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電磁學 (一) Electromagnetics (I)

13. 磁場與磁向量勢

Magnetic Field and Vector Potential

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In this lecture, we will introduce the concept of static magnetic field and how we will model it.

- 13.1 Postulates of Static Magnetism 靜磁學的 假設
- ■13.2 Ampere's Law 安培定律
- 13.3 Magnetic Vector Potential 磁向量勢
- 13.4 Biot-Savart Law 磁場直接求解公式
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磁場與磁向量勢 Magnetic Field and Vector Potential

13.1 靜磁學的假設 Postulates of Static Magnetism

Postulates of Magnetostatics (vacuum)

 \vec{B} : Magnetic Flux Density in Tesla

Postulate 1
$$\nabla \cdot \vec{B} = 0$$

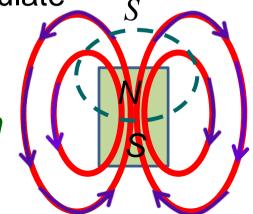
Postulate 2
$$\nabla \times \vec{B} = \mu_0 \vec{J}$$
 (Ampere's law)

where $\mu_0 = 4 \pi \times 10^{-7}$ Henry/m is the vacuum permeability

Apply the *divergence theorem* to the first postulate

$$\int_{V} \nabla \cdot \vec{B} dv = \oint_{S} \vec{B} \cdot d\vec{s} = 0$$

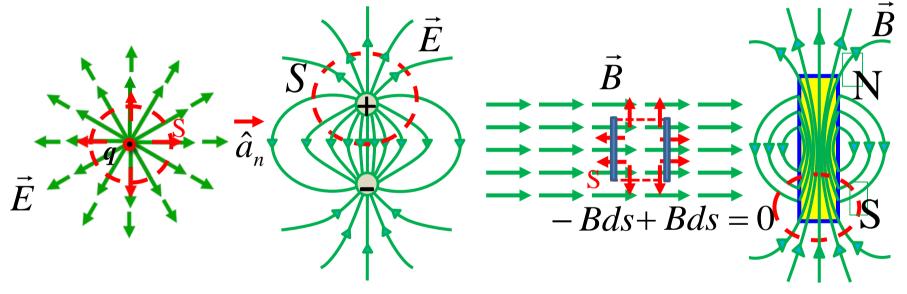
- ⇒ 1. magnetic field lines always return
- \Rightarrow 2. no magnetic monopole



Comparison between E and B Field Lines

Net outward flux surrounding q

No net flux over a volume



Electric monopole

 $\nabla \cdot \vec{E} \neq 0$

Electric dipole $\oint_{S} \vec{E} \cdot d\vec{s} \neq 0$

Solenoidal field

$$\nabla \cdot \vec{B} = 0$$

Magnet (dipole)

 $\oint_{S} \vec{B} \cdot d\vec{s} = 0$

Ampere's Law

$$\nabla \times \vec{B} = \mu_0 \vec{J} \implies \int_{s} \nabla \times \vec{B} \cdot d\vec{s} = \mu_0 \int_{s} \vec{J} \cdot d\vec{s} = \mu_0 I$$

Apply the Stokes theorem and write

$$\int_{S} \nabla \times \vec{B} \cdot d\vec{s} = \oint_{C} \vec{B} \cdot d\vec{l} = \mu_{0} \int_{S} \vec{J} \cdot d\vec{s} = \mu_{0} I$$

$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 I$$

 $|\oint_C \vec{B} \cdot d\vec{l}| = \mu_0 I$ Ampere's circuital law for magnetostatics

The circulation of magnetic fields is proportional to the current bounded by the circular path.

* The directional relationship between B and I is understood from the curl operator or the right-hand rule.

