

# EE 205003 Session 14

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# Ch 3 Vector Spaces and Subspaces

## New vector space

All  $3 \times 3$  matrices form a vector space  $\mathbf{M}$

(we can add matrices, multiply by scalar & there is a new matrix)

( $A + B, cA$ ) (not  $AB$  for now)

(All of rules are satisfied)

## Subspaces

- All upper triangular matrices ( $\mathcal{U}$ )
- All symmetric matrices ( $\mathbf{S}$ )
- All diagonal matrices ( $\mathbf{D}$ )

Note :  $\mathbf{D} = \mathcal{U} \cap \mathbf{S}$

# Ch 3 Vector Spaces and Subspaces

## Q: What is the dimension of $D$ ?

$$\dim(D) = 3$$

$$\text{basis : } \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

## Q: What is the dimension of $M$ ?

$$\dim(M) = 9$$

basis : (standard)

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \dots, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Very similar to  $\mathbb{R}^9$  just arrange in a matrix form

# Ch 3 Vector Spaces and Subspaces

**Q: What is the dimension of the subspace S ?**

$\dim(S) = 6$  (pick 3 diagonal elements + 3 in upper right)  
(lower left determined by upper right)

basis :

(Also basis for M)

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ & 0 \end{bmatrix}, \begin{bmatrix} 0 & \\ & 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 & \\ 1 & 0 & \\ & & 0 \end{bmatrix},$$
$$\begin{bmatrix} 0 & 1 & \\ & 0 & 0 \\ 1 & 0 & \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

(Not basis for M)

## Ch 3 Vector Spaces and Subspaces

**Q: What is the dim. of the subspace  $\mathcal{U}$  ?**

$\dim(\mathcal{U}) = 6$  (3 diagonal + 3 upper right)

basis : (different from  $\mathbf{S}$ )

$$\begin{bmatrix} 1 & & \\ & 0 & \\ & & 0 \end{bmatrix}, \begin{bmatrix} 0 & & \\ & 1 & \\ & & 0 \end{bmatrix}, \begin{bmatrix} 0 & & \\ & 0 & \\ & & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 & \\ & 0 & \\ & & 0 \end{bmatrix},$$

$$\begin{bmatrix} 0 & 0 & \\ & 0 & 1 \\ & & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ & 0 & 0 \\ & & 0 \end{bmatrix} \quad (\text{happens to be a subset of basis of } \mathbf{M})$$

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## Other subspaces

$\mathbf{S} \cap \mathcal{U}$  = symmetric & upper triangular  
=  $\mathbf{D}$

$$\dim(\mathbf{S} \cap \mathcal{U}) = 3$$

$\mathbf{S} \cup \mathcal{U}$  = symmetric or upper triangular

(Not a subspace since a symmetric matrix + a upper triangular matrix is NOT in  $\mathbf{S} \cup \mathcal{U}$  in general)

(Analogy : two lines in  $\mathbb{R}^2$  is NOT a subspace.  
Need to fill in between them)

# Ch 3 Vector Spaces and Subspaces

## Other subspaces (cont.)

Instead,

$\mathbf{S} + \mathcal{U}$  = any element of  $\mathbf{S}$  + any element of  $\mathcal{U}$

(sum subspace)

= All  $3 \times 3 = \mathbf{M}$

$$\left( \begin{bmatrix} 1 & 4 & 7 \\ 2 & 5 & 8 \\ 3 & 6 & 9 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 6 \\ 3 & 6 & 9 \end{bmatrix} + \begin{bmatrix} 0 & 2 & 4 \\ & 0 & 2 \\ & & 0 \end{bmatrix} \right)$$

$$\dim(\mathbf{S} + \mathcal{U}) = 9$$

In general,

$$\begin{array}{ccccccc} \dim(\mathbf{S}) & + & \dim(\mathcal{U}) & = & \dim(\mathbf{S} + \mathcal{U}) & + & \dim(\mathbf{S} \cap \mathcal{U}) \\ 6 & + & 6 & & 9 & + & 3 \end{array}$$

