

EE 205003 Session 17

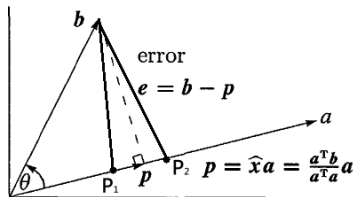
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Ch 4.2 Projections

Projection onto a line



Q: How do we find a point \mathbf{p} on the line (determined by vector \mathbf{a}) that is closest to \mathbf{b} ?

\mathbf{p} : intersection of a line through \mathbf{b} that is orthogonal to \mathbf{a}
($\mathbf{P}_1, \mathbf{P}_2$ have longer distance)

Ch 4.2 Projections

More precisely

Think of \mathbf{p} as an approximation of \mathbf{b} ,
then $\mathbf{e} = \mathbf{b} - \mathbf{p}$ is the error vector

Since \mathbf{p} is along the line of \mathbf{a}

$$\Rightarrow \mathbf{p} = \hat{x}\mathbf{a} \text{ for some } \hat{x}$$

Also, $\mathbf{a} \perp \mathbf{e}$

$$\Rightarrow \mathbf{a}^T(\mathbf{b} - \mathbf{p}) = \mathbf{a}^T(\mathbf{b} - \hat{x}\mathbf{a}) = 0$$

$$\Rightarrow \mathbf{a}^T\mathbf{a}\hat{x} = \mathbf{a}^T\mathbf{b} \Rightarrow \hat{x} = \frac{\mathbf{a}^T\mathbf{b}}{\mathbf{a}^T\mathbf{a}}$$

Now, we have

$$\mathbf{p} = \hat{x}\mathbf{a} = \mathbf{a}\hat{x} = \mathbf{a}\frac{\mathbf{a}^T\mathbf{b}}{\mathbf{a}^T\mathbf{a}}$$

(doubling \mathbf{b} doubles \mathbf{p} , doubling \mathbf{a} does NOT affect \mathbf{p})

Ch 4.2 Projections

Projection Matrix ($\mathbf{p} = P\mathbf{b}$)

$$\mathbf{p} = \mathbf{a} \frac{\mathbf{a}^T \mathbf{b}}{\mathbf{a}^T \mathbf{a}} = \underbrace{\frac{\mathbf{a} \mathbf{a}^T}{\mathbf{a}^T \mathbf{a}}}_{\mathbf{P}} \mathbf{b} \quad \begin{array}{l} \text{(For 3D)} \\ \mathbf{a} \ 3 \times 3 \\ \mathbf{P} = \frac{\mathbf{a} \mathbf{a}^T}{\mathbf{a}^T \mathbf{a}} \leftarrow \text{rank-one matrix} \\ \quad \quad \quad \leftarrow \text{a number} \end{array}$$

(Procedure : Find $\hat{x} \rightarrow \mathbf{p} \rightarrow P$)

Special case I : If $\mathbf{b} = \mathbf{a}$, $\hat{x} = 1$

$\Rightarrow P\mathbf{a} = \mathbf{a}$ (projection of \mathbf{a} onto \mathbf{a} is itself)

Special case II : If $\mathbf{b} \perp \mathbf{a}$, $\mathbf{a}^T \mathbf{b} = 0$

$\Rightarrow \mathbf{p} = \mathbf{0}$

Ch 4.2 Projections

Projection Matrix ($\mathbf{p} = P\mathbf{b}$) (cont.)

Note 1: col. space of P is spanned by \mathbf{a}
(\because for any \mathbf{b} , $P\mathbf{b}$ lies on the line determined by \mathbf{a})

Note 2: $\text{rank}(P) = 1$

Note 3 : P is symmetric

$$(P^T = (\frac{\mathbf{a}\mathbf{a}^T}{\mathbf{a}^T\mathbf{a}})^T = \frac{1}{\mathbf{a}^T\mathbf{a}}(\mathbf{a}\mathbf{a}^T)^T = \frac{\mathbf{a}\mathbf{a}^T}{\mathbf{a}^T\mathbf{a}} = P)$$

Note 4 : $P^2 = P$

$$(P^2\mathbf{b} = P\mathbf{b} \text{ or } P(P\mathbf{b}) = P\mathbf{b})$$

\because projection of a vector already on \mathbf{a} is itself)

Note 5 : $I - P$ is also a projection

$$((I - P)\mathbf{b} = \mathbf{b} - \mathbf{p} = \mathbf{e} \text{ in the left nullspace of } \mathbf{a} \because \mathbf{a}^T\mathbf{e} = 0)$$

(P : project onto one subspace

$I - P$: project onto the perpendicular subspace)

Ch 4.2 Projections

Q : Why project ?

