Define graph kernel that counts isomorphic graphlets in two graphs.

> ➤ Runtime problems:

>> ➤ Pairwise test of isomorphism is expensive.

>> ➤ Number of graphlets scales as $O(nk)$.

> ➤ Two solutions on unlabelled graphs:

>> ➤ Precompute isomorphisms.

>> ➤ Sample graphlets.

> ➤ Disadvantage:

>> ➤ Same solutions not feasible on labelled graphs.
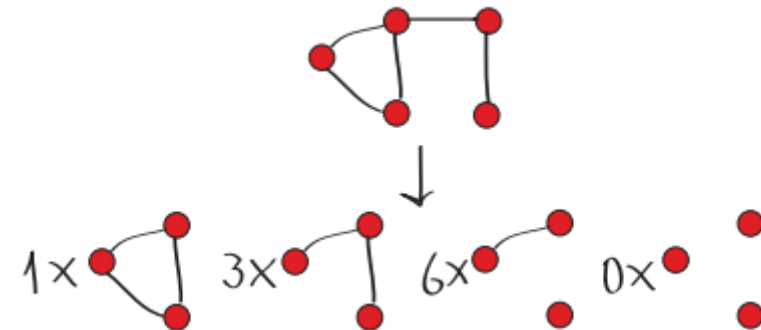
Size k-graphlet = 3, number of node n = 5

➤ Variety of subgraphs according to size *k*:
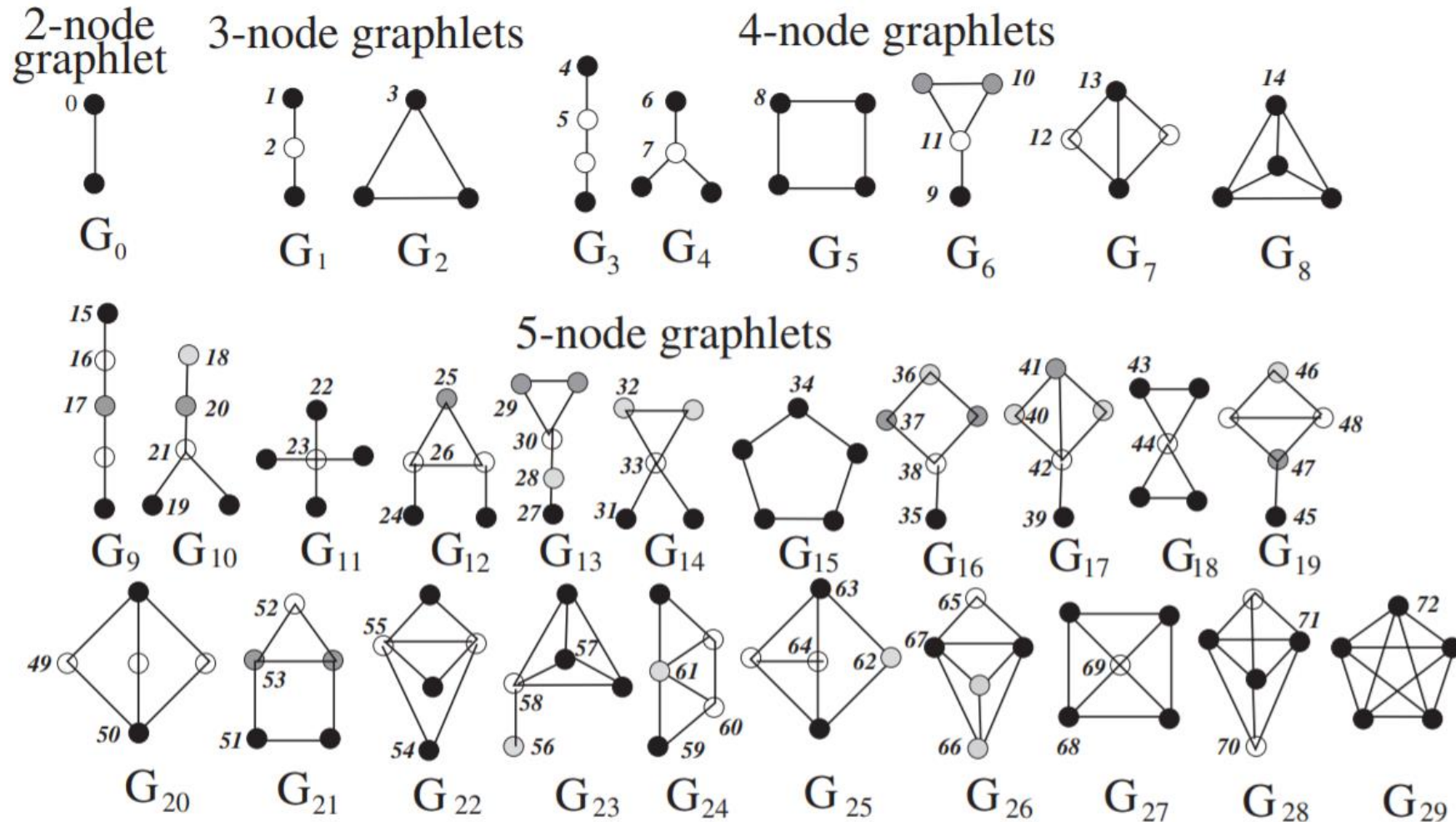
➢ Count subgraphs of limited size 3:

- Example for $k = 3$.

$$f_G = (1, \quad 3, \quad 6, \quad 0)^T$$
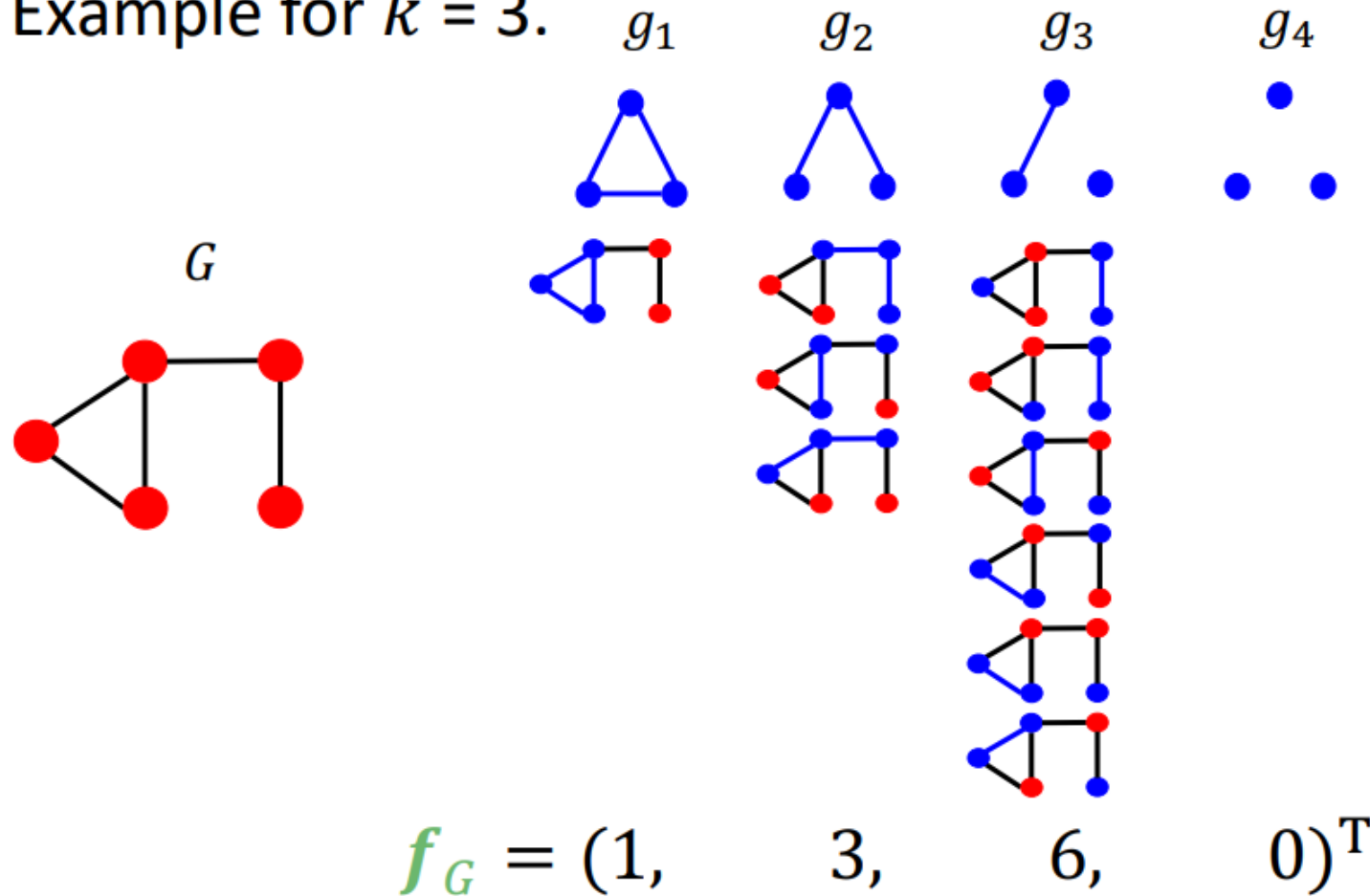
Floyd-transformation:

➤ Given an input graph G, outputs a shortest-path graph S.

