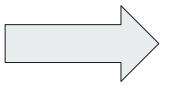
Midterm Deep Learning Images Caption

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What is images caption?

Image Captioning is the task of describing the content of an image in words. This task lies at the intersection of computer vision and natural language processing. Most image captioning systems use an encoder-decoder framework, where an input image is encoded into an intermediate representation of the information in the image, and then decoded into a descriptive text sequence.





A child in a pink dress is climbing up a set of stairs in an entry way .

Output

Input

Idea

The first problem of this problem is, this problem has 2 input data sources at the time of training. The first is the photo, the second is the caption of the photo.



A brown dog is running in the field grass

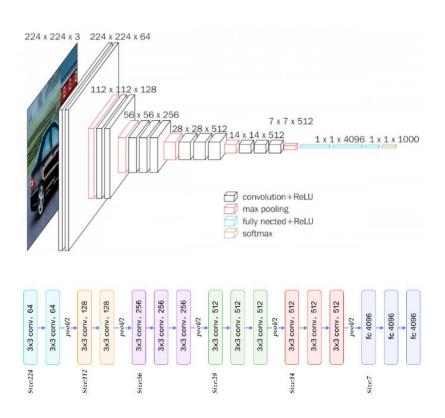


RNN

CNN

VGG16

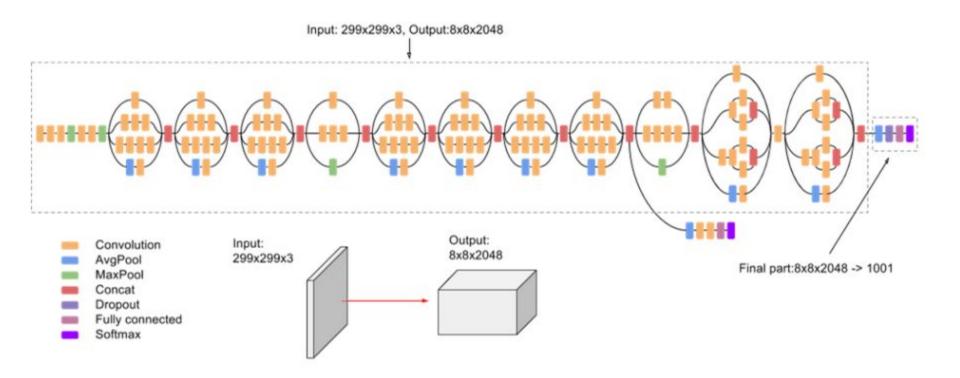
The full name of VGG is the Visual Geometry Group, which belongs to the Department of Science and Engineering of Oxford University. It has released a series of convolutional network models beginning with VGG, which can be applied to face recognition and image classification, from VGG16 to VGG19. The original purpose of VGG's research on the depth of convolutional networks is to understand how the depth of convolutional networks affects the accuracy and accuracy of large-scale image classification and recognition. -Deep-16 CNN), in order to deepen the number of network layers and to avoid too many parameters, a small 3x3 convolution kernel is used in all layers.



| Layer | | Feature Map | Size | Kernel Size | Stride | Activation |
|--------|-----------------|----------------|-----------------|-------------|----------|------------|
| Input | Image | 1 | 224 x 224 x 3 | 2 | <u>~</u> | - |
| 1 | 2 X Convolution | 64 | 224 x 224 x 64 | 3x3 | 1 | relu |
| | Max Pooling | 64 | 112 x 112 x 64 | 3x3 | 2 | relu |
| 3 | 2 X Convolution | 128 | 112 x 112 x 128 | 3x3 | 1 | relu |
| | Max Pooling | 128 | 56 x 56 x 128 | 3x3 | 2 | relu |
| 5 | 2 X Convolution | 256 | 56 x 56 x 256 | 3x3 | 1 | relu |
| | Max Pooling | 256 | 28 x 28 x 256 | 3x3 | 2 | relu |
| 7 | 3 X Convolution | 512 | 28 x 28 x 512 | 3x3 | 1 | relu |
| | Max Pooling | 512 | 14 x 14 x 512 | 3x3 | 2 | relu |
| 10 | 3 X Convolution | 512 | 14 x 14 x 512 | 3x3 | 1 | relu |
| | Max Pooling | 512 | 7 x 7 x 512 | 3x3 | 2 | relu |
| 13 | FC | - | 25088 | 4 | 2 | relu |
| 14 | FC | - | 4096 | - | = | relu |
| 15 | FC | = | 4096 | - | è | relu |
| Output | FC | - | 1000 | - | - | Softmax |

