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# Learning Docker Networking

Become a proficient Linux administrator by learning the art of container networking with elevated efficiency using Docker

Rajdeep Dua

Vaibhav Kohli

Santosh Kumar Konduri

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BIRMINGHAM - MUMBAI

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# Preface

This book helps the reader to learn, create, deploy, and provide administration steps for Docker networking. Docker is a Linux container implementation that enables the creation of light-weight portable development and production-quality environments. These environments can be updated incrementally. Docker achieves this by leveraging containment principles, such as cgroups and Linux namespaces, along with overlay filesystem-based portable images.

Docker provides the networking primitives that allow administrators to specify how different containers network with each application, connect to each of their components, then distribute them across a large number of servers, and ensure coordination between them irrespective of the host or the VM that they are running on. This book aggregates all the latest Docker networking technology and provides great in depth explanation with setup details.

## What this book covers

*Chapter 1, Docker Networking Primer*, explains the essential components of Docker networking, which have evolved from coupling simple Docker abstractions and powerful network components, such as Linux bridges, Open vSwitch, and so on. This chapter also explains how Docker containers can be created with various modes. In the default mode, port mapping helps us through the use of iptables NAT rules, allowing traffic arriving at the host to reach containers. Later in this chapter, basic linking of the container is covered and the next generation of Docker networking, which is libnetwork, is also discussed.

*Chapter 2, Docker Networking Internals*, discusses Docker's internal networking architecture. We will learn about IPv4, IPv6, and DNS configurations in Docker. Later in this chapter, Docker bridge and communication between containers in single host and multihost is covered. This chapter also explains overlay tunneling and different methods that are implemented on Docker networking, such as OVS, Flannel, and Weave.

*Chapter 3, Building Your First Docker Network*, shows how Docker containers communicate from multiple hosts using different networking options, such as Weave, OVS, and Flannel. Pipework uses legacy Linux bridge, Weave creates a virtual network, OVS uses GRE tunneling technology, and Flannel provides a separate subnet to each host to connect containers on multiple hosts. Some of the implementations, such as Pipework, are legacy and will become obsolete over a period of time, while others are designed to be used in the context of specific OSes, such as Flannel with CoreOS. Basic comparisons of Docker networking options are also covered in this chapter.

*Chapter 4, Networking in a Docker Cluster*, explains Docker networking in depth using various frameworks, such as native Docker Swarm, where using the libnetwork or the out-of-the-box overlay network, Swarm, provides the multihost networking features. Kubernetes, on the other hand, has a different perspective from Docker, where each pod will get a unique IP address and communication between pods can occur with the help of services. Using Open vSwitch or IP-forwarding advanced routing rules, the Kubernetes networking can be enhanced to provide connectivity between pods on different subnets across hosts and expose the pods to the external world. In the case of Mesosphere, we can see that Marathon is used as a backend for the networking of the deployed containers. In the case of DCOS of the Mesosphere, the entire deployed stack of machines is treated as one machine to provide a rich-networking experience between deployed container services.

*Chapter 5, Security and QoS for Docker Containers*, takes a dive into Docker security by referring to kernel and cgroups namespaces. We will also visit some of the aspects of filesystems and various Linux capabilities, which containers leverage in order to provide more features, such as the privileged container but at the cost of exposing itself more on the threat side. We will also see how containers can be deployed in a secured environment in AWS ECS using proxy containers to restrict the vulnerable traffic. We will also talk about how AppArmor is also provided with a rich set of **Mandatory Access Control (MAC)** system, which provides kernel-enhancement features in order to confine applications to a limited set of resources. Leveraging their benefits to Docker containers helps us deploy them in a secured environment. In the last section, we take a quick dive into Docker security benchmarks and some of the important recommendations that can be followed during auditing and Docker deployment in a production environment.

*Chapter 6, Next Generation Networking Stack for Docker: libnetwork*, will look into some of the deeper and conceptual aspects of Docker networking. One of these is libnetworking — the future of the Docker network model, which is already getting into shape with the release of Docker 1.9. While explaining the libnetworking concept, we will also study the CNM model, its various objects and components, along with its implementation code snippets. Next, we will look into drivers of CNM, the prime one being the overlay driver, in detail with deployment as part of Vagrant setup. We will look at standalone integrations of containers with overlay network with Docker Swarm and Docker Machine as well. In the next section, we explain the CNI interface, its executable plugins, and give a tutorial to configure Docker networking with the CNI plugin. In the last section, Project Calico is explained in detail, which provides scalable networking solutions that are based out of libnetwork and provides integration with Docker, Kubernetes, Mesos, bare-metal, and VMs, primarily.

## What you need for this book

Mostly all of the setups basically require Ubuntu 14.04 (either installed on a physical machine or as a virtual machine) and Docker 1.9, which is the latest version to date. Specific OS and software requirements (Open Source Git Projects) are mentioned before each setup if required.

## Who this book is for

If you are a Linux administrator who wants to learn networking using Docker to ensure the efficient administration of core elements and applications, then this book is for you. Basic knowledge of LXC/Docker is assumed.

## Conventions

You will also find a number of text styles that distinguish between different kinds of information. Here are some examples of these styles and an explanation of their meaning.

Code words in text, database table names, folder names, filenames, file extensions, pathnames, dummy URLs, user input, and Twitter handles are shown as follows: "You may notice that we used the Unix command, `rm`, to remove the `Drush` directory rather than the DOS `del` command."

A block of code is set as follows:

```
# * Fine Tuning
#
key_buffer = 16M
key_buffer_size = 32M
max_allowed_packet = 16M
thread_stack = 512K
thread_cache_size = 8
max_connections = 300
```


When we wish to draw your attention to a particular part of a code block, the relevant lines or items are set in bold:


```
# * Fine Tuning
#
key_buffer = 16M
key_buffer_size = 32M
max_allowed_packet = 16M
thread_stack = 512K
thread_cache_size = 8
max_connections = 300
```

Any command-line input or output is written as follows:

```
cd /ProgramData/Propeople
rm -r Drush
git clone --branch master http://git.drupal.org/project/drush.git
```

New terms and important words are shown in bold. Words that you see on the screen, in menus or dialog boxes for example, appear in the text like this: "On the **Select Destination Location** screen, click on **Next** to accept the default destination."

[  Warnings or important notes appear in a box like this. ]

[  Tips and tricks appear like this. ]

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# 1

## Docker Networking Primer

**Docker** is a lightweight container technology that has gathered enormous interest in recent years. It neatly bundles various Linux kernel features and services, such as namespaces, cgroups, SELinux, and AppArmor profiles, over union filesystems such as AUFS and BTRFS in order to make modular images. These images provide a highly configurable virtualized environment for applications and follow a **write once, run anywhere** workflow. An application can be composed of a single process running in a Docker container or it could be made up of multiple processes running in their own containers and being replicated as the load increases. Therefore, there is a need for powerful networking elements that can support various complex use cases.

In this chapter, you will learn about the essential components of Docker networking and how to build and run simple container examples.

This chapter covers the following topics:

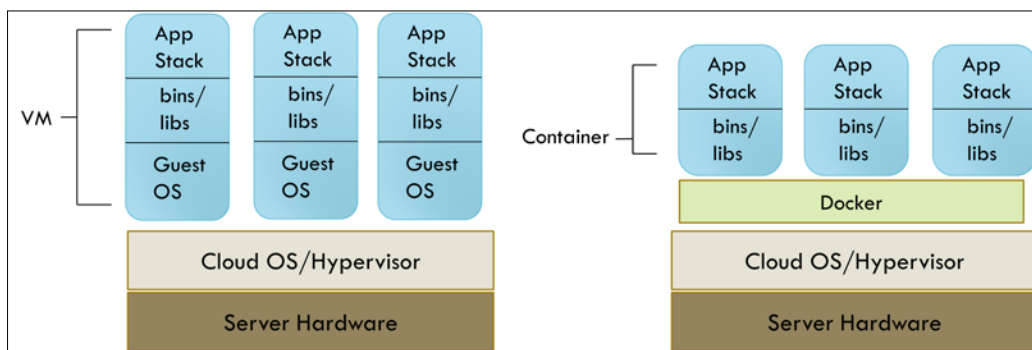
- Networking and Docker
- The `docker0` bridge networking
- Docker OVS networking
- Unix domain networks
- Linking Docker containers
- What's new in Docker networking

Docker is getting a lot of traction in the industry because of its performance-savvy and universal replicability architecture, while providing the following four cornerstones of modern application development:

- Autonomy
- Decentralization
- Parallelism
- Isolation

Furthermore, wide-scale adoption of Thoughtworks's microservices architecture, or **LOSA (Lots of Small Applications)**, is further bringing potential to Docker technology. As a result, big companies such as Google, VMware, and Microsoft have already ported Docker to their infrastructure, and the momentum is continued by the launch of myriad Docker start-ups, namely Tutum, Flocker, Giantswarm, and so on.

Since Docker containers replicate their behavior anywhere, be it your development machine, a bare metal server, virtual machine, or data center, application designers can focus their attention on development, while operational semantics are left with DevOps. This makes team workflow modular, efficient, and productive. Docker is not to be confused with a **virtual machine (VM)**, even though they are both virtualization technologies. While Docker shares an OS with providing a sufficient level of isolation and security to applications running in containers, it later completely abstracts away the OS and gives strong isolation and security guarantees. However, Docker's resource footprint is minuscule in comparison to a VM and hence preferred for economy and performance. However, it still cannot completely replace VMs and is therefore complementary to VM technology. The following diagram shows the architecture of VMs and Docker:



## Networking and Docker

Each Docker container has its own network stack, and this is due to the Linux kernel NET namespace, where a new NET namespace for each container is instantiated and cannot be seen from outside the container or from other containers.

Docker networking is powered by the following network components and services.

## Linux bridges

These are L2/MAC learning switches built into the kernel and are to be used for forwarding.

## Open vSwitch

This is an advanced bridge that is programmable and supports tunneling.

## NAT

Network address translators are immediate entities that translate IP addresses and ports (SNAT, DNAT, and so on).

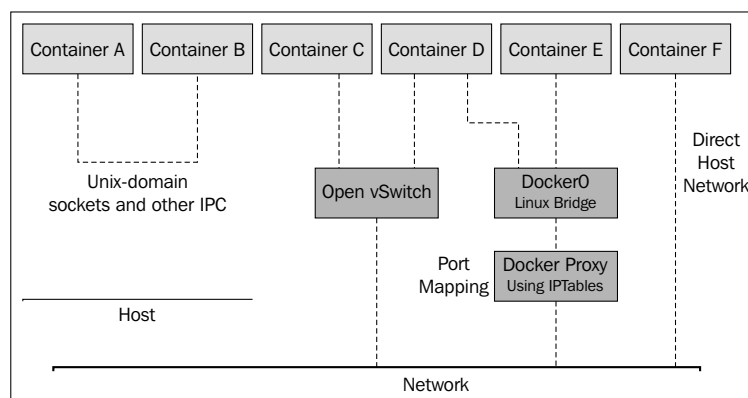
## IPtables

This is a policy engine in the kernel used for managing packet forwarding, firewall, and NAT features.

## AppArmor/SELinux

Firewall policies for each application can be defined with these.

Various networking components can be used to work with Docker, providing new ways to access and use Docker-based services. As a result, we see a lot of libraries that follow a different approach to networking. Some of the prominent ones are Docker Compose, Weave, Kubernetes, Pipework, libnetwork, and so on. The following figure depicts the root ideas of Docker networking:



## The docker0 bridge

The `docker0` bridge is the heart of default networking. When the Docker service is started, a Linux bridge is created on the host machine. The interfaces on the containers talk to the bridge, and the bridge proxies to the external world. Multiple containers on the same host can talk to each other through the Linux bridge.

`docker0` can be configured via the `--net` flag and has, in general, four modes:

- `--net default`
- `--net=none`
- `--net=container:$container2`
- `--net=host`

## The --net default mode

In this mode, the default bridge is used as the bridge for containers to connect to each other.

## The --net=none mode

With this mode, the container created is truly isolated and cannot connect to the network.

## The --net=container:\$container2 mode

With this flag, the container created shares its network namespace with the container called `$container2`.

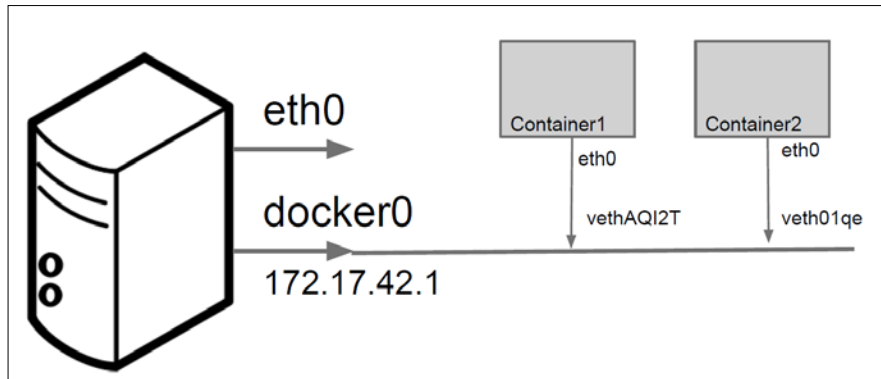
## The --net=host mode

With this mode, the container created shares its network namespace with the host.

## Port mapping in Docker container

In this section, we look at how container ports are mapped to host ports. This mapping can either be done implicitly by Docker Engine or can be specified.

If we create two containers called **Container1** and **Container2**, both of them are assigned an IP address from a private IP address space and also connected to the **docker0** bridge, as shown in the following figure:



Both the preceding containers will be able to ping each other as well as reach the external world.

For external access, their port will be mapped to a host port.

As mentioned in the previous section, containers use network namespaces. When the first container is created, a new network namespace is created for the container. A vEthernet link is created between the container and the Linux bridge. Traffic sent from `eth0` of the container reaches the bridge through the vEthernet interface and gets switched thereafter. The following code can be used to show a list of Linux bridges:

```
# show linux bridges
$ sudo brctl show
```

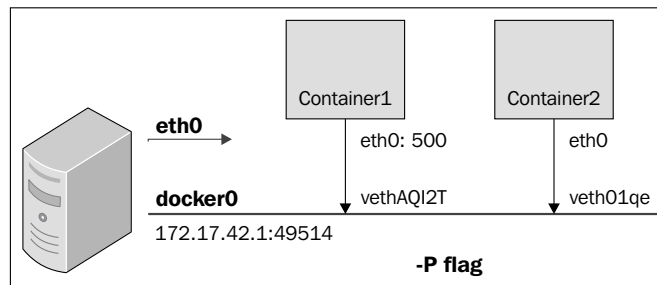
The output will be similar to the one shown as follows, with a bridge name and the veth interfaces on the containers it is mapped to:

bridge name	bridge id	STP enabled	interfaces
docker0	8000.56847afe9799	no	veth44cb727 veth98c3700

How does the container connect to the external world? The `iptables nat` table on the host is used to masquerade all external connections, as shown here:

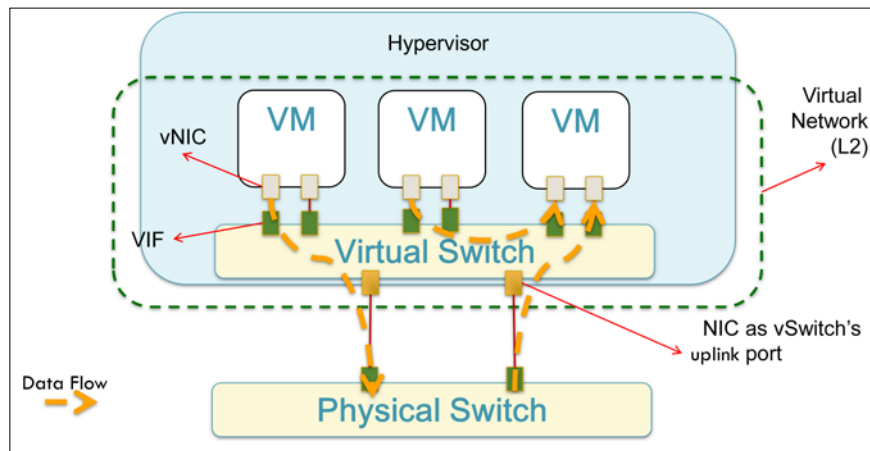
```
$ sudo iptables -t nat -L -n
...
Chain POSTROUTING (policy ACCEPT) target prot opt
source destination MASQUERADE all -- 172.17.0.0/16
!172.17.0.0/16
...
```

How to reach containers from the outside world? The port mapping is again done using the `iptables nat` option on the host machine.

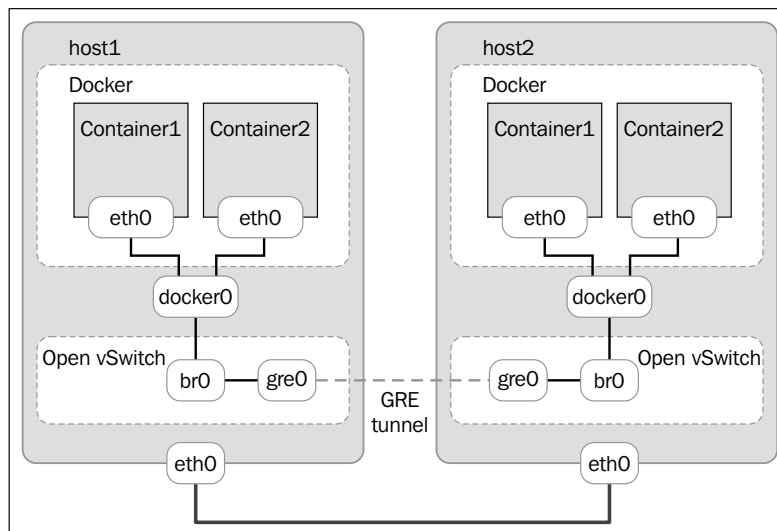


## Docker OVS

Open vSwitch is a powerful network abstraction. The following figure shows how OVS interacts with the VMs, **Hypervisor**, and the **Physical Switch**. Every VM has a **vNIC** associated with it. Every **vNIC** is connected through a **VIF** (also called a **virtual interface**) with the **Virtual Switch**:



OVS uses tunnelling mechanisms such as GRE, VXLAN, or STT to create virtual overlays instead of using physical networking topologies and Ethernet components. The following figure shows how OVS can be configured for the containers to communicate between multiple hosts using GRE tunnels:





## Unix domain socket

Within a single host, UNIX IPC mechanisms, especially UNIX domain sockets or pipes, can also be used to communicate between containers:

```
$ docker run --name c1 -v /var/run/foo:/var/run/foo -d -I -t base /bin/bash
$ docker run --name c2 -v /var/run/foo:/var/run/foo -d -I -t base /bin/bash
```

Apps on c1 and c2 can communicate over the following Unix socket address:

```
struct sockaddr_un address;
address.sun_family = AF_UNIX;
snprintf(address.sun_path, UNIX_PATH_MAX, "/var/run/foo/bar" );
```

C1: Server.c	C2: Client.c
<pre>bind(socket_fd, (struct sockaddr *) &amp;address, sizeof(struct sockaddr_un)); listen(socket_fd, 5); while((connection_fd = accept(socket_fd, (struct sockaddr *) &amp;address, &amp;address_length)) &gt; -1) nbytes = read(connection_fd, buffer, 256);</pre>	<pre>connect(socket_fd, (struct sockaddr *) &amp;address, sizeof(struct sockaddr_un)); write(socket_fd, buffer, nbytes);</pre>

## Linking Docker containers

In this section, we introduce the concept of linking two containers. Docker creates a tunnel between the containers, which doesn't need to expose any ports externally on the container. It uses environment variables as one of the mechanisms for passing information from the parent container to the child container.

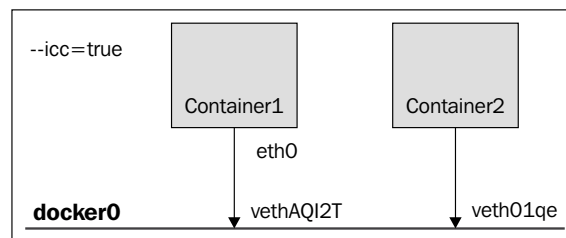
In addition to the environment variable `env`, Docker also adds a host entry for the source container to the `/etc/hosts` file. The following is an example of the host file:

```
$ docker run -t -i --name c2 --rm --link c1:clalias training/webapp /bin/bash
root@<container_id>:/opt/webapp# cat /etc/hosts
172.17.0.1 aed84ee21bde
...
172.17.0.2 clalalias 6e5cdeb2d300 c1
```

There are two entries:

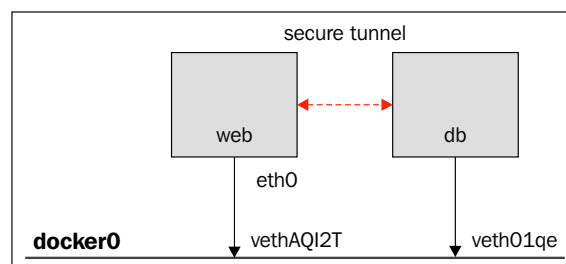
- The first is an entry for the container `c2` that uses the Docker container ID as a host name
- The second entry, `172.17.0.2 c1alarias 6e5cdeb2d300 c1`, uses the link alias to reference the IP address of the `c1` container

The following figure shows two containers **Container 1** and **Container 2** connected using veth pairs to the `docker0` bridge with `--icc=true`. This means these two containers can access each other through the bridge:



## Links

Links provide service discovery for Docker. They allow containers to discover and securely communicate with each other by using the flag `-link name:alias`. Inter-container communication can be disabled with the daemon flag `-icc=false`. With this flag set to `false`, **Container 1** cannot access **Container 2** unless explicitly allowed via a link. This is a huge advantage for securing your containers. When two containers are linked together, Docker creates a parent-child relationship between them, as shown in the following figure:



From the outside, it looks like this:

```
# start the database
$ sudo docker run -dp 3306:3306 --name todomvcdb \
```

```
-v /data/mysql:/var/lib/mysql cpswan/todomvc.mysql

# start the app server
$ sudo docker run -dp 4567:4567 --name todomvcapp \
--link todomvcdb:db cpswan/todomvc.sinatra
```

On the inside, it looks like this:

```
$ dburl = 'mysql://root:pa55Word@' + \
ENV['DB_PORT_3306_TCP_ADDR']
+ '/todomvc'
$ DataMapper.setup(:default, dburl)
```

## What's new in Docker networking?

Docker networking is at a very nascent stage, and there are many interesting contributions from the developer community, such as Pipework, Weave, Clocker, and Kubernetes. Each of them reflects a different aspect of Docker networking. We will learn about them in later chapters. Docker, Inc. has also established a new project where networking will be standardized. It is called **libnetwork**.

libnetwork implements the **container network model (CNM)**, which formalizes the steps required to provide networking for containers while providing an abstraction that can be used to support multiple network drivers. The CNM is built on three main components—sandbox, endpoint, and network.