  ➤ S contains the same set of nodes as the input graph G.

  ➤ There exists an edge between all nodes in S which are connected by a path in G.

  ➤ Every edge in S between two nodes is labelled by the shortest distance between these two nodes.

  ➤ This transformation can be done in $O(n^3)$ time.

Definition (Shortest-path graph kernel):

➢ Let G_1 and G_2 be two graphs that are Floyd-transformed into S_1 and S_2.

➢ We can then define shortest-path graph kernel on $S_1 = (G_1, E_1)$ and $S_2 = (G_2, E_2)$ as:

$$k_{shortest\ paths}(S_1, S_2) = \sum_{e_1 \in E_1} \sum_{e_2 \in E_2} k_{walk}^{(1)}(e_1, e_2),$$

where K_{walk} is a positive definite kernel on edge walks of length 1.

Shortest-path graph kernel:

$$k_{shortest\ paths}(S_1, S_2) = \sum_{e_1 \in E_1} \sum_{e_2 \in E_2} k_{walk}^{(1)}(e_1, e_2),$$
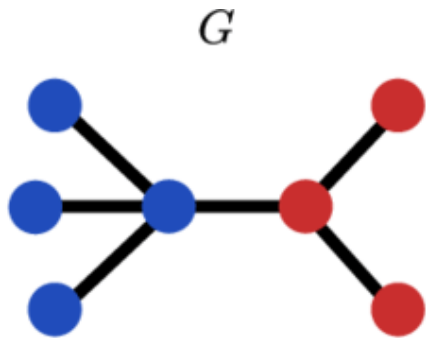
$\phi_{\text{path}}(G) = [\ 3\ \ 2\ \ 1\ \ 3\ \ 1\ \ 5\ \ 0\ \ 0\ \ 6\ ]$
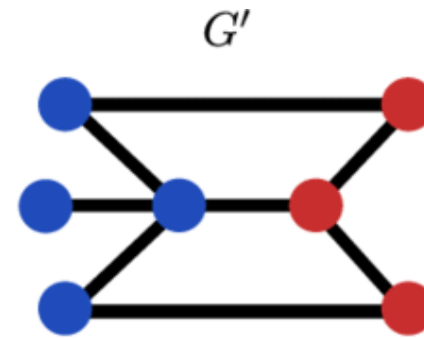
$\phi_{\text{path}}(G') = [\ 3\ \ 2\ \ 3\ \ 3\ \ 1\ \ 5\ \ 0\ \ 0\ \ 4\ ]$

➢ Random walk-kernels are based on the idea to count the number of matching walks in two input graphs. All pairs of matching walks in two input graphs G_1 and G_2 via a direct product graph G_X:

$$k_\times(G_1, G_2) = \sum_{i,j=1}^{|V_\times|} [\sum_{n=0}^{\infty} \lambda_n A_\times^n]_{ij},$$

where A_X is the adjacency matrix of G_X, defined from

$$V_\times(G_1 \times G_2) = \quad \{(v_1, w_1) \in V_1 \times V_2 : \\ label(v_1) = label(w_1)\}$$

$$E_\times(G_1 \times G_2) = \quad \{((v_1, w_1), (v_2, w_2)) \in V^2(G_1 \times G_2) : \\ (v_1, v_2) \in E_1 \wedge (w_1, w_2) \in E_2 \\ \wedge(label(v_1, v_2) = label(w_1, w_2))\}$$

λ_n must be chosen appropriately for k_X to converge

➢ Random walk-kernels are based on the idea to count the number of matching walks in two input graphs.
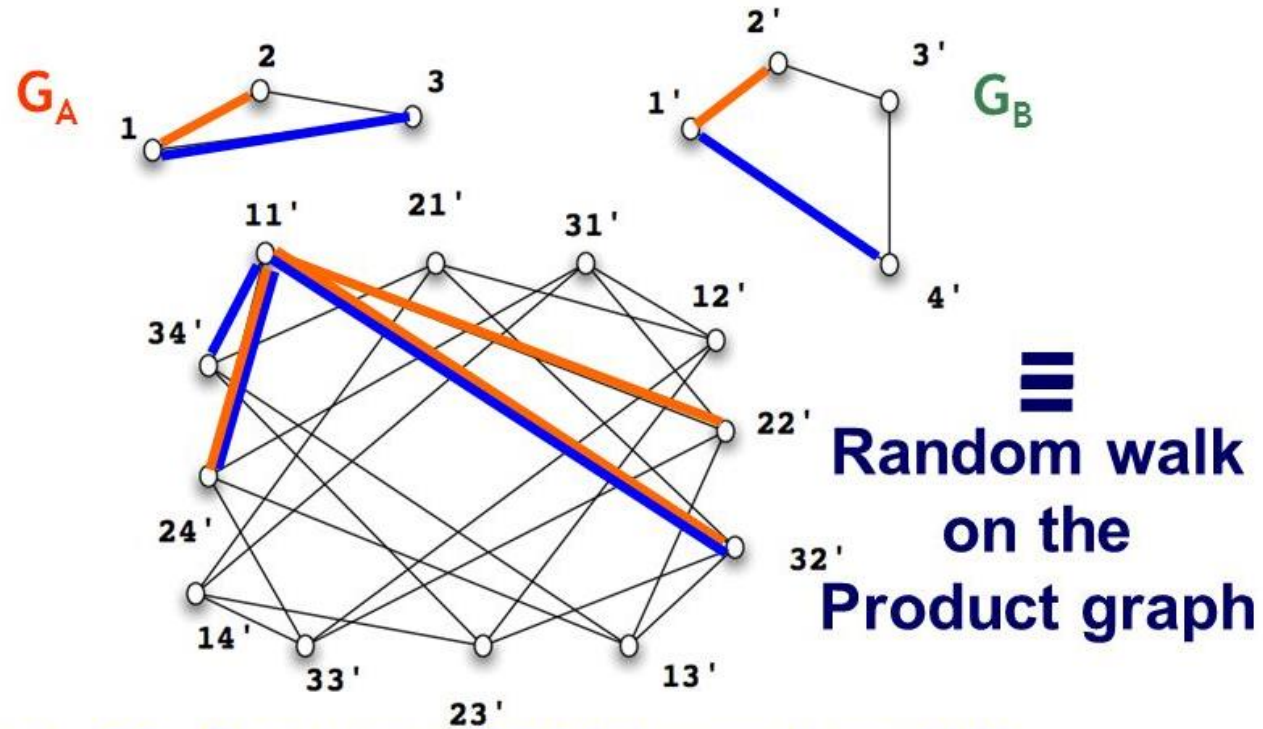
[Kashima+ '03, Gaertner+ '03, Vishwanathan '10]

SDM'14 Tutorial   D. Koutra & T. Eliassi-Rad & C. Faloutsos

Definition:

➢ The simple graphs $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ are isomorphic if there is a bijection (a one-to-one and onto function) f from V_1 to V_2 with the property that a and b are adjacent in G_1 if and only if $f(a)$ and $f(b)$ are adjacent in G_2, for all a and b in V_1.

➢ Such a function f is called an isomorphism.

➢ In other words, G_1 and G_2 are isomorphic if their vertices can be ordered in such a way that the adjacency matrices $M(G_1)$ and $M(G_2)$ are identical.

- ➢ For this purpose, we can check invariants, that is, properties that two isomorphic simple graphs must both have.

- ➢ For example, they must have

  - ➢ The same number of nodes,

  - ➢ the same number of edges,

  - ➢ And the same degrees of nodes.

- ➢ Note that two graphs that differ in any of these invariants are not isomorphic, but two graphs that match in all of them are not necessarily isomorphic.