13.1 靜磁學的假設

Postulates of Static Magnetism

Maxwell's Equations for Static Magnetic Field (in vacuum)

Differential form

Integral form

$$\nabla \cdot \vec{B} = 0$$

$$\oint_{S} \vec{B} \cdot d\vec{s} = 0$$

Magnetic Gauss Law

$$abla imes ec{B} = \mu_0 ec{J}$$

$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 I$$
 Ampere's Law

磁場與磁向量勢 Magnetic Field and Vector Potential

13.2 安培定律 Ampere's Law

Magnetic Flux Density of a Long Wire =

Assume a uniform current $\vec{J} = \frac{I}{\pi b^2} \hat{a}_z$

Circular symmetry
$$\Rightarrow$$
 only B_{ϕ} exists.
Apply Ampere's law $\oint \vec{B} \cdot d\vec{l} = \mu_0 I$,

Apply Ampere's law
$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 I$$
, where C is a circular path of a constant radius r .

i. In the region $r \leq b$, ii. In the region $r \geq b$, C_2

i. In the region
$$r \leq b$$
,

the current enclosed by
$$C$$

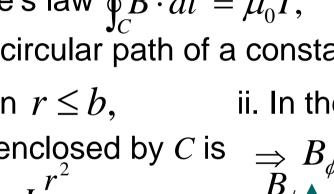
 $\Rightarrow B_{\phi} = \mu_0 I \frac{r}{2\pi h^2}$

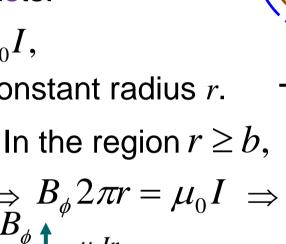
the current enclosed by
$$C$$
 is
$$I(r) = I\pi r^2 = I\frac{r^2}{r}$$

the current enclosed by
$$C$$
 is $I(r) = J\pi r^2 = I\frac{r^2}{b^2}$
Thus, $B_{\phi} 2\pi r = \mu_0 I(r) = \mu_0 I\frac{r^2}{b^2}$

In the region
$$r \le b$$
, ii. In the region $r \ge b$, c_2 ii. In the region $r \ge b$, c_2 if the current enclosed by C is $\Rightarrow B_{\phi} 2\pi r = \mu_0 I \Rightarrow B_{\phi} = \mu_0 I \frac{1}{2\pi}$
 $I(r) = J\pi r^2 = I \frac{r^2}{b^2}$

Thus. $B_{\phi} 2\pi r = \mu_0 I(r) = \mu_0 I \frac{r^2}{a^2}$





us
$$r$$
.

or $r \ge b$,

 $u_0 I \implies$

$$C_{2}$$

$$\Rightarrow B_{\phi} = 0$$

Magnetic Flux Density of a Toroid

The magnetic field at a constant r has a constant value along ϕ .

Again, apply Ampere's law,
$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 IN$$

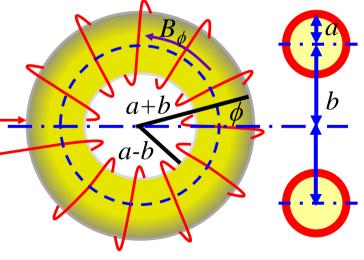
where *I* is the current in individual wires and *N* is the total number of wires around the toroid.

i. In the region
$$(b-a) \le r \le (b+a)$$

$$B_{\phi} 2\pi r = \mu_0 NI \implies B_{\phi} = \frac{\mu_0 NI}{2\pi r}$$

ii. In the regions
$$r < b - a \& r > a + b$$

$$\oint_C \vec{B} \cdot d\vec{l} = 0 \Rightarrow \vec{B} = 0$$



Magnetic Flux Density of a Solenoid

- 1. The symmetry of the problem indicates a magnetic field in the longitudinal direction.
- 2. For the dashed-line path

longitudinal direction.

2. For the dashed-line path shown in the figure, Ampere's law gives
$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 IN$$
3. For a very long solenoid, the return field $B_{\text{outside}} \sim 0$

*Assumption: solenoid length is long, fringe fields are ignored

$$\Rightarrow B_z L = \mu_0 nLI \text{ , where } n = N/L \text{ is the \# of wire loops per}$$

$$\Rightarrow B_z = \mu_0 nI \text{ unit length on the solenoid.}$$

13.2 安培定律

Ampere's Law

- With enough symmetry, the Ampere's law is useful to calculate the magnetic field subject to a current.
- A long wire with a uniform current, the magnetic field outside the wire drops with 1/r.
- In a toroid or a solenoid, the magnetic field is proportional to the density of wires carrying the current.

