

HW 2020-4

1. For the matrix $A = \begin{bmatrix} -1 & 2 & 1 & -1 & -2 \\ 2 & -4 & 1 & 5 & 7 \\ 2 & -4 & -3 & 1 & 3 \end{bmatrix}$, determine the dimension of

(a) Col A (b) Null A (c) Row A (d) Null A^T

$$A = \begin{bmatrix} -1 & 2 & 1 & -1 & -2 \\ 2 & -4 & 1 & 5 & 7 \\ 2 & -4 & -3 & 1 & 3 \end{bmatrix} \xrightarrow{\substack{r_2+2r_1 \rightarrow r_2 \\ r_3+2r_1 \rightarrow r_3}} \begin{bmatrix} -1 & 2 & 1 & -1 & -2 \\ 0 & 0 & 3 & 3 & 3 \\ 0 & 0 & -1 & -1 & -1 \end{bmatrix} \xrightarrow{\substack{r_3+\frac{1}{3}r_2 \rightarrow r_2 \\ \frac{1}{3}r_3 \rightarrow r_3}} \begin{bmatrix} -1 & 2 & 1 & -1 & -2 \\ 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\Rightarrow \text{Col } A = 2 \quad \text{Null } A = 5-2 = 3$$

$$\text{Row } A = 2 \quad \text{Null } A^T = 3-2 = 1 \quad \#$$

2.

For the linear transformation defined by $T\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right) = \begin{bmatrix} -x_1 - x_2 + x_3 \\ x_1 + 2x_2 + x_3 \\ x_1 + x_2 \end{bmatrix}$, determine

- (a) the dimension of the range of T
 (b) the dimension of the null space of T
 (c) whether T is one-to-one or on-to

$$\begin{bmatrix} -1 & -1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 0 \end{bmatrix} \xrightarrow{\substack{r_2+r_1 \rightarrow r_2 \\ r_3+r_1 \rightarrow r_3}} \begin{bmatrix} -1 & -1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{r_1+r_2 \rightarrow r_1} \begin{bmatrix} -1 & 0 & 3 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\substack{-r_1+3r_3 \rightarrow r_1 \\ r_2-2r_3 \rightarrow r_2}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

(a) $\dim \text{Range } T = 3 \quad \#$

(b) $\dim \text{Null Space} = 3-3 = 0 \quad \#$

(c) T is one-to-one.
 (\because the nullity of the function is zero)
 T is on-to
 (\because the number of row is equal to the rank)

3. Find the unique representation of $u = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$ as linear combination of $b_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$, $b_2 = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}$, $b_3 = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$

$$\begin{bmatrix} 1 & -1 & 1 & a \\ -1 & 2 & 0 & b \\ 1 & 1 & 2 & c \end{bmatrix} \xrightarrow{\substack{r_2+r_1 \rightarrow r_2 \\ r_3-r_1 \rightarrow r_3}} \begin{bmatrix} 1 & -1 & 1 & a \\ 0 & 1 & 1 & a+b \\ 0 & 2 & 1 & -a+c \end{bmatrix} \xrightarrow{\substack{r_1+r_2 \rightarrow r_1 \\ r_3-2r_2 \rightarrow r_3}} \begin{bmatrix} 1 & 0 & 2 & 2a+b \\ 0 & 1 & 1 & a+b \\ 0 & 0 & -1 & -3a-2b+c \end{bmatrix}$$

$$\begin{matrix} r_1+2r_3 \rightarrow r_1 \\ r_2+r_3 \rightarrow r_2 \\ -r_3 \rightarrow r_3 \end{matrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 & -4a-3b+2c \\ 0 & 1 & 0 & -2a-b+c \\ 0 & 0 & 1 & 3a+2b-c \end{bmatrix}$$

$$\Rightarrow [\vec{u}]_{B_3} = (-4a-3b+2c) \vec{b}_1 + (-2a-b+c) \vec{b}_2 + (3a+2b-c) \vec{b}_3 \quad \#$$

4 Let $B = \{b_1, b_2, b_3\}$, where $b_1 = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$, $b_2 = \begin{bmatrix} -1 \\ 3 \\ 0 \end{bmatrix}$, $b_3 = \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}$

