
EE3230 Lecture 8: Sequential Circuit Design

Ping-Hsuan Hsieh (謝秉璇)

Delta Building R908

EXT 42590

phsieh@ee.nthu.edu.tw

Outline

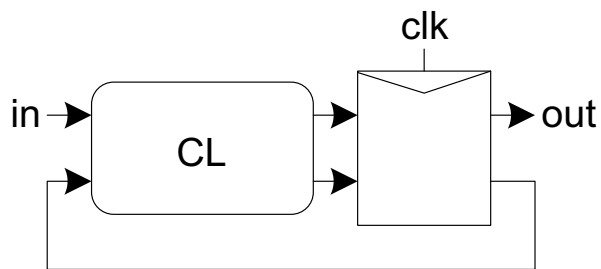
- Sequencing Methods
- Max/Min Delay, Clock Skew, Timing Borrowing
- Sequencing Element Design

Outline

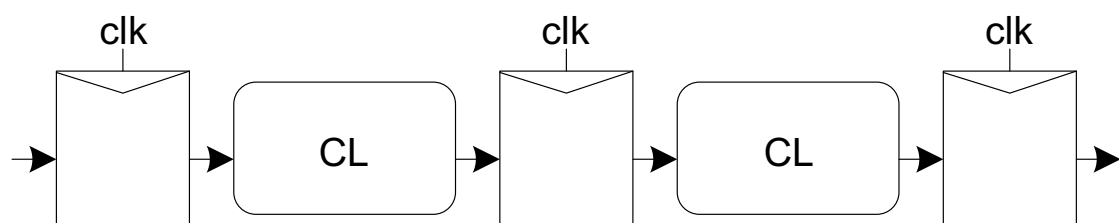
- **Sequencing Methods**
- Max/Min Delay, Clock Skew, Timing Borrowing
- Sequencing Element Design

Sequencing

- Combinational logic
 - Outputs depend on current inputs
- Sequential logic
 - Outputs depend on current and previous inputs
 - Previous, current, and future separated
 - Memory elements required
 - Called states or tokens
 - Examples: Finite-State Machine (FSM), pipeline



Finite State Machine

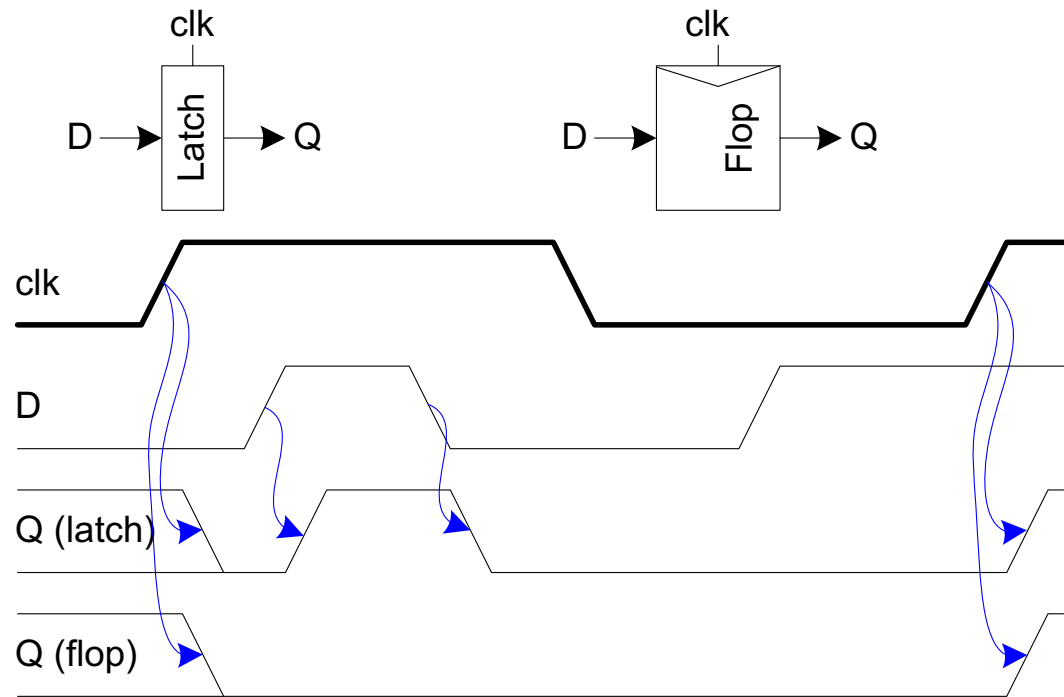


Pipeline

Sequencing Elements

- **Latch:** level-sensitive
 - a.k.a. transparent latch, D latch, etc.
- **Flip-flop:** edge-triggered
 - a.k.a. master-slave flip-flop, D flip-flop, D register, etc.

- Timing diagram
 - Transparent
 - Opaque
 - Edge-triggered

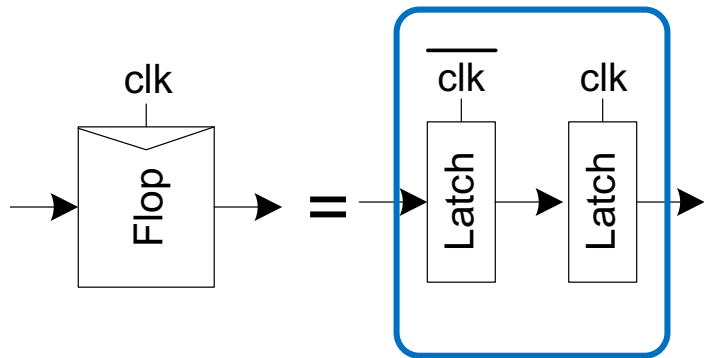


Latch vs. Flip-Flops

- **Latch: level-sensitive**
 - Passes input D to Q when the clock is high – transparent mode
 - Input D sampled on the falling edge of the clock is held stable when clock is low – hold mode
- **Flip-flop: edge-triggered**
 - Samples input D on a clock transition
 - Can be either positive edge-triggered or negative edge-triggered
 - Built using two latches (master-slave flip-flops)

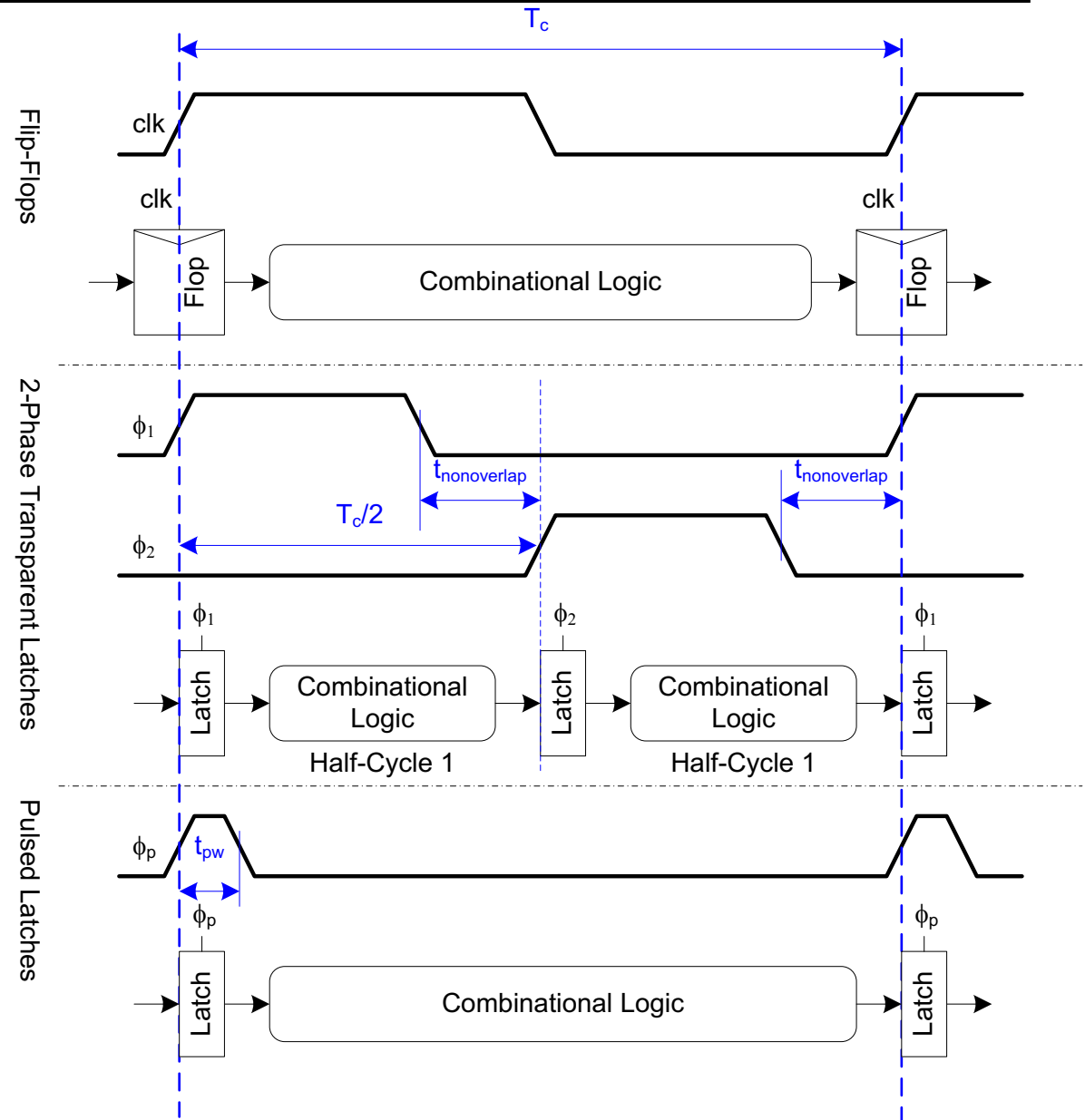
Sequencing Methods

- Flip-flops

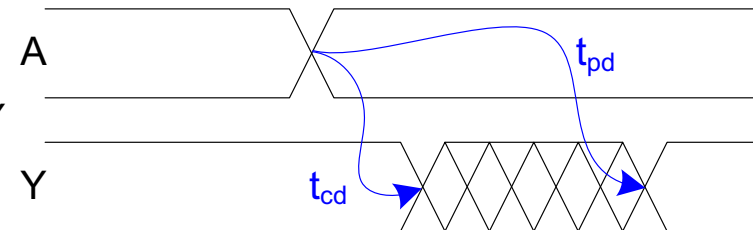
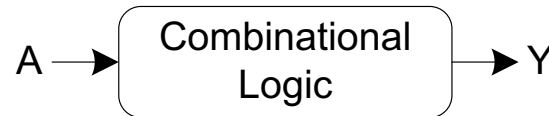


- 2-phase latches

- Pulsed latches

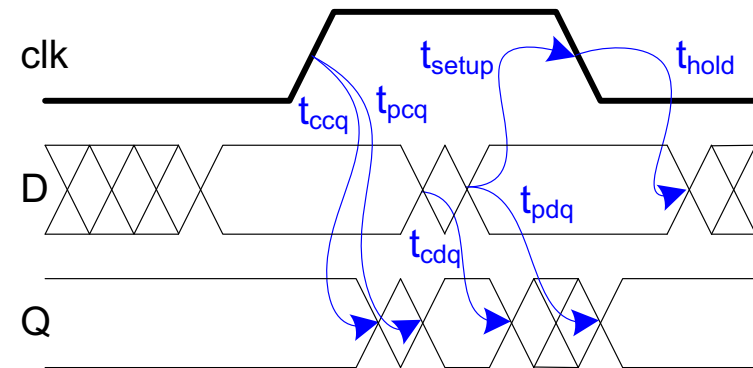
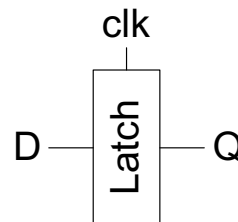
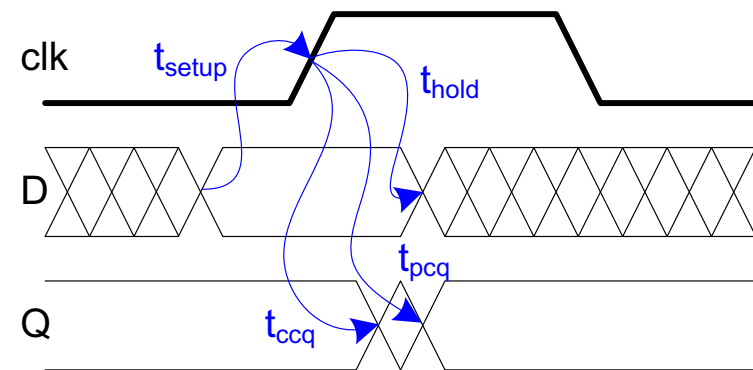
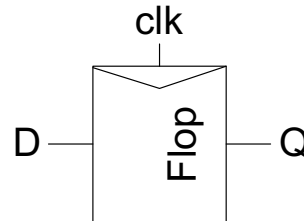


Timing Diagrams



t_{pd}	Logic Prop. Delay
t_{cd}	Logic Cont. Delay
t_{pcq}	Latch/Flop Clk-Q Prop Delay
t_{ccq}	Latch/Flop Clk-Q Cont. Delay
t_{pdq}	Latch D-Q Prop Delay
t_{cdq}	Latch D-Q Cont. Delay
t_{setup}	Latch/Flop Setup Time
t_{hold}	Latch/Flop Hold Time

* Contamination & Propagation delays



Sequencing Overhead

- Flip-flops are used to delay **fast tokens** so that they move through exactly one stage per cycle
- Inevitably add some delay to **slow tokens**
- Make circuits slower than just the logic delay
 - Called sequencing overhead
 - Some people call this clocking overhead
 - Inevitable side effect of maintaining sequence