磁場與磁向量勢 Magnetic Field and Vector Potential

13.3 磁向量勢 Magnetic Vector Potential

Vector Potential

From the postulate $\nabla \cdot \vec{B} = 0$, one can use the vector identity $\nabla \cdot \nabla \times \vec{A} = 0$ to write

$$\vec{B} = \nabla \times \vec{A}$$

where A is the so-called vector potential of the magnetic field in units of Weber/m.

Physical meaning of \vec{A} ?

Recall the total magnet flux

$$\Phi = \int_{S} \vec{B} \cdot d\vec{s} \implies \Phi = \int_{S} \nabla \times \vec{A} \cdot d\vec{s} = \oint_{C} \vec{A} \cdot d\vec{l}$$

The circulation of a magnetic vector potential is equal to the total magnetic flux going through the circulation path of A.

Solution to Vector Potential *A*

Insert $\vec{B} = \nabla \times \vec{A}$ into the Ampere's law $\nabla \times \vec{B} = \mu_0 \vec{J}$

$$\Rightarrow \nabla \times \nabla \times \vec{A} = \mu_0 \vec{J} \Rightarrow \nabla (\nabla \cdot \vec{A}) - \nabla^2 \vec{A} = \mu_0 \vec{J}$$

(refer to the definition of vector Laplacian in Lecture 4)

Recall that, to be unique for a vector solution, the Helmoltz's theorem requires simultaneous definitions of the divergence and curl of a vector and boundary conditions.

Choose $\nabla \cdot \vec{A} = 0$ to obtain the vector Poisson's equation

$$\nabla^2 \vec{A} = -\mu_0 \vec{J}$$

$$\nabla^2 A_x = -\mu_0 J_x, \ \nabla^2 A_y = -\mu_0 J_y, \ \nabla^2 A_z = -\mu_0 J_z$$

Recall, in electrostatics, the Poisson's equation
$$\nabla^2 V = -\frac{\rho}{\varepsilon_0} \text{ with the solution } V = \frac{1}{4\pi\varepsilon_0} \int_{V'} \frac{\rho}{R} dv'$$
 Similarly, the solution of \vec{A} is
$$A_{x,y,z} = \frac{\mu_0}{4\pi} \int_{V'} \frac{J_{x,y,z}}{R} dv' \quad \text{or} \quad \vec{A} = \frac{\mu_0}{4\pi} \int_{V'} \frac{\vec{J}}{R} dv'$$

The direction of a vector potential is along the same direction of current \Rightarrow easier to calculate A than B.

For a thin wire carrying a current $I = \vec{J} \cdot \vec{S}$ $\vec{A} = \frac{\mu_0}{4\pi} \int_{V'} \frac{\vec{J}}{R} dv' = \frac{\mu_0}{4\pi} \oint_{C'} \frac{\vec{J} \cdot \vec{S}}{R} d\vec{l}' = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l}'}{R}$

E.g. Find \vec{B} at P for a current element of length 2L.

The differential length along current flow is $d\vec{l}' = \hat{a}_z dz'$

From the geometry,
$$R = \sqrt{r^2 + z'^2}$$
 $\vec{A} = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l}'}{R} = \hat{a}_z \frac{\mu_0 I}{4\pi} \int_{-L}^{L} \frac{dz'}{\sqrt{r^2 + z'^2}}$ L

$$= \hat{a}_z \frac{\mu_0 I}{4\pi} \ln \frac{\sqrt{r^2 + L^2} + L}{\sqrt{r^2 + L^2} - L}$$
 L

$$I$$

$$= \frac{1}{4\pi} \int_{-L}^{L} \frac{d\vec{l}'}{\sqrt{r^2 + L^2} - L} d\vec{l}'$$

Calculate the magnetic field from $\vec{B} = \nabla \times \vec{A} \perp \vec{B} = \nabla \times \vec{A} = \nabla \times (\hat{a}_z A_z) = \hat{a}_r \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \hat{a}_\phi \frac{\partial A_z}{\partial r} = -\hat{a}_\phi \frac{\partial A_z}{\partial r} = \frac{\mu_0 IL}{2\pi r_0 \sqrt{L^2 + r^2}} \hat{a}_\phi$

13.3 磁向量勢

Vector Potential

- Because of $\nabla \cdot \vec{B} = 0$, we define the vector potential $\vec{B} = \nabla \times \vec{A}$.
- The vector potential is along the direction of a driving current, $\vec{A} = \frac{\mu_0}{4\pi} \int_{V'} \frac{\vec{J}}{R} dv' = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l}'}{R},$

which simplifies the calculation for A and then B.

