

Hw 2021-4

1. For the linear transformation defined by

$$T\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right) = \begin{bmatrix} -x_1 - x_2 + x_3 \\ x_1 + 2x_2 + x_3 \\ x_1 + x_2 \end{bmatrix}, \text{ determine}$$

- (a) the dimension of the range of T
- (b) the dimension of the null space of T
- (c) whether T is one-to-one or onto.

$$\begin{bmatrix} -1 & -1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 0 \end{bmatrix} \begin{array}{l} r_2 + r_1 \rightarrow r_2 \\ r_3 + r_1 \rightarrow r_3 \\ -r_1 \rightarrow r_1 \end{array} \Rightarrow \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{array}{l} r_1 - r_2 \rightarrow r_1 \\ r_1 - r_2 \rightarrow r_2 \end{array} \Rightarrow \begin{bmatrix} 1 & 0 & -3 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{array}{l} r_1 + 3r_3 \rightarrow r_1 \\ r_2 - 2r_3 \rightarrow r_2 \end{array} \Rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\Rightarrow (a) \dim \text{Range } T = 3$$

$$\Rightarrow (b) \dim \text{Null } T = 3 - 3 = 0$$

$$\Rightarrow (c) T \text{ is one-to-one (}\because \text{ the nullity of the function is zero)}$$

$$T \text{ is on-to (}\because \text{ the number of row is equal to the rank)}$$

2. (a) show that for any vector u in \mathbb{R}^n , $u^T u = 0$ if and only if $u = 0$

$$\Rightarrow u^T u = u_1^2 + u_2^2 + \dots + u_n^2 \text{ and for square of everything } \geq 0$$

$$\therefore u^T u = 0, \text{ if and only if } u = 0$$

(b) Prove for any matrix A , if u is in Row A and v is in Null A , then $u^T v = 0$

$$\Rightarrow \text{Let } u \in \text{Row } A = \text{Col } A^T, v \in \text{Null } A \Rightarrow Av = 0$$

$$\text{There exists } w \text{ such that } A^T w = u$$

$$\text{Hence } u^T v = (A^T w)^T v = w^T A v = w^T \cdot 0 = 0$$

(c) Show that, for any matrix A , if u belongs to both Row A and Null A , then $u = 0$

use (b), and let $v = u$

$$\Rightarrow u^T v = u^T u = 0 \quad \Rightarrow \text{use (a), if } u^T u = 0$$

$$\text{then } u = 0 \quad *$$

3. Let $B = \{b_1, b_2, b_3\}$, where $b_1 = \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$ $b_2 = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$ $b_3 = \begin{bmatrix} -1 \\ -2 \\ 1 \end{bmatrix}$

(a) Show that B is a basis for \mathcal{R}^3

\Rightarrow Let $B = [b_1 \ b_2 \ b_3] \Rightarrow$ the rref of B is $I_3 = R_B$

Since $\text{rank } R_B = 3$, B is linear independent subset of \mathcal{R}^3 containing 3 vectors *

(b) Determine the matrix $A = [[e_1]_B \ [e_2]_B \ [e_3]_B]$

$\Rightarrow A = [B^{-1}e_1 \ B^{-1}e_2 \ B^{-1}e_3] = B^{-1}I_3 = \begin{bmatrix} 2 & -1 & -1 \\ 1 & -1 & -2 \\ -1 & 1 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 3 \\ 0 & -1 & -1 \end{bmatrix} *$

(c) What is the relationship between A and $B = [b_1 \ b_2 \ b_3]$

$\Rightarrow A = B^{-1} *$

4. Determine $[T]_B$ for linear operator T and basis B

where $T\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right) = \begin{bmatrix} x_1 + x_2 \\ x_2 - 2x_3 \\ 2x_1 - x_2 + 3x_3 \end{bmatrix}$ and $B = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} \right\}$

$[T]_B = B^{-1}[T(b_1) \ T(b_2) \ T(b_3)] = B^{-1}AB$

$= \begin{bmatrix} 1 & 2 & 1 \\ 1 & 3 & 2 \\ 1 & 2 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 2 & 5 & 3 \\ -1 & -1 & -2 \\ 4 & 7 & 6 \end{bmatrix} = \begin{bmatrix} 10 & 19 & 16 \\ -5 & -8 & -8 \\ 2 & 2 & 3 \end{bmatrix} *$

