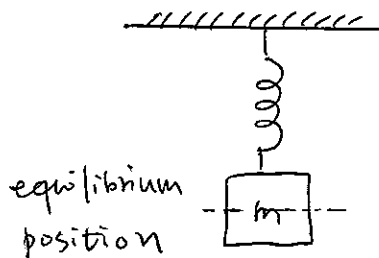


Introduction

Q1:

Example: A spring-mass system (Ch 5.1.1)



A mass  $m$  is attached to a spring with a spring constant  $K$ .

The motion of the mass follows Newton's 2nd law:

$$\sum F = ma = m \frac{d^2y}{dt^2}$$

What are the forces that the mass experiences?

- "external force":  $F_{ext}$
- "restoring force" of the spring (Hooke's law)
- "damping force" due to the resistance from air

$$\sum F = F_{ext} + F_{restoring} + F_{damping} = m \frac{d^2y}{dt^2}$$

$$\Rightarrow F_{ext} - Ky - b \frac{dy}{dt} = m \frac{d^2y}{dt^2}$$

$\Rightarrow$

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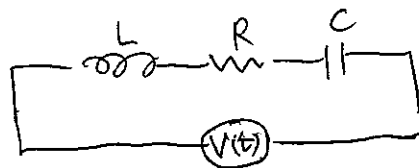
姓名 P2

(Note: In this system, a driving force  $F_{ext}$  is applied, causing the changes of the displacement  $y$ . So we call  $F_{ext}$  is the \_\_\_\_\_ of the system.

and  $y$  is the \_\_\_\_\_ of the system.

Now, consider a totally different system. In a circuit class, you will be dealing with circuit problems with  $R, L, C$  components.

For a LRC-series circuit driven by a voltage source  $V(t)$ .



By Kirchhoff's 2nd law, the charges of the circuit can be related to the driving voltage by



This is the circuit analogue of the spring-mass system. In the two completely different systems, not only the

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resulting DEs have the same form, but each term has similar physical interpretation.

ex: mass-spring  $\longleftrightarrow$  LRC ckt

From the above discussion, we then know

⇒ Many different engineering/physics systems involve changes of quantities under some operation conditions, that can be described by DEs.

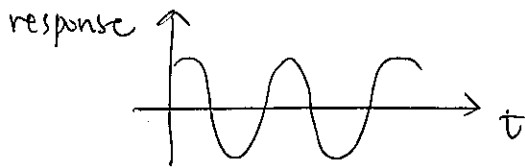
⇒ Many systems yield the same form of DE with similar physical interpretations.

In this class, we will learn how to solve some of the most commonly used DEs in engineering/physics.

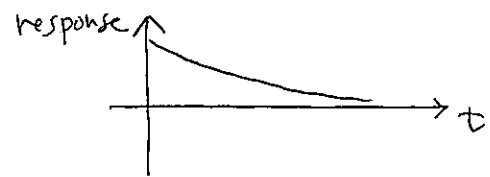
Q<sub>2</sub>: What are we interested in these systems?

→ How do the responses of the systems change (with time)?

ex:



or



or



(Note: Because  $y$  or  $q$  is a function of time (depend on time), we call "t" is the independent variable.

"y" is the dependent variable.  
"q")

→ Will this system be stable?

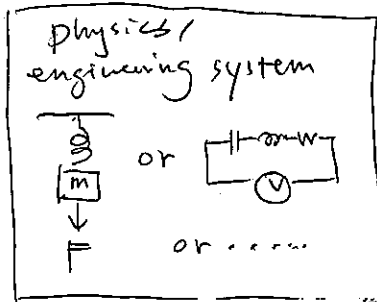
(What is the "long-term behavior" of the system?)

→ How do the responses change under

{ different driving forces?  
(inputs)  
different values of parameters?

Q3: What do we need to learn in this class?

→ learn how to "model" a system



1) Identify the quantities

- indep variables
- dep variables
- input (driving force)
- output (response)
- parameters

DE relating  
the quantities

$$a \frac{d^2 y}{dt^2} + b \frac{dy}{dt} + c y = V$$

2) Based on the system  
descriptions, create the DE.

→ learn how to solve DEs

Three types of approaches to solve DEs