(a) show that B is a basis of \mathbb{R}^3

$$\begin{bmatrix} 1 & -1 & 0 \\ -2 & 3 & 2 \\ 1 & 0 & 1 \end{bmatrix} \xrightarrow{\substack{r_2 + 2r_1 \rightarrow r_2 \\ r_3 - r_1 \rightarrow r_3}} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & 2 \\ 0 & 1 & 1 \end{bmatrix} \xrightarrow{-r_3 + r_2 \rightarrow r_3} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{\substack{r_2 - 2r_3 \rightarrow r_2 \\ r_2 + r_1 \rightarrow r_1}} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$\therefore B$ is the basis for \mathbb{R}^3

(b) Determine the matrix $A = [[e_1]_B \quad [e_2]_B \quad [e_3]_B]$

$$\begin{bmatrix} 1 & -1 & 0 & 1 & 0 & 0 \\ -2 & 3 & 2 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & -1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 2 & 2 & 1 & 0 \\ 0 & 1 & 1 & -1 & 0 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & -1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 2 & 2 & 1 & 0 \\ 0 & 0 & 1 & 3 & 1 & -1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 & -3 & -1 & 2 \\ 0 & 1 & 0 & -4 & -1 & 2 \\ 0 & 0 & 1 & 3 & 1 & -1 \end{bmatrix}$$

$$A = \begin{bmatrix} -3 & -1 & 2 \\ -4 & -1 & 2 \\ 3 & 1 & -1 \end{bmatrix} *$$

(c) What is the relationship between A and B

$$(AB = I_3) == (A = B^{-1})$$

5. Let $A = \{u_1, u_2, \dots, u_n\}$ be a basis for \mathbb{R}^n and c_1, c_2, \dots, c_n be nonzero scalars. Let $B = \{c_1 u_1, c_2 u_2, \dots, c_n u_n\}$, which is also a basis for \mathbb{R}^n .

If v is a vector in \mathbb{R}^n and $[v]_A = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix}$, compute $[v]_B$

$$\begin{aligned} \Rightarrow \vec{v} &= a_1 \vec{u}_1 + a_2 \vec{u}_2 + \dots + a_n \vec{u}_n = A [v]_A \\ &= B [v]_B = [c_1 u_1 \ c_2 u_2 \ \dots \ c_n u_n] [v]_B \end{aligned} \quad \text{Let } [v]_B = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_n \end{bmatrix}$$

$$\begin{aligned} \Rightarrow B [v]_B &= b_1 c_1 \vec{u}_1 + b_2 c_2 \vec{u}_2 + \dots + b_n c_n \vec{u}_n \\ \Rightarrow a_i &= c_i b_i \quad \Rightarrow \quad b_i = \frac{a_i}{c_i} \quad \Rightarrow [v]_B = \begin{bmatrix} \frac{a_1}{c_1} \\ \frac{a_2}{c_2} \\ \vdots \\ \frac{a_n}{c_n} \end{bmatrix} \quad \# \end{aligned}$$

6. Determine $[T]_B$ for linear operator T and basis B ,

$$\text{where } T \left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \right) = \begin{bmatrix} x_1 - 2x_2 + 4x_3 \\ 3x_1 \\ -3x_2 + 2x_3 \end{bmatrix} \quad \text{and } B = \left\{ \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -5 \\ 3 \end{bmatrix} \right\}$$

$$\Rightarrow T(\vec{b}_1) = T \left(\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} 9 \\ 3 \\ 8 \end{bmatrix}, \quad T(\vec{b}_2) = T \left(\begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} 6 \\ 0 \\ 5 \end{bmatrix}, \quad T(\vec{b}_3) = T \left(\begin{bmatrix} 1 \\ -5 \\ 3 \end{bmatrix} \right) = \begin{bmatrix} 23 \\ 3 \\ 21 \end{bmatrix}$$