➤ Are the following two graphs isomorphic?
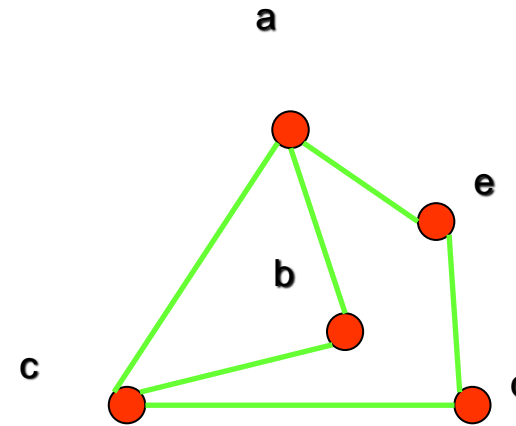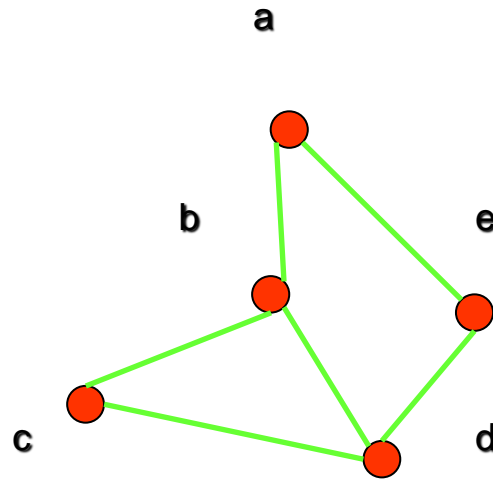
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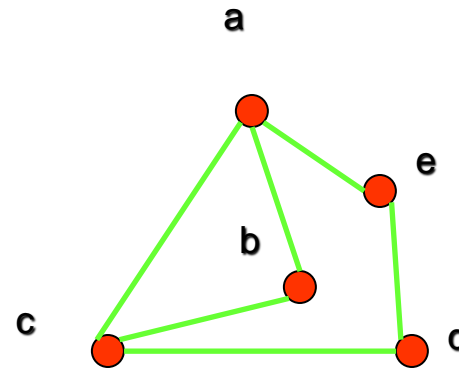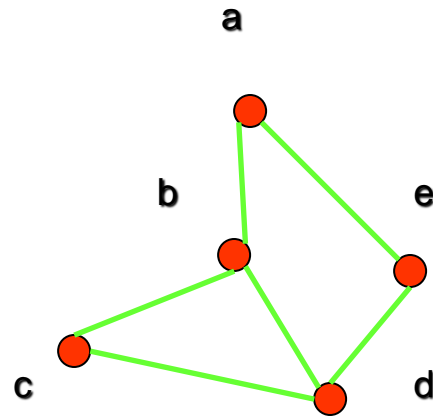
➢ **Solution**: Yes, they are isomorphic, because they can be arranged to look identical.

➢ You can see this if in the right graph you move vertex b to the left of the edge {a, c}. Then the isomorphism f from the left to the right graph is

f(a) = e, f(b) = a, f(c) = b, f(d) = c, f(e) = d.
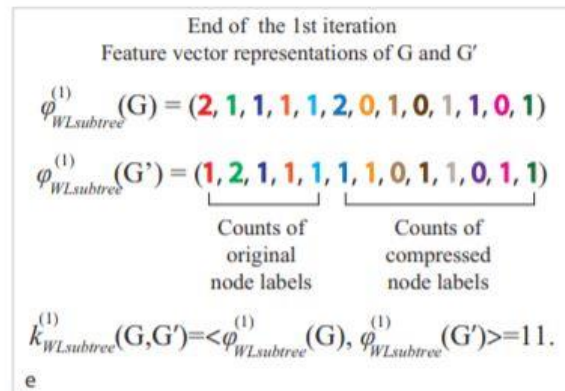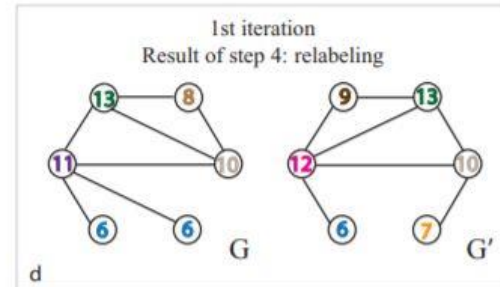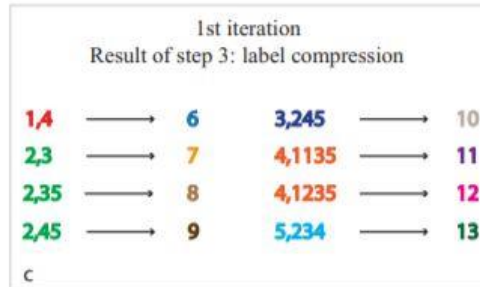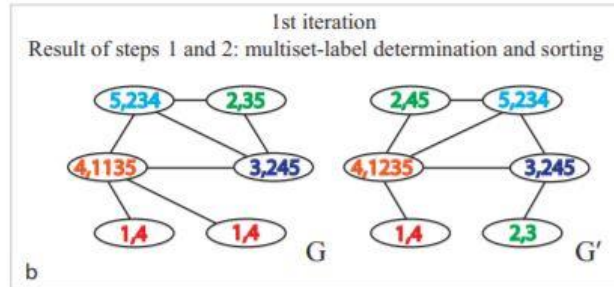
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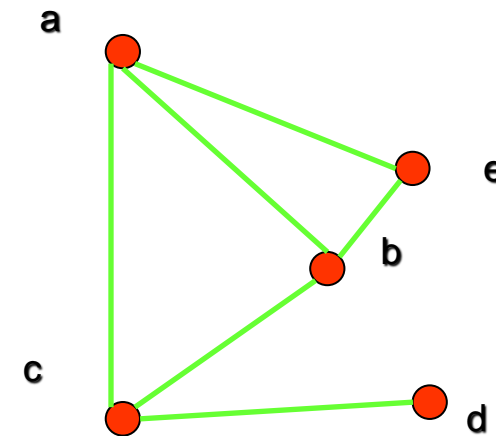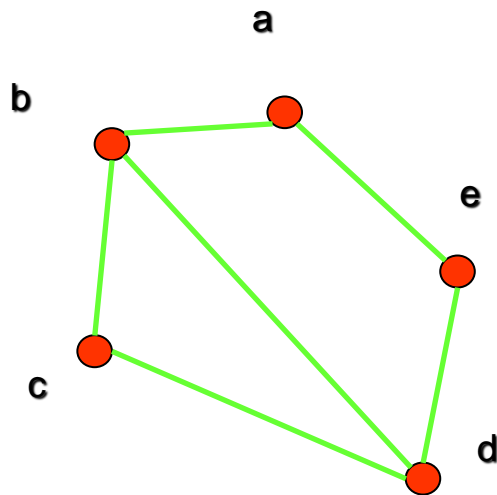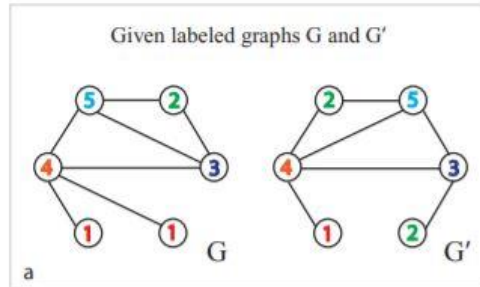
➢ Are the following two graphs isomorphic?
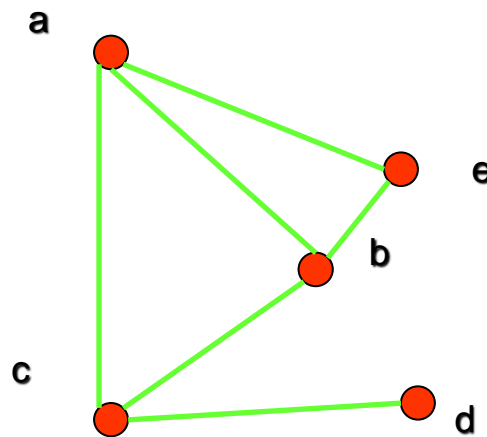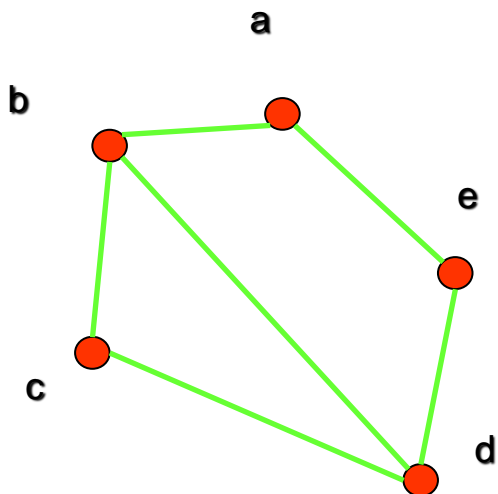
➢ **Solution**: No, they are not isomorphic, because they differ in the degrees of their vertices.

➢ Vertex d in right graph is of degree one, but there is no such vertex in the left graph.