## Sandbox

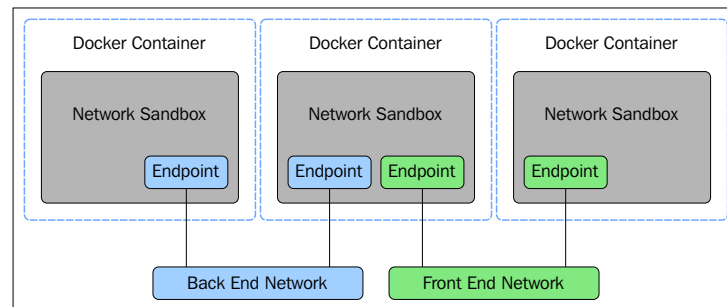
A sandbox contains the configuration of a container's network stack. This includes management of the container's interfaces, routing table, and DNS settings. An implementation of a sandbox could be a Linux network namespace, a FreeBSD jail, or other similar concept. A sandbox may contain many endpoints from multiple networks.

## Endpoint

An endpoint connects a sandbox to a network. An implementation of an endpoint could be a veth pair, an Open vSwitch internal port, or something similar. An endpoint can belong to only one network but may only belong to one sandbox.

## Network

A network is a group of endpoints that are able to communicate with each other directly. An implementation of a network could be a Linux bridge, a VLAN, and so on. Networks consist of many endpoints, as shown in the following diagram:



## The Docker CNM model

The CNM provides the following contract between networks and containers:

- All containers on the same network can communicate freely with each other
- Multiple networks are the way to segment traffic between containers and should be supported by all drivers
- Multiple endpoints per container are the way to join a container to multiple networks
- An endpoint is added to a network sandbox to provide it with network connectivity

We will discuss the details of how CNM is implemented in *Chapter 6, Next Generation Networking Stack for Docker: libnetwork*.

## Summary

In this chapter, we learned about the essential components of Docker networking, which have evolved from coupling simple Docker abstractions and powerful network components such as Linux bridges and Open vSwitch.

We learned how Docker containers can be created with various modes. In the default mode, port mapping helps through the use of iptables NAT rules, allowing traffic arriving at the host to reach containers. Later in the chapter, we covered the basic linking of containers. We also talked about the next generation of Docker networking, which is called libnetwork.



# 2

## Docker Networking Internals

This chapter discusses the semantics and syntax of Docker networking in detail, exposing strengths and weaknesses of the current Docker network paradigm.

It covers the following topics:

- Configuring the IP stack for Docker
  - IPv4 support
  - Issues with IPv4 address management
  - IPv6 support
- Configuring DNS
  - DNS basics
  - Multicast DNS
- Configuring the Docker bridge
- Overlay networks and underlay networks
  - What are they?
  - How does Docker use them?
  - What are some of their advantages?

## Configuring the IP stack for Docker

Docker uses the IP stack to interact with the outside world using TCP or UDP. It supports the IPv4 and IPv6 addressing infrastructures, which are explained in the following subsections.

### IPv4 support

By default, Docker provides IPv4 addresses to each container, which are attached to the default `docker0` bridge. The IP address range can be specified while starting the Docker daemon using the `--fixed-cidr` flag, as shown in the following code:

```
$ sudo docker -d --fixed-cidr=192.168.1.0/25
```

We will discuss more about this in the *Configuring the Docker bridge* section.

The Docker daemon can be listed on an IPv4 TCP endpoint in addition to a Unix socket:

```
$ sudo docker -H tcp://127.0.0.1:2375 -H unix:///var/run/docker.sock  
-d &
```

### IPv6 support

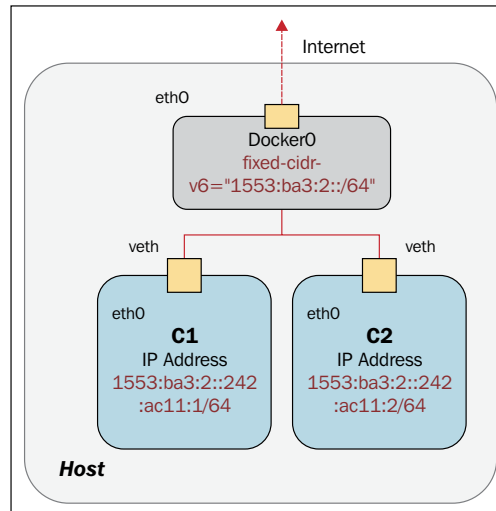
IPv4 and IPv6 can run together; this is called a **dual stack**. This dual stack support is enabled by running the Docker daemon with the `--ipv6` flag. Docker will set up the `docker0` bridge with the IPv6 link-local address `fe80::1`. All packets shared between containers flow through this bridge.

To assign globally routable IPv6 addresses to your containers, you have to specify an IPv6 subnet to pick the addresses from.

The following commands set the IPv6 subnet via the `--fixed-cidr-v6` parameter while starting Docker and also add a new route to the routing table:

```
# docker -d --ipv6 --fixed-cidr-v6="1553:ba3:2::/64"  
# docker run -t -i --name c0 ubuntu:latest /bin/bash
```

The following figure shows a Docker bridge configured with an IPv6 address range:



If you check the IP address range using `ifconfig` inside a container, you will notice that the appropriate subnet has been assigned to the `eth0` interface, as shown in the following code:


```
#ifconfig
eth0      Link encap:Ethernet HWaddr 02:42:ac:11:00:01
          inet addr:172.17.0.1  Bcast:0.0.0.0  Mask:255.255.0.0
          inet6 addr: fe80::42:acff:fe11:1/64 Scope:Link
          inet6 addr: 1553:ba3:2::242:ac11:1/64 Scope:Global
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:7 errors:0 dropped:0 overruns:0 frame:0
          TX packets:10 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:738 (738.0 B)  TX bytes:836 (836.0 B)

lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          inet6 addr: ::1/128 Scope:Host
          UP LOOPBACK RUNNING  MTU:65536  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
```

All the traffic to the `1553:ba3:2::/64` subnet will be routed via the `docker0` interface.



The preceding container is assigned using `fe80::42:acff:fe11:1/64` as the link-local address and `1553:ba3:2::242:ac11:1/64` as the global routable IPv6 address.

 Link-local and loopback addresses have link-local scope, which means they are to be used in a directly attached network (link). All other addresses have global (or universal) scope, which means they are globally routable and can be used to connect to addresses with global scope anywhere.

## Configuring a DNS server

Docker provides hostname and DNS configurations for each container without us having to build a custom image. It overlays the `/etc` folder inside the container with virtual files, in which it can write new information.

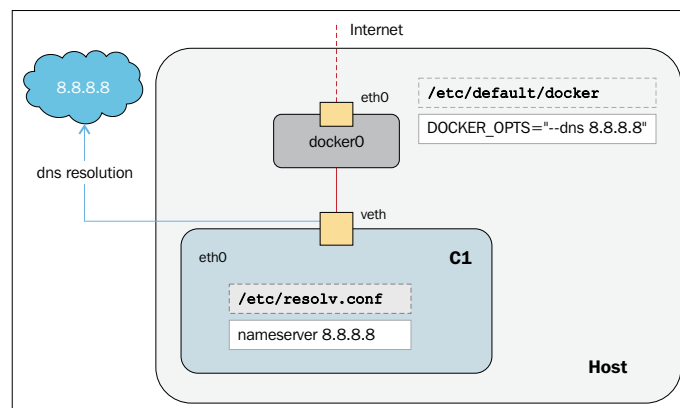
This can be seen by running the `mount` command inside the container. Containers receive the same `resolv.conf` file as that of the host machine when they are created initially. If a host's `resolv.conf` file is modified, this will be reflected in the container's `/resolv.conf` file only when the container is restarted.

In Docker, you can set DNS options in two ways:

- Using `docker run --dns=<ip-address>`
- Adding `DOCKER_OPTS="--dns ip-address"` to the Docker daemon file

You can also specify the search domain using `--dns-search=<DOMAIN>`.

The following figure shows a **nameserver** being configured in a container using the `DOCKER_OPTS` setting in the Docker daemon file:



The main DNS files are as follows:

- /etc/hostname
- /etc/resolv.conf
- /etc/hosts

The following is the command to add a DNS server:

```
# docker run --dns=8.8.8.8 --net="bridge" -t -i ubuntu:latest /bin/bash
```

Add hostnames using the following command:

```
# docker run --dns=8.8.8.8 --hostname=docker-vm1 -t -i ubuntu:latest /bin/bash
```

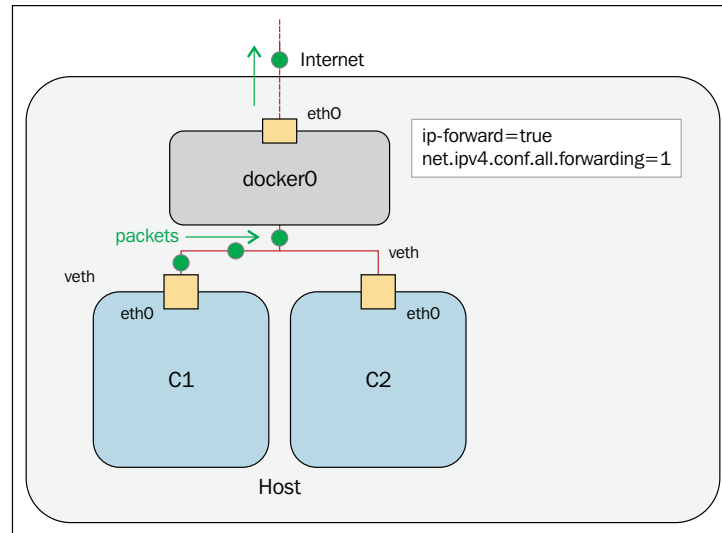
## Communication between containers and external networks

Packets can only pass between containers if the `ip_forward` parameter is set to 1. Usually, you will simply leave the Docker server at its default setting, `--ip-forward=true`, and Docker will set `ip_forward` to 1 for you when the server starts up.

To check the settings or to turn IP forwarding on manually, use these commands:

```
# cat /proc/sys/net/ipv4/ip_forward
0
# echo 1 > /proc/sys/net/ipv4/ip_forward
# cat /proc/sys/net/ipv4/ip_forward
1
```

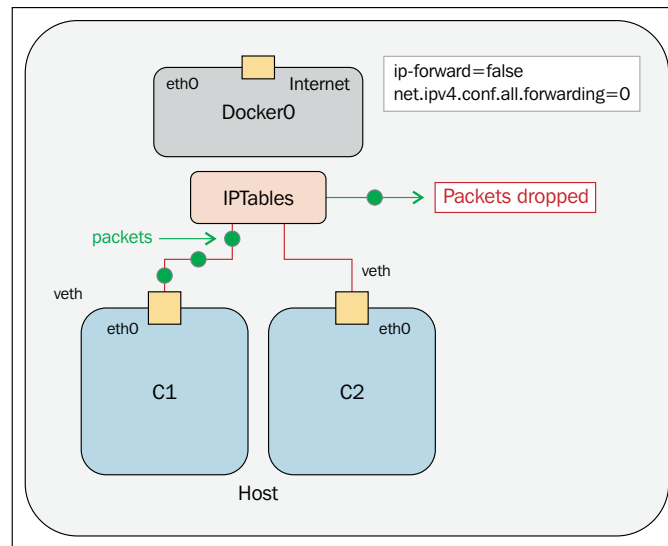
By enabling `ip_forward`, users can make communication possible between containers and the external world; it will also be required for inter-container communication if you are in a multiple-bridge setup. The following figure shows how `ip_forward = false` forwards all the packets to/from the container from/to the external network:



Docker will not delete or modify any pre-existing rules from the Docker filter chain. This allows users to create rules to restrict access to containers.

Docker uses the `docker0` bridge for packet flow between all the containers on a single host. It adds a rule to forward the chain using IPTables in order for the packets to flow between two containers. Setting `--icc=false` will drop all the packets.

When the Docker daemon is configured with both `--icc=false` and `--iptables=true` and `docker run` is invoked with the `--link` option, the Docker server will insert a pair of IPTables accept rules for new containers to connect to the ports exposed by the other containers, which will be the ports that have been mentioned in the exposed lines of its Dockerfile. The following figure shows how `ip_forward = false` drops all the packets to/from the container from/to the external network:



By default, Docker's `forward` rule permits all external IPs. To allow only a specific IP or network to access the containers, insert a negated rule at the top of the Docker filter chain.

For example, using the following command, you can restrict external access such that only the source IP `10.10.10.10` can access the containers:

```
#iptables -I DOCKER -i ext_if ! -s 10.10.10.10 -j DROP
```

## Restricting SSH access from one container to another

Following these steps to restrict SSH access from one container to another:

1. Create two containers, `c1` and `c2`.

For `c1`, use the following command:

```
# docker run -i -t --name c1 ubuntu:latest /bin/bash
```

The output generated is as follows:

```
root@7bc2b6cb1025:/# ifconfig
eth0      Link encap:Ethernet  HWaddr 02:42:ac:11:00:05
          inet addr:172.17.0.5  Bcast:0.0.0.0  Mask:255.255.0.0
          inet6 addr: 2001:db8:1::242:ac11:5/64 Scope:Global
```

```

    inet6 addr: fe80::42:acff:fe11:5/64 Scope:Link
    UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
    RX packets:7 errors:0 dropped:0 overruns:0 frame:0
    TX packets:8 errors:0 dropped:0 overruns:0 carrier:0
    collisions:0 txqueuelen:0
    RX bytes:738 (738.0 B)  TX bytes:696 (696.0 B)
lo    Link encap:Local Loopback
    inet addr:127.0.0.1  Mask:255.0.0.0
    inet6 addr: ::1/128 Scope:Host
    UP LOOPBACK RUNNING  MTU:65536  Metric:1
    RX packets:0 errors:0 dropped:0 overruns:0 frame:0
    TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
    collisions:0 txqueuelen:0
    RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
```

For c2, use the following command:

```
# docker run -i -t --name c2 ubuntu:latest /bin/bash
```

The following is the output generated:

```
root@e58a9bf7120b:/# ifconfig
eth0    Link encap:Ethernet  HWaddr 02:42:ac:11:00:06
        inet addr:172.17.0.6  Bcast:0.0.0.0
Mask:255.255.0.0
        inet6 addr: 2001:db8:1::242:ac11:6/64 Scope:Global
        inet6 addr: fe80::42:acff:fe11:6/64 Scope:Link
    UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
    RX packets:6 errors:0 dropped:0 overruns:0 frame:0
    TX packets:8 errors:0 dropped:0 overruns:0 carrier:0
    collisions:0 txqueuelen:0
    RX bytes:648 (648.0 B)  TX bytes:696 (696.0 B)
lo    Link encap:Local Loopback
    inet addr:127.0.0.1  Mask:255.0.0.0
    inet6 addr: ::1/128 Scope:Host
    UP LOOPBACK RUNNING  MTU:65536  Metric:1
    RX packets:0 errors:0 dropped:0 overruns:0 frame:0
    TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
    collisions:0 txqueuelen:0
```

---

```
RX bytes:0 (0.0 B) TX bytes:0 (0.0 B)
```

We can test connectivity between the containers using the IP address we've just discovered. Let's see this now using the `ping` tool:

```
root@7bc2b6cb1025:/# ping 172.17.0.6
PING 172.17.0.6 (172.17.0.6) 56(84) bytes of data.
64 bytes from 172.17.0.6: icmp_seq=1 ttl=64 time=0.139 ms
64 bytes from 172.17.0.6: icmp_seq=2 ttl=64 time=0.110 ms
^C
--- 172.17.0.6 ping statistics ---
2 packets transmitted, 2 received, 0% packet loss, time 999ms
rtt min/avg/max/mdev = 0.110/0.124/0.139/0.018 ms
root@7bc2b6cb1025:/#
```

```
root@e58a9bf7120b:/# ping 172.17.0.5
PING 172.17.0.5 (172.17.0.5) 56(84) bytes of data.
64 bytes from 172.17.0.5: icmp_seq=1 ttl=64 time=0.270 ms
64 bytes from 172.17.0.5: icmp_seq=2 ttl=64 time=0.107 ms
^C
--- 172.17.0.5 ping statistics ---
2 packets transmitted, 2 received, 0% packet loss, time 1002ms
rtt min/avg/max/mdev = 0.107/0.188/0.270/0.082 ms
root@e58a9bf7120b:/#
```

2. Install `openssh-server` on both the containers:

```
#apt-get install openssh-server
```

3. Enable `iptables` on the host machine:

1. Initially, you will be able to SSH from one container to another.
2. Stop the Docker service and add `DOCKER_OPTS="--icc=false --iptables=true"` to the default Dockerfile of the host machine. This option will enable the `iptables` firewall and drop all ports between the containers.

By default, `iptables` is not enabled on the host. Use the following command to enable it:

```
root@ubuntu:~# iptables -L -n
Chain INPUT (policy ACCEPT)
```

```

target      prot opt source      destination
Chain FORWARD (policy ACCEPT)
target      prot opt source      destination
DOCKER      all  --  0.0.0.0/0    0.0.0.0/0
ACCEPT      all  --  0.0.0.0/0    0.0.0.0/0
ctstate RELATED,ESTABLISHED
ACCEPT      all  --  0.0.0.0/0    0.0.0.0/0
DOCKER      all  --  0.0.0.0/0    0.0.0.0/0
ACCEPT      all  --  0.0.0.0/0    0.0.0.0/0
ctstate RELATED,ESTABLISHED
ACCEPT      all  --  0.0.0.0/0    0.0.0.0/0
ACCEPT      all  --  0.0.0.0/0    0.0.0.0/0
ACCEPT      all  --  0.0.0.0/0    0.0.0.0/0

```

```

#service docker stop
#vi /etc/default/docker

```

3. Docker Upstart and SysVinit configuration file. Customize the location of the Docker binary (especially for development testing):

```
#DOCKER="/usr/local/bin/docker"
```

4. Use DOCKER\_OPTS to modify the daemon's startup options:

```

#DOCKER_OPTS="--dns 8.8.8.8 --dns 8.8.4.4"
#DOCKER_OPTS="--icc=false --iptables=true"

```

5. Restart the Docker service:

```
# service docker start
```

6. Inspect iptables:

```

root@ubuntu:~# iptables -L -n
Chain INPUT (policy ACCEPT)
target      prot opt source      destination
Chain FORWARD (policy ACCEPT)
target      prot opt source      destination
DOCKER      all  --  0.0.0.0/0    0.0.0.0/0
ACCEPT      all  --  0.0.0.0/0    0.0.0.0/0    ctstate
RELATED, ESTABLISHED
ACCEPT      all  --  0.0.0.0/0    0.0.0.0/0
DOCKER      all  --  0.0.0.0/0    0.0.0.0/0

```

---

```

ACCEPT    all  --  0.0.0.0/0          0.0.0.0/0  ctstate
RELATED, ESTABLISHED
ACCEPT    all  --  0.0.0.0/0          0.0.0.0/0
ACCEPT    all  --  0.0.0.0/0          0.0.0.0/0
DROP      all  --  0.0.0.0/0          0.0.0.0/0

```

The DROP rule has been added to iptables on the host machine, which drops a connection between containers. Now you will be unable to SSH between the containers.