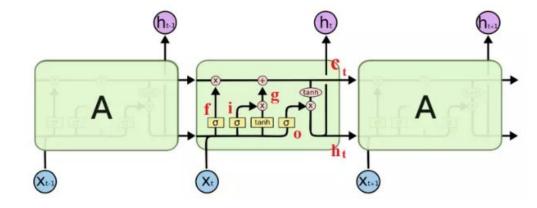
InceptionV3

Inception-v3 is a **pre-trained convolutional neural network** that is 48 layers deep, which is a version of the network already trained on more than a million images from the ImageNet database. This pretrained network can classify images into 1000 object categories, such as keyboard, mouse, pencil, and many animals. As a result, the network has learned rich feature representations for a wide range of images. The network has an image input size of 299-by-299. The model extracts general features from input images in the first part and classifies them based on those features in the second part.



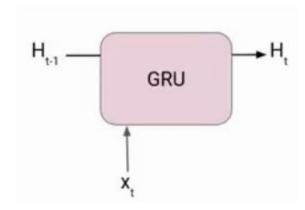
LSTM

Long Short Term Memory networks, commonly known as LSTMs - are a special type of RNN that is capable of learning distant dependencies. LSTM was introduced by Hochreiter & Schmidhuber (1997), and has since been refined and popularized by many people in the industry. They work extremely effectively on many different problems, so they have gradually become as popular as they are today.



GRU

GRUs are very similar to Long Short Term Memory(LSTM). Just like LSTM, GRU uses gates to control the flow of information. They are relatively new as compared to LSTM. This is the reason they offer some improvement over LSTM and have simpler architecture.

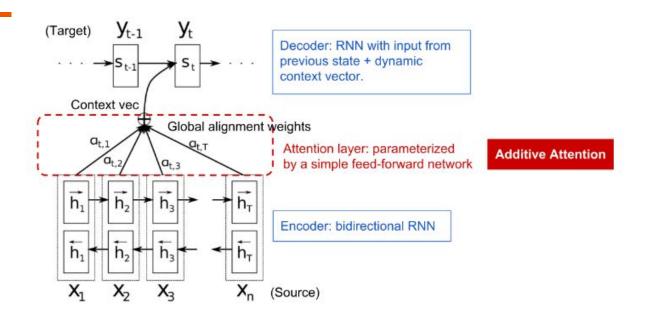


Reset Gate (Short term memory): $r_t = \sigma(x_t * U_r + H_{t-1} * W_r)$

Update Gate (Long Term memory): $u_t = \sigma (x_t * U_u + H_{t-1} * W_u)$

Attention mechanism

ATTENTION MECHANISM is a mechanism that makes it possible for the model to focus on important parts of the data, by creating an alignment model a that calculates the alignment score aij to REWEIGHT the hidden state hj of the encoder. In the NMT problem using seq2seq, that helps the model focus more on the important words in the input x sentence, thereby predicting the next yi word at the decoder, which is represented by brightly colored boxes as shown in the confusion matrix below. above, is also the degree of correlation from xj (source) and from yi (target)



BLEU score

BLEU stands for Bilingual Evaluation Understudy, which is a method for evaluating a translation based on reference translations, introduced in the paper BLEU: a Method for Automatic Evaluation of Machine Translation). BLEU is designed for use in machine translation, but in fact, this measurement is also used in tasks such as text summarization, speech recognition, image label generation, etc. Besides, this measurement can completely be used to assess the quality of the staff's translation.