➤ **Weisfeiler-Lehman Isomorphism Testing:**

Given labeled graphs G and G'

1st iteration
Result of steps 1 and 2: multiset-label determination and sorting

1st iteration
Result of step 3: label compression

1,4	→ 6	3,245	→ 10
2,3	→ 7	4,1135	→ 11
2,35	→ 8	4,1235	→ 12
2,45	→ 9	5,234	→ 13

1st iteration
Result of step 4: relabeling

End of the 1st iteration
Feature vector representations of G and G'

$$\varphi_{WLsubtree}^{(1)}(G) = (2, 1, 1, 1, 1, 2, 0, 1, 0, 1, 1, 0, 1)$$

$$\varphi_{WLsubtree}^{(1)}(G') = (1, 2, 1, 1, 1, 1, 1, 0, 1, 1, 0, 1, 1)$$

Counts of original node labels   Counts of compressed node labels

$$k_{WLsubtree}^{(1)}(G,G') = \langle \varphi_{WLsubtree}^{(1)}(G), \varphi_{WLsubtree}^{(1)}(G') \rangle = 11.$$

Algorithm 1: WL-1 algorithm (Weisfeiler & Lehmann, 1968)

Input: Initial node coloring $(h_1^{(0)}, h_2^{(0)}, ..., h_N^{(0)})$

Output: Final node coloring $(h_1^{(T)}, h_2^{(T)}, ..., h_N^{(T)})$
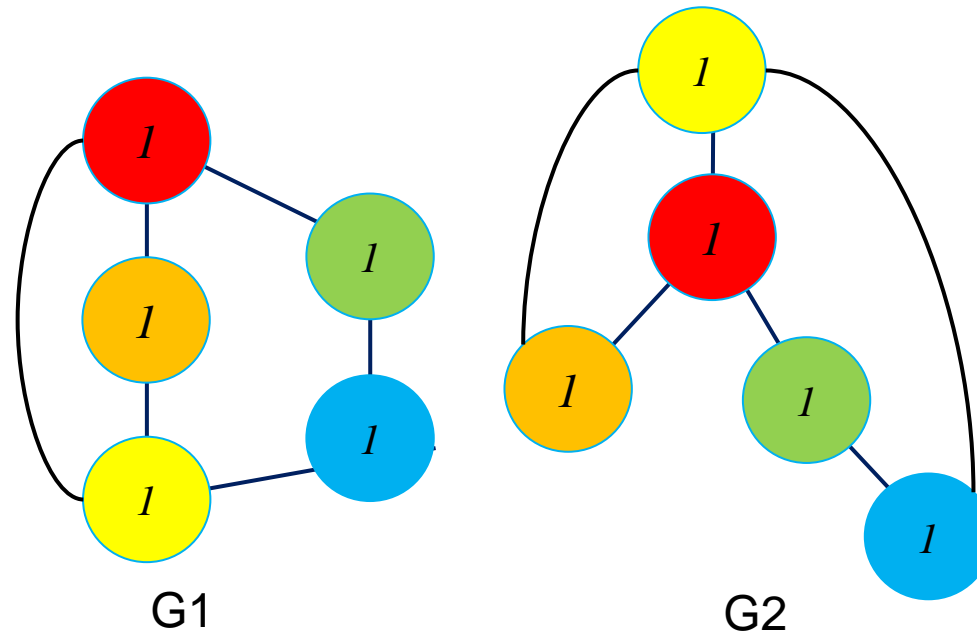
$t \leftarrow 0$;

repeat

    for $v_i \in \mathcal{V}$ **do**

        $h_i^{(t+1)} \leftarrow \text{hash}\left(\sum_{j \in \mathcal{N}_i} h_j^{(t)}\right)$;
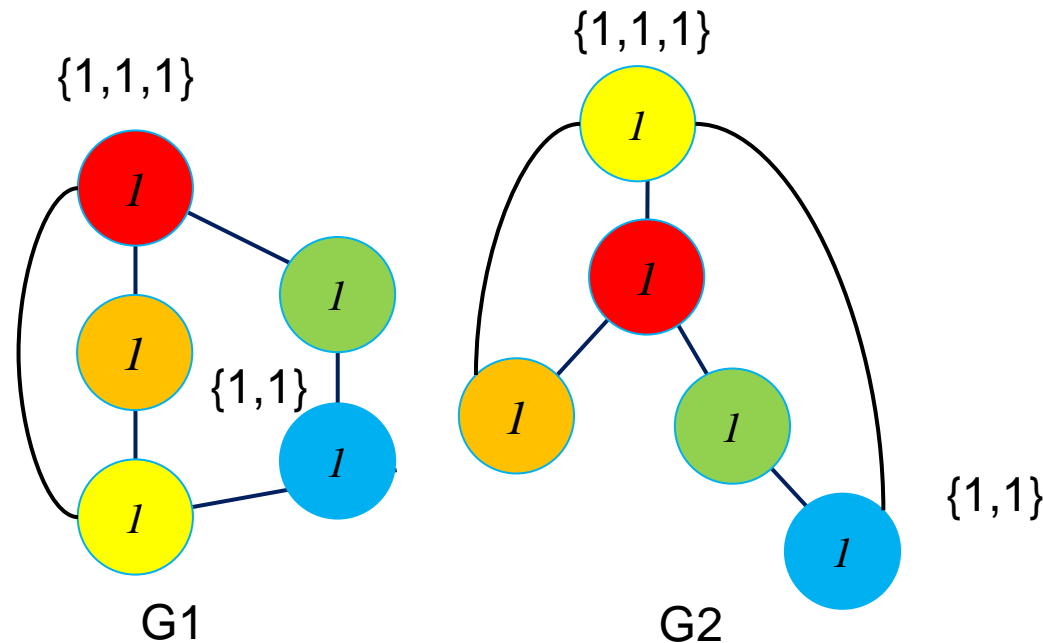
    $t \leftarrow t + 1$;
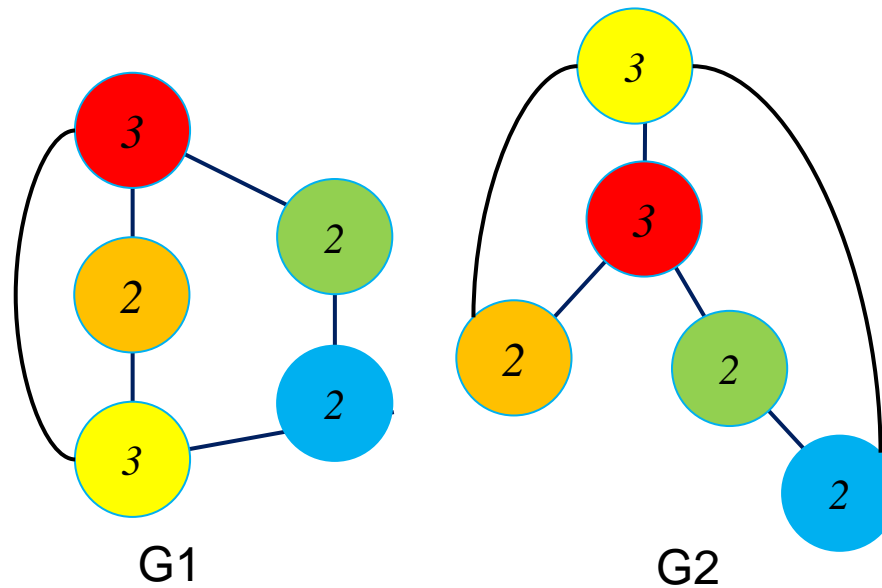
until *stable node coloring is reached*;