4. We can communicate with or connect containers using the `--link` parameter, with the help of following steps:
  1. Create the first container, which will act as the server, `sshserver`:
 

```

root@ubuntu:~# docker run -i -t -p 2222:22 --name sshserver
ubuntu bash
root@9770be5acbab:/#

```
  2. Execute the `iptables` command, and you will find a Docker chain rule added:
 

```

#root@ubuntu:~# iptables -L -n
Chain INPUT (policy ACCEPT)
target     prot opt source                destination
Chain FORWARD (policy ACCEPT)
target     prot opt source                destination
Chain OUTPUT (policy ACCEPT)
target     prot opt source                destination
Chain DOCKER (0 references)
target     prot opt source                destination
ACCEPT     tcp  --  0.0.0.0/0             172.17.0.3            tcp
dpt:22

```
  3. Create the second container, which acts like a client, `sshclient`:
 

```

root@ubuntu:~# docker run -i -t --name sshclient --link
sshserver:sshserver ubuntu bash
root@979d46c5c6a5:/#

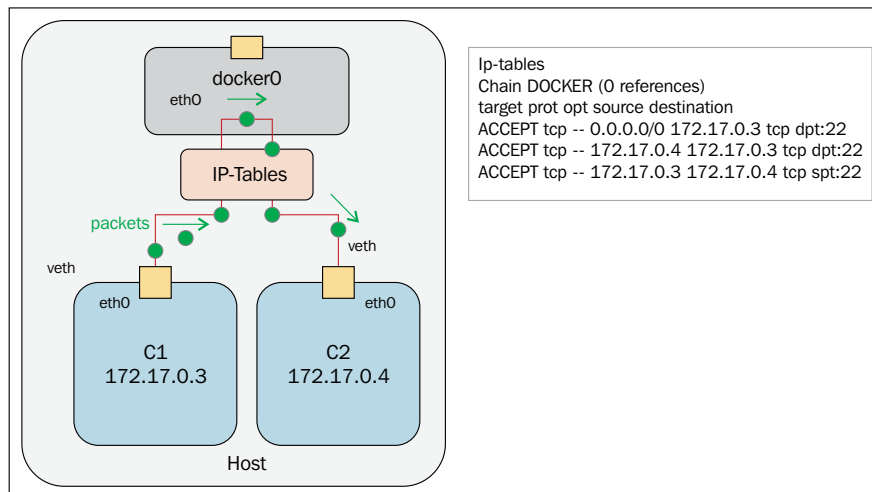
```



4. We can see that there are more rules added to the Docker chain rule:

```
root@ubuntu:~# iptables -L -n
Chain INPUT (policy ACCEPT)
target     prot opt source                destination
Chain FORWARD (policy ACCEPT)
target     prot opt source                destination
Chain OUTPUT (policy ACCEPT)
target     prot opt source                destination
Chain DOCKER (0 references)
target     prot opt source                destination
ACCEPT    tcp  --  0.0.0.0/0             172.17.0.3            tcp dpt:22
ACCEPT    tcp  --  172.17.0.4           172.17.0.3            tcp dpt:22
ACCEPT    tcp  --  172.17.0.3           172.17.0.4            tcp spt:22
root@ubuntu:~#
```

The following image explains communication between the containers using the `--link` flag:



5. You can inspect your linked container with the `docker inspect` command:

```
root@ubuntu:~# docker inspect -f "{{ .HostConfig.Links }}"
sshclient
[/sshserver:/sshclient/sshserver]
```

Now you can successfully ssh into sshserver with its IP.

```
#ssh root@172.17.0.3 -p 22
```

Using the `--link` parameter, Docker creates a secure channel between the containers that doesn't need to expose any ports externally on the containers.

## Configuring the Docker bridge

The Docker server creates a bridge called `docker0` by default inside the Linux kernel, and it can pass packets back and forth between other physical or virtual network interfaces so that they behave as a single Ethernet network. Run the following command to find out the list of interfaces in a VM and the IP addresses they are connected to:

```
root@ubuntu:~# ifconfig
docker0    Link encap:Ethernet  HWaddr 56:84:7a:fe:97:99
            inet addr:172.17.42.1  Bcast:0.0.0.0  Mask:255.255.0.0
            inet6 addr: fe80::5484:7aff:fefe:9799/64 Scope:Link
            inet6 addr: fe80::1/64 Scope:Link
            UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
            RX packets:11909 errors:0 dropped:0 overruns:0 frame:0
            TX packets:14826 errors:0 dropped:0 overruns:0 carrier:0
            collisions:0 txqueuelen:0
            RX bytes:516868 (516.8 KB)  TX bytes:46460483 (46.4 MB)

eth0       Link encap:Ethernet  HWaddr 00:0c:29:0d:f4:2c
            inet addr:192.168.186.129  Bcast:192.168.186.255
Mask:255.255.255.0
            inet6 addr: fe80::20c:29ff:fe0d:f42c/64 Scope:Link
            UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
            RX packets:108865 errors:0 dropped:0 overruns:0 frame:0
            TX packets:31708 errors:0 dropped:0 overruns:0 carrier:0
            collisions:0 txqueuelen:1000
            RX bytes:59902195 (59.9 MB)  TX bytes:3916180 (3.9 MB)
```

```
lo          Link encap:Local Loopback
            inet addr:127.0.0.1  Mask:255.0.0.0
            inet6 addr: ::1/128 Scope:Host
            UP LOOPBACK RUNNING  MTU:65536  Metric:1
            RX packets:4 errors:0 dropped:0 overruns:0 frame:0
            TX packets:4 errors:0 dropped:0 overruns:0 carrier:0
            collisions:0 txqueuelen:0
            RX bytes:336 (336.0 B)  TX bytes:336 (336.0 B)
```

Once you have one or more containers up and running, you can confirm that Docker has properly connected them to the `docker0` bridge by running the `brctl` command on the host machine and looking at the `interfaces` column of the output.

Before configuring the `docker0` bridge, install the bridge utilities:

```
# apt-get install bridge-utils
```

Here is a host with two different containers connected:

```
root@ubuntu:~# brctl show
bridge name      bridge id          STP enabled      interfaces
docker0          8000.56847afe9799  no               veth21b2e16
                  veth7092a45
```

Docker uses the `docker0` bridge settings whenever a container is created. It assigns a new IP address from the range available on the bridge whenever a new container is created, as can be seen here:

```
root@ubuntu:~# docker run -t -i --name container1 ubuntu:latest /bin/bash
root@e54e9312dc04:/# ifconfig
eth0          Link encap:Ethernet  HWaddr 02:42:ac:11:00:07
            inet addr:172.17.0.7  Bcast:0.0.0.0  Mask:255.255.0.0
            inet6 addr: 2001:db8:1::242:ac11:7/64 Scope:Global
            inet6 addr: fe80::42:acff:fe11:7/64 Scope:Link
            UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
            RX packets:7 errors:0 dropped:0 overruns:0 frame:0
            TX packets:8 errors:0 dropped:0 overruns:0 carrier:0
            collisions:0 txqueuelen:0
            RX bytes:738 (738.0 B)  TX bytes:696 (696.0 B)
```

```

lo          Link encap:Local Loopback
            inet addr:127.0.0.1  Mask:255.0.0.0
            inet6 addr: ::1/128 Scope:Host
            UP LOOPBACK RUNNING  MTU:65536  Metric:1
            RX packets:0 errors:0 dropped:0 overruns:0 frame:0
            TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
            collisions:0 txqueuelen:0
            RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)

root@e54e9312dc04:/# ip route
default via 172.17.42.1 dev eth0
172.17.0.0/16 dev eth0  proto kernel  scope link  src 172.17.0.7

```

By default, Docker provides a virtual network called `docker0`, which has the IP address `172.17.42.1`. Docker containers have IP addresses in the range of `172.17.0.0/16`.

To change the default settings in Docker, modify the file `/etc/default/docker`.

Changing the default bridge from `docker0` to `br0` can be done like this:

```

# sudo service docker stop
# sudo ip link set dev docker0 down
# sudo brctl delbr docker0
# sudo iptables -t nat -F POSTROUTING
# echo 'DOCKER_OPTS="-b=br0"' >> /etc/default/docker
# sudo brctl addbr br0
# sudo ip addr add 192.168.10.1/24 dev br0
# sudo ip link set dev br0 up
# sudo service docker start

```

The following command displays the new bridge name and the IP address range of the Docker service:

```

root@ubuntu:~# ifconfig
br0          Link encap:Ethernet  HWaddr ae:b2:dc:ed:e6:af
            inet addr:192.168.10.1  Bcast:0.0.0.0  Mask:255.255.255.0
            inet6 addr: fe80::acb2:dcff:feed:e6af/64 Scope:Link
            UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
            RX packets:0 errors:0 dropped:0 overruns:0 frame:0

```

```
TX packets:7 errors:0 dropped:0 overruns:0 carrier:0
collisions:0 txqueuelen:0
RX bytes:0 (0.0 B) TX bytes:738 (738.0 B)
eth0 Link encap:Ethernet HWaddr 00:0c:29:0d:f4:2c
      inet addr:192.168.186.129 Bcast:192.168.186.255
Mask:255.255.255.0
      inet6 addr: fe80::20c:29ff:fe0d:f42c/64 Scope:Link
UP BROADCAST RUNNING MULTICAST MTU:1500 Metric:1
RX packets:110823 errors:0 dropped:0 overruns:0 frame:0
TX packets:33148 errors:0 dropped:0 overruns:0 carrier:0
collisions:0 txqueuelen:1000
RX bytes:60081009 (60.0 MB) TX bytes:4176982 (4.1 MB)
lo Link encap:Local Loopback
  inet addr:127.0.0.1 Mask:255.0.0.0
  inet6 addr: ::1/128 Scope:Host
UP LOOPBACK RUNNING MTU:65536 Metric:1
RX packets:4 errors:0 dropped:0 overruns:0 frame:0
TX packets:4 errors:0 dropped:0 overruns:0 carrier:0
collisions:0 txqueuelen:0
RX bytes:336 (336.0 B) TX bytes:336 (336.0 B)
```

## Overlay networks and underlay networks

An overlay is a virtual network that is built on top of underlying network infrastructure (the underlay). The purpose is to implement a network service that is not available in the physical network.

Network overlay dramatically increases the number of virtual subnets that can be created on top of the physical network, which in turn supports multi-tenancy and virtualization.

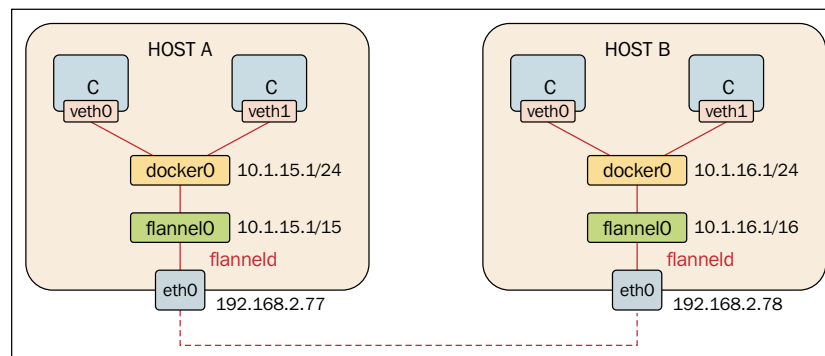
Every container in Docker is assigned an IP address, which is used for communication with other containers. If a container has to communicate with the external network, you set up networking in the host system and expose or map the port from the container to the host machine. With this, applications running inside containers will not be able to advertise their external IP and ports, as the information will not be available to them.

The solution is to somehow assign unique IPs to each Docker container across all hosts and have some networking product that routes traffic between hosts.

There are different projects to deal with Docker networking, as follows:

- Flannel
- Weave
- Open vSwitch

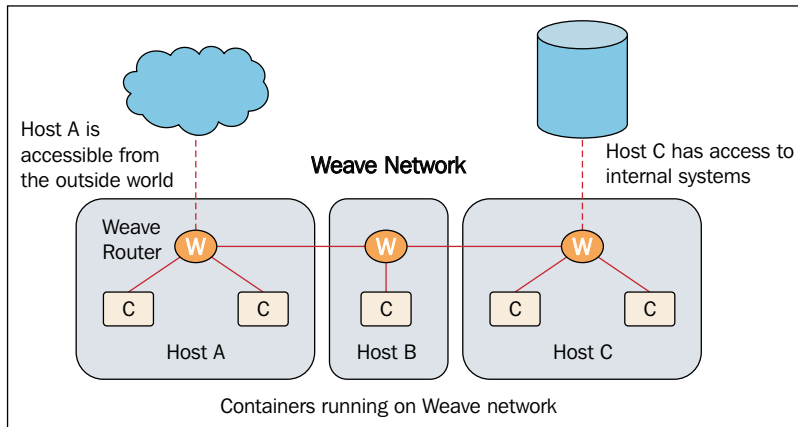
Flannel provides a solution by giving each container an IP that can be used for container-to-container communication. Using packet encapsulation, it creates a virtual overlay network over the host network. By default, Flannel provides a /24 subnet to hosts, from which the Docker daemon allocates IPs to containers. The following figure shows the communication between containers using Flannel:



Flannel runs an agent, **flanneld**, on each host and is responsible for allocating a subnet lease out of a preconfigured address space. Flannel uses etcd to store the network configuration, allocated subnets, and auxiliary data (such as the host's IP).

Flannel uses the universal TUN/TAP device and creates an overlay network using UDP to encapsulate IP packets. Subnet allocation is done with the help of etcd, which maintains the overlay subnet-to-host mappings.

Weave creates a virtual network that connects Docker containers deployed across hosts/VMs and enables their automatic discovery. The following figure shows a Weave network:



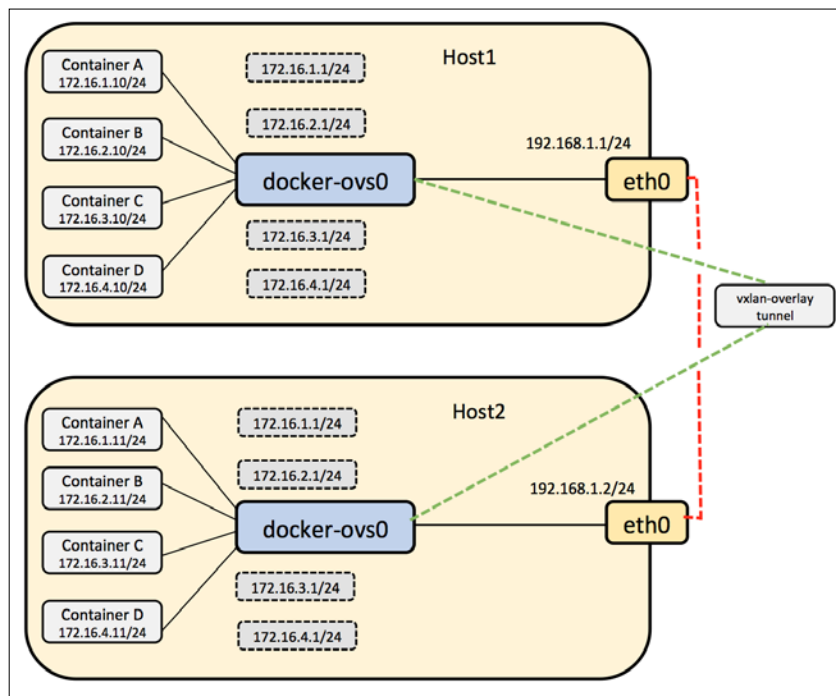
Weave can traverse firewalls and operate in partially connected networks. Traffic can be optionally encrypted, allowing hosts/VMs to be connected across an untrusted network.

Weave augments Docker's existing (single host) networking capabilities, such as the `docker0` bridge, so these can continue to be used by containers.

Open vSwitch is an open source OpenFlow-capable virtual switch that is typically used with hypervisors to interconnect virtual machines within a host and between different hosts across networks. Overlay networks need to create a virtual datapath using supported tunneling encapsulations, such as VXLAN and GRE.

The overlay datapath is provisioned between tunnel endpoints residing in the Docker host, which gives the appearance of all hosts within a given provider segment being directly connected to one another.

As a new container comes online, the prefix is updated in the routing protocol, announcing its location via a tunnel endpoint. As the other Docker hosts receive the updates, the forwarding rule is installed into the OVS for the tunnel endpoint that the host resides on. When the host is de-provisioned, a similar process occurs and tunnel endpoint Docker hosts remove the forwarding entry for the de-provisioned container. The following figure shows the communication between containers running on multiple hosts through OVS-based VXLAN tunnels:



## Summary

In this chapter, we discussed Docker's internal networking architecture. We learned about IPv4, IPv6, and DNS configuration in Docker. Later in the chapter, we covered the Docker bridge and communication between containers within a single host and in multiple hosts.

We also discussed overlay tunneling and different methods that are implemented in Docker networking, such as OVS, Flannel, and Weave.

In the next chapter, we will learn hands-on Docker networking, clubbed with various frameworks.





# 3

## Building Your First Docker Network

This chapter describes practical examples of Docker networking, spanning multiple containers over multiple hosts. We will cover the following topics:

- Introduction to Pipework
- Multiple containers over multiple hosts
- Towards scaling networks – introducing Open vSwitch
- Networking with overlay networks – Flannel
- Comparison of Docker networking options

### Introduction to Pipework

Pipework lets you connect together containers in arbitrarily complex scenarios.

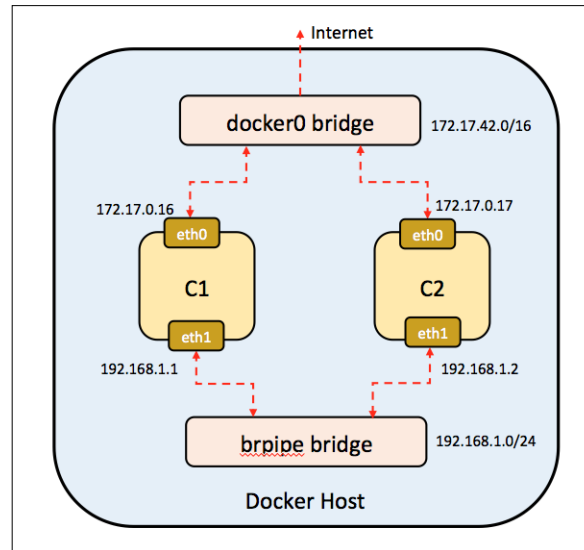
In practical terms, it creates a legacy Linux bridge, adds a new interface to the container, and then attaches the interface to that bridge; containers get a network segment on which to communicate with each other.

### Multiple containers over a single host

Pipework is a shell script and installing it is simple:

```
#sudo wget -O /usr/local/bin/pipework  
https://raw.githubusercontent.com/jpetazzo/pipework/master/pipework  
&& sudo chmod +x /usr/local/bin/pipework
```

The following figure shows container communication using Pipework:



First, create two containers:

```
#docker run -i -t --name c1 ubuntu:latest /bin/bash
root@5afb44195a69:/# ifconfig
eth0      Link encap:Ethernet  HWaddr 02:42:ac:11:00:10
          inet addr:172.17.0.16  Bcast:0.0.0.0  Mask:255.255.0.0
          inet6 addr: fe80::42:acff:fe11:10/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:13 errors:0 dropped:0 overruns:0 frame:0
          TX packets:9 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:1038 (1.0 KB)  TX bytes:738 (738.0 B)

lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          inet6 addr: ::1/128 Scope:Host
          UP LOOPBACK RUNNING  MTU:65536  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
```

```

collisions:0 txqueuelen:0
RX bytes:0 (0.0 B) TX bytes:0 (0.0 B)

#docker run -i -t --name c2 ubuntu:latest /bin/bash
root@c94d53a76a9b:/# ifconfig
eth0      Link encap:Ethernet  HWaddr 02:42:ac:11:00:11
          inet addr:172.17.0.17  Bcast:0.0.0.0  Mask:255.255.0.0
          inet6 addr: fe80::42:acff:fe11:11/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:8 errors:0 dropped:0 overruns:0 frame:0
          TX packets:9 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:648 (648.0 B)  TX bytes:738 (738.0 B)
lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          inet6 addr: ::1/128 Scope:Host
          UP LOOPBACK RUNNING  MTU:65536  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)

```

Now let's use Pipework to connect them:

```
#sudo pipework brpipe c1 192.168.1.1/24
```

This command creates a bridge, `brpipe`, on the host machine. It adds an `eth1` interface to the container `c1` with the IP address `192.168.1.1` and attaches the interface to the bridge as follows:

```

root@5afb44195a69:/# ifconfig
eth0      Link encap:Ethernet  HWaddr 02:42:ac:11:00:10
          inet addr:172.17.0.16  Bcast:0.0.0.0  Mask:255.255.0.0
          inet6 addr: fe80::42:acff:fe11:10/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:13 errors:0 dropped:0 overruns:0 frame:0
          TX packets:9 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:1038 (1.0 KB)  TX bytes:738 (738.0 B)

```

```
eth1      Link encap:Ethernet  HWaddr ce:72:c5:12:4a:1a
          inet addr:192.168.1.1  Bcast:0.0.0.0  Mask:255.255.255.0
          inet6 addr: fe80::cc72:c5ff:fe12:4a1a/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:23 errors:0 dropped:0 overruns:0 frame:0
          TX packets:9 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:1806 (1.8 KB)  TX bytes:690 (690.0 B)

lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          inet6 addr: ::1/128 Scope:Host
          UP LOOPBACK RUNNING  MTU:65536  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)

#sudo pipework brpipe c2 192.168.1.2/24
```

This command will not create bridge `brpipe` as it already exists. It will add an `eth1` interface to the container `c2` and connect it to the bridge as follows:

```
root@c94d53a76a9b:/# ifconfig

eth0      Link encap:Ethernet  HWaddr 02:42:ac:11:00:11
          inet addr:172.17.0.17  Bcast:0.0.0.0  Mask:255.255.0.0
          inet6 addr: fe80::42:acff:fe11:11/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:8 errors:0 dropped:0 overruns:0 frame:0
          TX packets:9 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:648 (648.0 B)  TX bytes:738 (738.0 B)

eth1      Link encap:Ethernet  HWaddr 36:86:fb:9e:88:ba
          inet addr:192.168.1.2  Bcast:0.0.0.0  Mask:255.255.255.0
          inet6 addr: fe80::3486:fbff:fe9e:88ba/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:8 errors:0 dropped:0 overruns:0 frame:0
          TX packets:9 errors:0 dropped:0 overruns:0 carrier:0
```

```

collisions:0 txqueuelen:1000
RX bytes:648 (648.0 B) TX bytes:690 (690.0 B)
lo    Link encap:Local Loopback
      inet addr:127.0.0.1  Mask:255.0.0.0
      inet6 addr: ::1/128 Scope:Host
      UP LOOPBACK RUNNING  MTU:65536  Metric:1
      RX packets:0 errors:0 dropped:0 overruns:0 frame:0
      TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
      collisions:0 txqueuelen:0
      RX bytes:0 (0.0 B) TX bytes:0 (0.0 B)

```

Now the containers are connected and will be able to ping each other as they are on the same subnet, 192.168.1.0/24. Pipework provides the advantage of adding static IP addresses to the containers.