# Ch 3 Vector Spaces and Subspaces

## Differential equations as a vector space

$\frac{d^2y}{dx^2} + y = 0$ , solution to this equation is a element of the nullspace  
possible solutions :

$$y = \underbrace{\cos x, \sin x}_{\text{basis}}, e^{ix} \text{ (special solutions)}$$

complete solutions :  $y = c_1 \cos x + c_2 \sin x$

$\dim(\text{solution space}) = 2$  (since this is a  $2^{nd}$ -order equation)

(Don't look like vectors, but we can build a vector space  
from it since we can add & multiply by a scalar)



# Ch 3 Vector Spaces and Subspaces

## Rank one matrices

$$A = \begin{bmatrix} 1 & 4 & 5 \\ 2 & 8 & 10 \end{bmatrix}$$

Q: What is the rank of  $A$  ?

$$\text{rank}(A) = 1 \text{ (row2} = 2 \cdot \text{row1)}$$

$$\dim(\mathbf{C}(A)) = \text{rank} = \dim(\mathbf{C}(A^T))$$

$$\text{or} \quad A = \begin{bmatrix} 1 & 4 & 5 \\ 2 & 8 & 10 \end{bmatrix} \overset{\substack{|| \\ 1}}{=} \begin{bmatrix} 1 \\ 2 \end{bmatrix}_{2 \times 1} \begin{bmatrix} 1 & 4 & 5 \end{bmatrix}_{1 \times 3}$$

(each col. is a multiple of col.1 or  
each row is a multiple of row1)

## Ch 3 Vector Spaces and Subspaces

### Q: What is the rank of $A$ ? (cont.)

In general, for every rank-1 matrix

$$A = \mathbf{u}\mathbf{v}^T = \begin{bmatrix} \phantom{0} \\ \phantom{0} \\ \phantom{0} \end{bmatrix} \begin{bmatrix} \phantom{0} & \phantom{0} & \phantom{0} \end{bmatrix}$$

(building blocks for more complicated matrix,  
e.g., a  $5 \times 17$  rank-4 matrix can be written as  
comb. of 4 rank-1 matrices)

(To be discussed later)

### Q: Is subset of rank-1 matrices a subspace ?

No, since sum of two rank-1 matrices may NOT be rank-1

# Ch 3 Vector Spaces and Subspaces

## Another example

In  $\mathbb{R}^4$ , the set of all vectors  $\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix}$  for which  $v_1 + v_2 + v_3 + v_4 = 0$

## Q: Is this a subspace ?

Yes ! it contains  $\mathbf{0}$  & closed under ADD & scalar MUL

$$\left( \mathbf{w} + \mathbf{v} = \begin{bmatrix} w_1 + v_1 \\ w_2 + v_2 \\ w_3 + v_3 \\ w_4 + v_4 \end{bmatrix} \text{ sum of all components} = 0 \right)$$

# Ch 3 Vector Spaces and Subspaces

## Q: What is the dimension ?

This is a null space of

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \end{bmatrix}$$

$$\text{rank}(A) = 1$$

$$\Rightarrow \dim(\mathbf{N}(A)) = n - r = 4 - 1 = 3$$

Basis :

Find special solutions

$$\left. \begin{array}{l} \text{col}_2 = 1 \cdot \text{col}_1 \\ \text{col}_3 = \dots \\ \text{col}_4 = \dots \end{array} \right) \Rightarrow \begin{bmatrix} -1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

## Q: What is $\mathbf{C}(A)$ ?

$$1 \text{ pivot \& } m = 1 \Rightarrow \mathbf{C}(A) = \mathbb{R}^1$$

# Ch 3 Vector Spaces and Subspaces

**Q: What is  $\mathbf{N}(A^T)$  ?**

$$\mathbf{y}^T \begin{bmatrix} 1 & 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 \end{bmatrix}$$

$$y = 0 \Rightarrow \mathbf{N}(A^T) = \{0\}$$

(basis is empty set)

**Q: What is  $\mathbf{C}(A^T)$  ?**

$$\dim(\mathbf{C}(A^T)) = r = 1$$

$$\text{basis : } \begin{bmatrix} 1 & 1 & 1 & 1 \end{bmatrix}$$

**Check dimension**

$$\dim(\mathbf{C}(A^T)) + \dim(\mathbf{N}(A)) = 1 + 3 = 4 = n$$

$$\dim(\mathbf{C}(A)) + \dim(\mathbf{N}(A^T)) = 1 + 0 = 1 = m$$