磁場與磁向量勢 Magnetic Field and Vector Potential

13.4 磁場直接求解公式 Biot-Savart Law

The Biot-Savart Law

The magnetic field can be calculated from

$$\vec{B} = \nabla \times \vec{A} = \frac{\mu_0 I}{4\pi} \oint_{C'} \nabla \times \left(\frac{d\vec{l}'}{R}\right) \text{ with } \vec{A} = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l}'}{R}$$

Use the formula $\nabla \times (f\vec{G}) = f\nabla \times \vec{G} + (\nabla f) \times \vec{G}$ and $\nabla \times d\vec{l}' = 0$ * (*differentiation of unprimed coordinates on primed ones)

$$\vec{B} = \frac{\mu_0 I}{4\pi} \oint_{C'} \nabla \times \left(\frac{d\vec{l}'}{R}\right) = \frac{\mu_0 I}{4\pi} \oint_{C'} \left(\nabla \frac{1}{R}\right) \times d\vec{l}' \quad \text{But,} \quad \nabla \left(\frac{1}{R}\right) = -\hat{a}_R \frac{1}{R^2}$$

$$\Rightarrow \vec{B} = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l}' \times \hat{a}_R}{R^2}$$
 (Biot-Savart Law)

- A direct way to calculate a magnetic field from a given current-carrying wire.

E.g. Find B at P for the following current element using the Biot-Savart law

element using the Biot-Savart law
$$\vec{B} = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l}' \times \vec{R}}{R^3}$$
 The differential length along the current is L

The differential length along the current is
$$L$$
 $d\vec{l}' = \hat{a}_z dz'$ The R vector is given by $\vec{R} = \hat{a}_r r - \hat{a}_z z'$ T with $R = \sqrt{r^2 + {z'}^2} \implies d\vec{l}' \times \vec{R} = \hat{a}_\phi r dz'$

with
$$R = \sqrt{r^2 + z'^2} \implies dl' \times R = \hat{a}_{\phi} r dz'$$

$$\vec{B} = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l}' \times \vec{R}}{R^3} = \hat{a}_{\phi} \frac{\mu_0 I}{4\pi} \int_{-L}^{L} \frac{r dz'}{(z'^2 + r^2)^{3/2}} = \hat{a}_{\phi} \frac{\mu_0 I L}{2\pi r \sqrt{L^2 + r^2}}$$

E.g. Find \vec{B} at \vec{P} for the current loop of radius \vec{b} by

using Biot-Savart law -
$$\vec{B} = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l}' \times \vec{R}}{R^3}$$

The differential length of the current is

$$d\vec{l}' = \hat{a}_{\phi}bd\phi'$$

Also, $\vec{R} = \hat{a}_z z - \hat{a}_r b$ with $R = \sqrt{b^2 + z^2}$ $\Rightarrow d\vec{l}' \times \vec{R} = \hat{a}_r bz d\phi' + \hat{a}_z b^2 d\phi'$

The first term is ineffective in the integration from symmetry.

Substitute the above into the Biot-Savart law

$$\vec{B} = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l}' \times \vec{R}}{R^3} = \hat{a}_z \frac{\mu_0 I}{4\pi} \int_0^{2\pi} \frac{b^2}{(z^2 + b^2)^{3/2}} d\phi' = \hat{a}_z \frac{\mu_0 I b^2}{2(z^2 + b^2)^{3/2}}$$

13.4 磁場直接求解公式

Biot-Savart Law

 The magnetic flux density generated by a current element can be calculated directly from the following integration:

$$\vec{B} = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l}' \times \vec{R}}{R^3}$$

where $d\vec{l}'$ is the differential length of the current element, \vec{R} is the position vector between the current and the point of interest.