## Weave your containers

Weave creates a virtual network that can connect Docker containers across multiple hosts as if they are all connected to a single switch. The Weave router itself runs as a Docker container and can encrypt routed traffic for transmission over the Internet. Services provided by application containers on the Weave network can be made accessible to the outside world, regardless of where those containers are running.

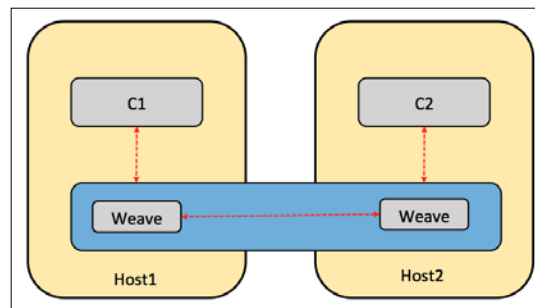
Use the following code to install Weave:

```

#sudo curl -L git.io/weave -o /usr/local/bin/weave
#sudo chmod a+x /usr/local/bin/weave

```

The following figure shows multihost communication using Weave:



On \$HOST1, we run the following:

```
# weave launch
# eval $(weave proxy-env)
# docker run --name c1 -ti ubuntu
```

Next, we repeat similar steps on \$HOST2:

```
# weave launch $HOST1
# eval $(weave proxy-env)
# docker run --name c2 -ti ubuntu
```

In the container started on \$HOST1, the following output is generated:

```
root@c1:/# ifconfig
eth0      Link encap:Ethernet  HWaddr 02:42:ac:11:00:21
          inet addr:172.17.0.33  Bcast:0.0.0.0  Mask:255.255.0.0
          inet6 addr: fe80::42:acff:fe11:21/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:38 errors:0 dropped:0 overruns:0 frame:0
          TX packets:34 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:3166 (3.1 KB)  TX bytes:2299 (2.2 KB)
ethwe     Link encap:Ethernet  HWaddr aa:99:8a:d5:4d:d4
          inet addr:10.128.0.3  Bcast:0.0.0.0  Mask:255.192.0.0
          inet6 addr: fe80::a899:8aff:fed5:4dd4/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:65535  Metric:1
          RX packets:130 errors:0 dropped:0 overruns:0 frame:0
          TX packets:74 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:11028 (11.0 KB)  TX bytes:6108 (6.1 KB)
lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          inet6 addr: ::1/128 Scope:Host
          UP LOOPBACK RUNNING  MTU:65536  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
```

You can see the Weave network interface, `ethwe`, using the `ifconfig` command:

```
root@c2:/# ifconfig
eth0      Link encap:Ethernet  HWaddr 02:42:ac:11:00:04
          inet addr:172.17.0.4  Bcast:0.0.0.0  Mask:255.255.0.0
          inet6 addr: fe80::42:acff:fe11:4/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:28 errors:0 dropped:0 overruns:0 frame:0
          TX packets:29 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:2412 (2.4 KB)  TX bytes:2016 (2.0 KB)
ethwe     Link encap:Ethernet  HWaddr 8e:7c:17:0d:0e:03
          inet addr:10.160.0.1  Bcast:0.0.0.0  Mask:255.192.0.0
          inet6 addr: fe80::8c7c:17ff:fe0d:e03/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:65535  Metric:1
          RX packets:139 errors:0 dropped:0 overruns:0 frame:0
          TX packets:74 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:11718 (11.7 KB)  TX bytes:6108 (6.1 KB)
lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          inet6 addr: ::1/128 Scope:Host
          UP LOOPBACK RUNNING  MTU:65536  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)

#root@c1:/# ping -c 1 -q c2
PING c2.weave.local (10.160.0.1) 56(84) bytes of data.
--- c2.weave.local ping statistics ---
1 packets transmitted, 1 received, 0% packet loss, time 0ms
rtt min/avg/max/mdev = 1.317/1.317/1.317/0.000 ms
```



Similarly, in the container started on \$HOST2, the following output is generated:

```
#root@c2:/# ping -c 1 -q c1
PING c1.weave.local (10.128.0.3) 56(84) bytes of data.
--- c1.weave.local ping statistics ---
1 packets transmitted, 1 received, 0% packet loss, time 0ms
rtt min/avg/max/mdev = 1.658/1.658/1.658/0.000 ms
```

So there we have it—two containers on separate hosts happily talking to each other.

## Open vSwitch

Docker uses the Linux bridge `docker0` by default. However, there are cases where **Open vSwitch (OVS)** might be required instead of a Linux bridge. A single Linux bridge can only handle 1024 ports – this limits the scalability of Docker as we can only create 1024 containers, each with a single network interface.

## Single host OVS

We will now install OVS on a single host, create two containers, and connect them to an OVS bridge.

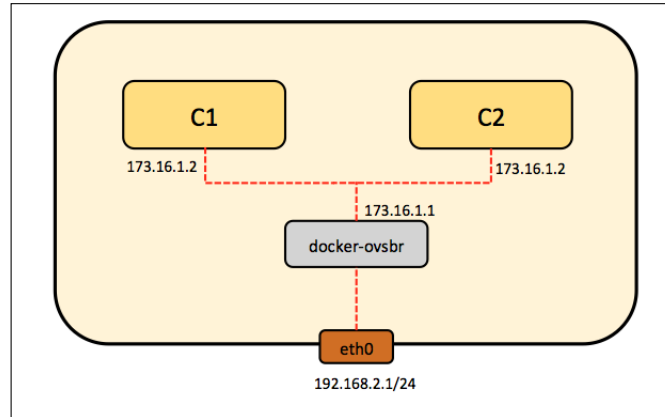
Use this command to install OVS:

```
# sudo apt-get install openvswitch-switch
```

Install the `ovs-docker` utility with the following:

```
# cd /usr/bin
# wget
https://raw.githubusercontent.com/openvswitch/ovs/master/utilities
/ovs-docker
# chmod a+rx ovs-docker
```

The following diagram shows the single-host OVS:



## Creating an OVS bridge

Here, we will be adding a new OVS bridge and configuring it so that we can get the containers connected on a different network, as follows:

```
# ovs-vsctl add-br ovs-br1
# ifconfig ovs-br1 173.16.1.1 netmask 255.255.255.0 up
```

Add a port from the OVS bridge to the Docker container using the following steps:

1. Create two Ubuntu Docker containers:
 

```
# docker run -I -t --name container1 ubuntu /bin/bash
# docekr run -I -t --name container2 ubuntu /bin/bash
```
2. Connect the container to the OVS bridge:
 

```
# ovs-docker add-port ovs-br1 eth1 container1 --
ipaddress=173.16.1.2/24
# ovs-docker add-port ovs-br1 eth1 container2 --
ipaddress=173.16.1.3/24
```
3. Test the connection between the two containers connected via an OVS bridge using the ping command. First, find out their IP addresses:

```
# docker exec container1 ifconfig
eth0      Link encap:Ethernet  HWaddr 02:42:ac:10:11:02
          inet addr:172.16.17.2  Bcast:0.0.0.0
          Mask:255.255.255.0
          inet6 addr: fe80::42:acff:fe10:1102/64 Scope:Link
```

```
UP BROADCAST RUNNING MULTICAST  MTU:1472
Metric:1
RX packets:36 errors:0 dropped:0 overruns:0
frame:0
TX packets:8 errors:0 dropped:0 overruns:0
carrier:0
collisions:0 txqueuelen:0
RX bytes:4956 (4.9 KB)  TX bytes:648 (648.0 B)

lo    Link encap:Local Loopback
      inet addr:127.0.0.1  Mask:255.0.0.0
      inet6 addr: ::1/128 Scope:Host
      UP LOOPBACK RUNNING  MTU:65536  Metric:1
      RX packets:0 errors:0 dropped:0 overruns:0
frame:0
      TX packets:0 errors:0 dropped:0 overruns:0
carrier:0
      collisions:0 txqueuelen:0
      RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)

# docker exec container2 ifconfig
eth0   Link encap:Ethernet  HWaddr 02:42:ac:10:11:03
      inet addr:172.16.17.3  Bcast:0.0.0.0
Mask:255.255.255.0
      inet6 addr: fe80::42:acff:fe10:1103/64 Scope:Link
      UP BROADCAST RUNNING MULTICAST  MTU:1472
Metric:1
      RX packets:27 errors:0 dropped:0 overruns:0
frame:0
      TX packets:8 errors:0 dropped:0 overruns:0
carrier:0
      collisions:0 txqueuelen:0
      RX bytes:4201 (4.2 KB)  TX bytes:648 (648.0 B)

lo    Link encap:Local Loopback
      inet addr:127.0.0.1  Mask:255.0.0.0
      inet6 addr: ::1/128 Scope:Host
      UP LOOPBACK RUNNING  MTU:65536  Metric:1
      RX packets:0 errors:0 dropped:0 overruns:0
frame:0
      TX packets:0 errors:0 dropped:0 overruns:0
carrier:0
```

```
collisions:0 txqueuelen:0
RX bytes:0 (0.0 B) TX bytes:0 (0.0 B)
```

Now that we know the IP addresses of container1 and container2, we can ping them:

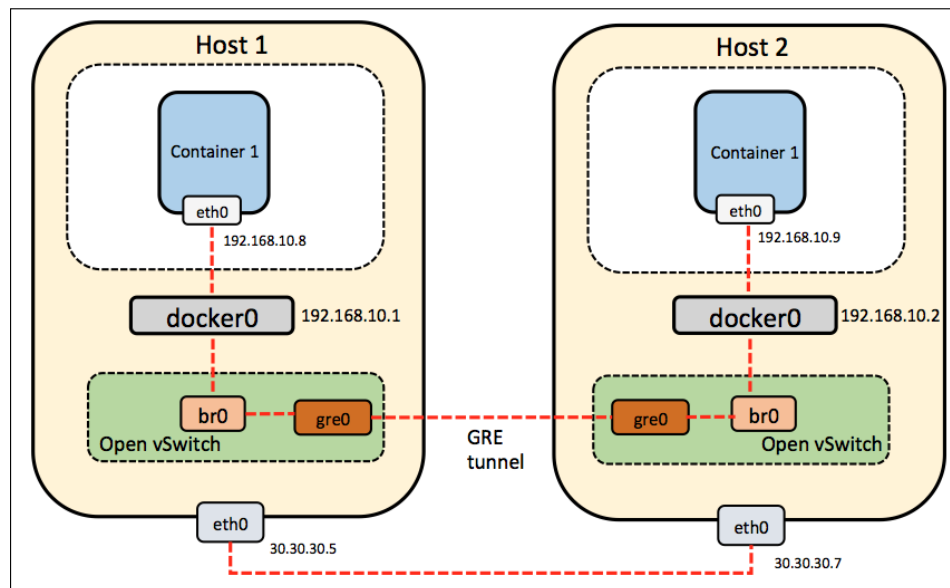
```
# docker exec container2 ping 172.16.17.2
PING 172.16.17.2 (172.16.17.2) 56(84) bytes of data.
64 bytes from 172.16.17.2: icmp_seq=1 ttl=64 time=0.257 ms
64 bytes from 172.16.17.2: icmp_seq=2 ttl=64 time=0.048 ms
64 bytes from 172.16.17.2: icmp_seq=3 ttl=64 time=0.052 ms

# docker exec container1 ping 172.16.17.2
PING 172.16.17.2 (172.16.17.2) 56(84) bytes of data.
64 bytes from 172.16.17.2: icmp_seq=1 ttl=64 time=0.060 ms
64 bytes from 172.16.17.2: icmp_seq=2 ttl=64 time=0.035 ms
64 bytes from 172.16.17.2: icmp_seq=3 ttl=64 time=0.031 ms
```

## Multiple host OVS

Let's see how to connect Docker containers on multiple hosts using OVS.

Let's consider our setup as shown in the following diagram, which contains two hosts, **Host 1** and **Host 2**, running Ubuntu 14.04:



Install Docker and Open vSwitch on both the hosts:

```
# wget -qO- https://get.docker.com/ | sh
# sudo apt-get install openvswitch-switch
```

Install the ovs-docker utility:

```
# cd /usr/bin
# wget
https://raw.githubusercontent.com/openvswitch/ovs/master/utilities/ov
s-docker
# chmod a+rx ovs-docker
```

By default, Docker chooses a random network to run its containers in. It creates a bridge, `docker0`, and assigns an IP address (`172.17.42.1`) to it. So, both **Host 1** and **Host 2** `docker0` bridge IP addresses are the same, due to which it is difficult for containers in both the hosts to communicate. To overcome this, let's assign static IP addresses to the network, that is, `192.168.10.0/24`.

Let's see how to change the default Docker subnet.

Execute the following commands on Host 1:

```
# service docker stop
# ip link set dev docker0 down
# ip addr del 172.17.42.1/16 dev docker0
# ip addr add 192.168.10.1/24 dev docker0
# ip link set dev docker0 up
# ip addr show docker0
# service docker start
```

Add the `br0` OVS bridge:

```
# ovs-vsctl add-br br0
```

Create the tunnel to the other host and attach it to the:

```
# add-port br0 gre0 -- set interface gre0 type=gre
options:remote_ip=30.30.30.8
```

Add the `br0` bridge to the `docker0` bridge:

```
# brctl addif docker0 br0
```

Execute the following commands on Host 2:

```
# service docker stop
# iptables -t nat -F POSTROUTING
# ip link set dev docker0 down
# ip addr del 172.17.42.1/16 dev docker0
# ip addr add 192.168.10.2/24 dev docker0
# ip link set dev docker0 up
# ip addr show docker0
# service docker start
```

Add the br0 OVS bridge:

```
# ip link set br0 up
# ovs-vsctl add-br br0
```

Create the tunnel to the other host and attach it to the:

```
# br0 bridge ovs-vsctl add-port br0 gre0 -- set interface gre0
type=gre options:remote_ip=30.30.30.7
```

Add the br0 bridge to the docker0 bridge:

```
# brctl addif docker0 br0
```

The docker0 bridge is attached to another bridge, br0. This time, it's an OVS bridge. This means that all traffic between the containers is routed through br0 too.

Additionally, we need to connect together the networks from both the hosts in which the containers are running. A GRE tunnel is used for this purpose. This tunnel is attached to the br0 OVS bridge and, as a result, to docker0 too.

After executing the preceding commands on both hosts, you should be able to ping the docker0 bridge addresses from both hosts.

On Host 1, the following output is generated on using the ping command:

```
# ping 192.168.10.2
PING 192.168.10.2 (192.168.10.2) 56(84) bytes of data.
64 bytes from 192.168.10.2: icmp_seq=1 ttl=64 time=0.088 ms
64 bytes from 192.168.10.2: icmp_seq=2 ttl=64 time=0.032 ms
^C
--- 192.168.10.2 ping statistics ---
2 packets transmitted, 2 received, 0% packet loss, time 999ms
rtt min/avg/max/mdev = 0.032/0.060/0.088/0.028 ms
```

On Host 2, the following output is generated on using the `ping` command:

```
# ping 192.168.10.1
PING 192.168.10.1 (192.168.10.1) 56(84) bytes of data.
64 bytes from 192.168.10.1: icmp_seq=1 ttl=64 time=0.088 ms
64 bytes from 192.168.10.1: icmp_seq=2 ttl=64 time=0.032 ms
^C
--- 192.168.10.1 ping statistics ---
2 packets transmitted, 2 received, 0% packet loss, time 999ms
rtt min/avg/max/mdev = 0.032/0.060/0.088/0.028 ms
```

Let's see how to create containers on both the hosts.

On Host 1, use the following code:

```
# docker run -t -i --name container1 ubuntu:latest /bin/bash
```

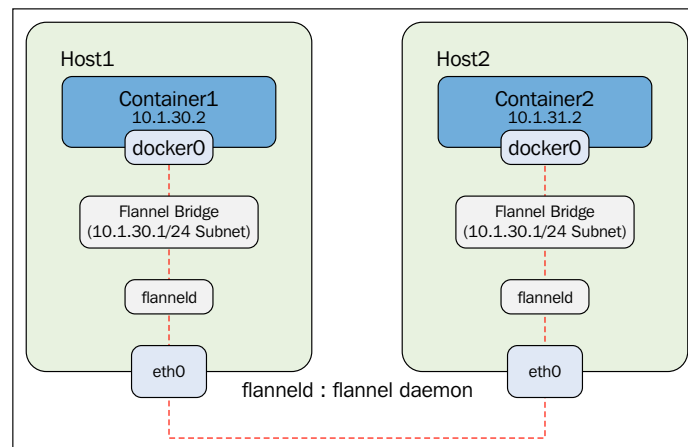
On Host 2, use the following code:

```
# docker run -t -i --name container2 ubuntu:latest /bin/bash
```

Now we can ping `container2` from `container1`. In this way, we connect Docker containers on multiple hosts using Open vSwitch.

## Networking with overlay networks – Flannel

Flannel is the virtual network layer that provides the subnet to each host for use with Docker containers. It is packaged with CoreOS but can be configured on other Linux OSes as well. Flannel creates the overlay by actually connecting itself to Docker bridge, to which containers are attached, as shown in the following figure. To setup Flannel, two host machines or VMs are required, which can be CoreOS or, more preferably, Linux OS, as shown in this figure:



The Flannel code can be cloned from GitHub and built locally, if required, on a different flavor of Linux OS, as shown here. It comes preinstalled in CoreOS:

```
# git clone https://github.com/coreos/flannel.git
Cloning into 'flannel'...
remote: Counting objects: 2141, done.
remote: Compressing objects: 100% (19/19), done.
remote: Total 2141 (delta 6), reused 0 (delta 0), pack-reused 2122
Receiving objects: 100% (2141/2141), 4.
Checking connectivity... done.
```

```
# sudo docker run -v `pwd`: /opt/flannel -i -t google/golang
/bin/bash -c "cd /opt/flannel && ./build"
Building flanneld...
```

CoreOS machines can be easily configured using Vagrant and VirtualBox, as per the tutorial mentioned in the following link:

<https://coreos.com/os/docs/latest/booting-on-vagrant.html>



After the machines are created and logged in to, we will find a Flannel bridge automatically created using the `etcd` configuration:

```
# ifconfig flannel0
flannel0: flags=4305<UP,POINTOPOINT,RUNNING,NOARP,MULTICAST> mtu 1472
    inet 10.1.30.0 netmask 255.255.0.0 destination 10.1.30.0
    unspec 00-00-00-00-00-00-00-00-00-00-00-00-00-00-00-00
txqueuelen 500 (UNSPEC)
    RX packets 243 bytes 20692 (20.2 KiB)
    RX errors 0 dropped 0 overruns 0 frame 0
    TX packets 304 bytes 25536 (24.9 KiB)
    TX errors 0 dropped 0 overruns 0 carrier 0 collisions 0
```

The Flannel environment can be checked by viewing `subnet.env`:

```
# cat /run/flannel/subnet.env
FLANNEL_NETWORK=10.1.0.0/16
FLANNEL_SUBNET=10.1.30.1/24
FLANNEL_MTU=1472
FLANNEL_IPMASQ=true
```

The Docker daemon requires to be restarted with the following commands in order to get the networking re-instantiated with the subnet from the Flannel bridge:

```
# source /run/flannel/subnet.env
# sudo rm /var/run/docker.pid
# sudo ifconfig docker0 ${FLANNEL_SUBNET}
# sudo docker -d --bip=${FLANNEL_SUBNET} --mtu=${FLANNEL_MTU}
& INFO[0000] [graphdriver] using prior storage driver "overlay"
INFO[0000] Option DefaultDriver: bridge
INFO[0000] Option DefaultNetwork: bridge
INFO[0000] Listening for HTTP on unix (/var/run/docker.sock)
INFO[0000] Firewall running: false
INFO[0000] Loading containers: start.
.....
INFO[0000] Loading containers: done.
INFO[0000] Daemon has completed initialization
INFO[0000] Docker daemon
commit=cedd534-dirty execdriver=native-0.2 graphdriver=overlay
version=1.8.3
```

The Flannel environment for the second host can also be checked by viewing `subnet.env`:

```
# cat /run/flannel/subnet.env
FLANNEL_NETWORK=10.1.0.0/16
FLANNEL_SUBNET=10.1.31.1/24
FLANNEL_MTU=1472
FLANNEL_IPMASQ=true
```

A different subnet is allocated to the second host. The Docker service can also be restarted in this host by pointing to the Flannel bridge:

```
# source /run/flannel/subnet.env
# sudo ifconfig docker0 ${FLANNEL_SUBNET}
# sudo docker -d --bip=${FLANNEL_SUBNET} --mtu=${FLANNEL_MTU} &
INFO[0000] [graphdriver] using prior storage driver "overlay"
INFO[0000] Listening for HTTP on unix (/var/run/docker.sock)
INFO[0000] Option DefaultDriver: bridge
INFO[0000] Option DefaultNetwork: bridge
INFO[0000] Firewall running: false
INFO[0000] Loading containers: start.
....
INFO[0000] Loading containers: done.
INFO[0000] Daemon has completed initialization
INFO[0000] Docker daemon
commit=cedd534-dirty execdriver=native-0.2 graphdriver=overlay
version=1.8.3
```

Docker containers can be created in their respective hosts, and they can be tested using the `ping` command in order to check the Flannel overlay network connectivity.