➢ We will apply the Weisfeiler-Lehman isomorphism test to these graphs as a means of illustrating the test.
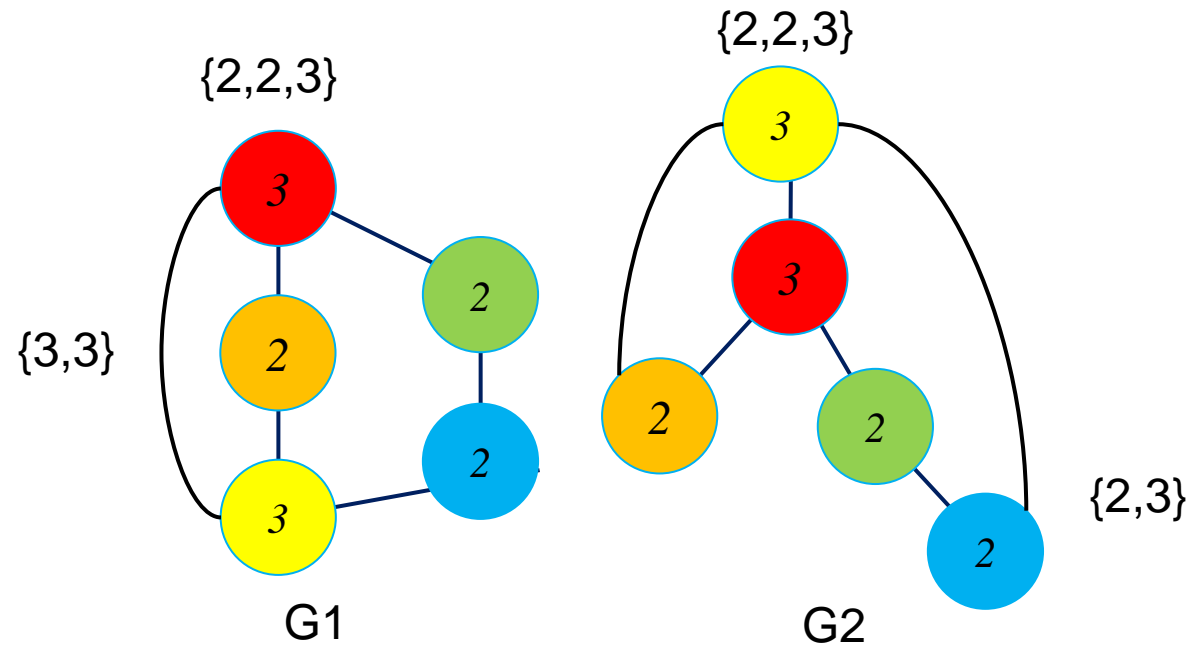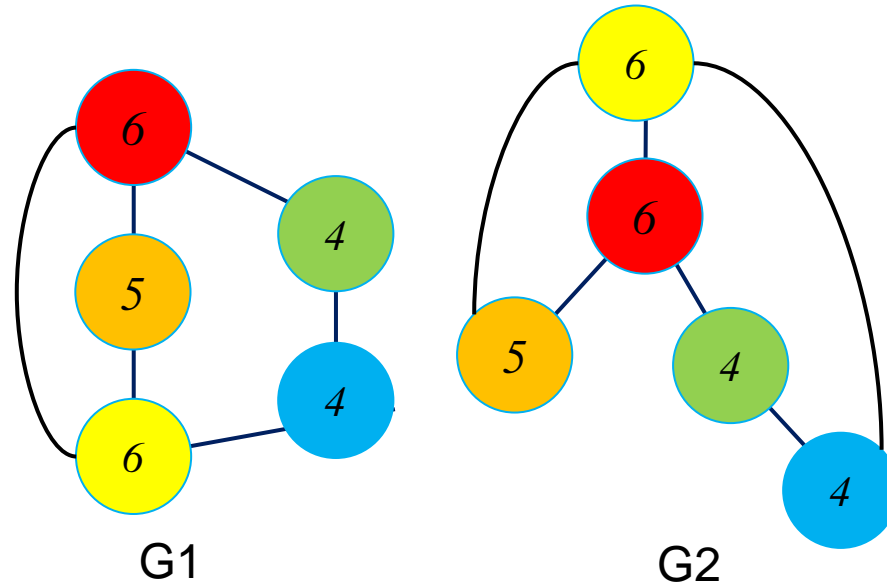
➢ Step 1: Set node label =1 for all nodes
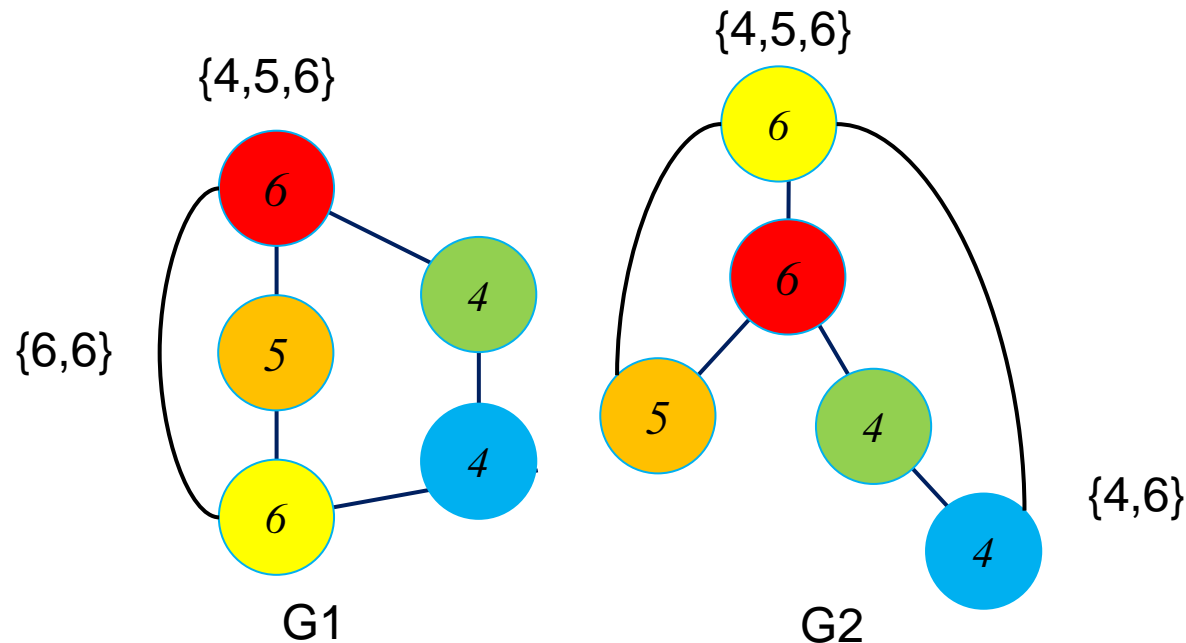

G1   G2

➢ We will apply the Weisfeiler-Lehman isomorphism test to these graphs as a means of illustrating the test.

➢ Step 1: Set node label =1 for all nodes

➢ Step 2: Compute multiset of the neighboring nodes' compressed labels.

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G1

G2

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- ➢ Step 2: Compute multiset of the neighboring nodes' compressed labels.

- ➢ Step 3: Continuous….

- ➢ Step 4: Since the partition of nodes by compressed label has not changed, we may terminate the algorithm here

G1   G2
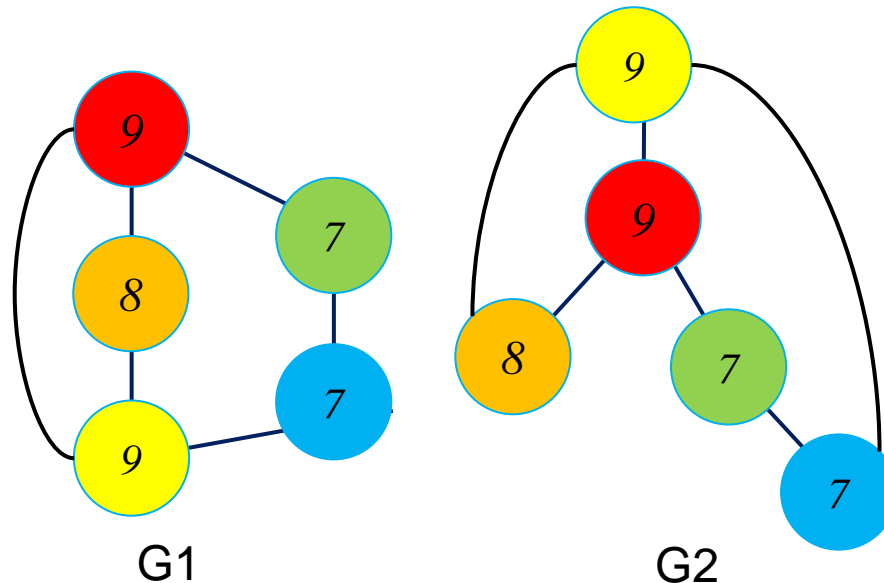
➢ Converts a given numeric or alphanumeric key to a small practical integer value.

➢ Hash function $h: (\{0,1\}^k \rightarrow \{0,1\}^{t(k)}$

  ➢ Compresses.

➢ Main goal: a little bit of difference in inputs will cause a big difference in outputs.
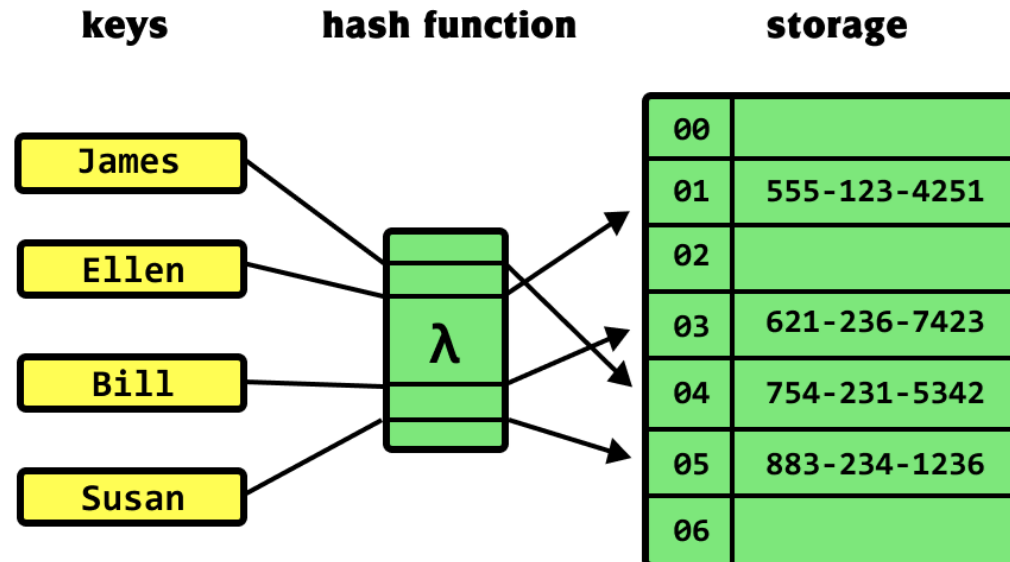
- ➢ Counts the number of matchings between subgraphs of bounded size in two graphs.

  - ➢ Can apply to graphs that contain node labels, edge labels, node attributes or edge attributes.

- ➢ Given two graphs $G = (V, E)$ and $G' = (V', E')$.

- ➢ Let $B(G, G')$ denote the set of all bijections between sets $S \subseteq V$ and $S' \subseteq V'$. $\lambda: B(G, G') \to \mathbb{R}^+$ be a weight function.