$$\Rightarrow B = \begin{bmatrix} 1 & 0 & 1 \\ -2 & -1 & -5 \\ 1 & 1 & 3 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 & 0 & 0 \\ -2 & -1 & -5 & 0 & 1 & 0 \\ 1 & 1 & 3 & 0 & 0 & 1 \end{bmatrix} \xrightarrow[r_3 - r_1 \rightarrow r_3]{r_2 + 2r_1 \rightarrow r_2} \begin{bmatrix} 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & -1 & -3 & 2 & 1 & 0 \\ 0 & 1 & 2 & -1 & 0 & 1 \end{bmatrix}$$

$$\xrightarrow[r_3 \rightarrow r_3]{r_3 + r_2 \rightarrow r_3} \begin{bmatrix} 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & -1 & -3 & 2 & 1 & 0 \\ 0 & 0 & 1 & -1 & -1 & -1 \end{bmatrix} \xrightarrow[r_2 + 3r_3 \rightarrow r_2]{r_1 - r_3 \rightarrow r_1} \begin{bmatrix} 1 & 0 & 0 & 2 & 1 & 1 \\ 0 & -1 & 0 & -1 & -2 & -3 \\ 0 & 0 & 1 & -1 & -1 & -1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 & 2 & 1 & 1 \\ 0 & 1 & 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & -1 & -1 & -1 \end{bmatrix}$$

$$\Rightarrow B^{-1} = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 3 \\ -1 & -1 & -1 \end{bmatrix}$$

$$\Rightarrow [T(\vec{b}_1)]_B = B^{-1} T(\vec{b}_1) = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 3 \\ -1 & -1 & -1 \end{bmatrix} \begin{bmatrix} 9 \\ 3 \\ 8 \end{bmatrix} = \begin{bmatrix} 29 \\ 39 \\ -20 \end{bmatrix}$$

$$\Rightarrow [T(\vec{b}_2)]_B = B^{-1} T(\vec{b}_2) = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 3 \\ -1 & -1 & -1 \end{bmatrix} \begin{bmatrix} 6 \\ 0 \\ 5 \end{bmatrix} = \begin{bmatrix} 17 \\ 21 \\ -11 \end{bmatrix} \quad \Rightarrow [T]_B = \begin{bmatrix} 29 & 17 & 70 \\ 39 & 21 & 92 \\ -20 & -11 & -47 \end{bmatrix} \quad \#$$

$$\Rightarrow [T(\vec{b}_3)]_B = B^{-1} T(\vec{b}_3) = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 3 \\ -1 & -1 & -1 \end{bmatrix} \begin{bmatrix} 23 \\ 3 \\ 21 \end{bmatrix} = \begin{bmatrix} 70 \\ 92 \\ -47 \end{bmatrix}$$

7. Given a basis $B = \left\{ \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \right\}$, $T\left(\begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + 2\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$,
 $T\left(\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}\right) = 4\begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} - \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$, $T\left(\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}\right) = -\begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} + 3\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + 2\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$

determine

- (a) $[T]_B$ (b) the standard matrix of T (c) an explicit formula for $T(x)$

(a) $[T]_B = \begin{bmatrix} 0 & 4 & -1 \\ 1 & 0 & 3 \\ 2 & -1 & 2 \end{bmatrix}$, $B = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ -1 & 1 & 3 \end{bmatrix}$ $B^{-1} = \begin{bmatrix} \frac{1}{3} & \frac{1}{3} & -\frac{1}{3} \\ -\frac{5}{3} & \frac{4}{3} & -\frac{1}{3} \\ \frac{2}{3} & -\frac{1}{3} & \frac{1}{3} \end{bmatrix}$ ←

$$\begin{bmatrix} 1 & 0 & 1 & 1 & 0 & 0 \\ 1 & 1 & 2 & 0 & 1 & 0 \\ -1 & 1 & 3 & 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & -1 & 1 & 0 \\ 0 & 1 & 4 & 1 & 0 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & -1 & 1 & 0 \\ 0 & 0 & 3 & 2 & -1 & 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 0 & \frac{1}{3} & \frac{1}{3} & -\frac{1}{3} \\ 0 & 1 & 0 & -\frac{5}{3} & \frac{4}{3} & -\frac{1}{3} \\ 0 & 0 & 1 & \frac{2}{3} & -\frac{1}{3} & \frac{1}{3} \end{bmatrix}$$