For Host 1, use the following commands:

```
#docker run -it ubuntu /bin/bash
INFO[0013] POST /v1.20/containers/create
INFO[0013] POST
/v1.20/containers/1d1582111801c8788695910e57c02fdb593f443c15e2f
1db9174ed9078db809/attach?stderr=1&stdin=1&stdout=1&stream=1
INFO[0013] POST
/v1.20/containers/1d1582111801c8788695910e57c02fdb593f443c15e2f
1db9174ed9078db809/start
```

```
INFO[0013] POST
/v1.20/containers/1d1582111801c8788695910e57c02fdb593f443c15e2f
1db9174ed9078db809/resize?h=44&w=80
```

```
root@1d1582111801:/# ifconfig
eth0      Link encap:Ethernet  HWaddr 02:42:0a:01:1e:02
          inet addr:10.1.30.2  Bcast:0.0.0.0  Mask:255.255.255.0
          inet6 addr: fe80::42:aff:fe01:1e02/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1472  Metric:1
          RX packets:11 errors:0 dropped:0 overruns:0 frame:0
          TX packets:6 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:969 (969.0 B)  TX bytes:508 (508.0 B)

lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          inet6 addr: ::1/128 Scope:Host
          UP LOOPBACK RUNNING  MTU:65536  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
```

For Host 2, use the following commands:

```
# docker run -it ubuntu /bin/bash
root@ed070166624a:/# ifconfig
eth0      Link encap:Ethernet  HWaddr 02:42:0a:01:1f:02
          inet addr:10.1.31.2  Bcast:0.0.0.0  Mask:255.255.255.0
          inet6 addr: fe80::42:aff:fe01:1f02/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1472  Metric:1
          RX packets:18 errors:0 dropped:2 overruns:0 frame:0
          TX packets:7 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:1544 (1.5 KB)  TX bytes:598 (598.0 B)
```

```
lo          Link encap:Local Loopback
            inet addr:127.0.0.1  Mask:255.0.0.0
            inet6 addr: ::1/128 Scope:Host
            UP LOOPBACK RUNNING  MTU:65536  Metric:1
            RX packets:0 errors:0 dropped:0 overruns:0 frame:0
            TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
            collisions:0 txqueuelen:0
            RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)

root@ed070166624a:/# ping 10.1.30.2
PING 10.1.30.2 (10.1.30.2) 56(84) bytes of data.
64 bytes from 10.1.30.2: icmp_seq=1 ttl=60 time=3.61 ms
64 bytes from 10.1.30.2: icmp_seq=2 ttl=60 time=1.38 ms
64 bytes from 10.1.30.2: icmp_seq=3 ttl=60 time=0.695 ms
64 bytes from 10.1.30.2: icmp_seq=4 ttl=60 time=1.49 ms
```

Thus, in the preceding example, we can see the complexity that Flannel reduces by running the `flanneld` agent on each host, which is responsible for allocating a subnet lease out of preconfigured address space. Flannel internally uses `etcd` to store the network configuration and other details, such as host IP and allocated subnets. The forwarding of packets is achieved using the backend strategy.

Flannel also aims to resolve the problem of Kubernetes deployment on cloud providers other than GCE, where a Flannel overlay mesh network can ease the issue of assigning a unique IP address to each pod by creating a subnet for each server.

## Summary

In this chapter, we learnt how Docker containers communicate across multiple hosts using different networking options such as Weave, OVS, and Flannel. Pipework uses the legacy Linux bridge, Weave creates a virtual network, OVS uses GRE tunneling technology, and Flannel provides a separate subnet to each host in order to connect containers to multiple hosts. Some of the implementations, such as Pipework, are legacy and will become obsolete over a period of time, while others are designed to be used in the context of specific OSes, such as Flannel with CoreOS.

The following diagram shows a basic comparison of Docker networking options:

	Network Type
Weave	Virtual Overlay Network
Flannel	Creates separate Subnet
Open vSwitch	GRE Tunneling
Pipework	Legacy Linux Bridge

In the next chapter, we will discuss how Docker containers are networked when using frameworks such as Kubernetes, Docker Swarm, and Mesosphere.

# 4

## Networking in a Docker Cluster

In this chapter, you will learn how Docker containers are networked when using frameworks like Kubernetes, Docker Swarm, and Mesosphere.

We will cover the following topics:

- Docker Swarm
- Kubernetes
  - Networked containers in a Kubernetes cluster
  - How Kubernetes networking differs from Docker networking
  - Kubernetes on AWS
- Mesosphere

### Docker Swarm

Docker Swarm is a native clustering system for Docker. Docker Swarm exposes the standard Docker API so that any tool that communicates with the Docker daemon can communicate with Docker Swarm as well. The basic aim is to allow the creation and usage of a pool of Docker hosts together. The cluster manager of Swarm schedules the containers based on the availability resources in a cluster. We can also specify the constrained resources for a container while deploying it. Swarm is designed to pack containers onto a host by saving other host resources for heavier and bigger containers rather than scheduling them randomly to a host in the cluster.

Similar to other Docker projects, Docker Swarm uses a Plug and Play architecture. Docker Swarm provides backend services to maintain a list of IP addresses in your Swarm cluster. There are several services, such as etcd, Consul, and Zookeeper; even a static file can be used. Docker Hub also provides a hosted discovery service, which is used in the normal configuration of Docker Swarm.

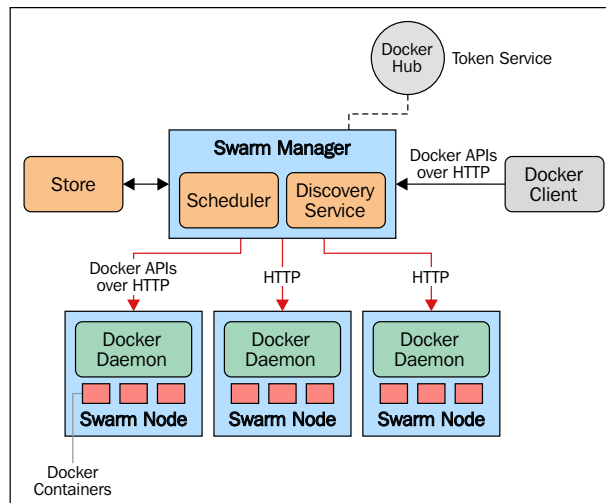
Docker Swarm scheduling uses multiple strategies in order to rank nodes. When a new container is created, Swarm places it on the node on the basis of the highest computed rank, using the following strategies:

1. **Spread:** This optimizes and schedules the containers on the nodes based on the number of containers running on the node at that point of time
2. **Binpack:** The node is selected to schedule the container on the basis of CPU and RAM utilization
3. **Random strategy:** This uses no computation; it selects the node randomly to schedule containers

Docker Swarm also uses filters in order to schedule containers, such as:

- **Constraints:** These use key/value pairs associated with nodes, such as `environment=production`
- **Affinity filter:** This is used to run a container and instruct it to locate and run next to another container based on the label, image, or identifier
- **Port filter:** In this case, the node is selected on the basis of the ports available on it
- **Dependency filter:** This co-schedules dependent containers on the same node
- **Health filter:** This prevents the scheduling of containers on unhealthy nodes

The following figure explains various components of a Docker Swarm cluster:



## Docker Swarm setup

Let's set up our Docker Swarm setup, which will have two nodes and one master.

We will be using a Docker client in order to access the Docker Swarm cluster. A Docker client can be set up on a machine or laptop and should have access to all the machines present in the Swarm cluster.

After installing Docker on all three machines, we will restart the Docker service from a command line so that it can be accessed from TCP port 2375 on the localhost (0.0.0.0:2375) or from a specific host IP address and can allow connections using a Unix socket on all the Swarm nodes, as follows:

```
$ docker -H tcp://0.0.0.0:2375 -H unix:///var/run/docker.sock -d &
```

Docker Swarm images are required to be deployed as Docker containers on the master node. In our example, the master node's IP address is 192.168.59.134. Replace it with your Swarm's master node. From the Docker client machine, we will be installing Docker Swarm on the master node using the following command:

```
$ sudo docker -H tcp://192.168.59.134:2375 run --rm swarm create
```

```
Unable to find image 'swarm' locally
```

```
Pulling repository swarm
```

```
e12f8c5e4c3b: Download complete
```

```
cf43a42a05d1: Download complete
```

```
42c4e5c90ee9: Download complete
```

```
22cf18566d05: Download complete
```

```
048068586dc5: Download complete
```

```
2ea96b3590d8: Download complete
```

```
12a239a7cb01: Download complete
```

```
26b910067c5f: Download complete
```

```
4fdfeb28bd618291eeb97a2096b3f841
```

The Swarm token generated after the execution of the command should be noted, as it will be used for the Swarm setup. In our case, it is this:

```
"4fdfeb28bd618291eeb97a2096b3f841"
```



The following are the steps to set up a two-node Docker Swarm cluster:

1. From the Docker client node, the following `docker` command is required to be executed with Node 1's IP address (in our case, 192.168.59.135) and the Swarm token generated in the preceding code in order to add it to the Swarm cluster:

```
$ docker -H tcp://192.168.59.135:2375 run -d swarm join --
addr=192.168.59.135:2375 token://
4fdfeb28bd618291eeb97a2096b3f841
Unable to find image 'swarm' locally
Pulling repository swarm
e12f8c5e4c3b: Download complete
cf43a42a05d1: Download complete
42c4e5c90ee9: Download complete
22cf18566d05: Download complete
048068586dc5: Download complete
2ea96b3590d8: Download complete
12a239a7cb01: Download complete
26b910067c5f: Download complete
e4f268b2cc4d896431dacdafdc1bb56c98fed01f58f8154ba13908c7e6fe67
5b
```

2. Repeat the preceding steps for Node 2 by replacing Node 1's IP address with Node 2's.
3. Swarm manager is required to be set up on the master node using the following command on the Docker client node:

```
$ sudo docker -H tcp://192.168.59.134:2375 run -d -p 5001:2375
swarm manage token:// 4fdfeb28bd618291eeb97a2096b3f841
f06ce375758f415614dc5c6f71d5d87cf8edecffc6846cd978fe07fafc3d05
d3
```

The Swarm cluster is set up and can be managed using the Swarm manager residing on the master node. To list all the nodes, the following command can be executed using a Docker client:

```
$ sudo docker -H tcp://192.168.59.134:2375 run --rm swarm list
\ token:// 4fdfeb28bd618291eeb97a2096b3f841
192.168.59.135:2375
192.168.59.136:2375
```

4. The following command can be used to get information about the cluster:

```
$ sudo docker -H tcp://192.168.59.134:5001 info
Containers: 0
Strategy: spread
Filters: affinity, health, constraint, port, dependency
Nodes: 2
agent-1: 192.168.59.136:2375
  L Containers: 0
  L Reserved CPUs: 0 / 8
  L Reserved Memory: 0 B / 1.023 GiB
agent-0: 192.168.59.135:2375
  L Containers: 0
  L Reserved CPUs: 0 / 8
  L Reserved Memory: 0 B / 1.023 GiB
```

5. The test `ubuntu` container can be launched onto the cluster by specifying the name as `swarm-ubuntu` and using the following command:

```
$ sudo docker -H tcp://192.168.59.134:5001 run -it --name
swarm-ubuntu ubuntu /bin/sh
```

6. The container can be listed using the Swarm master's IP address:

```
$ sudo docker -H tcp://192.168.59.134:5001 ps
```

This completes the setup of a two-node Docker Swarm cluster.

## Docker Swarm networking

Docker Swarm networking has integration with `libnetwork` and even provides support for overlay networks. `libnetwork` provides a Go implementation to connect containers; it is a robust container network model that provides network abstraction for applications and the programming interface of containers. Docker Swarm is now fully compatible with the new networking model in Docker 1.9 (note that we will be using Docker 1.9 in the following setup). The key-value store is required for overlay networks, which includes discovery, networks, IP addresses, and more information.

In the following example, we will be using Consul to understand Docker Swarm networking in a better way:

1. We will provision a VirtualBox machine called `sample-keystore` using `docker-machine`:

```
$ docker-machine create -d virtualbox sample-keystore
Running pre-create checks...
Creating machine...
Waiting for machine to be running, this may take a few
minutes...
Machine is running, waiting for SSH to be available...
Detecting operating system of created instance...
Provisioning created instance...
Copying certs to the local machine directory...
Copying certs to the remote machine...
Setting Docker configuration on the remote daemon...
To see how to connect Docker to this machine, run: docker-
machine.exe env sample-keystore
```

2. We will also deploy the `progrium/consul` container on the `sample-keystore` machine on port 8500 with the following command:

```
$ docker $(docker-machine config sample-keystore) run -d \
    -p "8500:8500" \
    -h "consul" \
    progrium/consul -server -bootstrap
Unable to find image 'progrium/consul:latest' locally
latest: Pulling from progrium/consul
3b4d28ce80e4: Pull complete
e5ab901dcf2d: Pull complete
30ad296c0ea0: Pull complete
3dba40dec256: Pull complete
f2ef4387b95e: Pull complete
53bc8dcc4791: Pull complete
75ed0b50ba1d: Pull complete
17c3a7ed5521: Pull complete
8aca9e0ecf68: Pull complete
4d1828359d36: Pull complete
46ed7df7f742: Pull complete
```

```

b5e8ce623ef8: Pull complete
049dca6ef253: Pull complete
bdb608bc4555: Pull complete
8b3d489cfb73: Pull complete
c74500bbce24: Pull complete
9f3e605442f6: Pull complete
d9125e9e799b: Pull complete

Digest:
sha256:8cc8023462905929df9a79ff67ee435a36848ce7a10f18d6d0faba9
306b97274

Status: Downloaded newer image for progridium/consul:latest
1a1be5d207454a54137586f1211c02227215644fa0e36151b000cfcde3b0df
7c

```

3. Set the local environment to the `sample-keystore` machine:

```
$ eval "$(docker-machine env sample-keystore)"
```

4. We can list the consul container as follows:

```
$ docker ps
```

CONTAINER ID	IMAGE	COMMAND	CREATED
STATUS	PORTS	NAMES	
1a1be5d20745	progridium/consul	/bin/start -server	5 minutes ago
Up 5 minutes	53/tcp, 53/udp, 8300-8302/tcp, 8400/tcp, 8301-8302/udp, 0.0.0.0:8500->8500/tcp	cocky_bhaskara	

5. Create a Swarm cluster using `docker-machine`. The two machines can be created in VirtualBox; one can act as the Swarm master. As we create each Swarm node, we will be passing the options required for Docker Engine to have an overlay network driver:

```

$ docker-machine create -d virtualbox --swarm --swarm-
image="swarm" --swarm-master --swarm-
discovery="consul://$(docker-machine ip sample-keystore):8500"
--engine-opt="cluster-store=consul://$(docker-machine ip
sample-keystore):8500" --engine-opt="cluster-
advertise=eth1:2376" swarm-master

Running pre-create checks...

Creating machine...

Waiting for machine to be running, this may take a few
minutes...

Machine is running, waiting for SSH to be available...

```

```
Detecting operating system of created instance...
Provisioning created instance...
Copying certs to the local machine directory...
Copying certs to the remote machine...
Setting Docker configuration on the remote daemon...
Configuring swarm...
To see how to connect Docker to this machine, run: docker-
machine env swarm-master
```

The use of the parameters used in the preceding command is as follows:

- `--swarm`: This is used to configure a machine with Swarm.
- `--engine-opt`: This option is used to define arbitrary daemon options required to be supplied. In our case, we will supply the engine daemon with the `--cluster-store` option during creation time, which tells the engine the location of the key-value store for the overlay network usability. The `--cluster-advertise` option will put the machine on the network at the specific port.
- `--swarm-discovery`: It is used to discover services to use with Swarm, in our case, consul will be that service.
- `--swarm-master`: This is used to configure a machine as the Swarm master.

6. Another host can also be created and added to Swarm cluster, like this:

```
$ docker-machine create -d virtualbox --swarm --swarm-
image="swarm:1.0.0-rc2" --swarm-discovery="consul://$(docker-
machine ip sample-keystore):8500" --engine-opt="cluster-
store=consul://$(docker-machine ip sample-keystore):8500" --
engine-opt="cluster-advertise=eth1:2376" swarm-node-1
Running pre-create checks...
Creating machine...
Waiting for machine to be running, this may take a few
minutes...
Machine is running, waiting for SSH to be available...
Detecting operating system of created instance...
Provisioning created instance...
Copying certs to the local machine directory...
Copying certs to the remote machine...
Setting Docker configuration on the remote daemon...
Configuring swarm...
To see how to connect Docker to this machine, run: docker-
machine env swarm-node-1
```

7. The machines can be listed as follows:

```
$ docker-machine ls
```

NAME	ACTIVE	DRIVER	STATE	URL
SWARM				
sample-keystore	-	virtualbox	Running	tcp://192.168.99.100:2376
swarm-master	-	virtualbox	Running	tcp://192.168.99.101:2376 swarm-master (master)
swarm-node-1	-	virtualbox	Running	tcp://192.168.99.102:2376 swarm-master

8. Now, we will set the Docker environment to swarm-master:

```
$ eval $(docker-machine env --swarm swarm-master)
```

9. The following command can be executed on the master in order to create the overlay network and have multihost networking:

```
$ docker network create --driver overlay sample-net
```

10. The network bridge can be checked on the master using the following command:

```
$ docker network ls
```

NETWORK ID	NAME	DRIVER
9f904ee27bf5	sample-net	overlay
7fca4eb8c647	bridge	bridge
b4234109be9b	none	null
cf03ee007fb4	host	host

11. When switching to a Swarm node, we can easily list the newly created overlay network, like this:

```
$ eval $(docker-machine env swarm-node-1)
$ docker network ls
```

NETWORK ID	NAME	DRIVER
7fca4eb8c647	bridge	bridge
b4234109be9b	none	null
cf03ee007fb4	host	host
9f904ee27bf5	sample-net	overlay

12. Once the network is created, we can start the container on any of the hosts, and it will be part of the network:

```
$ eval $(docker-machine env swarm-master)
```

13. Start the sample `ubuntu` container with the `constraint` environment set to the first node:

```
$ docker run -itd --name=os --net=sample-net --  
env="constraint:node==swarm-master" ubuntu
```

14. We can check using the `ifconfig` command that the container has two network interfaces, and it will be accessible from the container deployed using Swarm manager on any other host.

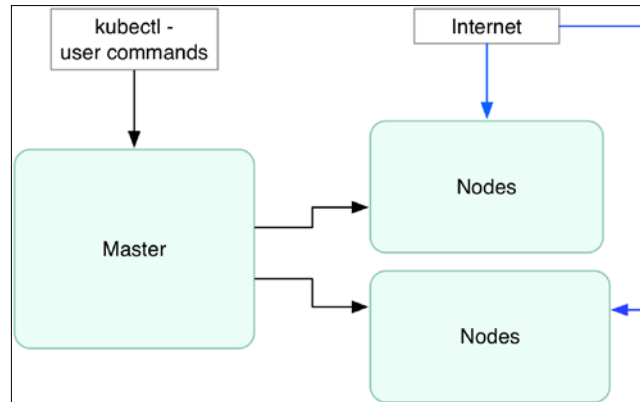
## Kubernetes

Kubernetes is a container cluster management tool. Currently, it supports Docker and Rocket. It is an open source project supported by Google, and the project was launched in June 2014 at Google I/O. It supports deployment on various cloud providers such as GCE, Azure, AWS, and vSphere as well as on bare metal. The Kubernetes manager is lean, portable, extensible, and self-healing.

Kubernetes has various important components, as explained in the following list:

- **Node:** This is a physical or virtual-machine part of a Kubernetes cluster, running the Kubernetes and Docker services, onto which pods can be scheduled.
- **Master:** This maintains the runtime state of the Kubernetes server runtime. It is the point of entry for all the client calls to configure and manage Kubernetes components.
- **Kubectl:** This is the command-line tool used to interact with the Kubernetes cluster to provide master access to Kubernetes APIs. Through it, the user can deploy, delete, and list pods.
- **Pod:** This is the smallest scheduling unit in Kubernetes. It is a collection of Docker containers that share volumes and don't have port conflicts. It can be created by defining a simple JSON file.
- **Replication controller:** It manages the lifecycle of a pod and ensures that a specified number of pods are running at a given time by creating or killing pods as required.
- **Label:** Labels are used to identify and organize pods and services based on key-value pairs.