- ➢ The subgraph matching kernel is

$$k(G, G') = \sum_{\phi \in \mathcal{B}(G, G')} \lambda(\phi) \prod_{v \in S} \kappa_V(v, \phi(v)) \prod_{e \in S \times S} \kappa_E(e, \psi(e))$$

Where $S = dom(\phi)$ and K_V, K_E are kernel functions defined on vertices and edges.

네트워크 과학 연구실
NETWORK SCIENCE LAB

가톨릭대학교
THE CATHOLIC UNIVERSITY OF KOREA

➢ The common subgraph isomorphism kernel:

$$\kappa_V(v, v') = \begin{cases} 1, & \text{if } \ell(v) \equiv \ell(v'), \\ 0, & \text{otherwise and} \end{cases}$$

$$\kappa_E(e, e') = \begin{cases} 1, & \text{if } e \in E \wedge e' \in E' \wedge \ell(e) \equiv \ell(e') \text{ or } e \notin E \wedge e' \notin E', \\ 0, & \text{otherwise.} \end{cases}$$

➡ counts the number of isomorphic subgraphs contained in two graphs.
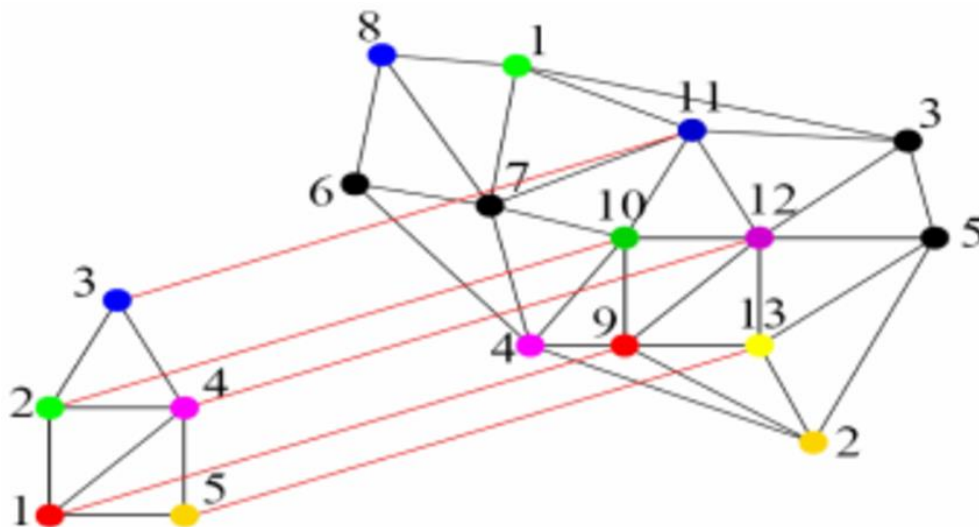
➢ Find Graphlet kernels size 3:

```python
import networkx as nx
import itertools
import matplotlib.pyplot as plt

g = nx.Graph()
g.add_edge(1,2)
g.add_edge(1,3)
g.add_edge(1,7)
g.add_edge(2,4)
g.add_edge(3,4)
g.add_edge(3,5)
g.add_edge(3,6)
g.add_edge(4,5)
g.add_edge(5,6)
g.add_edge(6,7)

target = nx.Graph()
target.add_edge(1,2)
target.add_edge(2,3)

colors = ['#DE7A6D', '#17BDF0',  '#3B88E9', '#212B83', '#EA43F3', '#EA3D11', '#C6A8C9', '#96FE21',
          '#C53A08', '#56B059', '#8EA7A2', '#BF9207', '#006843', '#2E68EA']
for sub_nodes in itertools.combinations(g.nodes(),len(target.nodes())):
    subg = g.subgraph(sub_nodes)
    if nx.is_connected(subg) and nx.is_isomorphic(subg, target):
        print(subg.edges())
        visualize_subgraph(subg, subg.nodes(), colors[i])
```
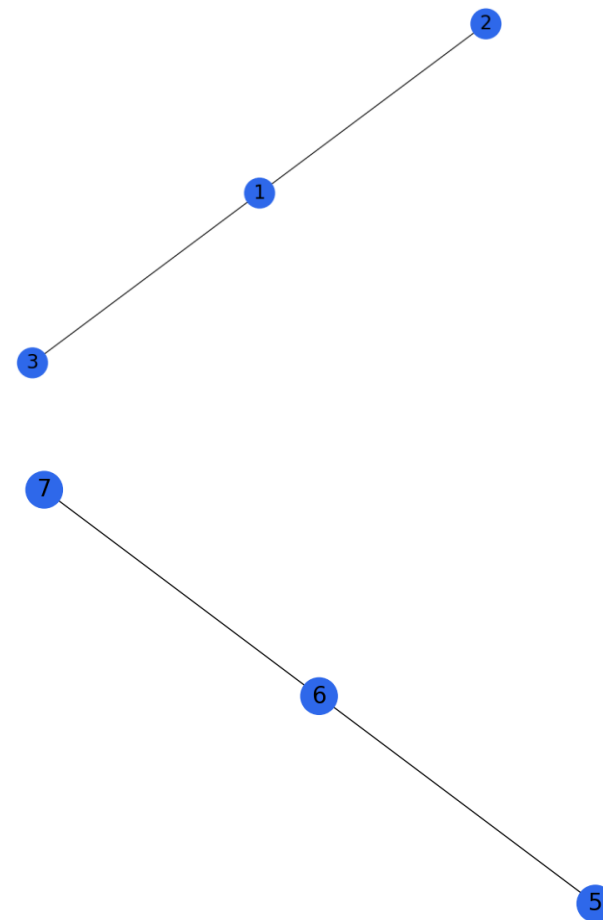
Shortest Path

Consider 2 molecules H20 and H30, an ion of water produced by protonation. Compute the Shortest Path Kernel.

The number are proximity same to each other, meaning that 2 molecules has same graph kernel.

```python
from grakel import Graph
from grakel.kernels import ShortestPath
import numpy as np

H2O_adjacency = [[0, 1, 1], [1, 0, 0], [1, 0, 0]]
H2O_node_labels = {0: 'O', 1: 'H', 2: 'H'}
H2O = Graph(initialization_object=H2O_adjacency, node_labels=H2O_node_labels)

H3O_adjacency = [[0, 1, 1, 1], [1, 0, 0, 0], [1, 0, 0, 0], [1, 0, 0, 0]]
H3O_node_labels = {0: 'O', 1: 'H', 2: 'H', 3:'H'}
H3O = Graph(initialization_object=H3O_adjacency, node_labels=H3O_node_labels)

sp_kernel = ShortestPath(normalize=True)
g1_sp = sp_kernel.fit_transform([H2O])
g2_sp = sp_kernel.transform([H3O])
print(g1_sp,g2_sp)

H2O_adjacency = np.matrix([[0, 1, 1], [1, 0, 0], [1, 0, 0]])
H3O_adjacency = np.matrix([[0, 1, 1, 1], [1, 0, 0, 0], [1, 0, 0, 0], [1, 0, 0, 0]])
G_h20=nx.from_numpy_array(H2O_adjacency)
nx.draw(G_h20)
```
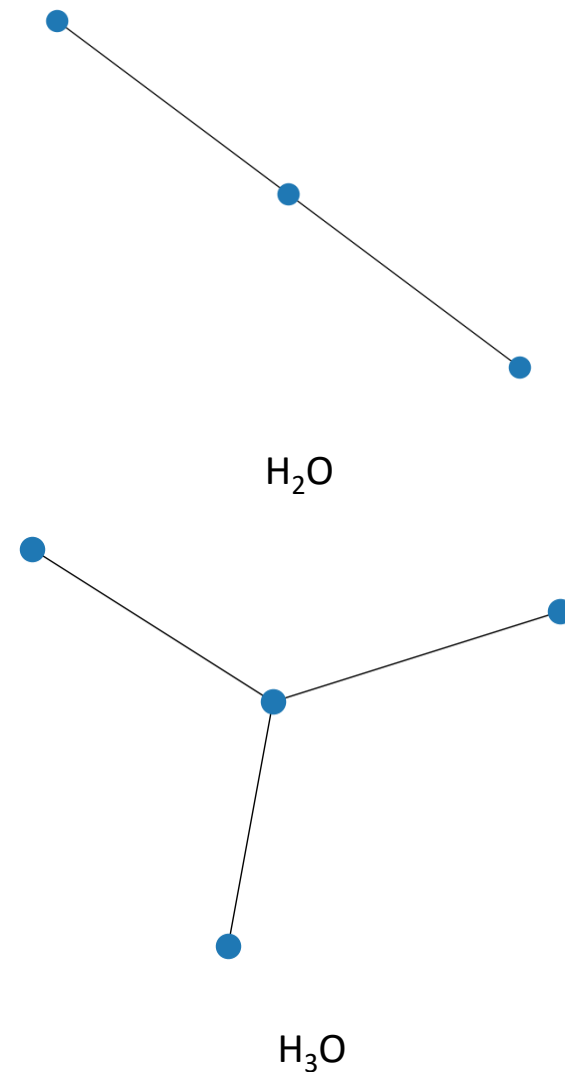
[[1.]] [[0.94280904]]

H_2O

H_3O

Random Walk

Consider 2 molecules Dimethyl_Ether and Ethanol. Compute the Random Walk Kernel.