Outline

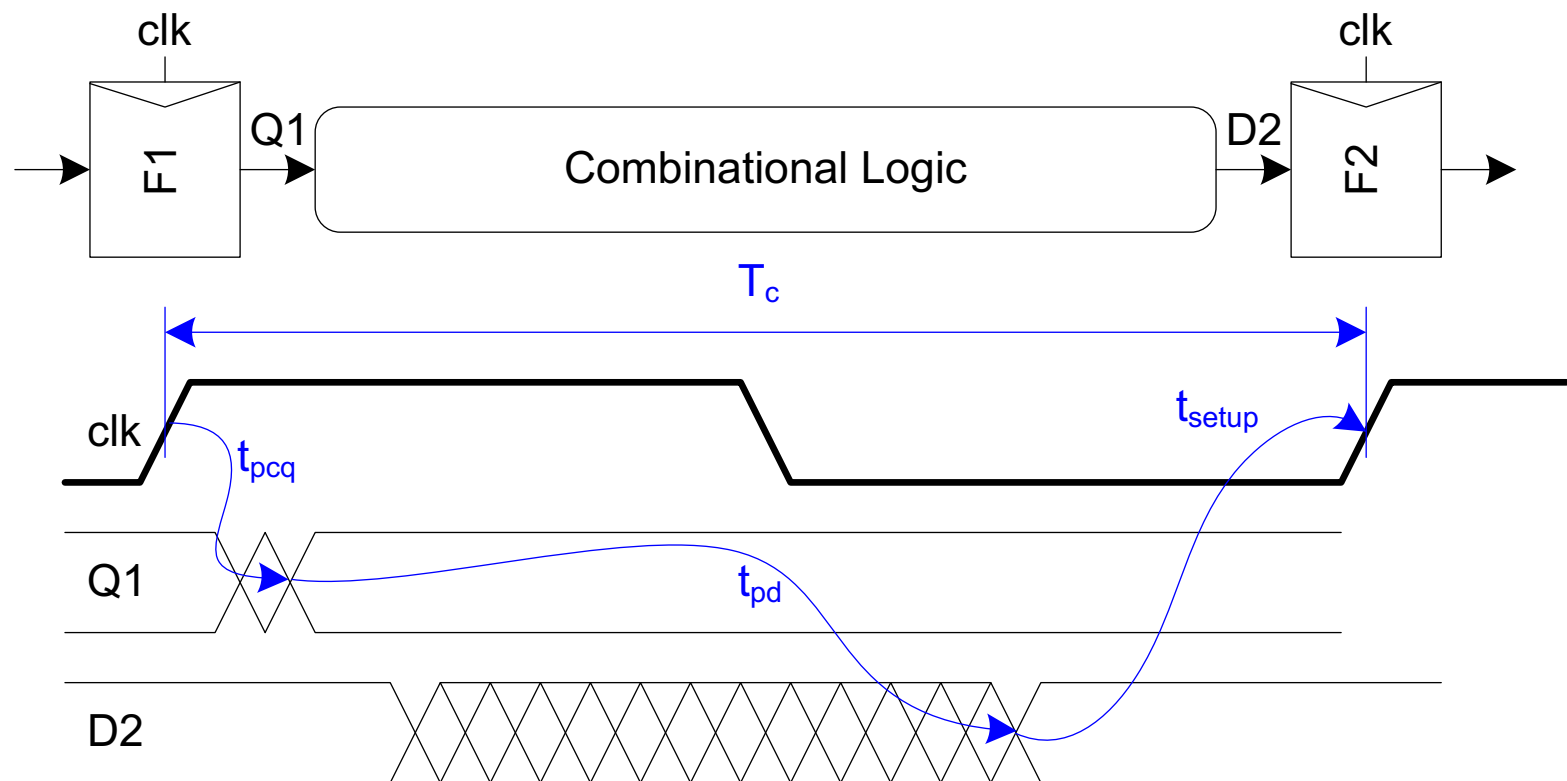
- Sequencing Methods
- **Max/Min Delay, Clock Skew, Timing Borrowing**
- Sequencing Element Design

Max/Min Delay Constraints

- Max delay constraint
 - Combinational logic delay cannot be too late, or the receiving element would miss its setup time and sample the wrong value → **setup time failure**
- Min delay constraint
 - Contamination delay of logic cannot be too small, or the data can incorrectly propagate through one clock edge and corrupt the state → **hold-time failure, race condition**
 - Redesign for slower logic

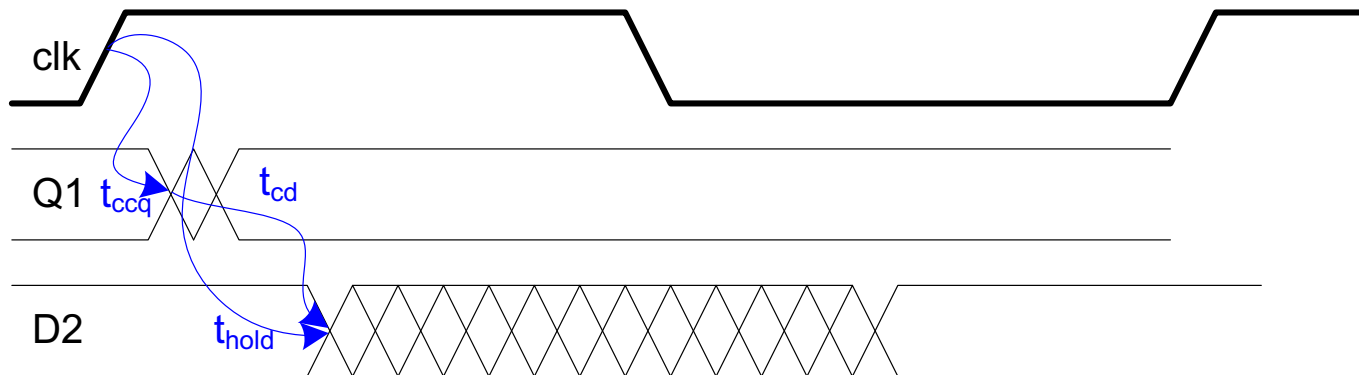
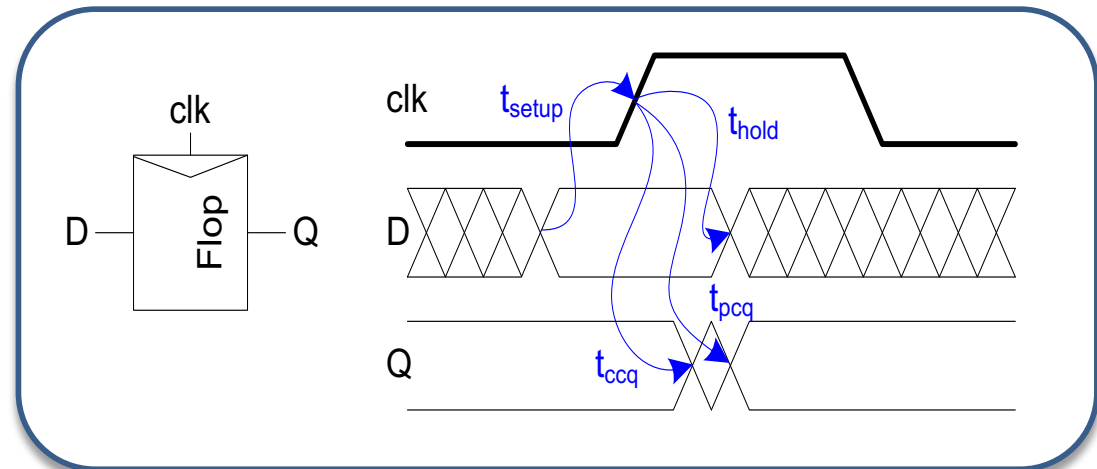
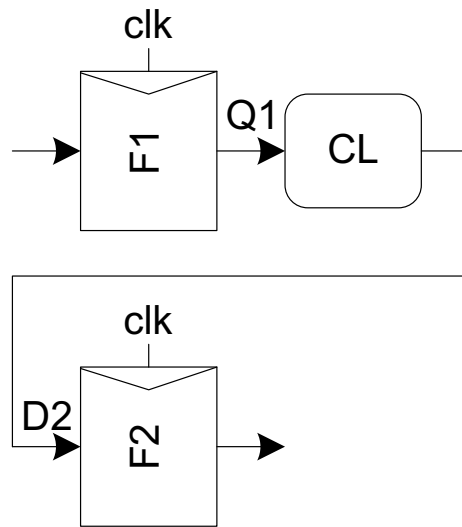
Max Delay: Flip-Flops

$$t_{pd} \leq T_c - \underbrace{(t_{\text{setup}} + t_{pcq})}_{\text{sequencing overhead}}$$



Min Delay: Flip-Flops

$$t_{cd} \geq t_{\text{hold}} - t_{ccq}$$

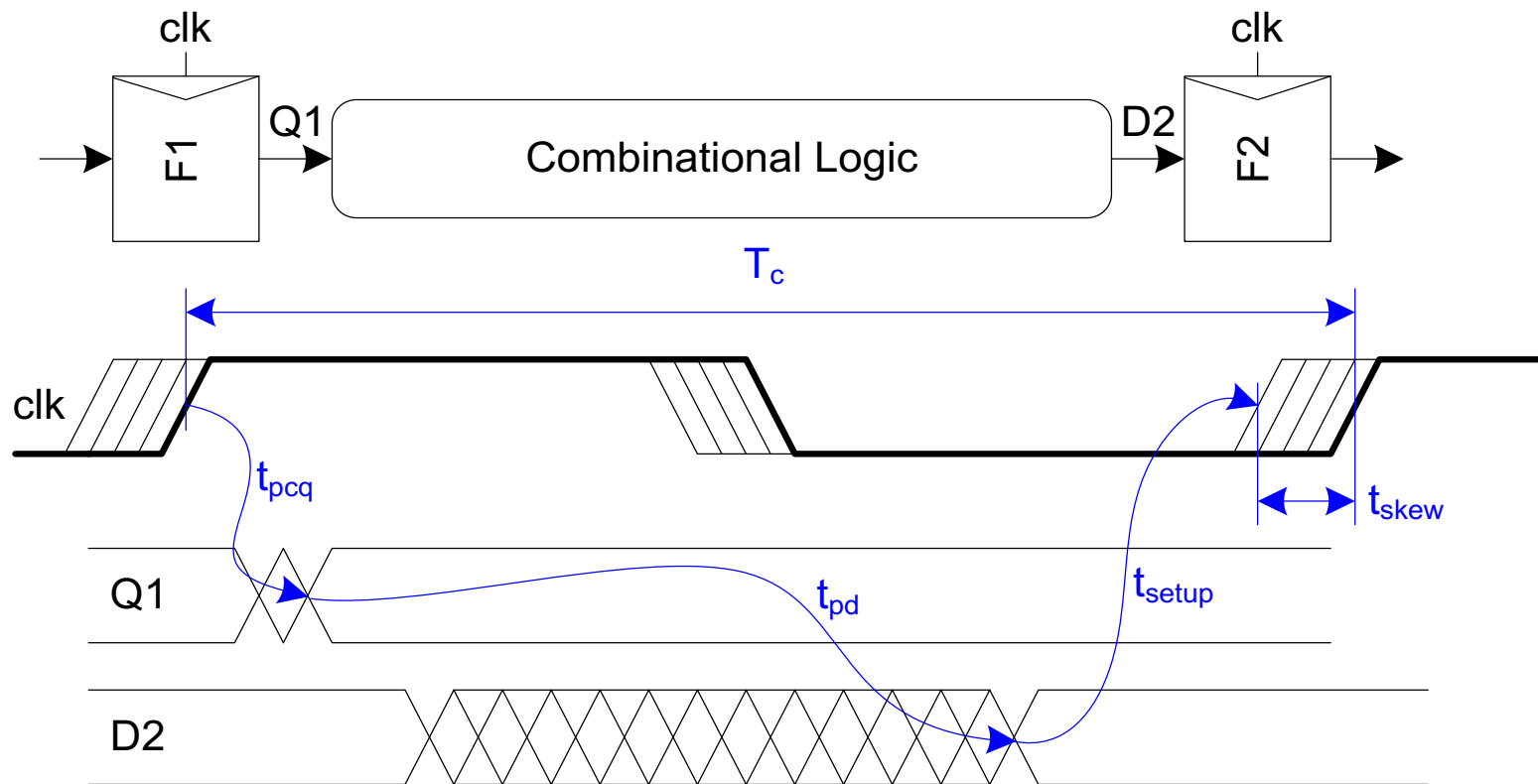


Clock Skew

- We have assumed zero clock skew
- Clock signals have uncertainty in arrival time

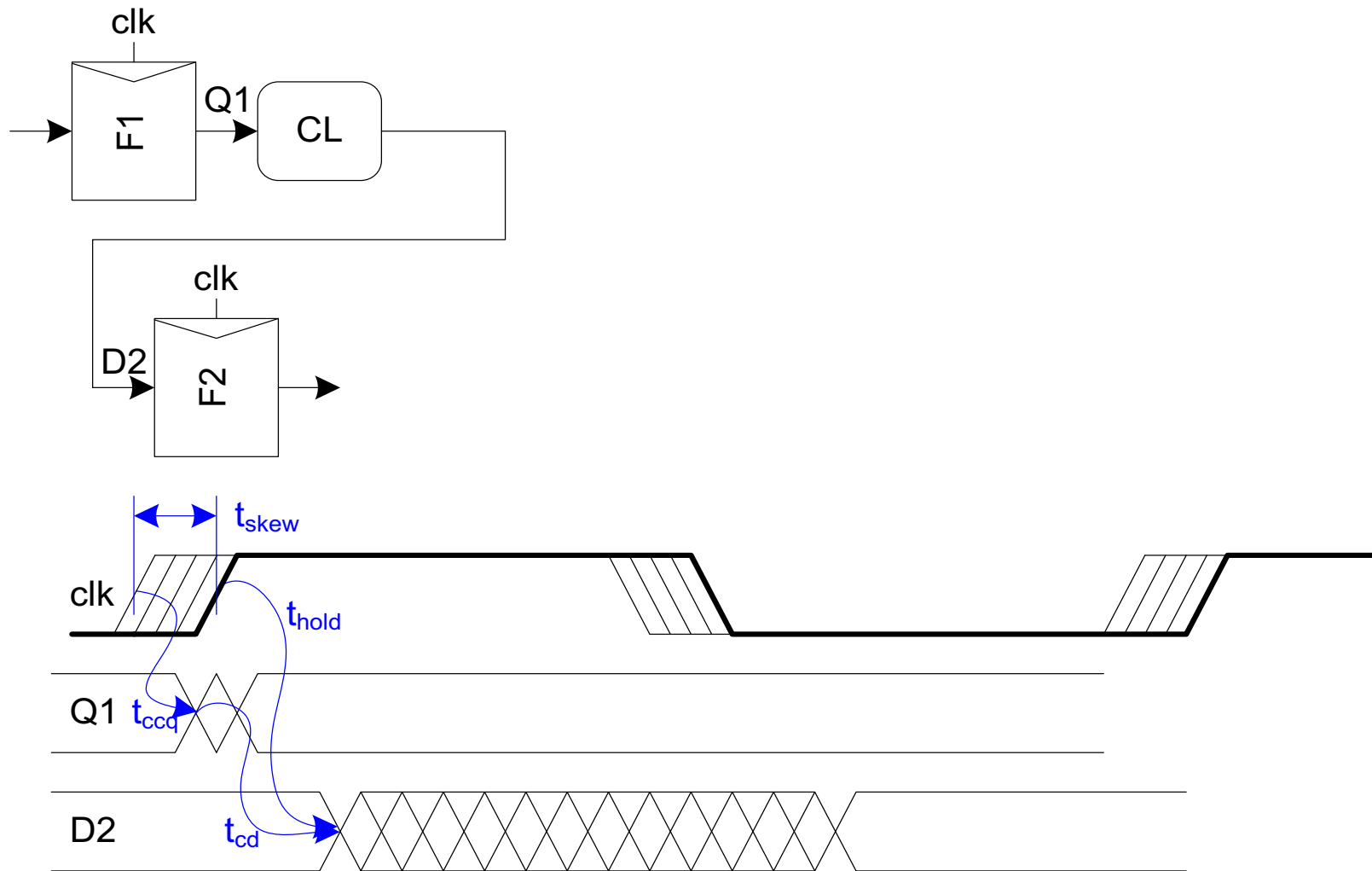
Skew: Flip-Flops: Max Delay

$$t_{pd} \leq T_c - \underbrace{(t_{pcq} + t_{setup} + t_{skew})}_{\text{sequencing overhead}}$$