$A\mathbf{x} = \mathbf{b}$ may have no solution

↓
always in col. space of A unlikely that $\mathbf{b} \in \mathbf{C}(A)$

If not, project \mathbf{b} onto $\mathbf{p} \in \mathbf{C}(A)$
then solve $A\hat{\mathbf{x}} = \mathbf{p}$

Ch 4.2 Projections

Projection onto a Subspace

Projection onto a plane (in \mathbb{R}^3)

If $\mathbf{a}_1, \mathbf{a}_2$ are basis of a plane

\Rightarrow the plane is $\mathbf{C}(A)$ of $A = [\mathbf{a}_1, \mathbf{a}_2]$

In general, for a subspace $\mathbf{S} \subseteq \mathbb{R}^m$ with

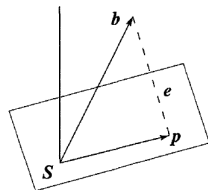
n independent basis $\mathbf{a}_1, \dots, \mathbf{a}_n$

\Rightarrow subspace is $\mathbf{C}(A)$ of $A_{m \times n} = [\mathbf{a}_1, \dots, \mathbf{a}_n]$

Ch 4.2 Projections

Problem : Find \mathbf{p} in \mathbf{S} closest to \mathbf{b}

Since $\mathbf{p} \in \mathbf{C}(A)$, $\mathbf{p} = A\hat{\mathbf{x}} = \hat{x}_1\mathbf{a}_1 + \cdots + \hat{x}_n\mathbf{a}_n$
(want to find \hat{x}_i)



$$\begin{aligned} \mathbf{p} &= A\hat{\mathbf{x}} \\ &= A(A^T A)^{-1} A^T \mathbf{b} \Rightarrow \mathbf{e} = \mathbf{b} - \mathbf{p} \perp \mathbf{S} \\ &= P\mathbf{b} \quad \text{or } \mathbf{b} - A\hat{\mathbf{x}} \perp \mathbf{S} \end{aligned}$$

$\Rightarrow \mathbf{e} = \mathbf{b} - A\hat{\mathbf{x}}$ perpendicular with $\mathbf{a}_1, \cdots, \mathbf{a}_n$

$$\begin{aligned} \Rightarrow \begin{aligned} \mathbf{a}_1^T(\mathbf{b} - A\hat{\mathbf{x}}) &= 0 \\ \mathbf{a}_2^T(\mathbf{b} - A\hat{\mathbf{x}}) &= 0 \\ &\vdots \\ \mathbf{a}_n^T(\mathbf{b} - A\hat{\mathbf{x}}) &= 0 \end{aligned} \quad \text{or} \quad \begin{bmatrix} -\mathbf{a}_1^T \\ \vdots \\ -\mathbf{a}_n^T \end{bmatrix} \begin{bmatrix} \mathbf{b} - A\hat{\mathbf{x}} \end{bmatrix} = \begin{bmatrix} 0 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} \Rightarrow A^T(\mathbf{b} - A\hat{\mathbf{x}}) &= 0 \Rightarrow A^T A\hat{\mathbf{x}} = A^T \mathbf{b} \\ &\parallel \\ &\mathbf{e} \text{ (in the null space of } A) \end{aligned}$$

Ch 4.2 Projections

Find $\hat{\mathbf{x}}$

$$\hat{\mathbf{x}} = (A^T A)^{-1} A^T \mathbf{b}$$

(Q: Is $A^T A$ invertible ?

Yes, if n columns of A are linear independent)

(will prove this later)

Find \mathbf{p}

$$\mathbf{p} = A\hat{\mathbf{x}} = \underbrace{A(A^T A)^{-1} A^T}_{\text{projection matrix } P} \mathbf{b}$$

projection matrix $P = A(A^T A)^{-1} A^T$

(Find $\hat{\mathbf{x}} \rightarrow \mathbf{p} \rightarrow P$)

Ch 4.2 Projections

Alternative derivation

1. our subspace is $\mathbf{C}(A)$
2. error vector $\mathbf{e} = \mathbf{b} - A\hat{\mathbf{x}} \perp \mathbf{C}(A)$
3. so \mathbf{e} in left null space of A
($\mathbf{C}(A)$ and $\mathbf{N}(A^T)$) are orthogonal components)
 $\Rightarrow A^T \mathbf{e} = A^T (\mathbf{b} - A\hat{\mathbf{x}}) = \mathbf{0}$
(\mathbf{b} splitted into \mathbf{p} & \mathbf{e})
($\in \mathbf{C}(A)$) ($\in \mathbf{N}(A^T)$)