 $Bleu(N) = Brevity\ Penalty \cdot Geometric\ Average\ Precision\ Scores(N)$

Implement

We use Flickr8k data for our model

It contains 8000 pictures and each picture has 5 captions



"A man holding money

A man holds a dollar bill in front of his face while posing in front of a street band

A man holds money in the air

A man in a green jacket is standing outside a store holding some money in front of his face

"An African-American man wearing a green sweatshirt and blue vest is holding up 2 dollar bills in front of his face

Clean data

Converting to lowercase

Remove punctuation

Remove numeric values

Add <start> and end tag

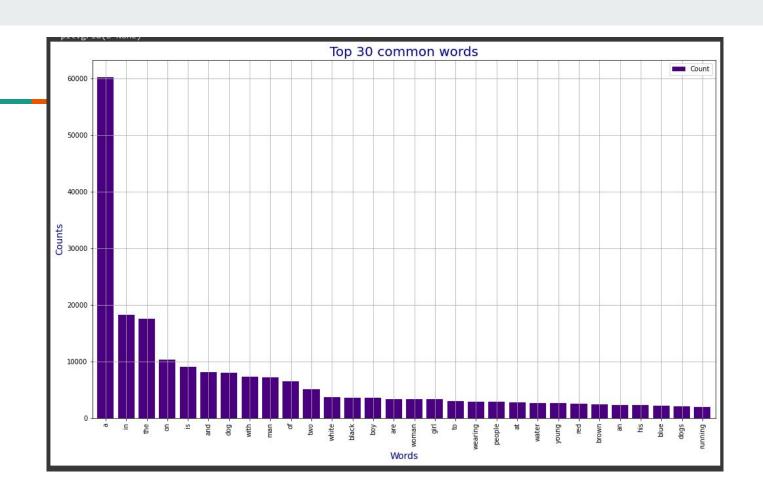
A child in a pink dress is climbing up a set of stairs in an entry way .



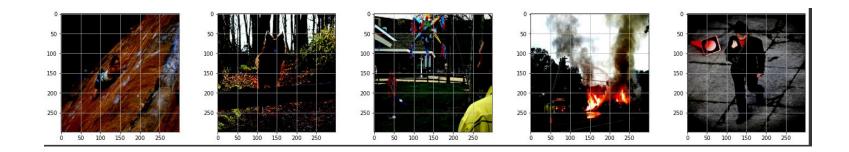
<start> child in pink dress is climbing up set of stairs in an entry way <end>

Data processing

Remove symbols and add UNK for unknown words



Store images and resize(299, 299, 3)



```
image_model = tf.keras.applications.InceptionV3(include_top=False,weights='imagenet')
new_input = image_model.input
hidden_layer = image_model.layers[-1].output
image_features_extract_model = tf.compat.v1.keras.Model(new_input, hidden_layer)
```

Once the features are created, you need to reshape them such that feature shape is in order of (batch_size, 8*8, 2048) image features extract model.summary()

```
# extract features from each image in the dataset
img_features = {}
for image, image_path in tqdm(New_Img) :
  batch_features = image_features_extract_model(image)
  #squeeze out the features in a batch
  batch_features_flattened = tf.reshape(batch_features, (batch_features.shape[0], -1, batch_features.shape[3]))
  for batch_feat, path in zip(batch_features_flattened, image_path) :
    feature_path = path.numpy().decode('utf-8')
    img_features[feature_path] = batch_feat.numpy()
```

```
[ ] # Setting parameters
    embedding_dim = 256
    units = 512
    #top 5,000 words +1
    vocab size = 5001
    train_num_steps = len(path_train) // BATCH_SIZE
    test num steps = len(path test) // BATCH SIZE
    max length = 31
    feature_shape = batch_feat.shape[1]
    attention feature shape = batch feat.shape[0]
```

```
tf.compat.v1.reset default graph()
# print(tf.compat.v1.get default graph())
<tensorflow.python.framework.ops.Graph object at 0x7fb9d8da6f40>
#Building Encoder using CNN Keras subclassing method
class Encoder(Model):
    def init (self,embed dim):
        super(Encoder, self). init ()
        self.dense = tf.keras.layers.Dense(embed dim) #build your Dense layer with relu activation
    def call(self, features):
        features = self.dense(features) # extract the features from the image shape: (batch, 8*8, embed dim)
        features = tf.keras.activations.relu(features, alpha=0.01, max value=None, threshold=0)
        return features
encoder=Encoder(embedding dim)
from keras.utils.vis utils import plot model
```

```
class Attention model(Model):
    def init (self, units):
        super(Attention_model, self).__init__()
        self.W1 = tf.keras.layers.Dense(units)
        self.W2 = tf.keras.layers.Dense(units)
        self.V = tf.keras.layers.Dense(1)
        self.units=units
    def call(self, features, hidden):
        hidden with time axis = hidden[:, tf.newaxis]
        score = tf.keras.activations.tanh(self.W1(features) + self.W2(hidden_with_time_axis))
        attention_weights = tf.keras.activations.softmax(self.V(score), axis=1)
        context vector = attention weights * features
        context vector = tf.reduce sum(context vector, axis=1)
        return context vector, attention weights
```

```
def init (self, embed dim, units, vocab size):
   super(Decoder, self). init ()
   self.units=units
   self.attention = Attention model(self.units) #iniitalise your Attention model with units
   self.embed = tf.keras.layers.Embedding(vocab size, embed dim) #build your Embedding layer
   self.gru = tf.keras.layers.GRU(self.units,return sequences=True,return state=True,recurrent initializer='glorot uniform')
   self.d1 = tf.keras.layers.Dense(self.units) #build your Dense layer
   self.d2 = tf.keras.layers.Dense(vocab size) #build your Dense layer
def call(self,x,features, hidden):
   context_vector, attention_weights = self.attention(features, hidden) #create your context vector & attention weights from attention model
   embed = self.embed(x) # embed your input to shape: (batch size, 1, embedding dim)
   embed = tf.concat([ff.expand dims(context vector, 1), embed], axis = -1) # Concatenate your input with the context vector from attention layer. Shape: (batch size, 1, embedding dim + embedding dim)
   output, state = self.gru(embed) # Extract the output & hidden state from GRU layer. Output shape : (batch_size, max_length, hidden_size)
   output = self.d1(output)
   output = tf.reshape(output, (-1, output.shape[2])) # shape : (batch size * max length, hidden size)
   output = self.d2(output) # shape : (batch size * max length, vocab size)
   return output, state, attention_weights
```