Skew: Flip-Flops: Min Delay

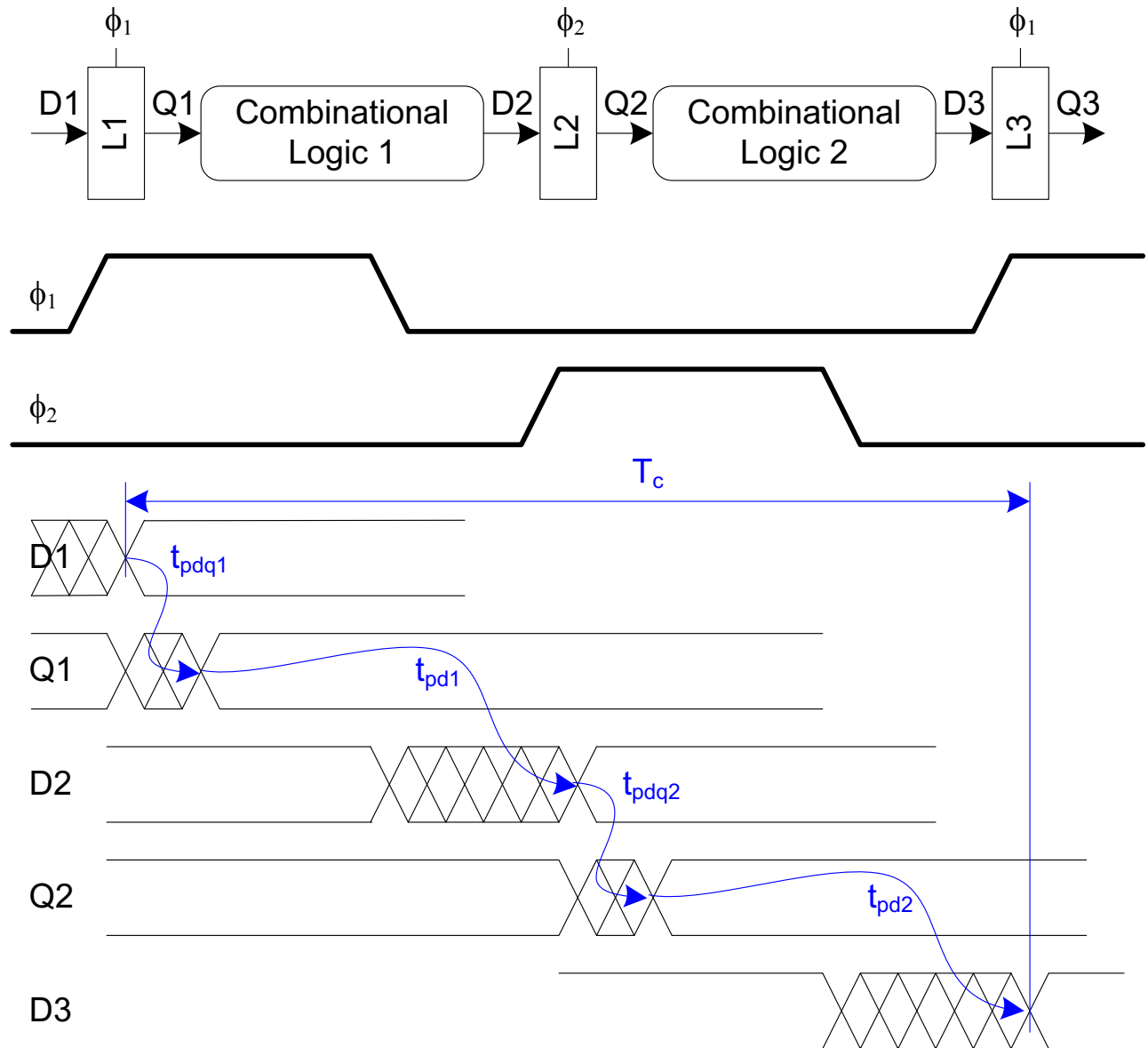
$$t_{cd} \geq t_{\text{hold}} - t_{ccq} + t_{\text{skew}}$$



Max Delay: 2-Phase Latches

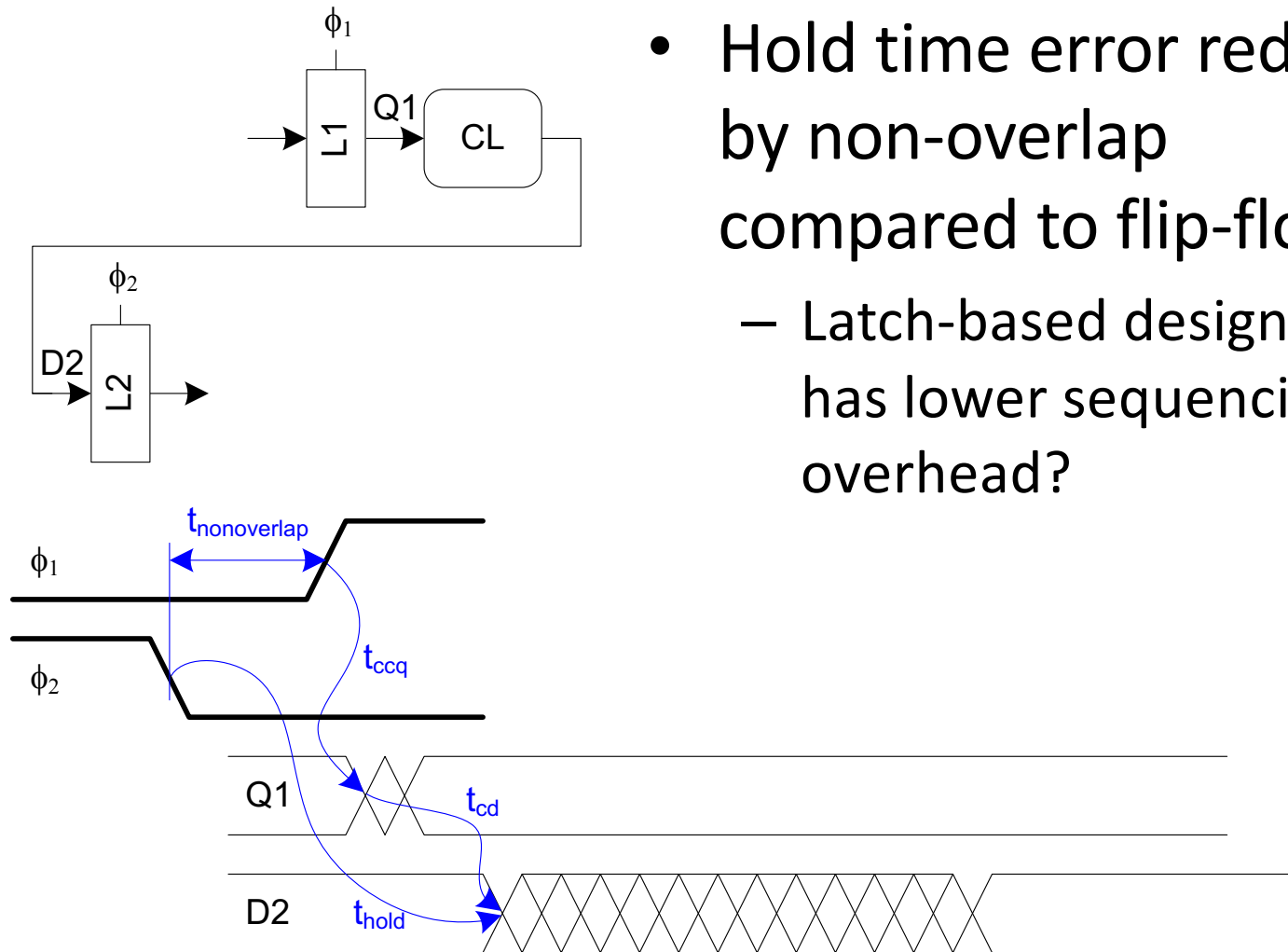
$$t_{pd} = t_{pd1} + t_{pd2}$$

$$\leq T_c - \underbrace{(2t_{pdq})}_{\text{sequencing overhead}}$$



Min Delay: 2-Phase Latches

$$t_{cd1}, t_{cd2} \geq t_{\text{hold}} - t_{ccq} - t_{\text{nonoverlap}}$$

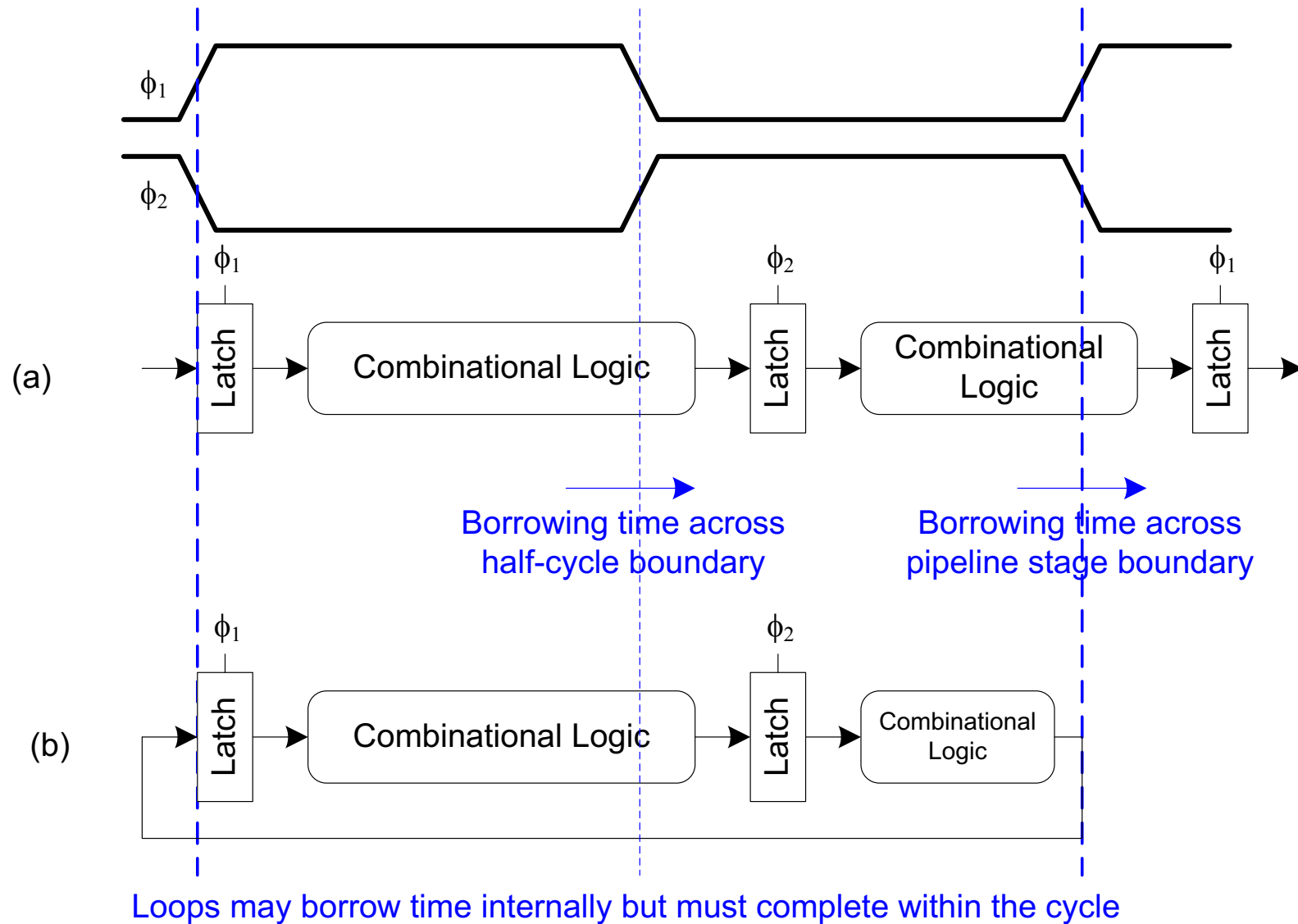


- Hold time error reduced by non-overlap compared to flip-flops
 - Latch-based design has lower sequencing overhead?

Timing Borrowing

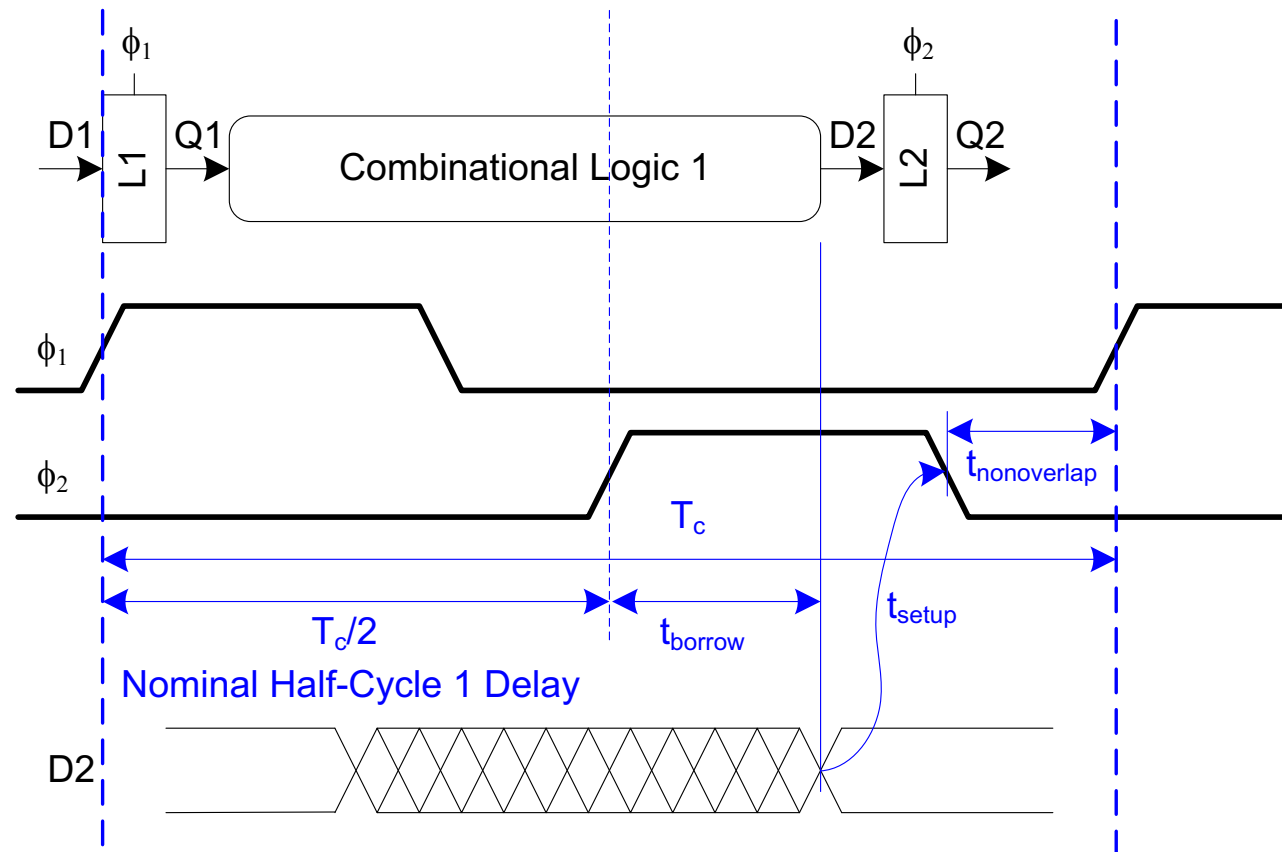
- In flip-flop systems
 - Data launch on one rising edge
 - Must setup before next rising edge
 - If data arrive late → system fails
 - If data arrive early → system fails
 - **Flip-flop systems have hard edges**
- In latched-based systems
 - Data can pass through latches while transparent
 - Long logic delay can borrow time into next cycle
 - As long as each loop completes in time

Time Borrowing Example



How Much Borrowing?