The number are proximity same to each other, meaning that 2 molecules has same graph kernel.

```python
from grakel import Graph
from grakel.kernels import RandomWalk
import numpy as np

Ethanol_adjacency = [[0, 0, 0, 0, 0, 0, 1, 0, 0],
                     [0, 0, 0, 0, 0, 0, 1, 0, 0],
                     [0, 0, 0, 0, 0, 0, 0, 1, 0],
                     [0, 0, 0, 0, 0, 0, 0, 0, 1],
                     [0, 0, 0, 0, 0, 0, 0, 1, 0],
                     [0, 0, 0, 0, 0, 0, 1, 0, 0],
                     [1, 1, 0, 0, 0, 1, 0, 1, 0],
                     [0, 0, 1, 0, 1, 0, 1, 0, 1],
                     [0, 0, 0, 1, 0, 0, 0, 1, 0],
                     ]
Ethanol_node_labels = {0: 'H', 1: 'H', 2: 'H', 3:'H', 4:'H', 5:'H', 6:'C', 7:'C', 8 :'O'}

Ethanol = Graph(initialization_object=Ethanol_adjacency, node_labels=Ethanol_node_labels)

Dimethyl_Ether_adjacency = [[0, 0, 0, 0, 0, 0, 1, 0, 0],
                     [0, 0, 0, 0, 0, 0, 1, 0, 0],
                     [0, 0, 0, 0, 0, 0, 0, 0, 1],
                     [0, 0, 0, 0, 0, 0, 0, 0, 1],
                     [0, 0, 0, 0, 0, 0, 0, 0, 1],
                     [0, 0, 0, 0, 0, 0, 1, 0, 0],
                     [1, 1, 0, 0, 0, 1, 0, 1, 0],
                     [0, 0, 0, 0, 0, 0, 1, 0, 1],
                     [0, 0, 1, 1, 1, 0, 0, 1, 0],
                     ]
Dimethyl_Ether_node_labels = {0: 'H', 1: 'H', 2: 'H', 3:'H', 4:'H', 5:'H', 6:'C', 7:'O', 8 :'C'}
Dimethyl_Ether = Graph(initialization_object=Dimethyl_Ether_adjacency, node_labels=Dimethyl_Ether_node_labels)

rw_kernel = RandomWalk(normalize=True)
g1_rw = rw_kernel.fit_transform([Ethanol])
g2_rw = rw_kernel.transform([Dimethyl_Ether])
print(g1_rw,g2_rw)
```
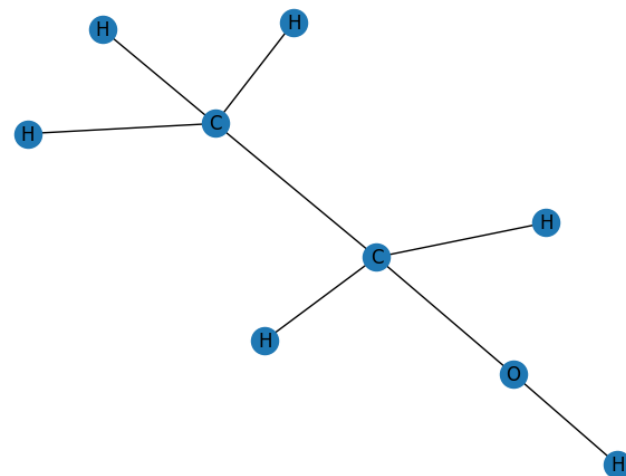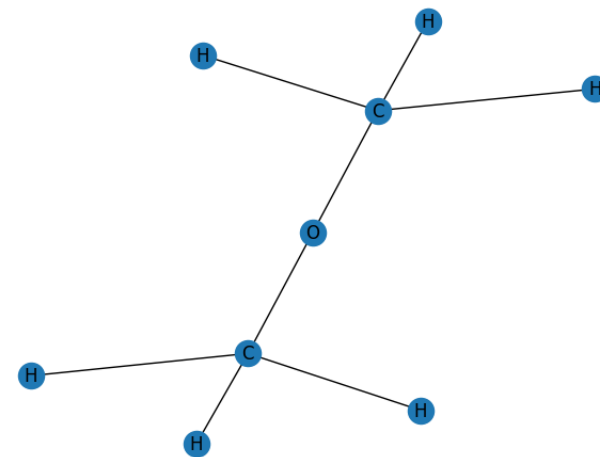
[[1.]] [[0.99860269]]

Ethanol (C_2H_5OH)

Dimethyl Ether (CH_3OCH_3)

➢ **Check isomorphism mapping from undirected graph G1 to undirected graph G2**

```python
import networkx as nx
import numpy as np
from networkx.algorithms import isomorphism
```

```python
# Generate 2 graphs
G1 = nx.Graph()
G2 = nx.Graph()

G1.add_nodes_from(range(0,7))
G2.add_nodes_from(range(0,7))
G1.add_edges_from([(0,1), (1,2), (2,3), (3,4), (2,5), (5,6)])
G2.add_edges_from([(0,1), (1,4), (2,4), (2,6), (4,3), (3,5)])

# Mapping 2 graph G1 and G2
GM = isomorphism.GraphMatcher(G2,G1)
print(f" Checking graph isomorphic: {GM.is_isomorphic()}")
GM.mapping
```
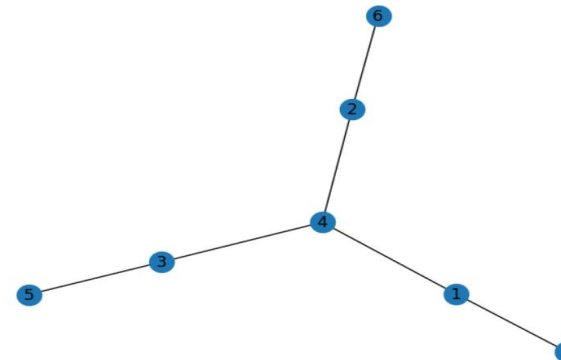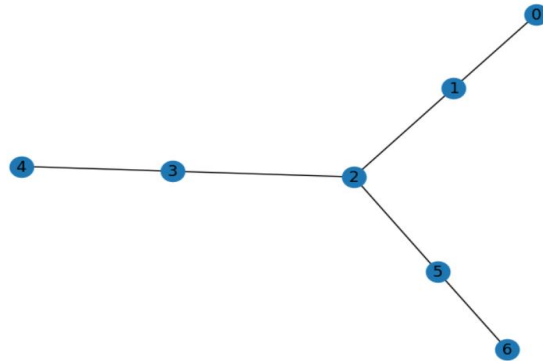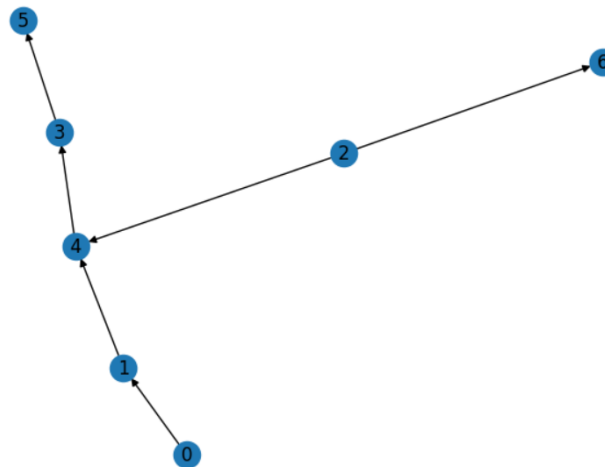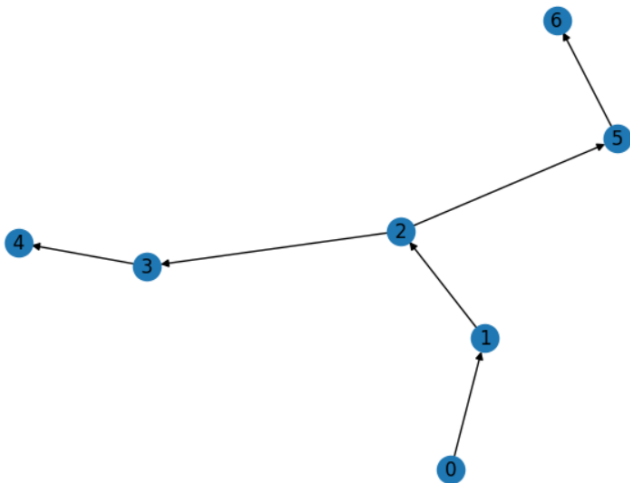
```
Checking graph isomorphic: True

{0: 0, 1: 1, 4: 2, 2: 3, 6: 4, 3: 5, 5: 6}
```

