

# Linear Algebra, EE 10810/EECS 205004

1st Exam  
(Dated: Fall, 2021)

Total scores: 120%

-6

1. ( $\pm 30\%$ ) [True or False] Note that: a Correct answer gaining +3%; but a Wrong answer loosing -3% (答錯倒扣).

- (1) : In any vector space,  $a\vec{x} = b\vec{x}$  implies that  $a = b$ .  $\checkmark$
- (2) The zero vector space has no basis.  $\checkmark$
- (3) Any set containing the zero vector is linearly dependent.  $\checkmark$
- (4) If  $\hat{T}$  is linear, then  $\hat{T}(\vec{0}_V) = \vec{0}_W$ .  $\checkmark$
- (5)  $\vec{A}^2 = \vec{I}$  implies that  $\vec{A} = \vec{I}$  or  $\vec{A} = -\vec{I}$ .  $\checkmark$   $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$
- (6) If  $\vec{A}$  is invertible, then  $(\vec{A}^{-1})^{-1} = \vec{A}$ .  $\checkmark$
- (7) Every change of coordinate matrix is invertible.  $\checkmark$
- (8) A linear functional defined on a field may be represented as a  $1 \times 1$  matrix.  $\checkmark$
- (9) The transpose of an elementary matrix is an elementary matrix.  $\checkmark$
- (10) If  $\vec{A}\vec{B} = \vec{0}$ , then either  $\vec{A} = \vec{0}$  or  $\vec{B} = \vec{0}$ , where  $\vec{0}$  is the zero matrix.  $\checkmark$

2. (10%) [Linearly dependent]

Let  $\mathcal{V}$  be a vector space, and let  $\mathcal{S}_1 \subseteq \mathcal{S}_2 \subseteq \mathcal{V}$ . If  $\mathcal{S}_1$  is linear dependent. Prove that  $\mathcal{S}_2$  is linearly dependent.

3. (10%) [Matrix representation]

Let  $\hat{T} : \mathcal{R}^2 \rightarrow \mathcal{R}^3$  be defined by

$$\hat{T}(a_1, a_2) = (a_1 - a_2, a_1, 2a_1 + a_2).$$

(1)

Let  $\alpha = \{(1, 2), (2, 3)\}$  be the basis for  $\mathcal{R}^2$  and  $\gamma = \{(1, 1, 0), (0, 1, 1), (2, 2, 3)\}$ . Compute  $[\hat{T}]_{\alpha}^{\gamma}$ .

4. (15%) [Basis and Dimension]

Let  $S$  be the set of all positive real numbers. Now, we want to make  $S$  as a vector space in  $\mathcal{V}$  by asking the following definitions for vectors, vector addition and scalar multiplication:

- Each element of  $S$  will be considered as a "vector" in  $\mathcal{V}$ .
- For  $A, B \in S$ , a "vector sum" is defined as

$$A + B \equiv AB, \quad (2)$$

where the product on the right is the usual product of two real numbers.

- For  $c \in \mathcal{R}(\text{real})$ , and  $A \in S$ , a "scalar multiplication" is defined as

$$c \cdot A \equiv A^c, \quad (3)$$

that is the real number  $A$  raised to the  $c$  power.

Now the questions are

- (a) (5%) What is the zero vector in  $\mathcal{V}$ ?
- (b) (5%) Give an example of a set of basis vectors for  $\mathcal{V}$ .
- (c) (5%) What is the dimension of  $\mathcal{V}$ ?

## 5. (15%) [System of Linear Equations]

Find the solution(s) of the following system of linear equations

$$\begin{aligned} 2x_1 - 2x_2 - x_3 + 6x_4 - 2x_5 &= 1 \\ x_1 - x_2 + x_3 + 2x_4 - x_5 &= 2 \\ 4x_1 - 4x_2 + 5x_3 + 7x_4 - x_5 &= 6 \end{aligned} \quad (4)$$

$$\begin{aligned} 6x_1 - 6x_2 - 9x_3 + 2x_4 &= 6 \\ 9x_1 - 9x_2 - 6x_3 + 2x_4 &= 6 \end{aligned}$$

## 6. (20%) [Linear Transformation]

Let  $V$  be the subspace of  $2 \times 2$  real matrices defined by Find the solution(s) of the following system of linear equations

$$\mathcal{V} = \left\{ \overline{A} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \text{ where } a - 2b - 3c - 4d = 0 \right\} \quad (5)$$

and let Find the solution(s) of the following system of linear equations

$$\mathcal{W} = \{f(x) = l e^x + m e^{2x} + n e^{3x}, \text{ where } l, m, n \in \mathcal{R} \text{ and } 0 \leq x \leq 1\}. \quad (6)$$

Also, define a linear transformation  $\hat{T}: V \rightarrow W$  by Find the solution(s) of the following system of linear equations

$$\hat{T} \left( \begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) = (a - 2b) e^x + (a - 3c) e^{2x} + (a - 4d) e^{3x}. \quad (7)$$

(a) (5%) Find the range of  $\hat{T}$ .(b) (5%) Find the null space of  $\hat{T}$ .(c) (10%) Is  $\hat{T}$  invertible? Justify your answer and if yes, Find  $\hat{T}^{-1}$ .

## 7. (20%) [Parabola transformation with a Rotation]

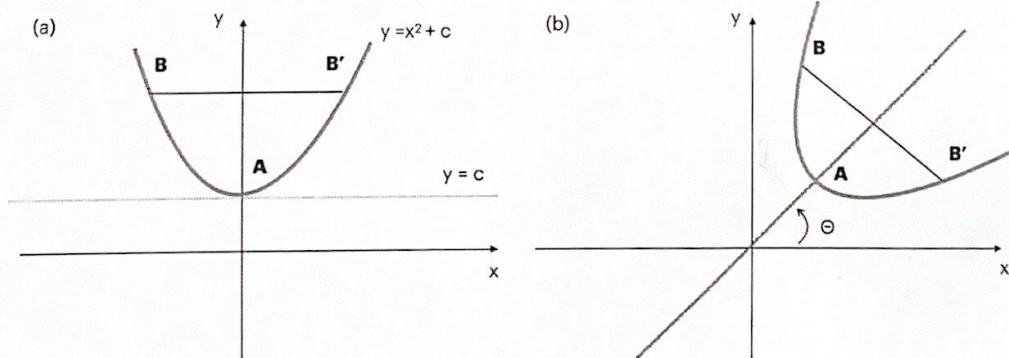
As shown in FIG. 1(a), let  $\hat{T}_0$  be the transformation sending every horizontal line  $y = c$  into the parabola  $y = x^2 + c$ (a) (5%) Find  $\hat{T}_0$ , i.e.,  $\begin{pmatrix} x' \\ y' \end{pmatrix} = \hat{T}_0 \begin{pmatrix} x \\ y \end{pmatrix}$ . Try to have the matrix representation of  $[\hat{T}_0]_{\beta}^{\beta'}$  in the standard ordered basis. If not, explain why.(b) (5%) Now, if we rotation the  $x - y$  coordinate by an angle  $\Theta$ , find the corresponding matrix for the change of coordinate.(c) (10%) Let  $\hat{T}_1$  be the parabola transformation about the new coordinate, i.e., about the line in Red-color shown in FIG. 1(b). Find the corresponding transformation  $\hat{T}_1$ , i.e.,  $\begin{pmatrix} x' \\ y' \end{pmatrix} = \hat{T}_1 \begin{pmatrix} x \\ y \end{pmatrix}$ 

FIG. 1: Problem 7.