class Decoder(Model):

def init state(self, batch size):

decoder=Decoder(embedding dim, units, vocab size)

return tf.zeros((batch size, self.units))

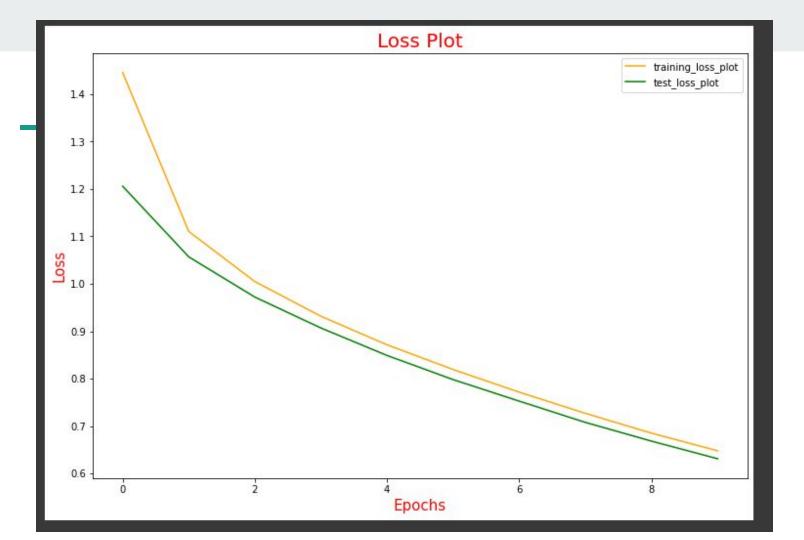
```
features=encoder(sample_img_batch)

hidden = decoder.init_state(batch_size=sample_cap_batch.shape[0])
dec_input = tf.expand_dims([tokenizer.word_index['<start>']] * sample_cap_batch.shape[0], 1)

predictions, hidden_out, attention_weights= decoder(dec_input, features, hidden)
print('Feature shape from Encoder: {}'.format(features.shape)) #(batch, 8*8, embed_dim)
print('Predcitions shape from Decoder: {}'.format(predictions.shape)) #(batch,vocab_size)
print('Attention weights shape from Decoder: {}'.format(attention_weights.shape)) #(batch, 8*8, embed_dim)
```

Predcitions shape from Decoder: (64, 5001) Attention weights shape from Decoder: (64, 64, 1)

Feature shape from Encoder: (64, 64, 256)



BLEU score: 48.555993224365864

Real Caption: two girls are wearing life vests and hugging each other

Prediction Caption: two girls are hugging each other