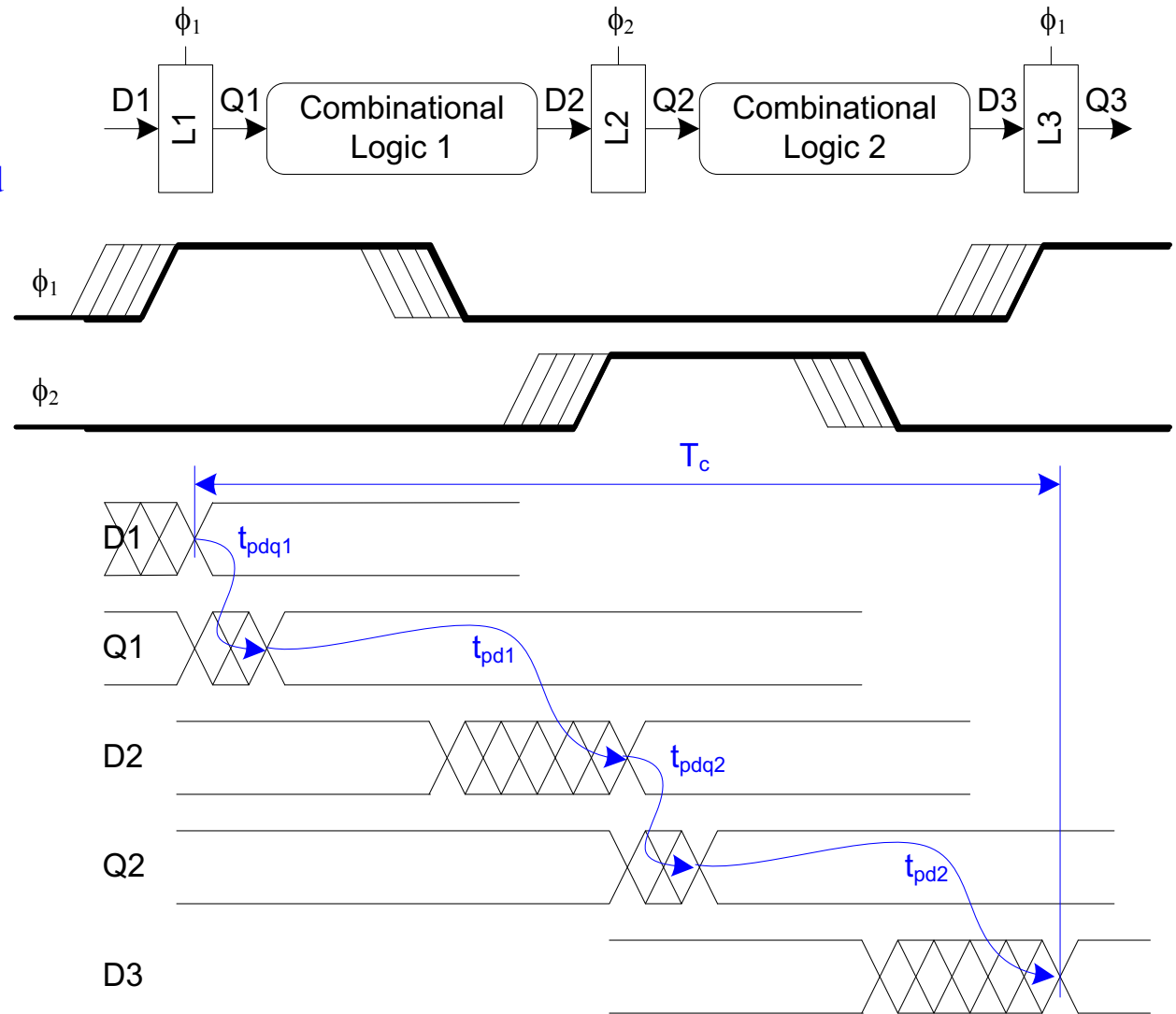
$$t_{\text{borrow}} \leq \frac{T_c}{2} - (t_{\text{setup}} + t_{\text{nonoverlap}})$$



Skew: 2-Phase Latches: Max Delay

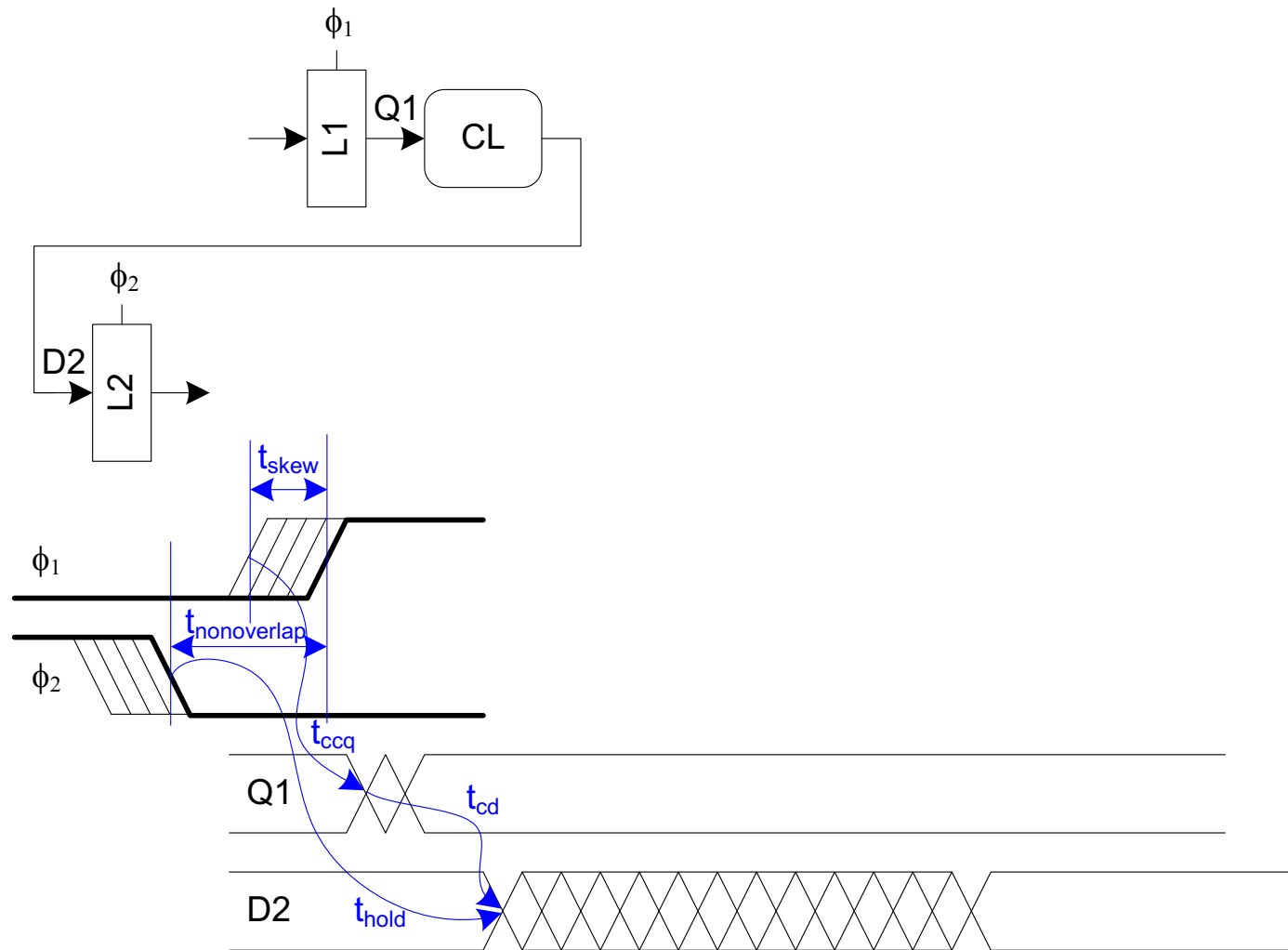
$$t_{pd} \leq T_c - \underbrace{(2t_{pdq})}_{\text{sequencing overhead}}$$

- Latch-based designs are **skew-tolerant**



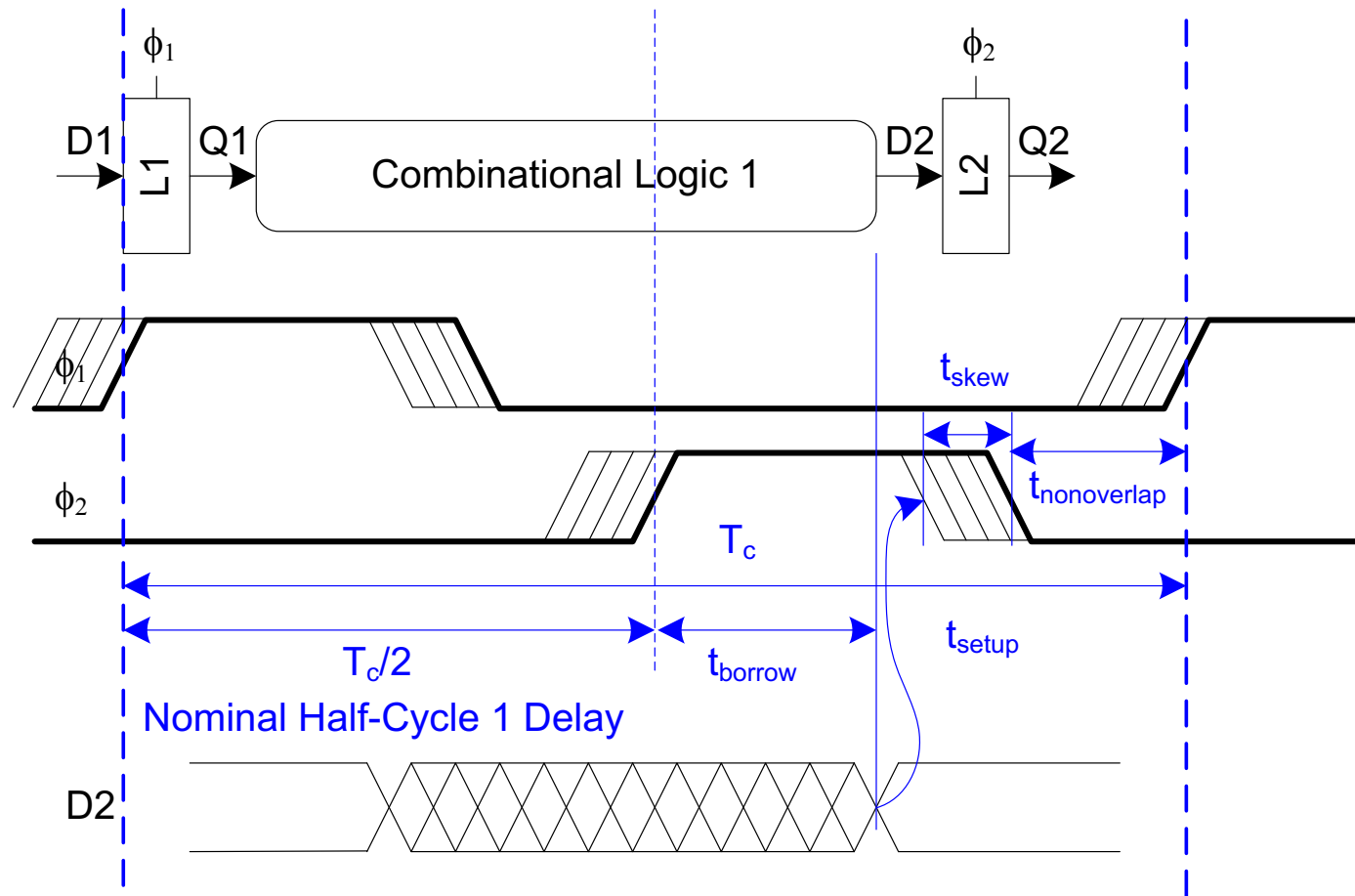
Skew: 2-Phase Latches: Min Delay

$$t_{cd1}, t_{cd2} \geq t_{\text{hold}} - t_{ccq} - t_{\text{nonoverlap}} + t_{\text{skew}}$$



Skew: How Much Borrowing?

$$t_{\text{borrow}} \leq \frac{T_c}{2} - (t_{\text{setup}} + t_{\text{nonoverlap}} + t_{\text{skew}})$$

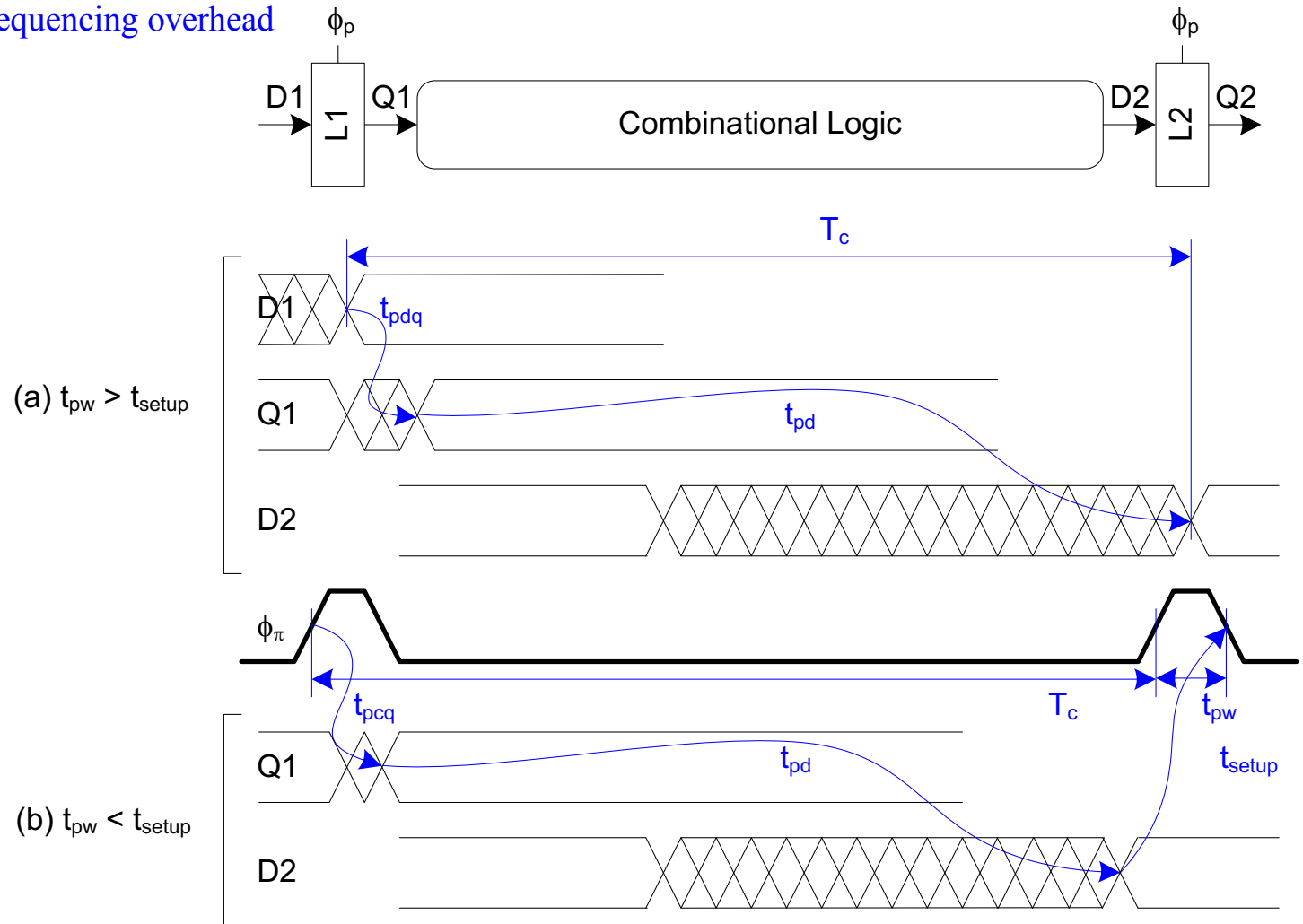


Clock Skew

- We have assumed zero clock skew
- Clock signals have uncertainty in arrival time
 - Negative impact on timing margin
 - Decrease setup time margin
(effectively increase maximum delay)
 - Decrease hold time margin
(effectively decrease contamination delay)
 - Decrease timing borrowing