The following diagram shows the Kubernetes Master/Minion flow:



## Deploying Kubernetes on AWS

Let's get started with Kubernetes cluster deployment on AWS, which can be done by using the config file that already exists in the Kubernetes codebase:

1. Log in to AWS Console at <http://aws.amazon.com/console/>.
2. Open the IAM console at <https://console.aws.amazon.com/iam/home?#home>.
3. Choose the IAM username, select the **Security Credentials** tab, and click on the **Create Access Key** option.
4. After the keys have been created, download and keep them in a secure place. The downloaded `.csv` file will contain an `Access Key ID` and `Secret Access Key`, which will be used to configure the AWS CLI.
5. Install and configure the AWS CLI. In this example, we have installed AWS CLI on Linux using the following command:

```
$ sudo pip install awscli
```



6. In order to configure the AWS CLI, use the following command:

```
$ aws configure
AWS Access Key ID [None]: XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX
AWS Secret Access Key [None]: YYYYYYYYYYYYYYYYYYYYYYYYYYYYYY
Default region name [None]: us-east-1
Default output format [None]: text
```

7. After configuring the AWS CLI, we will create a profile and attach a role to it with full access to S3 and EC2:

```
$ aws iam create-instance-profile --instance-profile-name Kube
```

8. The role can be created separately using the console or AWS CLI with a JSON file that defines the permissions the role can have:

```
$ aws iam create-role --role-name Test-Role --assume-role-policy-document /root/kubernetes/Test-Role-Trust-Policy.json
```

A role can be attached to the preceding profile, which will have complete access to EC2 and S3, as shown in the following screenshot:



9. After the creation of the role, it can be attached to a policy using the following command:

```
$ aws iam add-role-to-instance-profile --role-name Test-Role --instance-profile-name Kube
```

10. By default, the script uses the default profile. We can change it as follows:

```
$ export AWS_DEFAULT_PROFILE=Kube
```

11. The Kubernetes cluster can be easily deployed using one command, as follows:

```
$ export KUBERNETES_PROVIDER=aws; wget -q -O -
https://get.k8s.io | bash

Downloading kubernetes release v1.1.1 to
/home/vkohli/kubernetes.tar.gz

--2015-11-22 10:39:18--
https://storage.googleapis.com/kubernetes-
release/release/v1.1.1/kubernetes.tar.gz

Resolving storage.googleapis.com (storage.googleapis.com)...
216.58.220.48, 2404:6800:4007:805::2010

Connecting to storage.googleapis.com
(storage.googleapis.com)|216.58.220.48|:443... connected.
HTTP request sent, awaiting response... 200 OK
Length: 191385739 (183M) [application/x-tar]
Saving to: 'kubernetes.tar.gz'

100%[=====>] 191,385,739
1002KB/s in 3m 7s

2015-11-22 10:42:25 (1002 KB/s) - 'kubernetes.tar.gz' saved
[191385739/191385739]

Unpacking kubernetes release v1.1.1
Creating a kubernetes on aws...
... Starting cluster using provider: aws
... calling verify-prereqs
... calling kube-up

Starting cluster using os distro: vivid

Uploading to Amazon S3
Creating kubernetes-staging-e458a611546dc9dc0f2a2ff2322e724a
make_bucket: s3://kubernetes-staging-
e458a611546dc9dc0f2a2ff2322e724a/

+++ Staging server tars to S3 Storage: kubernetes-staging-
e458a611546dc9dc0f2a2ff2322e724a/devel

upload: ../../tmp/kubernetes.6B8Fmm/s3/kubernetes-
salt.tar.gz to s3://kubernetes-staging-
e458a611546dc9dc0f2a2ff2322e724a/devel/kubernetes-salt.tar.gz

Completed 1 of 19 part(s) with 1 file(s) remaining
```

12. The preceding command will call `kube-up.sh` and, in turn, `utils.sh` using the `config-default.sh` script, which contains the basic configuration of a K8S cluster with four nodes, as follows:

```
ZONE=${KUBE_AWS_ZONE:-us-west-2a}
MASTER_SIZE=${MASTER_SIZE:-t2.micro}
MINION_SIZE=${MINION_SIZE:-t2.micro}
NUM_MINIONS=${NUM_MINIONS:-4}
AWS_S3_REGION=${AWS_S3_REGION:-us-east-1}
```

13. The instances are `t2.micro` running Ubuntu OS. The process takes 5 to 10 minutes, after which the IP addresses of the master and minions get listed and can be used to access the Kubernetes cluster.

## Kubernetes networking and its differences to Docker networking

Kubernetes strays from the default Docker system's networking model. The objective is for each pod to have an IP at a level imparted by the system's administration namespace, which has full correspondence with other physical machines and containers over the system. Allocating IPs per pod unit makes for a clean, retrogressive, and good model where units can be dealt with much like VMs or physical hosts from the point of view of port allotment, system administration, naming, administration disclosure, burden adjustment, application design, and movement of pods from one host to another. All containers in all pods can converse with all other containers in all other pods using their addresses. This also helps move traditional applications to a container-oriented approach.

As every pod gets a real IP address, they can communicate with each other without any need for translation. By making the same configuration of IP addresses and ports both inside as well as outside of the pod, we can create a NAT-less flat address space. This is different from the standard Docker model since there, all containers have a private IP address, which will allow them to be able to access the containers on the same host. But in the case of Kubernetes, all the containers inside a pod behave as if they are on the same host and can reach each other's ports on the localhost. This reduces the isolation between containers and provides simplicity, security, and performance. Port conflict can be one of the disadvantages of this; thus, two different containers inside one pod cannot use the same port.

In GCE, using IP forwarding and advanced routing rules, each VM in a Kubernetes cluster gets an extra 256 IP addresses in order to route traffic across pods easily.

Routes in GCE allow you to implement more advanced networking functions in the VMs, such as setting up many-to-one NAT. This is leveraged by Kubernetes.

This is in addition to the main Ethernet bridge which the VM has; this bridge is termed as the container bridge `cbr0` in order to differentiate it from the Docker bridge, `docker0`. In order to transfer packets out of the GCE environment from a pod, it should undergo an SNAT to the VM's IP address, which GCE recognizes and allows.

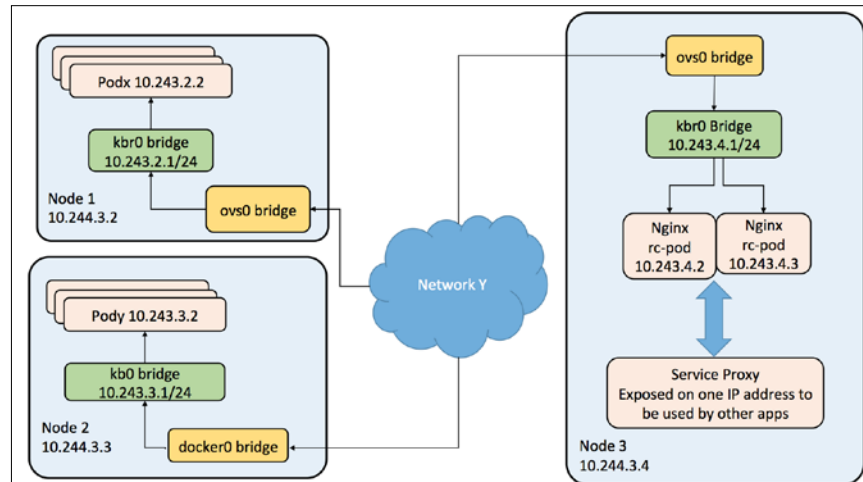
Other implementations with the primary aim of providing an IP-per-pod model are Open vSwitch, Flannel, and Weave.

In the case of a GCE-like setup of an Open vSwitch bridge for Kubernetes, the model where the Docker bridge gets replaced by `kbr0` to provide an extra 256 subnet addresses is followed. Also, an OVS bridge (`ovs0`) is added, which adds a port to the Kubernetes bridge in order to provide GRE tunnels to transfer packets across different minions and connect pods residing on these hosts. The IP-per-pod model is also elaborated more in the upcoming diagram, where the service abstraction concept of Kubernetes is also explained.

A service is another type of abstraction that is widely used and suggested for use in Kubernetes clusters as it allows a group of pods (applications) to be accessed via virtual IP addresses and gets proxied to all internal pods in a service. An application deployed in Kubernetes could be using three replicas of the same pod, which have different IP addresses. However, the client can still access the application on the one IP address which is exposed outside, irrespective of which backend pod takes the request. A service acts as a load balancer between different replica pods and a single point of communication for clients utilizing this application. Kubeproxy, one of the services of Kubernetes, provides load balancing and uses rules to access the service IPs and redirects them to the correct backend pod.

## Deploying the Kubernetes pod

Now, in the following example, we will be deploying two nginx replication pods (rc-pod) and exposing them via a service in order to understand Kubernetes networking. Deciding where the application can be exposed via a virtual IP address and which replica of the pod (load balancer) the request is to be proxied to is taken care of by **Service Proxy**. Please refer to the following diagram for more details:



The following are the steps to deploy the Kubernetes pod:

1. In the Kubernetes master, create a new folder:  

```
$ mkdir nginx_kube_example  
$ cd nginx_kube_example
```
2. In the editor of your choice, create the .yaml file that will be used to deploy the nginx pods:  

```
$ vi nginx_pod.yaml
```

Copy the following into the file:

```
apiVersion: v1  
kind: ReplicationController  
metadata:  
  name: nginx  
spec:  
  replicas: 2
```

```

selector:
  app: nginx
template:
  metadata:
    name: nginx
    labels:
      app: nginx
  spec:
    containers:
    - name: nginx
      image: nginx
      ports:
      - containerPort: 80

```

3. Create the nginx pod using `kubectl`:  
`$ kubectl create -f nginx_pod.yaml`
4. In the preceding pod creation process, we created two replicas of the nginx pod, and its details can be listed using the following command:  
`$ kubectl get pods`

The following is the output generated:

NAME	READY	REASON	RESTARTS	AGE
nginx-karne	1/1	Running	0	14s
nginx-mo5ug	1/1	Running	0	14s

To list replication controllers on a cluster, use the `kubectl get` command:

```
$ kubectl get rc
```

The following is the output generated:

CONTROLLER	CONTAINER(S)	IMAGE(S)	SELECTOR	REPLICAS
nginx	nginx	nginx	app=nginx	2

5. The container on the deployed minion can be listed using the following command:  
`$ docker ps`

The following is the output generated:

CONTAINER ID	IMAGE	COMMAND
CREATED	STATUS	NAMES

```
1d3f9cedff1d      nginx:latest      "nginx"
-g 'daemon of 41 seconds ago      Up 40 seconds
      k8s_nginx.6171169d_nginx-karne_default
_5d5bc813-3166-11e5-8256-ecf4bb2bbd90_886ddf56
0b2b03b05a8d      nginx:latest
"nginx -g 'daemon of 41 seconds ago      Up 40 seconds
```

6. Deploy the nginx service using the following .yaml file in order to expose the nginx pod on host port 82:

```
$ vi nginx_service.yaml
```

Copy the following into the file:

```
apiVersion: v1
kind: Service
metadata:
  labels:
    name: nginxservice
  name: nginxservice
spec:
  ports:
    # The port that this service should serve on.
    - port: 82
    # Label keys and values that must match in order to receive
    traffic for this service.
  selector:
    app: nginx
  type: LoadBalancer
```

7. Create the nginx service using the `kubectl create` command:

```
$ kubectl create -f nginx_service.yaml
services/nginxservice
```

8. The nginx service can be listed using the following command:

```
$ kubectl get services
```

The following is the output generated:

NAME	LABELS	
SELECTOR	IP(S)	PORT(S)
kubernetes	component=apiserver,provider=kubernetes	
<none>	192.168.3.1	443/TCP
nginxservice	name=nginxservice	
app=nginx	192.168.3.43	82/TCP

9. Now, the nginx server's test page can be accessed on the following URL via the service:

```
http://192.168.3.43:82
```

## Mesosphere

Mesosphere is a software solution that provides ways of managing server infrastructures and basically expands upon the cluster-management capabilities of Apache Mesos. Mesosphere has also launched the **DCOS (data center operating system)**, used to manage data centers by spanning all the machines and treating them as a single computer, providing a highly scalable and elastic way of deploying apps on top of it. DCOS can be installed on any public cloud or your own private data center, ranging from AWS, GCE, and Microsoft Azure to VMware. Marathon is the framework for Mesos and is designed to launch and run applications; it serves as a replacement for the init system. Marathon provides various features such as high availability, application health check, and service discovery, which help you run applications in Mesos clustered environments.

This session describes how to bring up a single-node Mesos cluster.

## Docker containers

Mesos can run and manage Docker containers using the Marathon framework.

In this exercise, we will use CentOS 7 to deploy a Mesos cluster:

1. Install Mesosphere and Marathon using the following command:

```
# sudo rpm -Uvh
http://repos.mesosphere.com/el/7/noarch/RPMS/mesosphere-el-
repo-7-1.noarch.rpm
# sudo yum -y install mesos marathon
```

Apache Mesos uses Zookeeper to operate. Zookeeper acts as the master election service in the Mesosphere architecture and stores states for the Mesos nodes.

2. Install Zookeeper and the Zookeeper server package by pointing to the RPM repository for Zookeeper, as follows:

```
# sudo rpm -Uvh http://archive.cloudera.com/cdh4/one-click-
install/redhat/6/x86_64/cloudera-cdh-4-0.x86_64.rpm
# sudo yum -y install zookeeper zookeeper-server
```



3. Validate Zookeeper by stopping and restarting it:

```
# sudo service zookeeper-server stop
# sudo service zookeeper-server start
```

Mesos uses a simple architecture to give you intelligent task distribution across a cluster of machines without worrying about where they are scheduled.

4. Configure Apache Mesos by starting the `mesos-master` and `mesos-slave` processes as follows:

```
# sudo service mesos-master start
# sudo service mesos-slave start
```

5. Mesos will be running on port 5050. As shown in the following screenshot, you can access the Mesos interface with your machine's IP address, here, `http://192.168.10.10:5050`:

The screenshot displays the Mesos web interface. On the left, a sidebar shows cluster details: 'Cluster: (Unnamed)', 'Server: 30.30.30.16:5050', 'Version: 0.25.0', 'Built: a month ago by root', 'Started: 3 days ago', and 'Elected: 3 hours ago'. Below this are links for 'LOG', 'Slaves' (1 Activated, 0 Deactivated), and 'Tasks' (0 Staged, 0 Started, 58 Finished). The main area is divided into 'Active Tasks' and 'Completed Tasks'. 'Active Tasks' shows two tasks: 'ubuntu.95e86cb5-927e-11e5-b488-0242e86e9ff6' in STAGING state and 'outyet.b30d6c3c-926d-11e5-b488-0242e86e9ff6' in RUNNING state. 'Completed Tasks' shows three finished tasks, all in FINISHED state, with their respective start and stop times.

ID	Name	State	Started	Host
ubuntu.95e86cb5-927e-11e5-b488-0242e86e9ff6	ubuntu	STAGING		centos7.novalocal
outyet.b30d6c3c-926d-11e5-b488-0242e86e9ff6	outyet	RUNNING	2 hours ago	centos7.novalocal

ID	Name	State	Started	Stopped	Host
ubuntu.53b196a4-927e-11e5-b488-0242e86e9ff6	ubuntu	FINISHED	2 minutes ago	a minute ago	centos7.novalocal
ubuntu.054e4c13-927e-11e5-b488-0242e86e9ff6	ubuntu	FINISHED	3 minutes ago	3 minutes ago	centos7.novalocal
ubuntu.b1364832-927d-11e5-b488-0242e86e9ff6	ubuntu	FINISHED	6 minutes ago	6 minutes ago	centos7.novalocal

6. Test Mesos using the `mesos-execute` command:

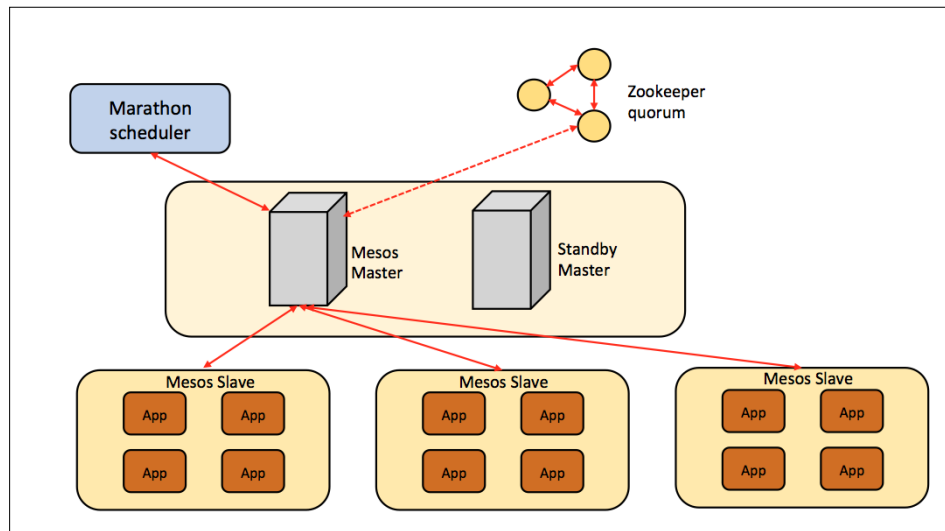
```
# export MASTER=$(mesos-resolve `cat /etc/mesos/zk`
2>/dev/null)
# mesos help
# mesos-execute --master=$MASTER --name="cluster-test" --
command="sleep 40"
```

7. With the `mesos-execute` command running, enter `Ctrl + Z` to suspend the command. You can see how it appears in the web UI and command line:

```
# hit ctrl-z
```

```
# mesos ps --master=$MASTER
```

The Mesosphere stack uses Marathon to manage processes and services. It serves as a replacement for the traditional `init` system. It simplifies the running of applications in a clustered environment. The following figure shows the Mesosphere Master slave topology with Marathon:



Marathon can be used to start other Mesos frameworks; as it is designed for long-running applications, it will ensure that the applications it has launched will continue running even if the slave nodes they are running on fail.

8. Start the Marathon service using the following command:

```
# sudo service marathon start
```

You can view the Marathon GUI at <http://192.168.10.10:8080>.

## Deploying a web app using Docker

In this exercise, we will install a simple Outyet web application:

1. Install Docker using the following commands:

```
# sudo yum install -y golang git device-mapper-event-libs
docker
# sudo chkconfig docker on
# sudo service docker start
# export GOPATH=~/go
# go get github.com/golang/example/outyet
# cd $GOPATH/src/github.com/golang/example/outyet
# sudo docker build -t outyet.
```

2. The following command tests the Docker file before adding it to Marathon:

```
# sudo docker run --publish 6060:8080 --name test --rm outyet
```

3. Go to <http://192.168.10.10:6060/> on your browser in order to confirm it works. Once it does, you can hit *CTRL + C* to exit the Outyet Docker.

4. Create a Marathon application using Marathon Docker support, as follows:

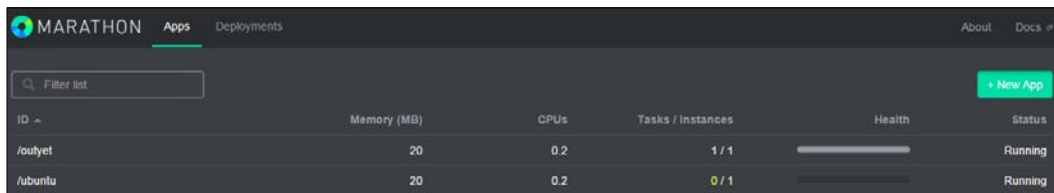
```
# vi /home/user/outyet.json
{
  "id": "outyet",
  "cpus": 0.2,
  "mem": 20.0,
  "instances": 1,
  "constraints": [["hostname", "UNIQUE", ""]],
  "container": {
    "type": "DOCKER",
    "docker": {
      "image": "outyet",
      "network": "BRIDGE",
      "portMappings": [ { "containerPort": 8080,
        "hostPort": 0, "servicePort": 0, "protocol": "tcp" }
      ]
    }
  }
}
```

```
# echo 'docker,mesos' | sudo tee /etc/mesos-slave/containerizers
# sudo service mesos-slave restart
```

- Containers are configured and managed better with Marathon Docker, as follows:

```
# curl -X POST http://192.168.10.10:8080/v2/apps -d
/home/user/outyet.json -H "Content-type: application/json"
```

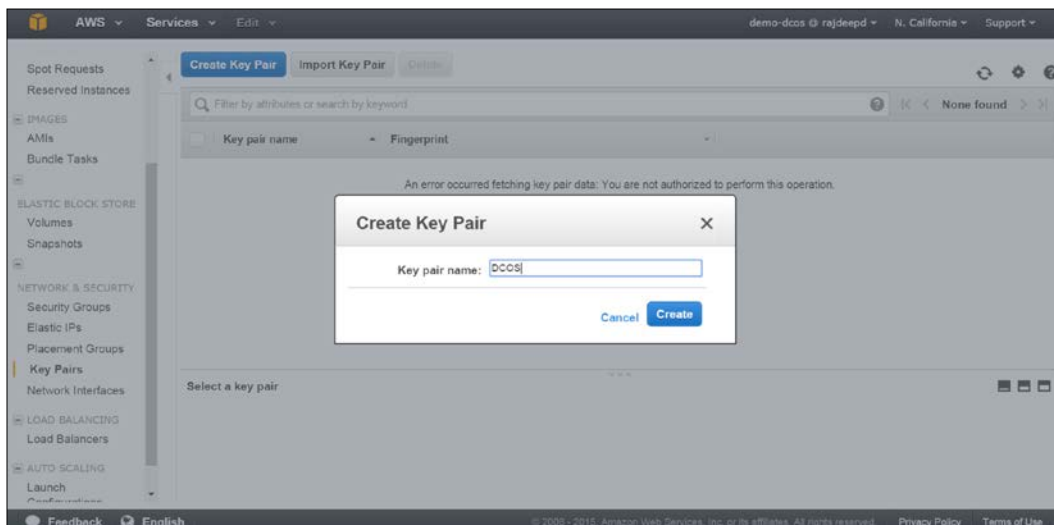
- You can check all your applications on the Marathon GUI at <http://192.168.10.10:8080>, as shown in the following screenshot:



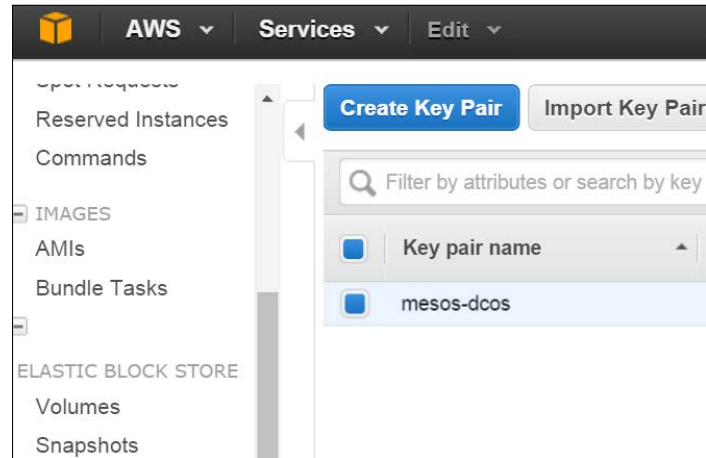
## Deploying Mesos on AWS using DCOS

In this final section, we will be deploying the latest launch of DCOS by Mesosphere on AWS in order to manage and deploy Docker services in our data center:

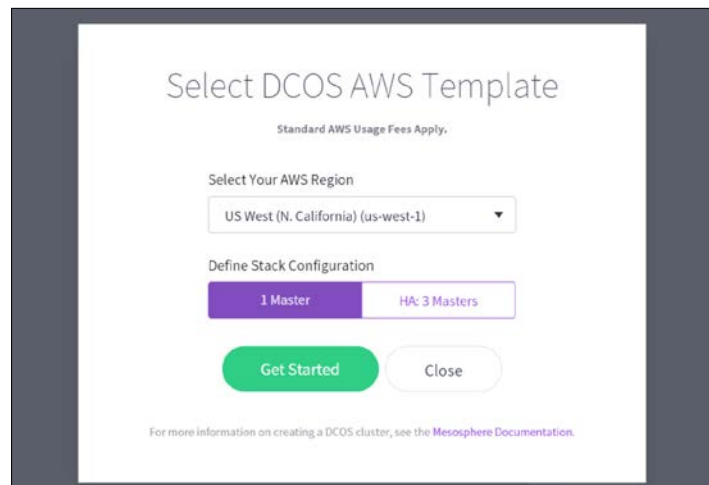
- Create an AWS key pair in the region where the cluster is required to be deployed by going to the navigation pane and choosing **Key Pairs** under **NETWORK & SECURITY**:



2. After being created, the key can be viewed as follows and the generated key pair (.pem) file should be stored in a secure location for future use:



3. The DCOS cluster can be created by selecting the **1 Master** template on the official Mesosphere site:



It can also be done by providing the link for the Amazon S3 template URL in the stack deployment:

The screenshot shows the 'Select Template' page in the AWS CloudFormation console. The left sidebar has 'Select Template' highlighted. The main area has a 'Select Template' heading and a description: 'Select the template that describes the stack that you want to create. A stack is a group of related resources that you manage as a single unit.' Below this are two sections: 'Design a template' with a 'Design template' button, and 'Choose a template' with three radio buttons. The third radio button, 'Specify an Amazon S3 template URL', is selected. Below it, the URL 'https://s3.amazonaws.com/downloads.mesosphere.io/docs/ist/' is entered in a text box. At the bottom right, there are 'Cancel' and 'Next' buttons.

