

# Computer Vision 1 - Final Project Part 1

## Bag-of-Words based Image Classification

### 30 Points

March 14, 2017

All the files should be zipped and sent to **computervision1.uva(at)gmail.com** before **03-04-2017 , 23.59** (Amsterdam Time).

## 1 Introduction

The goal of the assignment is to implement a system for image classification; in other words, this system should tell if there is an object of given class in an image. We will perform four-class (airplanes, motorbikes, faces, and cars) image classification based on bag-of-words approach. The provided data file contains training and test subdirectories for each category (all images are taken from Caltech Vision Group). For each class, test subdirectories contain 50 images, and training subdirectories contain up to 500 images.

### 1.1 Training Phase

Training must be conducted over a (training) dataset in which there exist at least 50 training images per class (take either the first 50 ones or a random subset of 50). Keep in mind that using more samples in training will (almost certainly) result in better performance. However, if your computational resources are limited and your system is slow, it's OK to use less training data to save time.

*Hint:* In order to debug your code use a small amount of input images/descriptors. Once you make sure everything works properly, you can run your code for the experiment using all the data points.

### 1.2 Testing Phase

You have to test your system using the specified subset of test images which will be supplemented separately. The instructions regarding how to use this set will be released together with the meta data. (**Note:** This is to ensure that we can verify your results while grading.)

## 2 Bag-of-Words based Image Classification

Bag-of-Words based Image Classification system contains the following steps:

1. Feature extraction and description
2. Building a visual vocabulary
3. Quantize features using visual dictionary (encoding)
4. Representing images by frequencies of visual words
5. Classification

We will consider each step in detail.

### 2.1 Feature Extraction and Description

SIFT descriptors can be extracted from key points. As an alternative to key points, SIFT descriptors can be extracted densely. You can use VLFeat functions for dense SIFT (e.g. `vl_dsift`) and key points SIFT descriptor extraction (e.g. `vl_sift`).

**Note:** As in the previous assignment, you can download and install VLFeat library from <http://www.vlfeat.org/>.

Moreover, it is expected that you implement all the steps also for RGBSIFT, rgbSIFT and opponentSIFT.

*Hint:* Check out the MATLAB API for further information in the following link:

<http://www.vlfeat.org/matlab/matlab.html>

*Hint:* Use VLFeat functions in order to extract SIFT descriptors while working on RGBSIFT and etc.

### 2.2 Building Visual Vocabulary

Here we will obtain visual words by clustering feature descriptors, so each cluster center is a visual word. Take a subset of all training images (this subset should contain images from ALL categories), extract SIFT descriptors from all of these images, and run k-means clustering (a script for k-means clustering is provided to you, but you can use any implementation you like) on these SIFT descriptors to build visual vocabulary. Take about half of train images from each class to calculate visual dictionary (around 1000 images), however, you can also use less images, say 100 from each class. Please, remember first to debug all the code with a small amount of input images and only when you are sure that code functions correctly run it for training over the larger data. Pre-defined cluster numbers will be the size of your vocabulary. Set the vocabulary size to 400, and experiment with several different sizes (800, 1600, 2000 and 4000).