Max Delay: Pulsed Latches

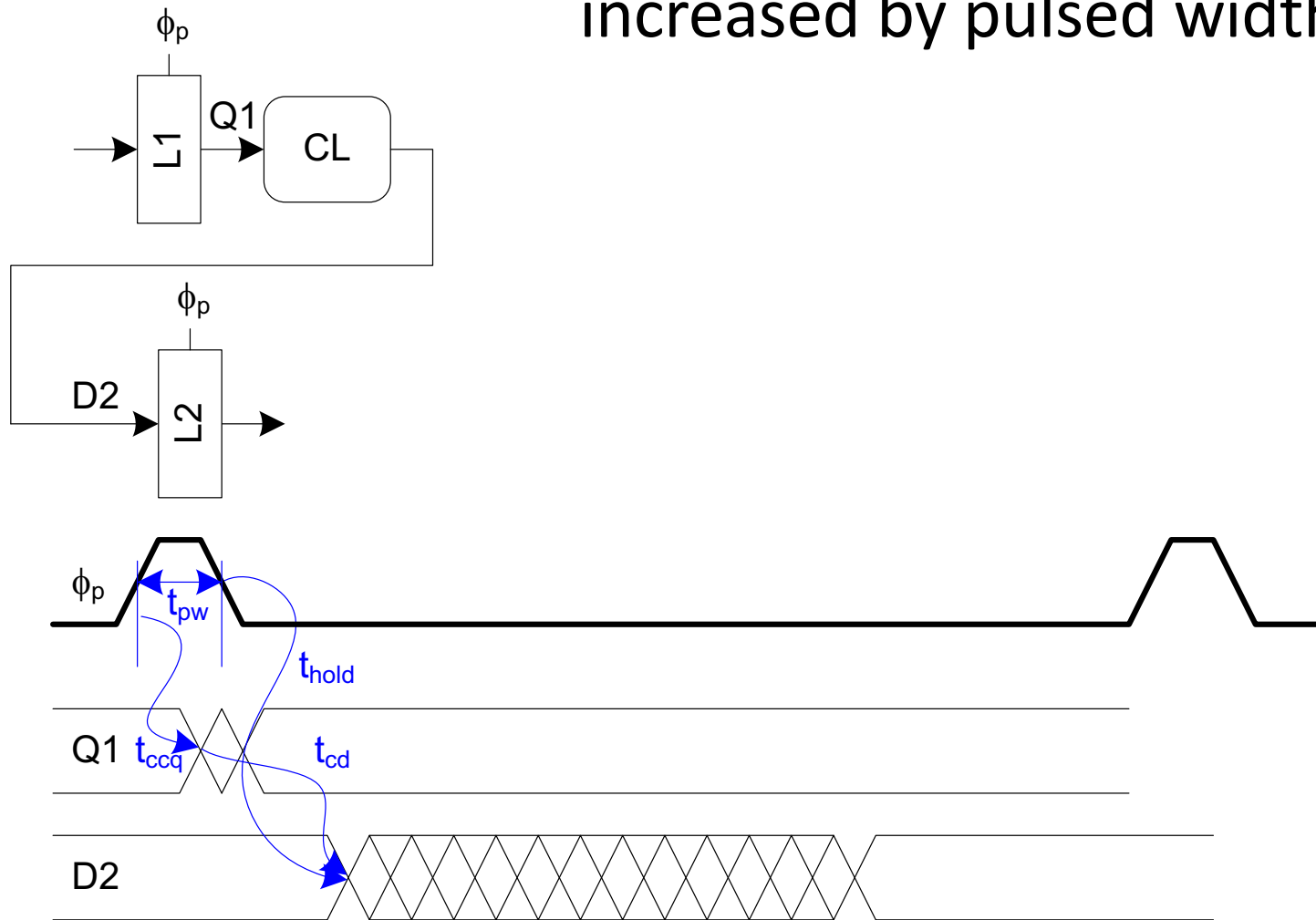
$$t_{pd} \leq T_c - \underbrace{\max(t_{pdq}, t_{pcq} + t_{\text{setup}} - t_{pw})}_{\text{sequencing overhead}}$$



Min Delay: Pulsed Latches

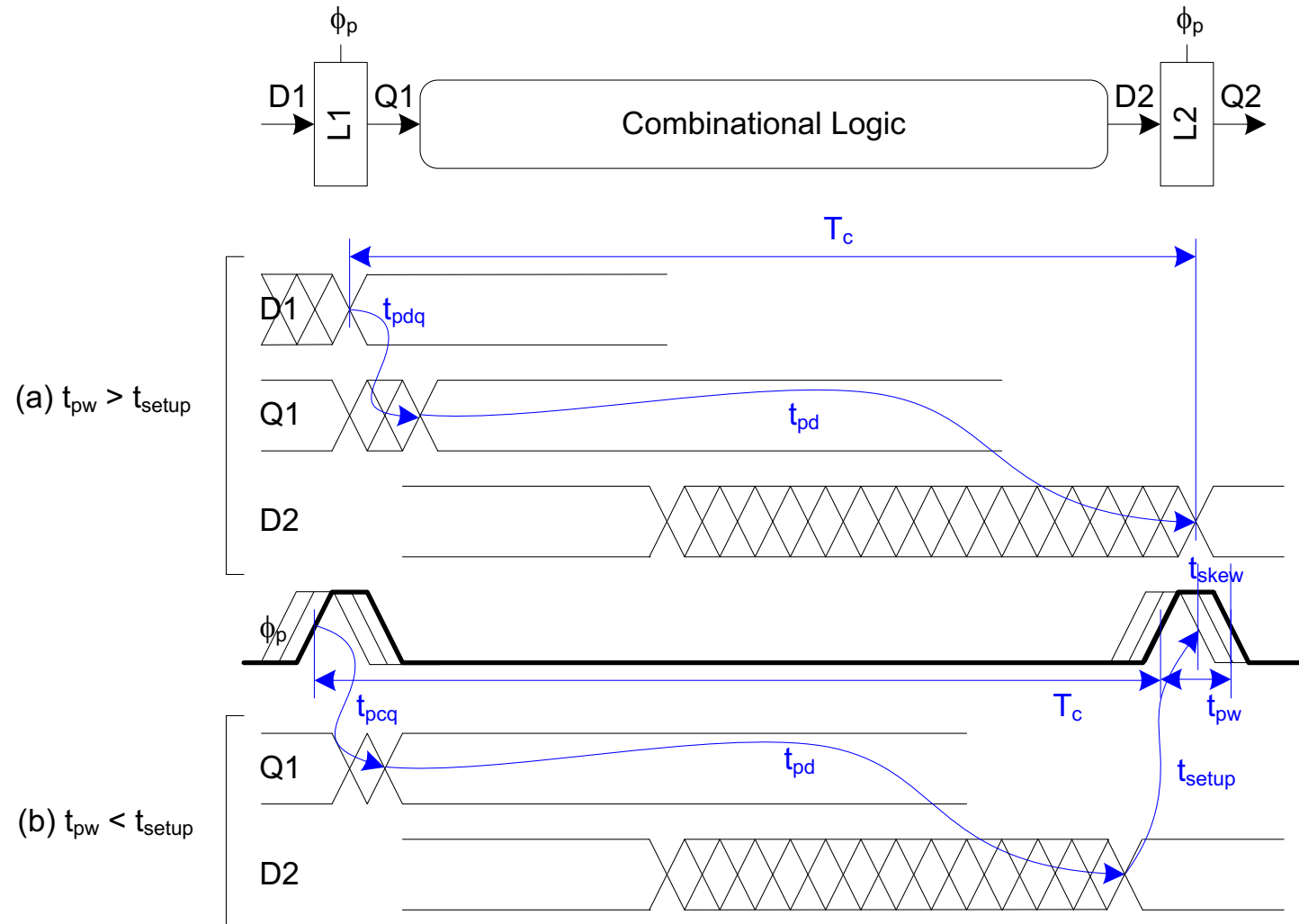
$$t_{cd} \geq t_{\text{hold}} - t_{ccq} + t_{pw}$$

- Hold-time error increased by pulsed width



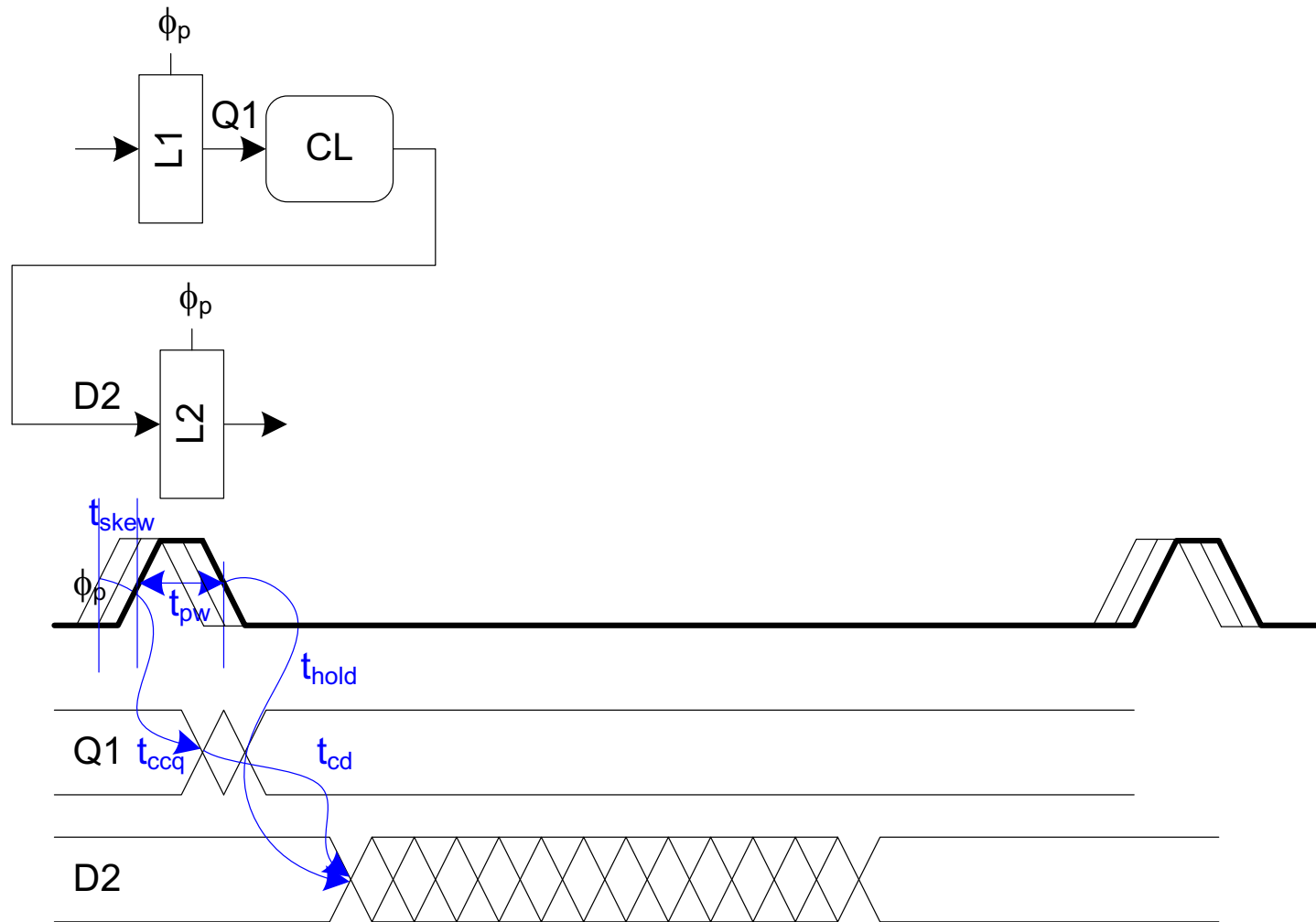
Skew: Pulsed Latches: Max Delay

$$t_{pd} \leq T_c - \underbrace{\max(t_{pdq}, t_{pcq} + t_{setup} - t_{pw} + t_{skew})}_{\text{sequencing overhead}}$$



Skew: Pulsed Latches: Min Delay

$$t_{cd} \geq t_{\text{hold}} + t_{pw} - t_{ccq} + t_{\text{skew}}$$



Outline

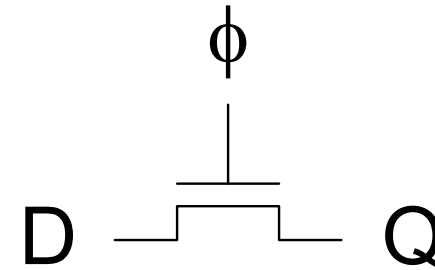
- Sequencing Methods
- Max/Min Delay, Clock Skew, Timing Borrowing
- **Sequencing Element Design**

Static vs. Dynamic Storage

- Static Storage
 - Preserve state as long as power is on
 - Use positive feedback (**regeneration**) with an internal connection between output and input
 - Useful when updates are infrequent
- Dynamic Storage
 - Store state on parasitic capacitors
 - Hold state only for short period of time (milli-seconds)
 - Require periodic refresh
 - Simpler design, higher speed, and lower power

Latch Design (I)

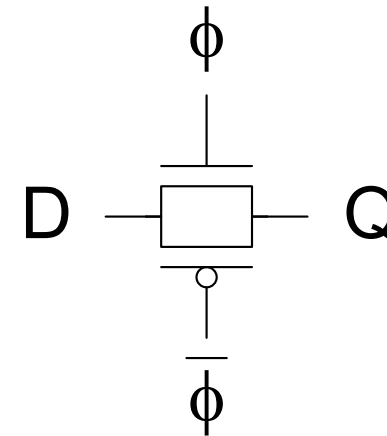
- Pass-transistor latch
- Pros:
 - Tiny
 - Low load on clock signal
- Cons:
 - V_{th} drop (not rail-to-rail)
 - Non-restoring
 - Back-driving
 - Output noise sensitivity
 - Dynamic (float when opaque)
 - Diffusion input



(used in 1970's)

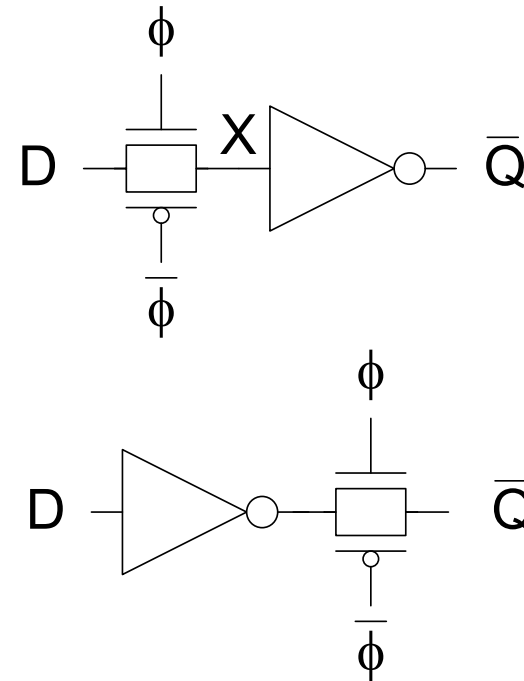
Latch Design (II)

- Transmission gate
- Pros:
 - No V_{th} drop
- Cons:
 - Inverted clock signal required