- Click on the **Next** button. Fill in the details such as **Stack name** and **KeyName**, generated in the previous step:

The screenshot shows the 'Specify Details' page in the AWS CloudFormation console. The left sidebar has 'Specify Details' highlighted. The main area has a 'Specify Details' heading and a description: 'Specify a stack name and parameter values. You can use or change the default parameter values, which are defined in the AWS CloudFormation template. Learn more.' Below this is a 'Stack name' field with the value 'Mesos'. Under the 'Parameters' section, there are several fields: 'AcceptEULA' with a dropdown set to 'Yes', 'AdminLocation' with the value '0.0.0.0/0', 'KeyName' with the value 'mesos-dcos', 'PublicSlaveInstanceCount' with the value '1', and 'SlaveInstanceCount' with the value '5'.

- Review the details before clicking on the **Create** button:

The screenshot shows the 'Review' tab in the AWS CloudFormation console. On the left, there are navigation links: 'Select Template', 'Specify Details', 'Options', and 'Review' (which is highlighted). The main content area is titled 'Review' and contains two sections: 'Template' and 'Stack details'. The 'Template' section shows the 'Template URL' as <https://s3.amazonaws.com/downloads.mesosphere.io/dcos/stable/cloudformation/single-master.cloudformation.json>, the 'Description' as 'Launching the Mesosphere DCOS cluster', and the 'Estimate cost' as 'Cost'. The 'Stack details' section shows the 'Stack name' as 'Mesos', 'AcceptEULA' as 'Yes', 'AdminLocation' as '0.0.0.0', 'KeyName' as 'KeyName', 'PublicSlaveInstanceCount' as '1', 'SlaveInstanceCount' as '5', and 'Create IAM resources' as 'Yes'. At the bottom, there is a link for 'Options'.

- After 5 to 10 minutes, the Mesos stack will be deployed and the Mesos UI can be accessed at the URL shown in the following screenshot:

The screenshot shows the 'Outputs' tab in the AWS CloudFormation console for the 'Mesos-DCOS' stack. The stack is in the 'CREATE\_COMPLETE' status. The 'Outputs' table lists the following outputs:

Key	Value	Description
PublicSlaveDnsAddress	Mesos-DCO-PublicSI-1RECZNALUVA2i-342612872.us-west-1.elb.amazonaws.com	Public slaves
DnsAddress	Mesos-DCO-Elastic-17LQe4CH09R07-3358f61817.us-west-1.elb.amazonaws.com	Master

- Now, we will be installing the DCOS CLI on a Linux machine with Python (2.7 or 3.4) and pip preinstalled, using the following commands:

```
$ sudo pip install virtualenv
$ mkdir dcos
$ cd dcos
```

---

```

$ curl -O https://downloads.mesosphere.io/dcos-cli/install.sh
% Total    % Received % Xferd  Average Speed   Time    Time
Time  Current
                                Dload  Upload  Total  Spent
Left  Speed
100 3654 100 3654    0      0  3631      0  0:00:01  0:00:01
--:--:-- 3635

$ ls
install.sh

$ bash install.sh . http://mesos-dco-elastic1-171qe4oh09r07-
1358461817.us-west-1.elb.amazonaws.com
Installing DCOS CLI from PyPI...
New python executable in /home/vkohli/dcos/bin/python
Installing setuptools, pip, wheel...done.
[core.reporting]: set to 'True'
[core.dcos_url]: set to 'http://mesos-dco-elastic1-
171qe4oh09r07-1358461817.us-west-1.elb.amazonaws.com'
[core.ssl_verify]: set to 'false'
[core.timeout]: set to '5'
[package.cache]: set to '/home/vkohli/.dcos/cache'
[package.sources]: set to '[u'https://github.com/mesosphere/
universe/archive/version-1.x.zip']'
Go to the following link in your browser:
https://accounts.mesosphere.com/oauth/authorize?scope=&redirect_ur
i=urn%3Aietf%3Awg%3Aoauth%3A2.0%3Aacces&response_type=code&client_
id=6a552732-ab9b-410d-9b7d-d8c6523b09a1&access_type=offline
Enter verification code: Skipping authentication.
Enter email address: Skipping email input.
Updating source [https://github.com/mesosphere/universe/archive/
version-
1.x.zip]
Modify your bash profile to add DCOS to your PATH? [yes/no]
yes
Finished installing and configuring DCOS CLI.
Run this command to set up your environment and to get
started:
source ~/.bashrc && dcos help

```



The DCOS help file can be listed as follows:

```
$ source ~/.bashrc && dcos help
```

```
Command line utility for the Mesosphere Datacenter Operating
System (DCOS). The Mesosphere DCOS is a distributed operating
system built around Apache Mesos. This utility provides tools
for easy management of a DCOS installation.
```

Available DCOS commands:

config	Get and set DCOS CLI configuration properties
help	Display command line usage information
marathon	Deploy and manage applications on the DCOS
node	Manage DCOS nodes
package	Install and manage DCOS packages
service	Manage DCOS services
task	Manage DCOS tasks

8. Now, we will deploy a Spark application on top of the Mesos cluster using the DCOS package after updating it. Get a detailed command description with `dcos <command> --help`:

```
$ dcos config show package.sources
```

```
[
  "https://github.com/mesosphere/universe/archive/version-
  1.x.zip"
]
```

```
$ dcos package update
```

```
Updating source
```

```
[https://github.com/mesosphere/universe/archive/version-
1.x.zip]
```

```
$ dcos package search
```

NAME	VERSION	FRAMEWORK	SOURCE	DESCRIPTION
arangodb	0.2.1	True	https://github.com/mesosphere/universe/archive/version-1.x.zip	A distributed free and open-source database with a flexible data model for documents, graphs, and key-values. Build high performance applications using a convenient SQL-like query language or JavaScript extensions.

```

cassandra 0.2.0-1 True
https://github.com/mesosphere/universe/archive/version-1.x.zip
Apache Cassandra running on Apache Mesos.

chronos 2.4.0 True
https://github.com/mesosphere/universe/archive/version-1.x.zip
A fault tolerant job scheduler for Mesos which handles
dependencies and ISO8601 based schedules.

hdfs 0.1.7 True
https://github.com/mesosphere/universe/archive/version-1.x.zip
Hadoop Distributed File System (HDFS), Highly Available.

kafka 0.9.2.0 True
https://github.com/mesosphere/universe/archive/version-1.x.zip
Apache Kafka running on top of Apache Mesos.

marathon 0.11.1 True
https://github.com/mesosphere/universe/archive/version-1.x.zip
A cluster-wide init and control system for services in cgroups
or Docker containers.

spark 1.5.0-multi-roles-v2 True
https://github.com/mesosphere/universe/archive/version-1.x.zip
Spark is a fast and general cluster computing system for Big
Data.

```

9. The Spark package can be installed as follows:

```
$ dcos package install spark
```

Note that the Apache Spark DCOS Service is beta and there may be bugs, incomplete features, incorrect documentation or other discrepancies.

We recommend a minimum of two nodes with at least 2 CPU and 2GB of RAM available for the Spark Service and running a Spark job.

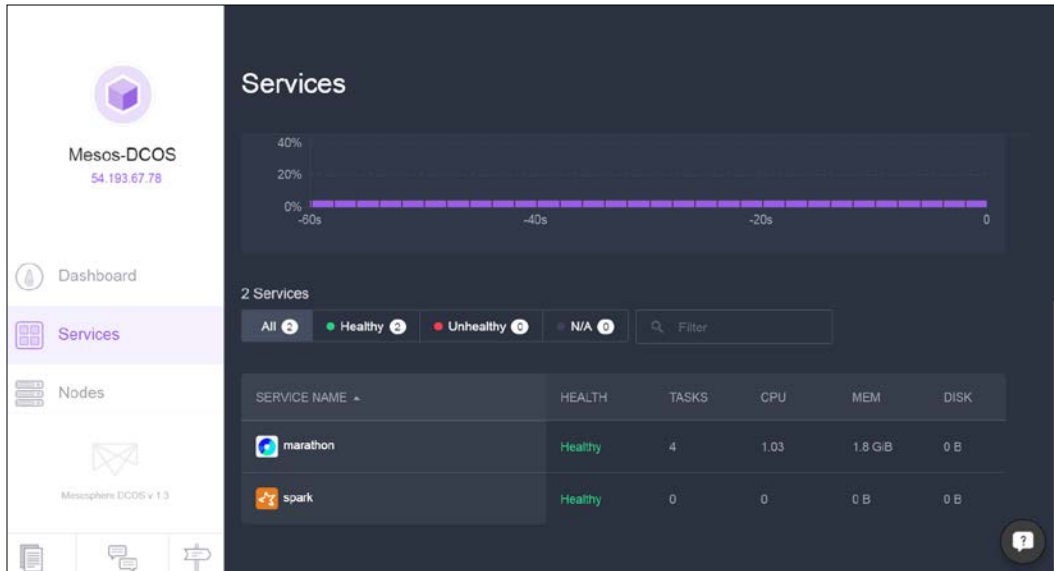
Note: The Spark CLI may take up to 5min to download depending on your connection.

```
Continue installing? [yes/no] yes
```

```
Installing Marathon app for package [spark] version [1.5.0-
multi-roles-v2]
```

```
Installing CLI subcommand for package [spark] version [1.5.0-
multi-roles-v2]
```

10. After deployment, it can be seen in the DCOS UI under the **Services** tab, as shown in the following screenshot:



11. In order to deploy a dummy Docker application on the preceding Marathon cluster, we can use the JSON file to define the container image, command to execute, and ports to be exposed after deployment:

```
$ nano definition.json
{
  "container": {
    "type": "DOCKER",
    "docker": {
      "image": "superguenter/demo-app"
    }
  },
  "cmd": "python -m SimpleHTTPServer $PORT",
  "id": "demo",
  "cpus": 0.01,
  "mem": 256,
  "ports": [3000]
}
```

12. The app can be added to Marathon and listed as follows:

```
$ dcos marathon app add definition.json
$ dcos marathon app list
```

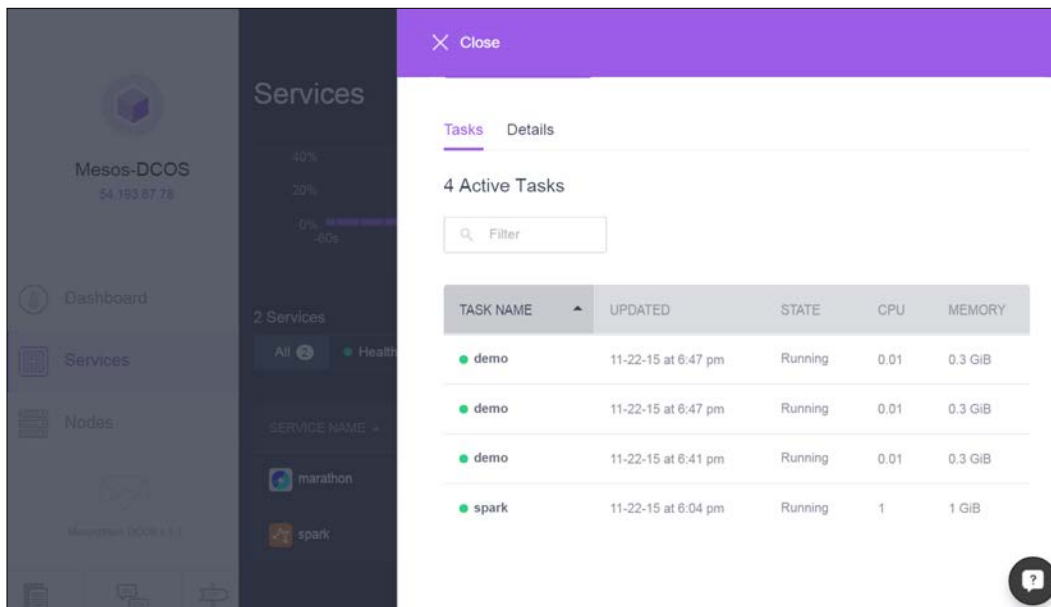
ID	MEM	CPUS	TASKS	HEALTH	DEPLOYMENT	CONTAINER	CMD
/demo	256.0	0.01	1/1	---	---	DOCKER	python -m SimpleHTTPServer \$PORT
/spark	1024.0	1.0	1/1	1/1	---	DOCKER	mv /mnt/mesos/sandbox/log4j.properties conf/log4j.properties && ./bin/spark-class org.apache.spark.deploy.mesos.MesosClusterDispatcher --port \$PORT0 --webui-port \$PORT1 --master mesos://zk://master.mesos:2181/mesos --zk master.mesos:2181 --host \$HOST --name spark

13. Three instances of the preceding Docker app can be started as follows:

```
$ dcos marathon app update --force demo instances=3
Created deployment 28171707-83c2-43f7-afa1-5b66336e36d7
$ dcos marathon deployment list
```

APP	ACTION	PROGRESS	ID
/demo	scale	0/1	28171707-83c2-43f7-afa1-5b66336e36d7

14. The deployed application can be seen in the DCOS UI by clicking on the **Tasks** tab under **Services**:



## Summary

In this chapter, we learnt about Docker networking using various frameworks, such as the native Docker Swarm. Using libnetwork or out-of-the-box overlay networks, Swarm provides multihost networking features.

Kubernetes, on the other hand, has a different perspective from Docker, in which each pod gets its unique IP address and communication between pods can occur with the help of services. Using Open vSwitch or IP forwarding and advanced routing rules, Kubernetes networking can be enhanced to provide connectivity between pods on different subnets across hosts and the ability to expose the pods to the external world. In the case of Mesosphere, we can see that Marathon is used as the backend for the networking of the deployed containers. In the case of DCOS by Mesosphere, the entire deployed stack of machines is treated as one machine in order to provide a rich networking experience between deployed container services.

In the next chapter, we will learn about security and QoS for basic Docker networking by understanding kernel namespace, cgroups, and virtual firewalls.

# 5

## Security and QoS for Docker Containers

In this chapter, we will learn how security is implemented in the context of containers in general and how QoS policies are implemented to make sure that resources such as CPU and IO are shared as intended. Most of the discussion will focus on the relevance of these topics in the context of Docker.

We will cover the following in this chapter:

- File system restrictions
  - Read-only mount points
  - Copy on write
- Linux capabilities and Docker
- Securing containers in AWS ECS (EC2 container service)
- Understanding Docker security I – kernel namespaces
- Understanding Docker security II – cgroups
- Using AppArmor to secure Docker containers
- Docker security benchmark

### Filesystem restrictions

In this section, we are going to study filesystem restrictions with which Docker containers are started. The following section explains the read-only mount points and copy-on-write filesystems, which are used as a base for Docker containers and the representation of kernel objects.

## Read-only mount points

Docker needs access to filesystems such as `sysfs` and `proc` for processes to function. But it doesn't necessarily need to modify these mount points.

Two primary mount points loaded in read-only mode are:

- `/sys`
- `/proc`

### sysfs

The `sysfs` filesystem is loaded into mount point `/sys`. `sysfs` is a mechanism for representing kernel objects, their attributes, and their relationships with each other. It provides two components:

- A kernel programming interface for exporting these items via `sysfs`
- A user interface to view and manipulate these items that maps back to the kernel objects that they represent

The following code shows the mount points being mounted:

```
{
  Source:      "sysfs",
  Destination: "/sys",
  Device:      "sysfs",
  Flags:       defaultMountFlags | syscall.MS_RDONLY,
},
```

A reference link for the preceding code is at [https://github.com/docker/docker/blob/ecc3717cb17313186ee711e624b960b096a9334f/daemon/execdriver/native/template/default\\_template\\_linux.go](https://github.com/docker/docker/blob/ecc3717cb17313186ee711e624b960b096a9334f/daemon/execdriver/native/template/default_template_linux.go).

### procfs

The `proc` filesystem (`procfs`) is a special file system in Unix-like operating systems, which presents information about processes and other systems information in a hierarchical file-like structure. It is loaded into `/proc`. It provides a more convenient and standardized method for dynamically accessing process data held in the kernel than traditional tracing methods or direct access to kernel memory. It is mapped to a mount point named `/proc` at boot time:

```
{
  Source:      "proc",
  Destination: "/proc",
```

---

```

    Device:      "proc",
    Flags:       defaultMountFlags,
},

```

Read-only paths with /proc:

```

ReadonlyPaths: []string{
    "/proc/asound",
    "/proc/bus",
    "/proc/fs",
    "/proc/irq",
    "/proc/sys",
    "/proc/sysrq-trigger",
}

```

## **/dev/pts**

This is another mount point that is mounted as read-write for the container during creation. /dev/pts lives purely in memory and nothing is stored on disk, hence it is safe to load it in read-write mode.

Entries in /dev/pts are pseudo-terminals (pty for short). Unix kernels have a generic notion of terminals. A terminal provides a way for applications to display output and to receive input through a terminal device. A process may have a controlling terminal. For a text mode application, this is how it interacts with the user:

```

{
    Source:      "devpts",
    Destination: "/dev/pts",
    Device:      "devpts",
    Flags:       syscall.MS_NOSUID | syscall.MS_NOEXEC,
    Data:       "newinstance,ptmxmode=0666,mode=0620,gid=5",
},

```

## **/sys/fs/cgroup**

This is the mount point where cgroups are implemented and is loaded as MS\_RDONLY for the container:

```

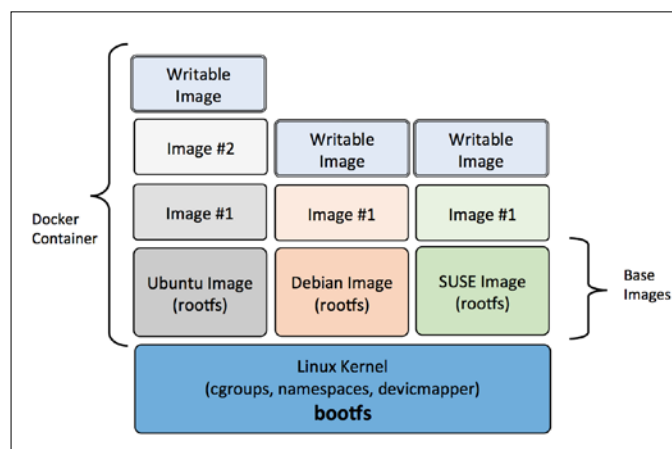
{
    Source:      "cgroup",
    Destination: "/sys/fs/cgroup",
    Device:      "cgroup",
    Flags:       defaultMountFlags | syscall.MS_RDONLY,
},

```



## Copy-on-write

Docker uses union filesystems, which are copy-on-write filesystems. This means containers can use the same filesystem image as the base for the container. When a container writes content to the image, it gets written to a container-specific filesystem. It prevents one container from being able to access the changes of another container even if they are created from the same filesystem image. One container cannot change the image content to effect the processes in another container. The following figure explains this process:



## Linux capabilities

Docker containers before 1.2 could either be given complete capabilities under privileged mode, or they can all follow a whitelist of allowed capabilities while dropping all others. If the flag `--privileged` is used, it will grant all capabilities to the container. This was not recommended for production use because it's really unsafe; it allowed Docker all privileges as a process under the direct host.

With Docker 1.2, two flags have been introduced with `docker run`:

- `--cap-add`
- `--cap-drop`

These two flags provide fine-grain control to a container, for example, as follows:

- Change the status of the Docker container's interface:  
`docker run --cap-add=NET_ADMIN busybox sh -c "ip link eth0 down"`

- Prevent any chown in the Docker container:

```
docker run --cap-drop=CHOWN ...
```

- Allow all capabilities except `mknod`:

```
docker run --cap-add=ALL --cap-drop=MKNOD ...
```

Docker starts containers with a restricted set of capabilities by default. Capabilities convert a binary mode of root and non-root to a more fine-grained access control. As an example, a web server which serves HTTP request needs to be bound to port 80 for HTTP and 443 for HTTPS. These servers need not be run in the root mode. These servers can be granted `net_bind_service` capability.