➢ **In directed graph:**

```python
import networkx as nx
import numpy as np
from networkx.algorithms import isomorphism
```
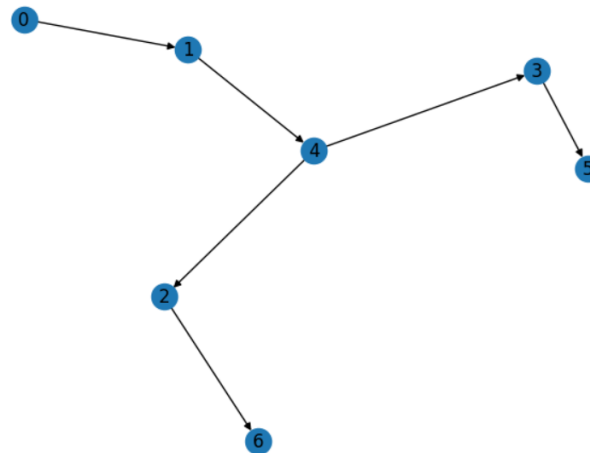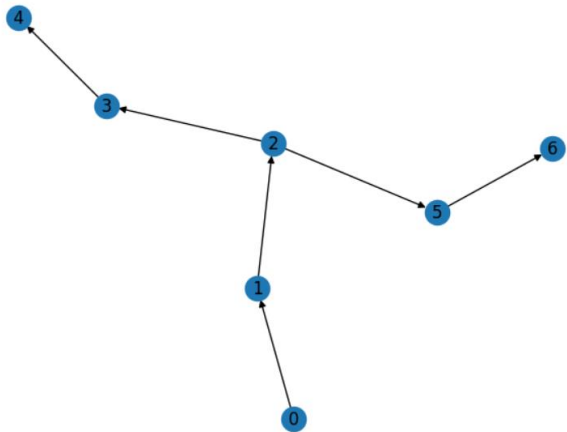
```python
# Generate 2 graphs
G1 = nx.DiGraph()
G2 = nx.DiGraph()

G1.add_nodes_from(range(0,7))
G2.add_nodes_from(range(0,7))
G1.add_edges_from([(0,1), (1,2), (2,3), (3,4), (2,5), (5,6)])
G2.add_edges_from([(0,1), (1,4), (2,4), (2,6), (4,3), (3,5)])

# Mapping 2 graph G1 and G2
GM = isomorphism.GraphMatcher(G2,G1)
print(f" Checking graph isomorphic: {GM.is_isomorphic()}")
GM.mapping
```

```
Checking graph isomorphic: False

{}
```

➢ **Another example for directed graph**

```python
# Generate 2 directed graphs
G1 = nx.DiGraph()
G2 = nx.DiGraph()

G1.add_nodes_from(range(0,7))
G2.add_nodes_from(range(0,7))
G1.add_edges_from([(0,1), (1,2), (2,3), (3,4), (2,5), (5,6)])
G2.add_edges_from([(0,1), (1,4), (4,2), (2,6), (4,3), (3,5)])

# Mapping 2 graph G1 and G2
GM = isomorphism.GraphMatcher(G2,G1)
print(f" Checking graph isomorphic: {GM.is_isomorphic()}")
GM.mapping
```

```python
import networkx as nx
import numpy as np
from networkx.algorithms import isomorphism
```

```
Checking graph isomorphic: True

{0: 0, 1: 1, 4: 2, 2: 3, 6: 4, 3: 5, 5: 6}
```

➢ Weisfeiler Lehman (WL) – hash function: Undirected graph
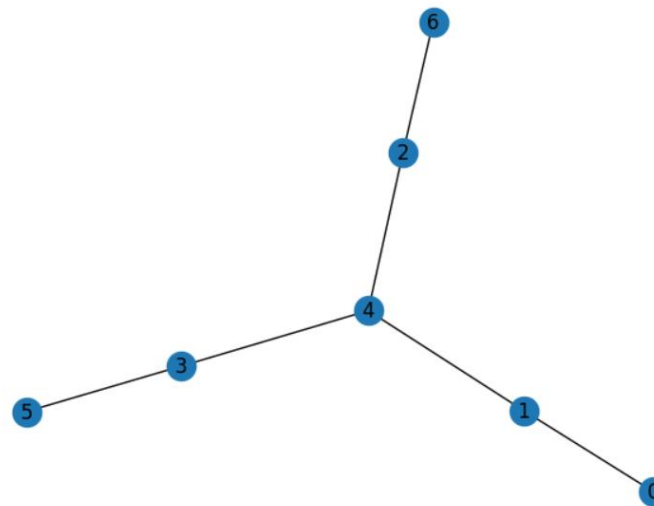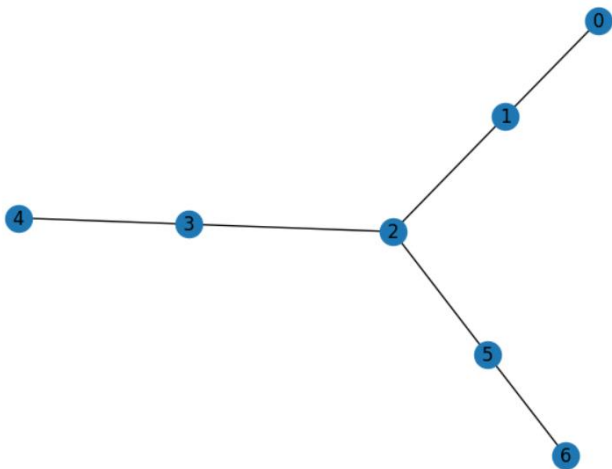
```python
import networkx as nx

G1 = nx.Graph()
G2 = nx.Graph()

G1.add_nodes_from(range(0,7))
G2.add_nodes_from(range(0,7))
G1.add_edges_from([(0,1), (1,2), (2,3), (3,4), (2,5), (5,6)])
G2.add_edges_from([(0,1), (1,4), (2,4), (2,6), (4,3), (3,5)])

g1_hash = nx.weisfeiler_lehman_graph_hash(G1)
g2_hash = nx.weisfeiler_lehman_graph_hash(G2)

# g1_hash and g2_hash are equal when they are isomorphic
print(f"First  graph hash: {g1_hash}")
print(f"Second graph hash: {g2_hash}")
print(f"Checking graph isomorphic: {g1_hash==g2_hash}")
```

```
First  graph hash: 61f645001e86ad8a32357cc828ae33cb
Second graph hash: 61f645001e86ad8a32357cc828ae33cb
Checking graph isomorphic: True
```

➢ Weisfeiler Lehman (WL) – hash function : Directed graph
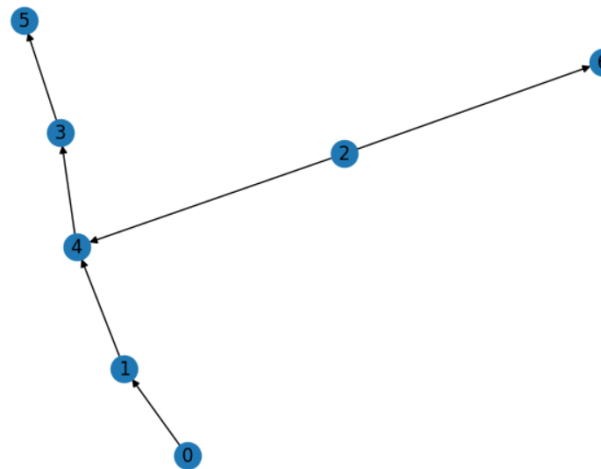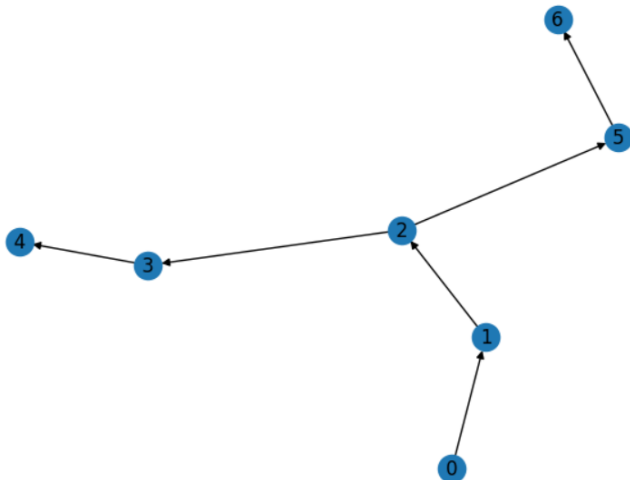
```python
import networkx as nx

G1 = nx.DiGraph()
G2 = nx.DiGraph()

G1.add_nodes_from(range(0,7))
G2.add_nodes_from(range(0,7))
G1.add_edges_from([(0,1), (1,2), (2,3), (3,4), (2,5), (5,6)])
G2.add_edges_from([(0,1), (1,4), (2,4), (2,6), (4,3), (3,5)])

g1_hash = nx.weisfeiler_lehman_graph_hash(G1)
g2_hash = nx.weisfeiler_lehman_graph_hash(G2)

# g1_hash and g2_hash are equal when they are isomorphic
print(f"First  graph hash: {g1_hash}")
print(f"Second graph hash: {g2_hash}")
print(f"Checking graph isomorphic: {g1_hash==g2_hash}")
```

```
First  graph hash: 7d77c6474bd3835fe0f19ac0f27881e2
Second graph hash: 9dacf03794ba1624e5a8f373848e5ec5
Checking graph isomorphic: False
```