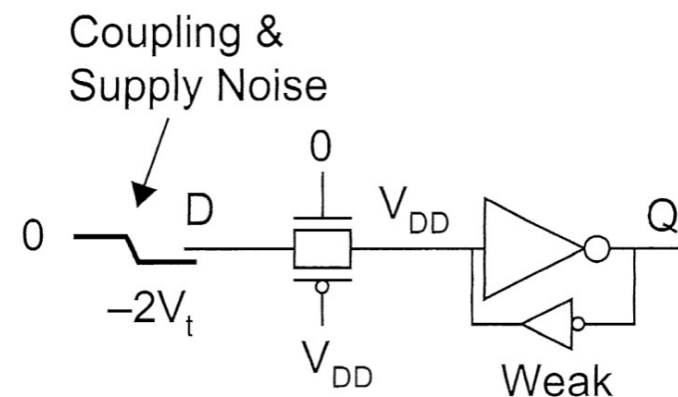
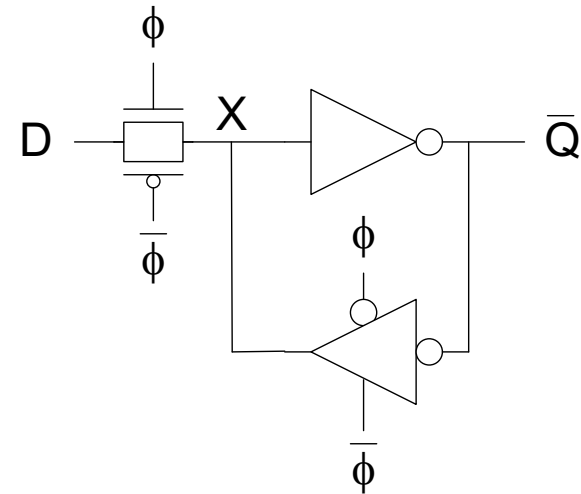
Latch Design (III)

- Buffered version
- Pros:
 - Restoring
 - No back-driving that fixes either one of the followings
 - Output noise sensitivity
 - Diffusion input
- Cons:
 - Inverted output



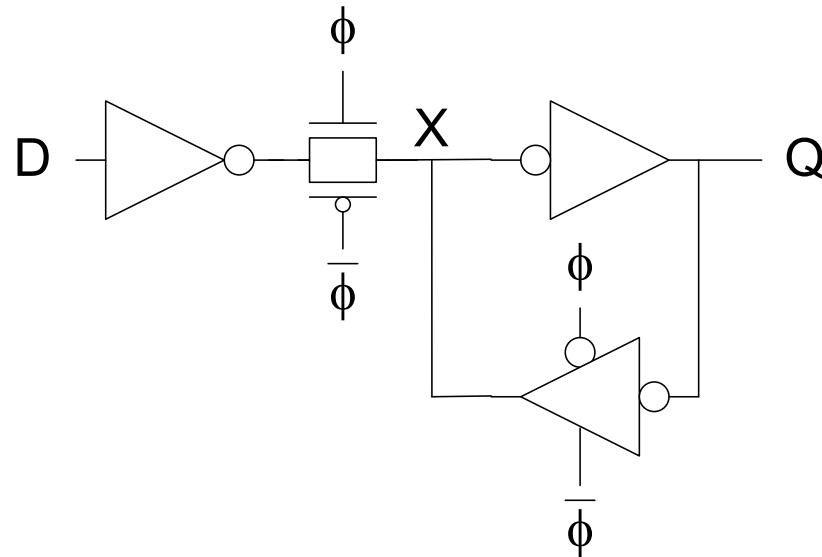
Latch Design (IV)

- Tristate feedback
- Pros:
 - Static
 - Static latches are now essential
- Cons:
 - Back-driving risk
 - Diffusion input
 - Noise can sneak through OFF transmission gate and destroy output

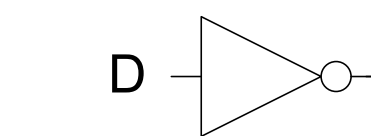


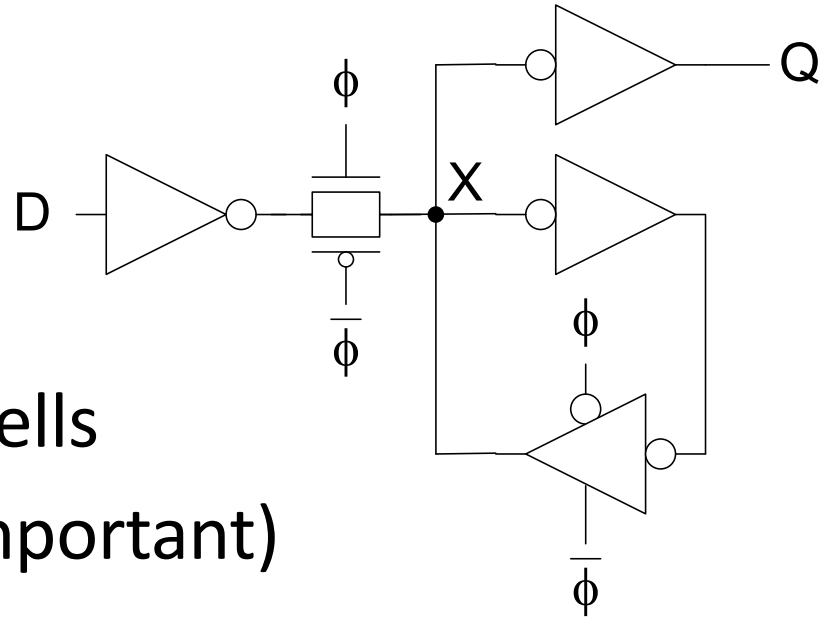
Latch Design (V)

- Buffered input with feedback
- Pros:
 - Fixes diffusion input
 - Non-inverting
- Cons:
 - Output noise back-driving



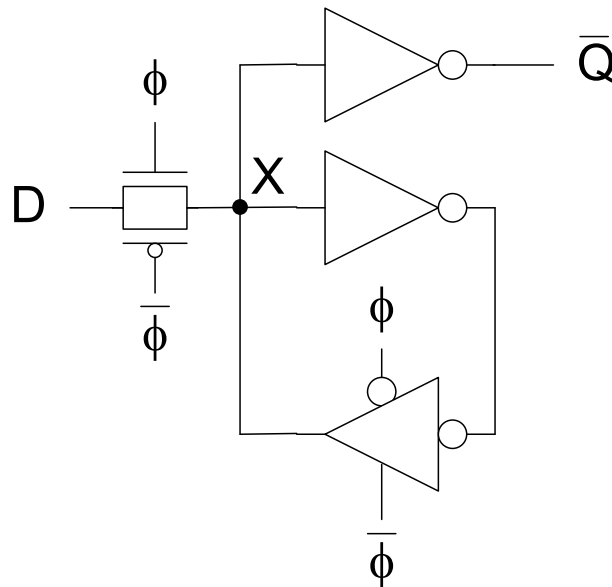
Latch Design (VI)

- Buffered output
 - No back-driving
- 
- Widely used in standard cells
 - Pros: very robust (most important)
 - Cons:
 - Rather large
 - Rather slow (1.5 to 2 FO4 delays)
 - High clock loading



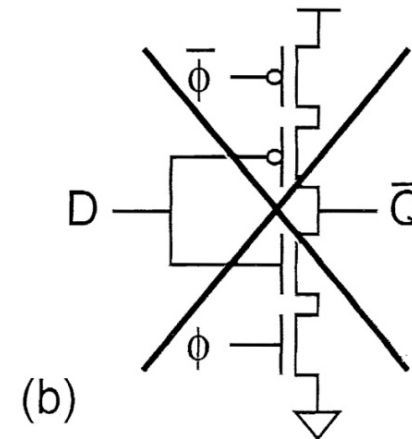
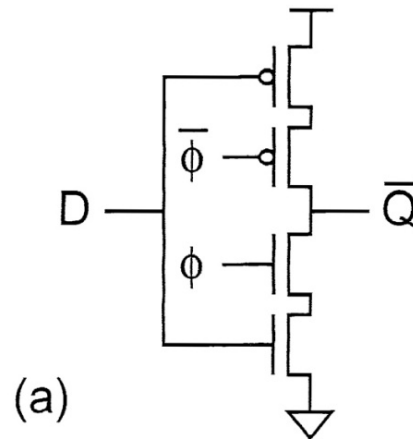
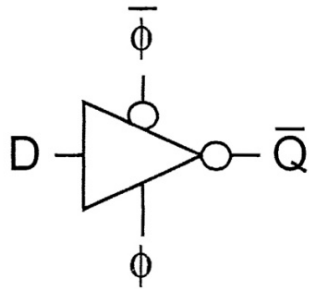
Latch Design (VII)

- Another alternative
 - Smaller and faster
 - Need to be careful with noise control