5. Given a basis $B = \left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 0 \\ -1 \end{bmatrix} \right\}$

$$T\left(\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}\right) = 3\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} - 2\begin{bmatrix} -2 \\ 0 \\ -1 \end{bmatrix}, \quad T\left(\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}\right) = -\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + 4\begin{bmatrix} -2 \\ 0 \\ -1 \end{bmatrix}, \quad T\left(\begin{bmatrix} -2 \\ 0 \\ -1 \end{bmatrix}\right) = 2\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + 5\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$

determine

- $[T]_B$
- the standard matrix of T
- an explicit formula for $T(x)$

$$(a) [T]_B = \begin{bmatrix} 0 & -1 & 2 \\ 3 & 0 & 5 \\ -2 & 4 & 0 \end{bmatrix}$$

$$(b) A = B[T]_B B^{-1} = \begin{bmatrix} 1 & -1 & -2 \\ 0 & 1 & 0 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} 0 & -1 & 2 \\ 3 & 0 & 5 \\ -2 & 4 & 0 \end{bmatrix} \begin{bmatrix} 1 & -1 & -2 \\ 0 & 1 & 0 \\ 1 & 0 & -1 \end{bmatrix}^{-1} = \begin{bmatrix} 2 & -7 & -1 \\ -8 & -8 & 11 \\ -4 & -9 & 6 \end{bmatrix} *$$

$$(c) T\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right) = A \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 & -7 & -1 \\ -8 & -8 & 11 \\ -4 & -9 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2x_1 - 7x_2 - x_3 \\ -8x_1 - 8x_2 + 11x_3 \\ -4x_1 - 9x_2 + 6x_3 \end{bmatrix} *$$

7. Let $T: \mathcal{R}^n \rightarrow \mathcal{R}^m$ be a linear transformation,
 $B = \{b_1, b_2, \dots, b_n\}$ be basis for \mathcal{R}^n , $C = \{c_1, c_2, \dots, c_m\}$ be basis for \mathcal{R}^m .
 Let B and C be the matrices whose columns are vectors in B and C .

(a) If A is the standard matrix of T , then $[T]_B^C = C^{-1}AB$

$$\begin{aligned} \Rightarrow [T]_B^C &= [[T(b_1)]_C \quad [T(b_2)]_C \quad \dots \quad [T(b_n)]_C] = [C^{-1}T(b_1) \quad C^{-1}T(b_2) \quad \dots \quad C^{-1}T(b_n)] \\ &= C^{-1} [T(b_1) \quad T(b_2) \quad \dots \quad T(b_n)] = C^{-1} [Ab_1 \quad Ab_2 \quad \dots \quad Ab_n] = C^{-1}AB * \end{aligned}$$

(b) $[T(v)]_C = [T]_B^C [v]_B$ for any vector v in \mathcal{R}^n

$$\Rightarrow [T(v)]_C = C^{-1}T(v) = C^{-1}Av = C^{-1}AB B^{-1}v = [T]_B^C [v]_B *$$

(c) Let $U: \mathcal{R}^m \rightarrow \mathcal{R}^p$ be linear, and let D be a basis for \mathcal{R}^p
 Then $[UT]_B^D = [U]_C^D [T]_B^C$

$$\text{by (a), } [UT]_B^D = D^{-1}PAB = D^{-1}PC C^{-1}AB = [U]_C^D [T]_B^C *$$

6.

8. (a) Prove that if λ is an eigenvalue of matrix A , then λ^2 is an eigenvalue of A^2

$$\Rightarrow \text{Let } Av = \lambda v$$

$$\Rightarrow A^2v = A(\lambda v) = \lambda(Av) = \lambda^2v \quad \#$$

(b) Let v_1 and v_2 be eigenvectors of a linear transformation T on \mathbb{R}^n
Let λ_1, λ_2 respectively, be the corresponding eigenvalues

Prove that if $\lambda_1 \neq \lambda_2$, then $\{v_1, v_2\}$ is linearly independent

$$\Rightarrow \text{Let } C_1v_1 + C_2v_2 = 0$$

$$\Rightarrow 0 = T(0) = T(C_1v_1 + C_2v_2) = C_1\lambda_1v_1 + C_2\lambda_2v_2$$

$$= \lambda_1(-C_2v_2) + \lambda_2(C_2v_2) = (\lambda_2 - \lambda_1)(C_2v_2)$$

$$\because \lambda_1 \neq \lambda_2 \text{ and } v_2 \neq 0 \quad \therefore C_2 = 0 \text{ and we have } C_1 = 0$$

$$\Rightarrow \text{so } \{v_1, v_2\} \text{ is linearly independent. } \#$$