磁場與磁向量勢 Magnetic Field and Vector Potential

13.5 單元回顧 Review

1. There are two postulates for static magnetism:

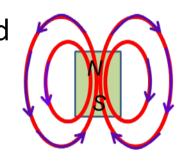
Differential form

Integral form

$$\nabla \cdot \vec{B} = 0$$

$$\oint_{S} \vec{B} \cdot d\vec{s} = 0 \implies$$

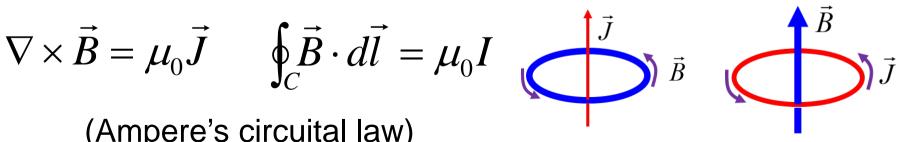
Magnetic field lines always close upon themselves



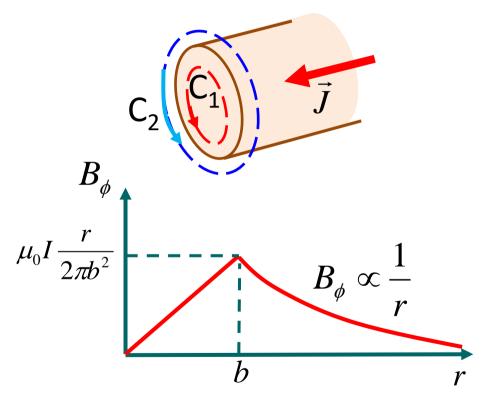
$$abla imes ec{B} = \mu_0 ec{J}$$

$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 I$$

(Ampere's circuital law)



2. The magnetic flux density of a long wire carrying a uniform current increases over r inside the wire and decreases with 1/routside the wire.



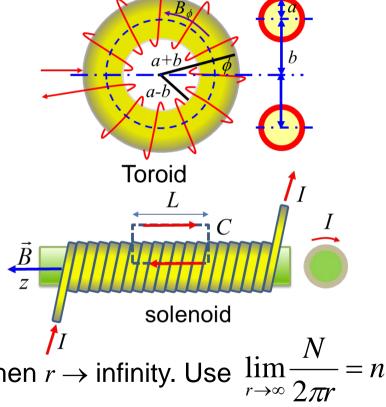
3. The magnetic flux density in a toroid is given by

$$B_{\phi} = \frac{\mu_0 NI}{2\pi r}$$

4. The magnetic flux density in a solenoid is given by

$$B_z = \mu_0 nI$$

where n is the number density of the current loops.

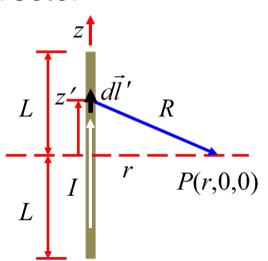


Remark: a toroid becomes a solenoid when $r \to \text{infinity.}$ Use $\lim_{r \to \infty} \frac{1}{2\pi r} = n$

for the solution of a toroid to obtain the same solution for a solenoid.

- 5. Because of $\nabla \cdot \vec{B} = 0$, we can define the vector potential \vec{A} from $\vec{B} = \nabla \times \vec{A}$.
- 6. Given a current, the vector potential is along the direction of the current,

$$\vec{A} = \frac{\mu_0}{4\pi} \int_{V'} \frac{\vec{J}}{R} dv' = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l}'}{R},$$

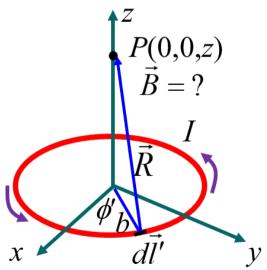


which simplifies the calculation for A and then B.

7. It is possible to calculate the magnetic field directly for a given circuit element by using the so-called Biot-Savart

law

$$\vec{B} = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{d\vec{l}' \times \vec{R}}{R^3}$$



THANK YOU FOR YOUR ATTENTION