Clocked CMOS: C²MOS

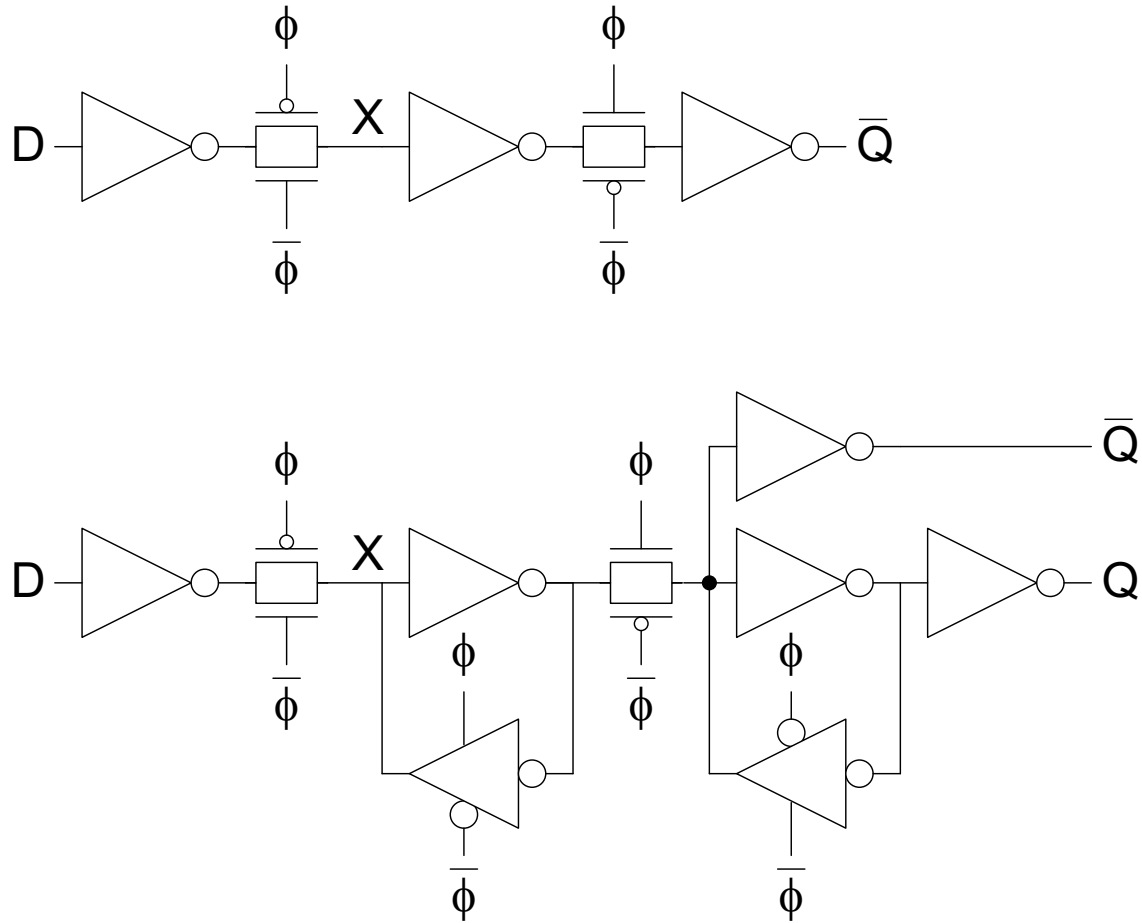
- C²MOS latch
 - Smaller
 - Slower



Bad design: toggling in D causes charge sharing noise when opaque

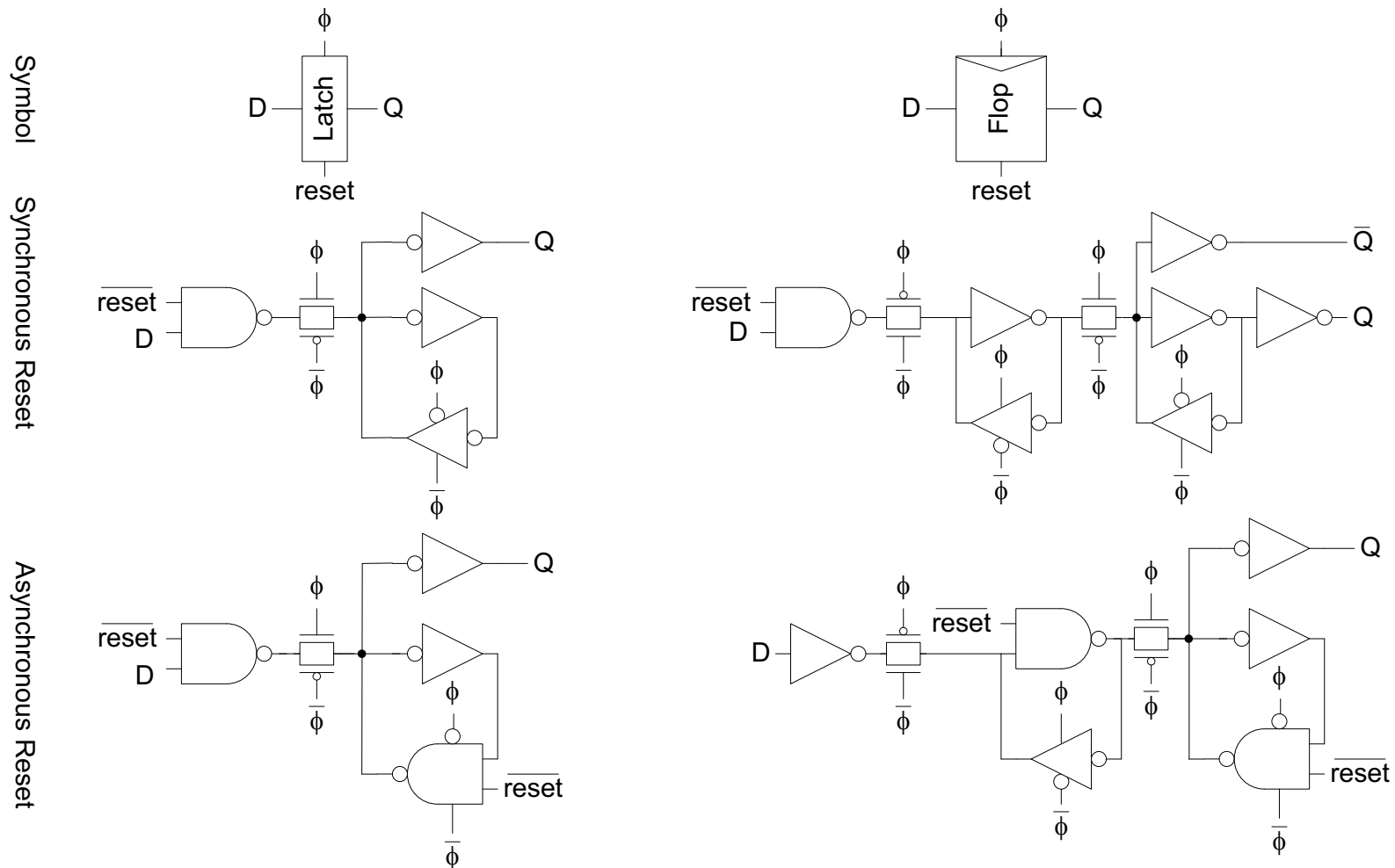
Flip-Flop Design

- Flip-flop is built as a pair of back-to-back latches



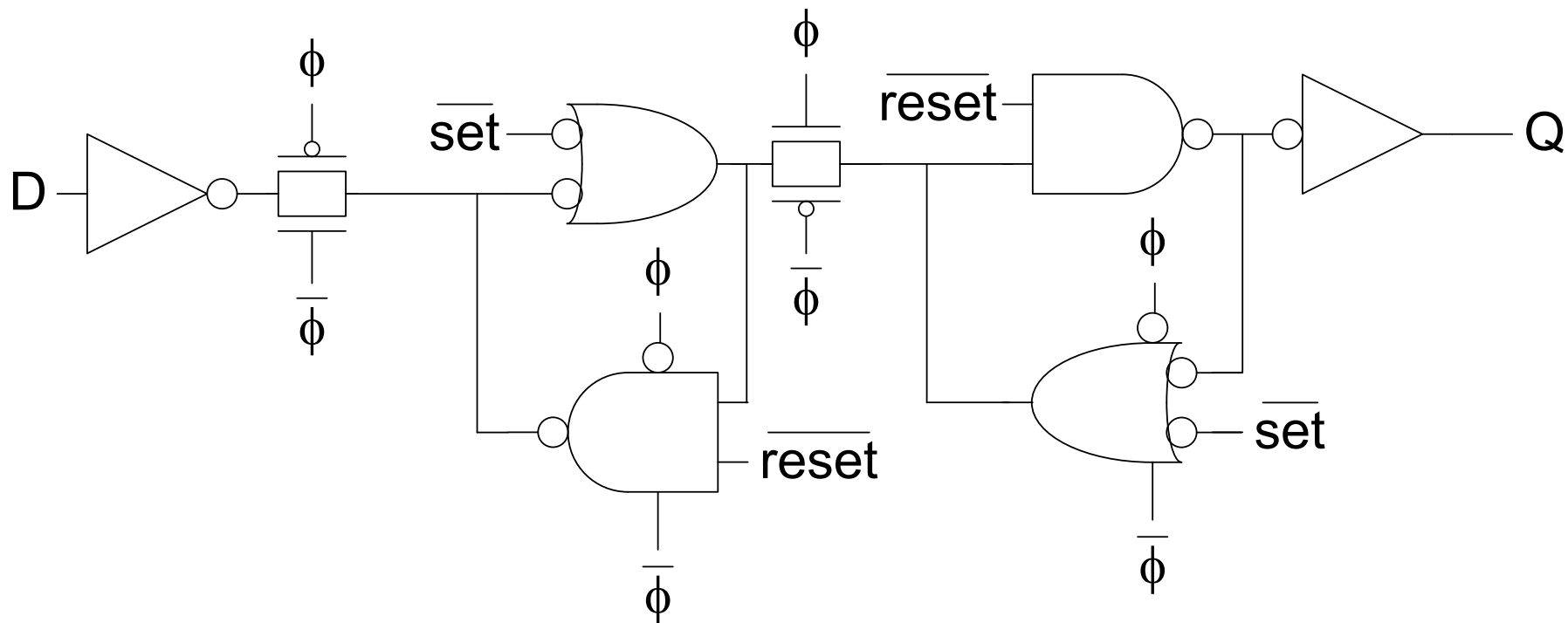
Reset

- Force output low when **reset** signal is asserted
- Synchronous vs. asynchronous



Set/Reset

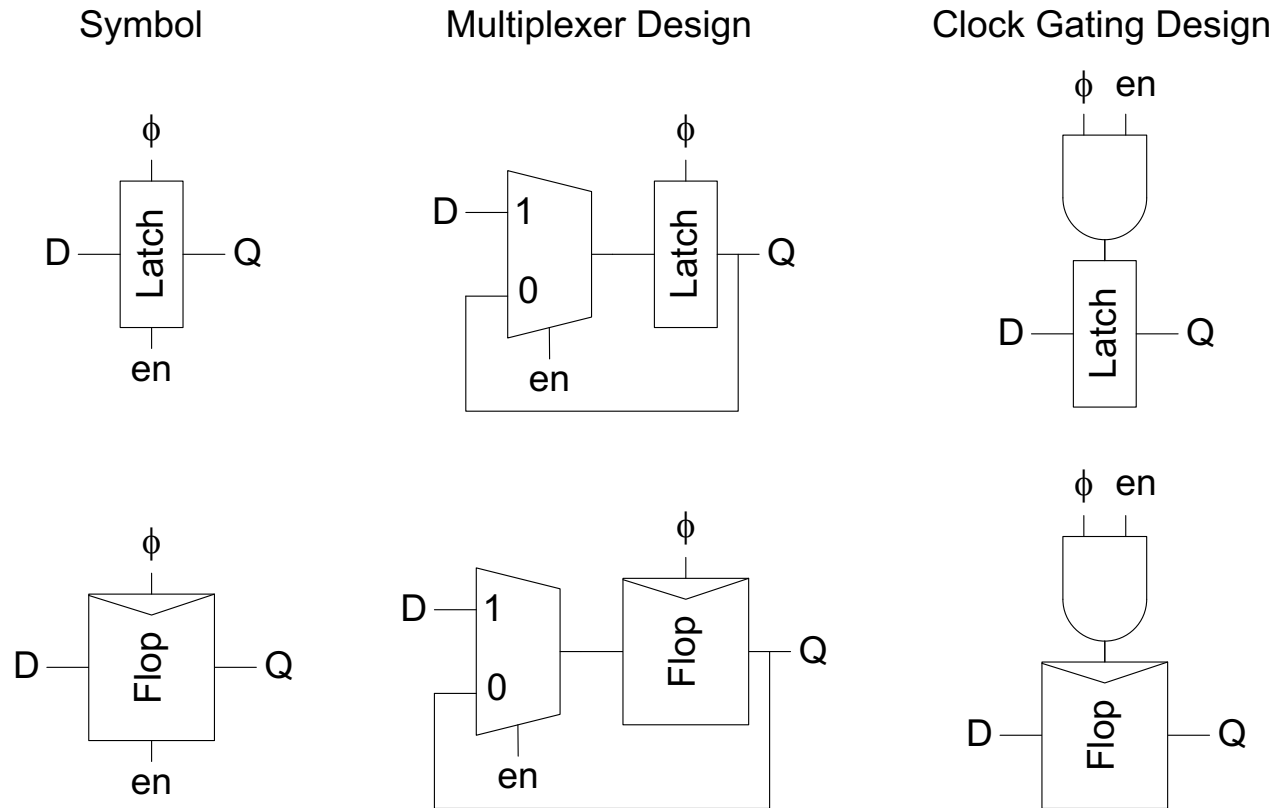
- Force output low when **reset** signal is asserted
- Force output high when **set** signal is asserted



- **Example:** flip-flop with asynchronous set and reset

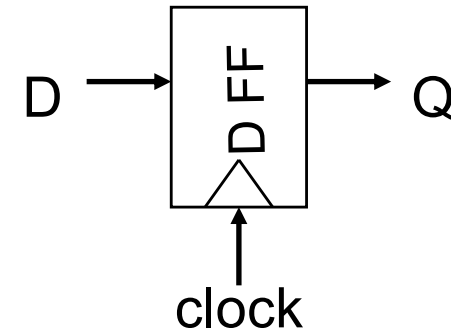
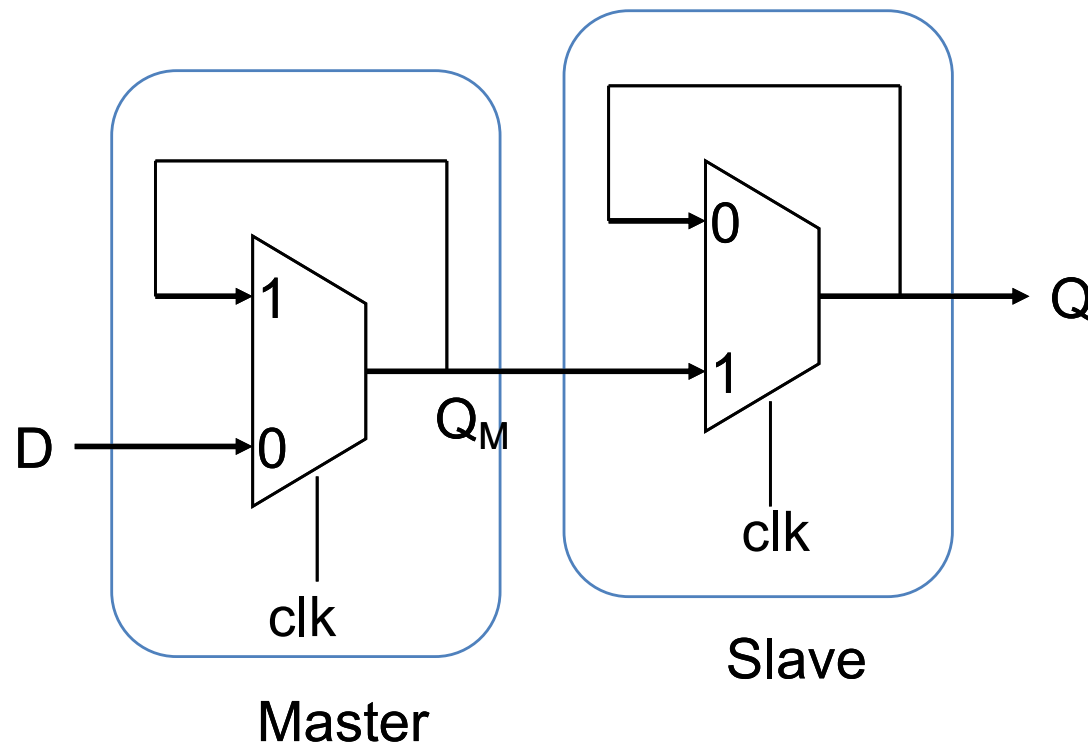
Enable

- Ignore clock when $en = 0$
 - MUX: increase D-to-Q delay
 - Clock gating: increase set-up time and skew

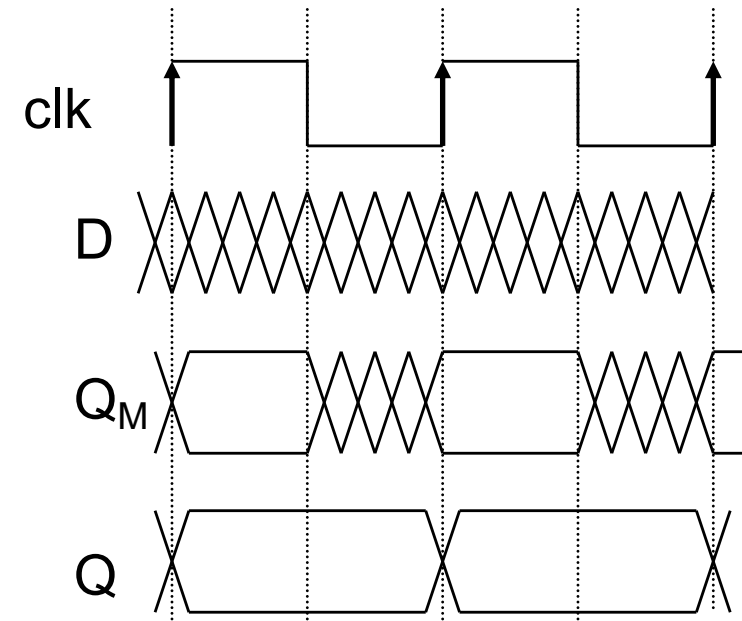


Sequencing Elements Characterization

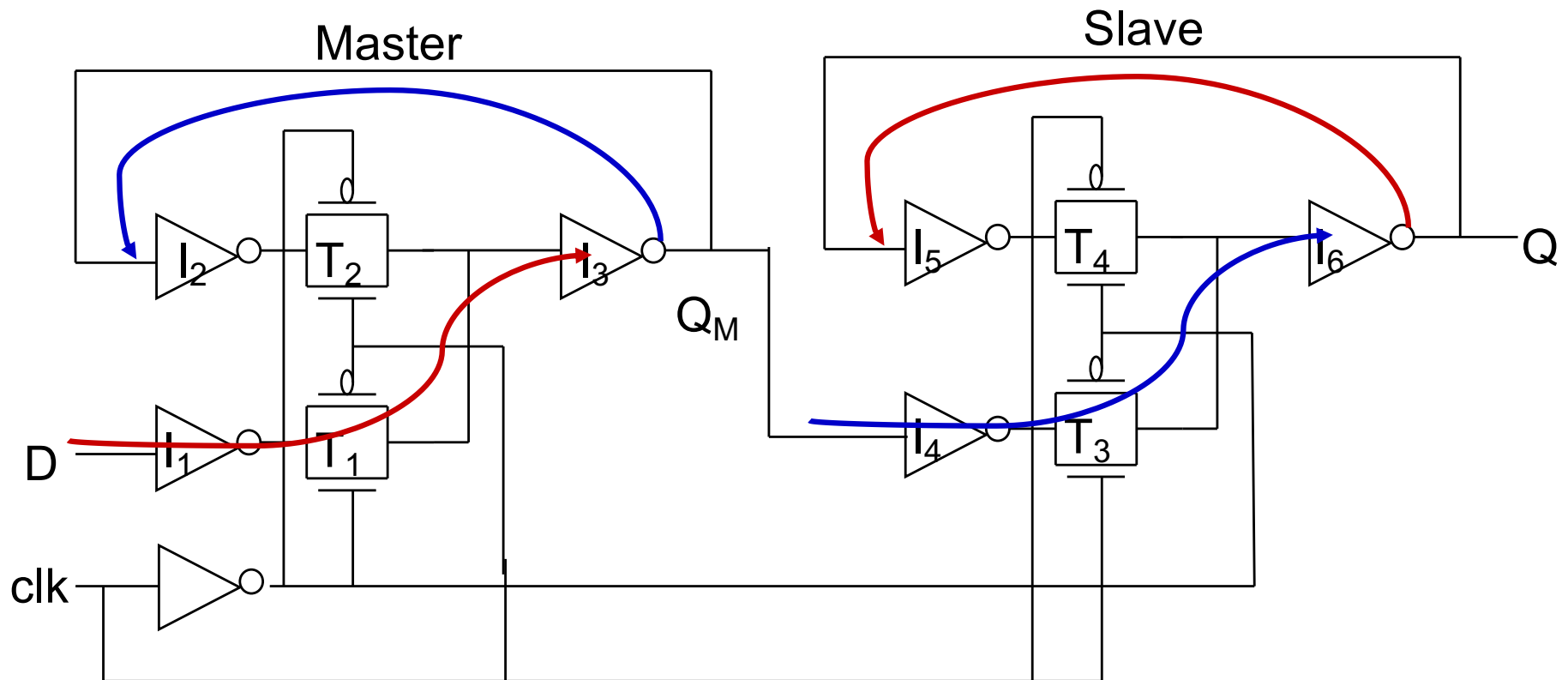
- Master-slave-based edge-triggered flip-flop