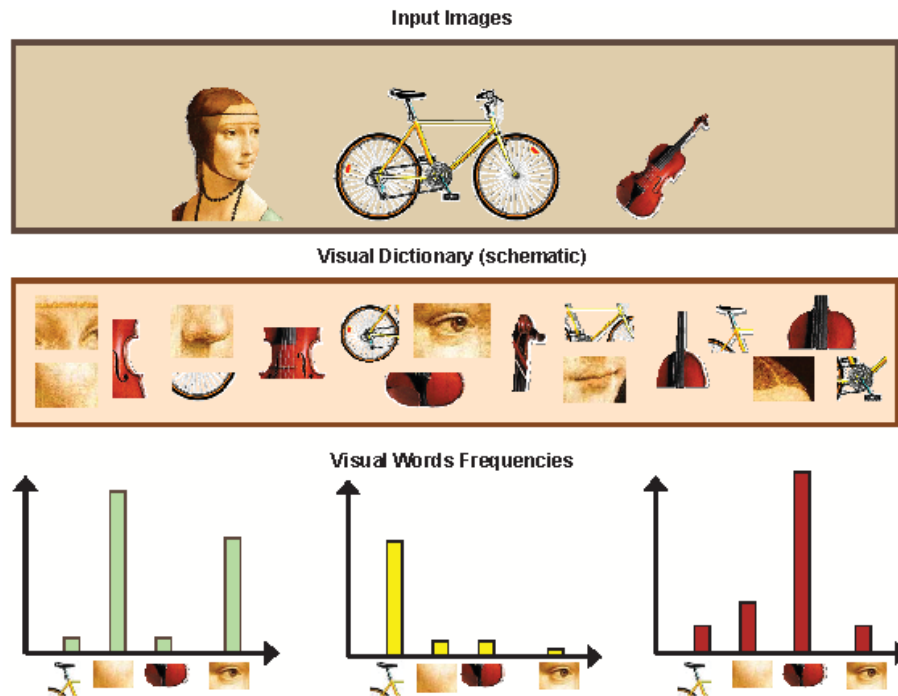


Figure 2: Schematic representation of Bag-Of-Words system.

vector machine classifier to assign it to the most probable object class. (Note that for proper SVM scores you need to use cross-validation to get a proper estimate of the SVM parameters. In this assignment you do not have to do this cross-validation.)

For the second part of the assignment we will use LIBLINEAR library <https://www.csie.ntu.edu.tw/~cjlin/liblinear/> to use support vector machines. So, it is better if you also use it for this part to get familiar with the library. For this part, you can use other SVM libraries if you like.

## 2.6 Evaluation

To evaluate your system you should take all test images from all classes and rank them based on each binary classifier, so you should classify each test image with each classifier and then sort them based on the classification score. As a result you will have four lists of test images. Ideally, you would have images with airplanes on the top of your list which is created based on your airplane classifier, and images with cars on the top of your list which is created based on your car classifier, and so on.

In addition to the qualitative analysis you should measure the performance of the system quantitatively with the Mean Average Precision over all classes. The Average Precision for a

single class  $c$  is defined as

$$\frac{1}{m_c} \sum_{i=1}^n \frac{f_c(x_i)}{i}, \quad (1)$$

where  $n$  is the number of images ( $n = 50 \times 4 = 200$ ),  $m$  is the number of images of class  $c$  ( $m_c = 50$ ),  $x_i$  is the  $i^{th}$  image in the ranked list  $X = \{x_1, x_2, \dots, x_n\}$ , and finally,  $f_c$  is a function which returns the number of images of class  $c$  in the first  $i$  images if  $x_i$  is of class  $c$ , and 0 otherwise. For example, if we want to retrieve  $R$  and we get the following sequence:  $[R, R, T, R, T, T, R]$ , then  $n = 7$ ,  $m = 4$ , and  $AP(R, R, T, R, T, T, R) = \frac{1}{4} \left( \frac{1}{1} + \frac{2}{2} + \frac{0}{3} + \frac{3}{4} + \frac{0}{5} + \frac{0}{6} + \frac{4}{7} \right)$ .

### 3 Deliverables

1. Students are expected to prepare a report for this project. The report should include the following:
  - Analysis of the results for different settings such as key points vs dense sampling
  - mAP based on vocabulary size
  - mAP based on SIFT descriptor used (e.g., RGB-SIFT, rgb-SIFT and etc.)
  - mAP based on number of training samples used
  - mAP based on kernel choice for SVM (e.g. linear, RBF and etc.).
2. A demo function which runs the whole system should be prepared and submitted with all other implemented functions (excluding VLFeat and LIBSVM functions).
3. You are supposed to fill in the template html file, which is provided, with four ranked lists of test images as discussed in Section 2.6. This document should contain all your settings (e.g. size of visual vocabulary, number of positive and negative samples, and so on), Average Precision per class, and Mean Average Precision. You should submit a separate html for each descriptor type.

**Advice:** Having visual elements such as charts, graphs and plots are always useful for everyone. Please, keep this in mind while writing your reports.

**BONUS:** We will award groups who prove to put extra efforts into their project. By *extra* we mean one or more of the following:

- **[1 pts.]** Using another classification approach (such as k-Nearest Neighbor). You can simply use the features you extracted in this project.
- **[2 pts.]** Using another type of features other than SIFT.
- **[Up to 5 pts.]** Any other thing that you can think of or find from the literature that can boost the results.

In order to get the bonus, your submission should first satisfy the previous steps. You need to implement and explain the method and justify your reasoning. You can get at most 5 points from bonus part.