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Case II: $\frac{dy}{dt} = f(y) \stackrel{\text{ex:}}{=} 4y(1-y)$

- * Such DE is called " " DE, where the RHS does not depend on the independent variable t .
 ** Many of the DEs that arise in application are " "
- for , slope is the same.
 - geometrically, all the slopes on each line are parallel.

Feature:

- ① We can get infinite solutions from one solution curve by translating the curve
(ex:
- ② Depending on the values of the slopes, we can divide the slope field into the following regions:

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Remarks:

- ① We can use the phase line to roughly and quickly predict the system

Ex: If a system can be modeled by an ODE as

$$\frac{dy}{dt} = \left(1 - \frac{y}{20}\right)^3 \left(\frac{y}{5} - 1\right) y^7, \quad y(0) = 8$$

- ② Classification of critical points:

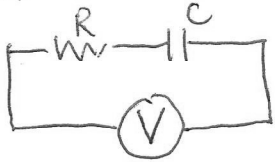


- ③ For a system with "growing and bounded" feature, the response normally exhibits an , and yields an ODE with a math form of

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Example: Use qualitative approach to analyze a circuit problem.

An RC circuit

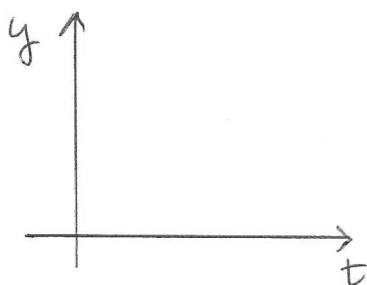


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II. Numerical approach (Ch 2-6)

The geometric concept of the _____ is closely related to the ideas used in numerical methods for approximating solutions to a DE. In this class, we will discuss a numerical method called

Example: Solve $\frac{dy}{dt} = 0.2ty$, $y(t_0) = y_0$ by Euler's method.



procedures:

- ① Start at (t_0, y_0) in the slope field
- ② Move a tiny step
- ③ Use the slope at _____ to get the
- ④ At (t_1, y_1) , the procedures are repeated.
Take a step whose size is Δt and whose direction is determined by

General expression of Euler's method for $\frac{dy}{dt} = f(t, y)$

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Remarks:

- ① In Euler's method, we always make an error in each step. (called "truncation error").
- ② More numerical methods, such as Runge-Kutta, are used with improved accuracy.
- ③ Numerical methods are commonly used to solve complicated PDEs and are widely used in many fields.