clk = 0 transparent hold
clk = 0 → 1 hold transparent



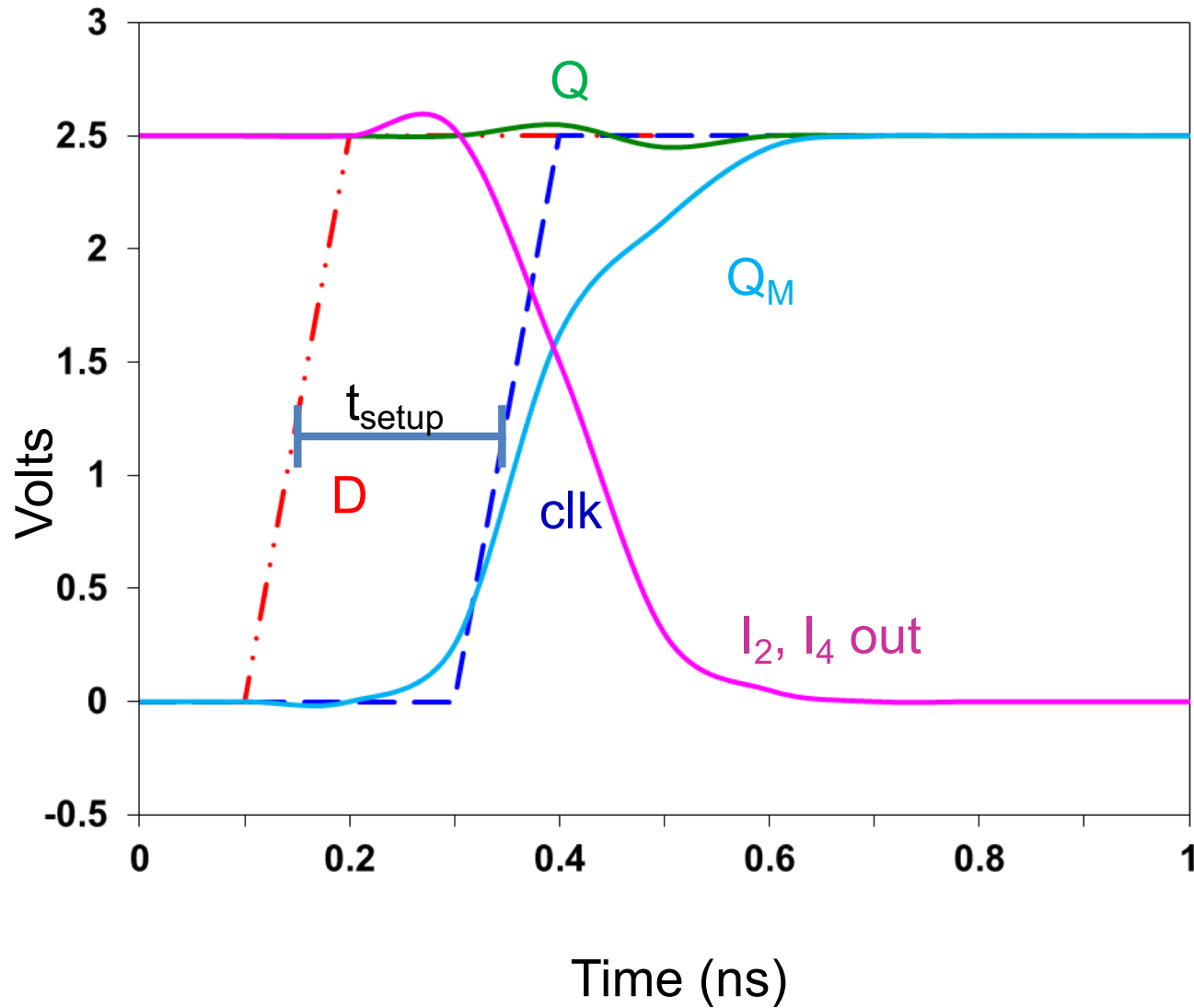
Implementation



Timing Properties

- Assume
 - Propagation delays are t_{pd_inv} and t_{pd_tx}
 - Contamination delay is 0
 - Inverter delay to clk is 0
- **Setup time:** time before rising edge of clk that D must be valid
$$t_{su} = 3 * t_{pd_inv} + t_{pd_tx}$$
- **Propagation delay:** time for D to reach Q
$$t_{c2q} = t_{pd_inv} + t_{pd_tx}$$
- **Hold time:** time D must be stable after rising edge of clk
$$t_{hold} = \text{zero}$$
 - Slow clock can cause both latches transparent and increase hold time

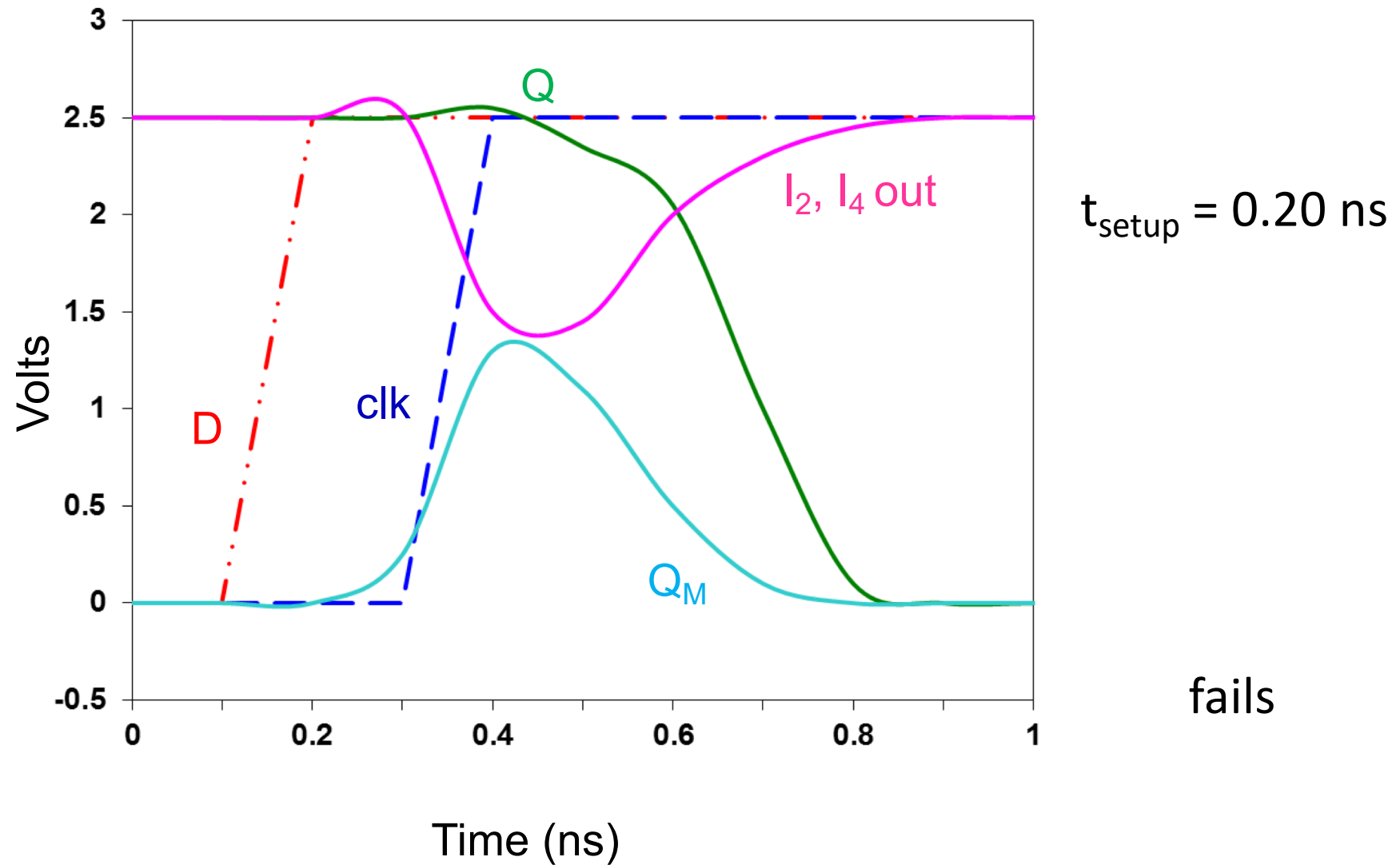
Setup Time Simulation (I)



$$t_{\text{setup}} = 0.21 \text{ ns}$$

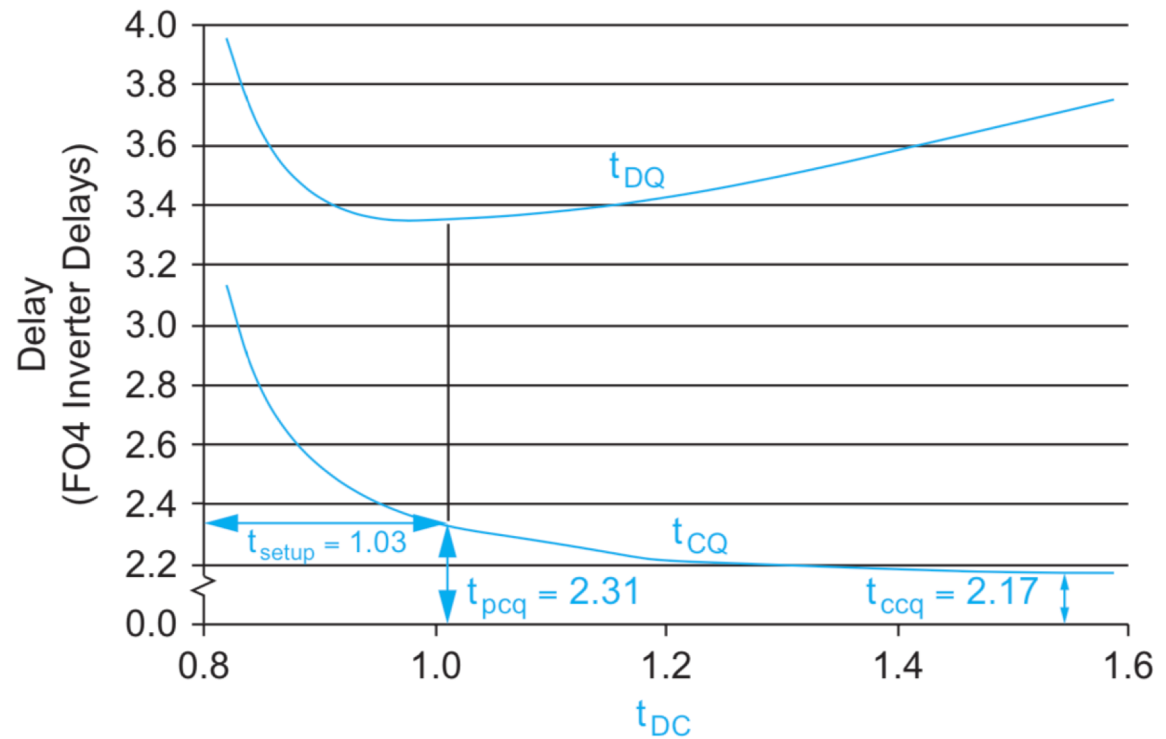
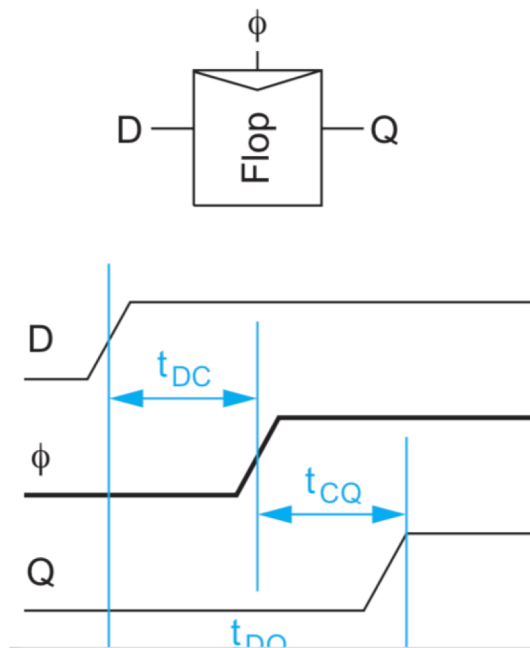
works correctly

Setup Time Simulation (II)



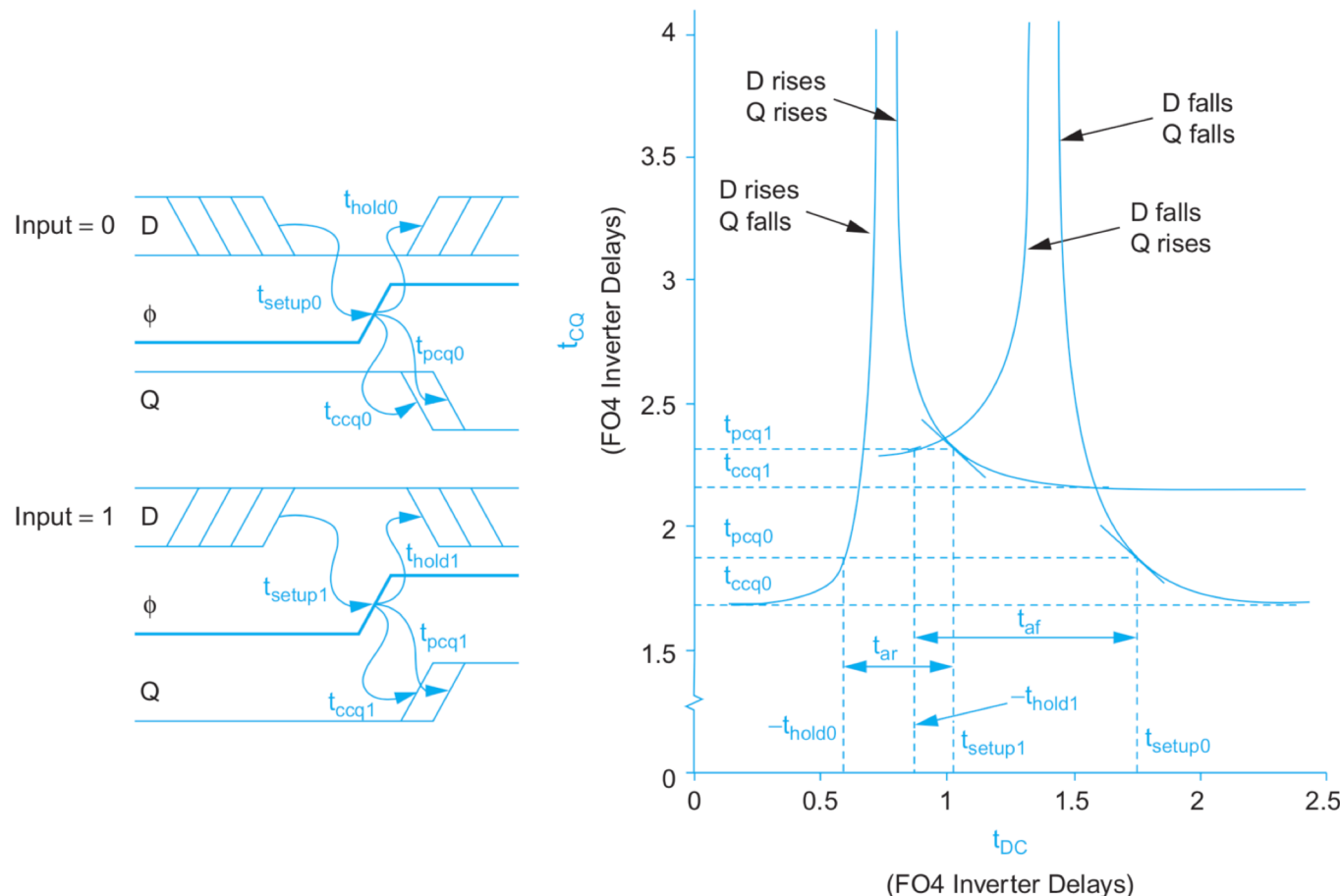
Sequencing Element Characterization (I)

- Flip flops
- **Setup time:** minimize t_{D2Q}



Sequencing Element Characterization (II)

- **Hold time:** min. time from clock to D for $t_{C2Q} < t_{pcq}$
- **Aperture width:** the width of timing window around clock edge during which data must not transition



Sequencing Element Characterization (III)

- Latches
- Setup time: t_{D2Q} 5% greater than min. value