Special cases

1. $\mathbf{b} \perp \mathbf{C}(A) : \mathbf{b} \in \mathbf{N}(A^T) \text{ \& } P\mathbf{b} = \mathbf{0}$
2. $\mathbf{b} \in \mathbf{C}(A) : A\mathbf{x} = \mathbf{b} \text{ for some } \mathbf{x} \text{ \& } P\mathbf{b} = \mathbf{b}$

Ch 4.2 Projections

Q: Can we further simplify $P = A(A^T A)^{-1} A^T$?

$$\begin{aligned} P &= A(A^T A)^{-1} A^T = A(A^{-1}(A^T)^{-1}) A^T \\ &= (A A^{-1})((A^T)^{-1} A^T) \\ &= I ? \end{aligned}$$

Wrong ! A is rectangular $\Rightarrow A$ has no inverse matrix !

Fact $P = P^T$, $P^2 = P$ (still true for general \mathbf{v})

distance from \mathbf{b} to subspace = $\|\mathbf{e}\|$

Ch 4.2 Projections

Fact A is invertible iff A has linear independent columns

pf : First, we want to show that $A^T A$ and A have same nullspace

if \mathbf{x} is in $\mathbf{N}(A)$, then $A\mathbf{x} = \mathbf{0}$

$$\Rightarrow A^T A\mathbf{x} = A^T(\mathbf{0}) = \mathbf{0}$$

$$\Rightarrow \mathbf{x} \text{ in } \mathbf{N}(A^T A)$$

if \mathbf{x} in $\mathbf{N}(A^T A)$, then $A^T A\mathbf{x} = \mathbf{0}$

$$\Rightarrow \mathbf{x}^T A^T A\mathbf{x} = \mathbf{x}^T \mathbf{0} = 0$$

$$\Rightarrow \|A\mathbf{x}\|^2 = 0 \Rightarrow A\mathbf{x} = \mathbf{0} \Rightarrow \mathbf{x} \in \mathbf{N}(A)$$

So A & $A^T A$ have same nullspace

Now, if A has independent columns

then $\text{rank}(A) = n \Rightarrow \mathbf{N}(A) = \{\mathbf{0}\}$

$$\Rightarrow \mathbf{N}(A^T A) = \{\mathbf{0}\} \Rightarrow A^T A \text{ is invertible}$$

If $A^T A$ is invertible, then $A^T A$ has independent columns

$$\Rightarrow \mathbf{N}(A^T A) = \{\mathbf{0}\} \Rightarrow \mathbf{N}(A) = \{\mathbf{0}\}$$

$$\Rightarrow A \text{ has independent columns}$$

Ch 4.2 Projections

Ex3 : (on p.211, textbook)

$$\text{If } A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 6 \\ 0 \\ 0 \end{bmatrix}, \text{ find } \hat{\mathbf{x}}, \mathbf{p} \text{ \& } P$$

Normal equation :

$$A^T A \hat{\mathbf{x}} = A^T \mathbf{b}$$

$$\Rightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} \hat{\mathbf{x}} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} 6 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 3 & 3 \\ 3 & 5 \end{bmatrix} \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix} = \begin{bmatrix} 6 \\ 0 \end{bmatrix} \Rightarrow \hat{\mathbf{x}} = \begin{bmatrix} 5 \\ -3 \end{bmatrix}$$

Ch 4.2 Projections

Ex3 : (on p.211, textbook) (cont.)

$$\mathbf{p} = A\hat{\mathbf{x}} = 5 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - 3 \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 5 \\ 2 \\ -1 \end{bmatrix}$$

$$\mathbf{e} = \mathbf{b} - \mathbf{p} = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \text{ (indeed } \perp \text{ both columns of } A\text{)}$$

To find \mathbf{p} for every \mathbf{b} , we need P

$$P = A(A^T A)^{-1} A^T$$

$$(A^T A)^{-1} = \frac{1}{6} \begin{bmatrix} 5 & -3 \\ -3 & 3 \end{bmatrix} \Rightarrow P = \begin{bmatrix} 5 & 2 & -1 \\ 2 & 2 & 2 \\ -1 & 2 & 5 \end{bmatrix}$$

(check : $P\mathbf{b} = \mathbf{p}$ & $P^2 = P$, $P^T = P$)