(b) $A = B[T]_B B^{-1} = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ -1 & 1 & 3 \end{bmatrix} \begin{bmatrix} 0 & 4 & -1 \\ 1 & 0 & 3 \\ 2 & -1 & 2 \end{bmatrix} \begin{bmatrix} \frac{1}{3} & \frac{1}{3} & -\frac{1}{3} \\ -\frac{5}{3} & \frac{4}{3} & -\frac{1}{3} \\ \frac{2}{3} & -\frac{1}{3} & \frac{1}{3} \end{bmatrix} = \begin{bmatrix} 2 & 3 & 1 \\ 5 & 2 & 6 \\ 7 & -7 & 10 \end{bmatrix} \begin{bmatrix} \frac{1}{3} & \frac{1}{3} & -\frac{1}{3} \\ -\frac{5}{3} & \frac{4}{3} & -\frac{1}{3} \\ \frac{2}{3} & -\frac{1}{3} & \frac{1}{3} \end{bmatrix} = \begin{bmatrix} -\frac{11}{3} & \frac{13}{3} & -\frac{4}{3} \\ \frac{7}{3} & \frac{7}{3} & -\frac{1}{3} \\ \frac{62}{3} & -\frac{21}{3} & \frac{10}{3} \end{bmatrix} \#$

(c) $T\left(\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}\right) = \begin{bmatrix} -\frac{11}{3}x_1 + \frac{13}{3}x_2 - \frac{4}{3}x_3 \\ \frac{7}{3}x_1 + \frac{7}{3}x_2 - \frac{1}{3}x_3 \\ \frac{62}{3}x_1 - \frac{21}{3}x_2 + \frac{10}{3}x_3 \end{bmatrix} \#$

8. Let $T: \mathcal{R}^n \rightarrow \mathcal{R}^m$ be a linear transformation, $B = \{b_1, b_2, \dots, b_n\}$, $C = \{c_1, c_2, \dots, c_m\}$
be basis for \mathcal{R}^n , \mathcal{R}^m , respectively.

Let B and C be the matrices whose columns are the vectors in B , C .

Prove

(a) If A is the standard matrix of T , then $[T]_B^C = C^{-1}AB$

$$\begin{aligned} \Rightarrow [T]_B^C &= \begin{bmatrix} [T(b_1)]_C & [T(b_2)]_C & \dots & [T(b_n)]_C \end{bmatrix} \\ &= \begin{bmatrix} C^{-1}T(b_1) & C^{-1}T(b_2) & \dots & C^{-1}T(b_n) \end{bmatrix} = C^{-1} \begin{bmatrix} T(b_1) & T(b_2) & \dots & T(b_n) \end{bmatrix} \\ &= C^{-1} \begin{bmatrix} Ab_1 & Ab_2 & \dots & Ab_n \end{bmatrix} \\ &= C^{-1}A \begin{bmatrix} b_1 & b_2 & \dots & b_n \end{bmatrix} = C^{-1}AB \# \end{aligned}$$

(b) $[T(v)]_C = [T]_B^C [v]_B$ for any vector v in \mathcal{R}^n

$$\begin{aligned} \Rightarrow [T(v)]_C &= C^{-1}T(v) = C^{-1}A\vec{v} = C^{-1}A I_n \vec{v} = C^{-1}A(BB^{-1}\vec{v}) \\ &= (C^{-1}AB)(B^{-1}\vec{v}) = [T]_B^C [v]_B \# \end{aligned}$$

(c) Let $U: \mathcal{R}^m \rightarrow \mathcal{R}^p$ be linear, and let D be a basis for \mathcal{R}^p .

$$\text{Then } [UT]_B^D = [U]_C^D [T]_B^C$$

\Rightarrow Let A , E be standard matrices of U and T , respectively

Notice that UT is defined for the given linear transformations of U and T .

$$[UT]_B^D = D^{-1}(AE)B = D^{-1}AIEB = D^{-1}ACC^{-1}EB$$

(a)

$$= (D^{-1}AC)(C^{-1}EB) = [U]_C^D [T]_B^C \#$$