Containers and servers are a little different in this context. Servers need to run a few processes in the root mode. For example, `ssh`, `cron`, and network configurations to handle `dhcp`, and so on. Containers, on the other hand, do not need this access.

The following tasks need not happen in the container:

- `ssh` access is managed by Docker host
- `cron` jobs should be run in the user mode
- Network configuration such as `ipconfig` and routing should not happen inside the container

We can safely deduce containers might not need root privileges.

Examples that can be denied are as follows:

- Do not allow mount operations
- Do not allow access to sockets
- Prevent access to filesystem operations such as changing file attributes or ownership of the files
- Prevent the container from loading new modules

Docker allows only the following capabilities:

```
Capabilities: []string{
    "CHOWN",
    "DAC_OVERRIDE",
    "FSETID",
    "FOWNER",
    "MKNOD",
    "NET_RAW",
    "SETGID",
    "SETUID",
```

```
"SETFCAP",  
"SETPCAP",  
"NET_BIND_SERVICE",  
"SYS_CHROOT",  
"KILL",  
"AUDIT_WRITE",  
},
```

A reference to the preceding code is at [https://github.com/docker/docker/blob/master/daemon/execdriver/native/template/default\\_template\\_linux.go](https://github.com/docker/docker/blob/master/daemon/execdriver/native/template/default_template_linux.go).

A full list of available capabilities can be found in the Linux man-pages (<http://man7.org/linux/man-pages/man7/capabilities.7.html>).

One primary risk with running Docker containers is that the default set of capabilities and mounts given to a container may provide incomplete isolation, either independently or when used in combination with kernel vulnerabilities.

Docker supports the addition and removal of capabilities, allowing the use of a non-default profile. This may make Docker more secure through capability removal or less secure through the addition of capabilities. The best practice for users would be to remove all capabilities except those explicitly required for their processes.

## Securing containers in AWS ECS

The Amazon **EC2 container service** (ECS) provides a highly scalable, high-performance container management service that supports Docker containers. It allows you to easily run applications on a managed cluster of Amazon EC2 instances. Amazon ECS eliminates the need for you to install, operate, and scale your own cluster management infrastructure. With simple API calls, you can launch and stop Docker-enabled applications and query the complete state of your cluster.

In the following example, we will see how to deploy a secured web application using two Docker containers, one containing a simple web application (application container), and the other containing a reverse proxy with throttling enabled (proxy container), which can be used to protect the web application. These containers will be deployed on the Amazon EC2 instance using ECS. As can be seen in the following diagram, all the network traffic will be routed through the proxy container that throttles requests. Also, we can perform activities such as filtering, logging, and intrusion detection at proxy containers using various security software.

The following are the steps to do so:

1. We will build a basic PHP web application container from the GitHub project. The following steps can be performed on a separate EC2 instance or a local machine:  

```
$ sudo yum install -y git
```

```
$ git clone https://github.com/aws-labs/ecs-demo-php-simple-app
```
2. Change directories to the `ecs-demo-php-simple-app` folder:  

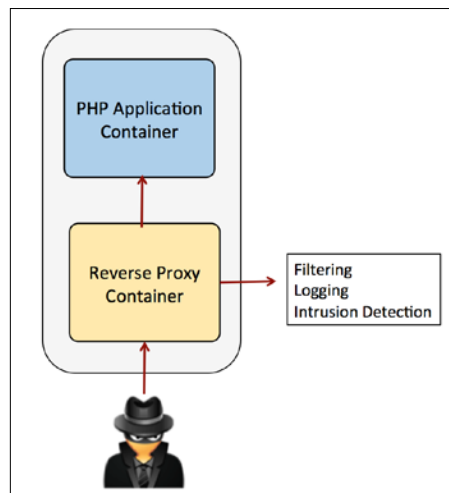
```
$ cd ecs-demo-php-simple-app
```
3. We can examine `Dockerfile` as follows in order to understand the web application it will deploy:  

```
$ cat Dockerfile
```
4. Build the container image using `Dockerfile` and then push it in your Docker Hub account. The Docker Hub account is required as it helps to deploy the containers on the Amazon ECS service by just specifying the container name:  

```
$ docker build -t my-dockerhub-username/amazon-ecs-sample.
```

The image built over here is required to have `dockerhub-username` (correct without spaces) as the first parameter.

The following figure depicts a hacker not able to access the web application, as the request is filtered via a proxy container and access is blocked:



5. Upload the Docker image to the Docker Hub account:  

```
$ docker login
```

6. Check to ensure your login worked:

```
$ docker info
```

7. Push your image to the Docker Hub account:

```
$ docker push my-dockerhub-username/amazon-ecs-sample
```

8. After creating the sample web application Docker container, we will now create the proxy container, which can also contain some security-related software, if required, in order to strengthen security. We will create a new proxy Docker container using a customized Dockerfile and then push the image to your Docker Hub account:

```
$ mkdir proxy-container
$ cd proxy-container
$ nano Dockerfile
FROM ubuntu
RUN apt-get update && apt-get install -y nginx
COPY nginx.conf /etc/nginx/nginx.conf
RUN echo "daemon off;" >> /etc/nginx/nginx.conf
EXPOSE 80
CMD service nginx start
```

In the previous Dockerfile we are using a base Ubuntu image and installing nginx and exposing it on port 80.

9. Next, we will create a customized `nginx.conf`, which will override the default `nginx.conf` in order to ensure the reverse proxy is configured properly:

```
user www-data;
worker_processes 4;
pid /var/run/nginx.pid;

events {
    worker_connections 768;
    # multi_accept on;
}

http {
    server {
        listen          80;
```

---

```

    # Proxy pass to servlet container
    location / {
        proxy_pass      http://application-container:80;
    }
}
}

```

10. Build the proxy Docker image and push the built image to the Docker Hub account:
 

```

$ docker build -t my-dockerhub-username/proxy-image.
$ docker push my-dockerhub-username/proxy-image

```
11. The ECS container service can be deployed by navigating to **AWS Management Console** (<https://aws.amazon.com/console/>).
12. Click **Task Definitions** in the left sidebar and then click **Create a New Task Definition**.
13. Give your task definition a name, such as `SecurityApp`.
14. Next, click on **Add Container** and insert the name of the proxy web container pushed to the Docker Hub account, as well as the name of the application web container. View the contents of the JSON using **Configure via JSON** tab to see the task definition that you have created. It should be like this:

```

Proxy-container:
Container Name: proxy-container
Image: username/proxy-image
Memory: 256
Port Mappings
Host port: 80
Container port: 80
Protocol: tcp
CPU: 256
Links: application-container
Application container:
Container Name: application-container
Image: username/amazon-ecs-sample
Memory: 256
CPU: 256

```

Click the **Create** button in order to deploy the application.

15. Click **Clusters** in the left sidebar. If a default cluster does not exist, create one.
16. Launch an ECS-optimized **Amazon Machine Image (AMI)**, ensuring it has a public IP address and a path to the Internet.
17. When your instance is up and running, navigate to the **ECS** section of the **AWS Management Console** and click **Clusters**, then **default**. Now, we should be able to see our instance under the **ECS Instances** tab.
18. Navigate to the **TASK** definitions from the left side of the **AWS Management Console** tab and click **Run Task**.
19. On the next page, ensure the cluster is set to **Default** and the number of tasks is **1**, then click **Run Task**.
20. After the process completes we can see the state of the task from a pending state to a green running state.
21. Clicking on the **ECS** tab, we can see the container instance created earlier. By clicking on it, we will get information about its public IP address. By hitting this public IP address via the browser we will be able to see our sample PHP application.

## Understanding Docker security I – kernel namespaces

A namespace provides a wrapper around a global system resource of the kernel and makes the resource appear to the process within the namespace as if they have an isolated instance. Global resource changes are visible to processes in the same namespace but invisible to others. Containers are considered an excellent implementation of a kernel namespace.

The following namespaces are implemented by Docker:

- **pid namespace**: Used for process isolation (**PID – Process ID**)
- **net namespace**: Used for managing network interfaces (**NET – Networking**)
- **ipc namespace**: Used for managing access to IPC resources (**IPC – Inter Process Communication**)
- **mnt namespace**: Used for managing mount points (**MNT – Mount**)
- **uts namespace**: Used for isolating kernel and version identifiers (**UTS – Unix Time sharing System**)

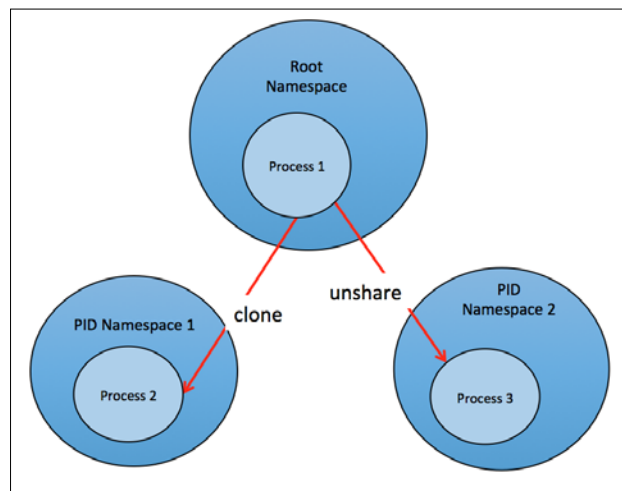
Adding namespace support in libcontainer required adding patches in the system layer of GoLang ([https://codereview.appspot.com/126190043/patch/140001/150001,src/syscall/exec\\_linux.go](https://codereview.appspot.com/126190043/patch/140001/150001,src/syscall/exec_linux.go)) so that new data structures could be maintained for PIDs, user UIDs, and so on.

## pid namespace

pid namespaces isolate the process ID number space; processes in different pid namespaces can have the same pid. pid namespaces allow containers to provide functionality such as suspending/resuming the set of processes in the container, and migrating the container to a new host while the processes inside the container maintain the same pids.

pids in a new namespace start with PID 1. The kernel needs to be configured for the flag `CONFIG_PID_NS` for the namespace to work.

pid namespaces can be nested. Each pid namespace has a parent, except for the initial (root) pid namespace. The parent of a pid namespace is the pid namespace of the process that created the namespace using `clone` or `unshare`. pid namespaces form a tree, with all namespaces ultimately tracing their ancestry to the root namespace as shown in the following figure:



## net namespace

net namespace provides isolation of the system resources associated with networking. Each network namespace has its own network devices, IP addresses, IP routing tables, `/proc/net` directory, port numbers, and so on.



Network namespaces make containers useful from a networking perspective: each container can have its own (virtual) network device and its own applications that bind to the per-namespace port number space; suitable routing rules in the host system can direct network packets to the network device associated with a specific container. Use of network namespaces requires a kernel that is configured with the `CONFIG_NET_NS` option (<https://lwn.net/Articles/531114/>).

As each container has its own network namespace, which basically means its own network interface and routing tables, net namespace is also directly leveraged by Docker to isolate IP addresses, port numbers, and so on.

## Basic network namespace management

Network namespaces are created by passing a flag to the `clone()` system call, `CLONE_NEWNET`. From the command line, though, it is convenient to use the IP networking configuration tool to set up and work with network namespaces:

```
# ip netns add netns1
```

This command creates a new network namespace called `netns1`. When the IP tool creates a network namespace, it will create a bind mount for it under `/var/run/netns`, which allows the namespace to persist, even when no processes are running within it, and facilitates the manipulation of the namespace itself. Since network namespaces typically require a fair amount of configuration before they are ready for use, this feature will be appreciated by systems administrators.

The `ip netns exec` command can be used to run network management commands within the namespace:

```
# ip netns exec netns1 ip link list
1: lo: <LOOPBACK> mtu 65536 qdisc noop state DOWN mode DEFAULT
link/loopback 00:00:00:00:00:00 brd 00:00:00:00:00:00
```

This command lists the interfaces visible inside the namespace. A network namespace can be removed with the use of following command:

```
# ip netns delete netns1
```

This command removes the bind mount referring to the given network namespace. The namespace itself, however, will persist for as long as any processes are running within it.

## Network namespace configuration

New network namespaces will have a loopback device but no other network devices. Aside from the loopback device, each network device (physical or virtual interfaces, bridges, and so on) can only be present in a single network namespace. In addition, physical devices (those connected to real hardware) cannot be assigned to namespaces other than the root. Instead, virtual network devices (for example, virtual Ethernet or vEth) can be created and assigned to a namespace. These virtual devices allow processes inside the namespace to communicate over the network; it is the configuration, routing, and so on that determines who they can communicate with.

When first created, the `lo` loopback device in the new namespace is down, so even a loopback ping will fail.

```
# ip netns exec netns1 ping 127.0.0.1
connect: Network is unreachable
```

In the previous command, we can see that since the net namespace for a Docker container is stored in a separate location, and thus a symlink is required to be created to `/var/run/netns`, it can be done in the following way:

```
# pid=$(docker inspect -f '{{.State.Pid}}' $container_id)
# ln -s /proc/$pid/ns/net /var/run/netns/$container_id
```

In this example, it is done by bringing that interface up, which will allow the pinging of the loopback address.

```
# ip netns exec netns1 ip link set dev lo up
# ip netns exec netns1 ping 127.0.0.1
PING 127.0.0.1 (127.0.0.1) 56(84) bytes of data.
64 bytes from 127.0.0.1: icmp_seq=1 ttl=64 time=0.052 ms
64 bytes from 127.0.0.1: icmp_seq=2 ttl=64 time=0.042 ms
64 bytes from 127.0.0.1: icmp_seq=3 ttl=64 time=0.044 ms
64 bytes from 127.0.0.1: icmp_seq=4 ttl=64 time=0.031 ms
64 bytes from 127.0.0.1: icmp_seq=5 ttl=64 time=0.042 ms
```

This still doesn't allow communication between `netns1` and the root namespace. To do that, virtual Ethernet devices need to be created and configured.

```
# ip link add veth0 type veth peer name veth1
# ip link set veth1 netns netns1
```

The first command sets up a pair of virtual Ethernet devices that are connected. Packets sent to veth0 will be received by veth1 and vice versa. The second command assigns veth1 to the netns1 namespace.

```
# ip netns exec netns1 ifconfig veth1 10.0.0.1/24 up
# ifconfig veth0 10.0.0.2/24 up
```

Then, these two commands set IP addresses for the two devices.

```
# ping 10.0.0.1
# ip netns exec netns1 ping 10.0.0.2
```

Communication in both directions is now possible as the previous ping commands show.

As mentioned, though, namespaces do not share routing tables or firewall rules, as running `route` and `iptables -L` in netns1 will attest:

```
# ip netns exec netns1 route
Kernel IP routing table
Destination    Gateway      Genmask      Flags        Metric Ref    Use Iface
10.0.0.0        *           255.255.255.0  U            0    0    0      veth1

# ip netns exec netns1 iptables -L
Chain INPUT (policy ACCEPT)
target     prot opt source                destination
Chain FORWARD (policy ACCEPT)
target     prot opt source                destination
Chain OUTPUT (policy ACCEPT)
target     prot opt source                destination
```

## User namespace

User namespaces allows per-namespace mappings of user and group IDs. This means that user IDs and group IDs of a process inside a user namespace can be different from its IDs outside of the namespace. A process can have a non-zero user ID outside a namespace while, at the same time, having a user ID of zero inside the namespace. The process is unprivileged for operations outside the user namespace but has root privileges inside the namespace.

## Creating a new user namespace

User namespaces are created by specifying the `CLONE_NEWUSER` flag when calling `clone()` or `unshare()`:

`clone()` allows the child process to share parts of its execution context with the calling process, such as the memory space, the table of file descriptors, and the table of signal handlers.

`unshare()` allows a process (or thread) to disassociate parts of its execution context that are currently being shared with other processes (or threads). Part of the execution context, such as the mount namespace, is shared implicitly when a new process is created using `fork()` or `vfork()`.

As mentioned previously, Docker containers are very similar to LXC containers as a set of namespaces and control groups are created separately for containers. Each container gets its own network stack and namespace. Until and unless containers do not have the privileged access, they are not allowed to access other hosts sockets or interfaces. If the host network mode is given to the container, then only it gets the ability to access the host ports and IP address, which can cause a potential threat to other programs running on the host.

As shown in the following example, where we use the host network mode in the container and it is able to access all the hosts bridges:

```
docker run -it --net=host ubuntu /bin/bash
$ ifconfig
docker0    Link encap:Ethernet  HWaddr 02:42:1d:36:0d:0d
            inet addr:172.17.0.1  Bcast:0.0.0.0  Mask:255.255.0.0
            inet6 addr: fe80::42:1dff:fe36:d0d/64 Scope:Link
            UP BROADCAST MULTICAST  MTU:1500  Metric:1
            RX packets:24  errors:0  dropped:0  overruns:0  frame:0
            TX packets:38  errors:0  dropped:0  overruns:0  carrier:0
            collisions:0 txqueuelen:0
            RX bytes:1608 (1.6 KB)  TX bytes:5800 (5.8 KB)

enol6777736 Link encap:Ethernet  HWaddr 00:0c:29:02:b9:13
            inet addr:192.168.218.129  Bcast:192.168.218.255
Mask:255.255.255.0
            inet6 addr: fe80::20c:29ff:fe02:b913/64 Scope:Link
            UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
```

```
RX packets:4934 errors:0 dropped:0 overruns:0 frame:0
TX packets:4544 errors:0 dropped:0 overruns:0 carrier:0
collisions:0 txqueuelen:1000
RX bytes:2909561 (2.9 MB) TX bytes:577079 (577.0 KB)
```

```
$ docker ps -q | xargs docker inspect --format '{{ .Id }}:
NetworkMode={{ .HostConfig.NetworkMode }}'
52afb14d08b9271bd96045bebd508325a2adff98dbef8c10c63294989441954d:
NetworkMode=host
```

While auditing, it should be checked that all the containers, by default, have network mode set to default and not host:

```
$ docker ps -q | xargs docker inspect --format '{{ .Id }}:
NetworkMode={{ .HostConfig.NetworkMode }}'
1aca7fe47882da0952702c383815fc650f24da2c94029b5ad8af165239b78968:
NetworkMode=default
```

Each Docker container is connected to an Ethernet bridge in order to provide inter-connectivity between containers. They can ping each other to send/receive UDP packets and establish TCP connections, but that can be restricted if necessary. Namespace also provides a straightforward isolation in restricting the access of the processes running in the other container as well as the host.

We will be using the following `nsenter` command line utility in order to enter into namespaces. It is an open-source project on GitHub available at <https://github.com/jpetazzo/nsenter>.

Using it, we will try to enter existing container namespaces or try to spawn a new set of namespaces. It is different from the Docker `exec` command as `nsenter` doesn't enter the cgroups, which gives potential benefits for debugging and external audits by escaping the resource limitations using namespace.

We can install `nsenter` from PyPI (it requires Python 3.4) and use the command line utility to connect to a running container:

```
$ pip install nsenter
```

To replace pid with the container's pid, use the following command:

```
$ sudo nsenter --net --target=PID /bin/ip a
1: lo: <LOOPBACK,UP,LOWER_UP> mtu 65536 qdisc noqueue state UNKNOWN group
default
    link/loopback 00:00:00:00:00:00 brd 00:00:00:00:00:00
    inet 127.0.0.1/8 scope host lo
        valid_lft forever preferred_lft forever
    inet6 ::1/128 scope host
        valid_lft forever preferred_lft forever
14: eth0: <BROADCAST,UP,LOWER_UP> mtu 1500 qdisc noqueue state UP
group default
    link/ether 02:42:ac:11:00:06 brd ff:ff:ff:ff:ff:ff
    inet 172.17.0.6/16 scope global eth0
        valid_lft forever preferred_lft forever
    inet6 fe80::42:acff:fe11:6/64 scope link
        valid_lft forever preferred_lft forever
```

We can use the `docker inspect` command to make it more convenient as follows:

1. First start a new nginx server:  

```
$ docker run -d --name=nginx -t nginx
```
2. Then get pid of the container:  

```
PID=$(docker inspect --format {{.State.Pid}} nginx)
```
3. Connect to the running nginx container:  

```
$ nsenter --target $PID --uts --ipc --net -pid
```

`docker-enter` is also one of the wrappers that can be used to enter inside the container specifying the shell commands, and if no command is specified, a shell will be invoked instead. If it is required to inspect or manipulate containers without executing another command line tool, we can use context manager to do this:

```
import subprocess
from nsenter import Namespace
with Namespace(mypid, 'net'):
    # output network interfaces as seen from within the mypid's net NS:
    subprocess.check_output(['ip', 'a'])
```

## Understanding Docker security II – cgroups

In this section, we look at how cgroups form the backbone of isolation for a container.

### Defining cgroups

Control groups provide a mechanism for aggregating/partitioning sets of tasks (processes), and all their future children, into hierarchical groups.

A cgroup associates a set of tasks with parameters from a subsystem. A subsystem itself is a resource controller used to define boundaries for cgroups or for provisioning a resource.

A hierarchy is a set of cgroups arranged in a tree, such that every task in the system is in exactly one of the cgroups in the hierarchy and a set of subsystems.

### Why are cgroups required?

There are multiple efforts to provide process aggregations in the Linux kernel, mainly for resource-tracking purposes.

Such efforts include cpusets, CKRM/ResGroups, UserBeanCounters, and virtual server namespaces. These all require the basic notion of a grouping/partitioning of processes, with newly forked processes ending up in the same group (cgroup) as their parent process.

The kernel cgroup patch provides essential kernel mechanisms to efficiently implement such groups. It has minimal impact on the system fast paths and provides hooks for specific subsystems such as cpusets to provide additional behavior as desired.

### Creating a cgroup manually

In the following steps, we will create a cpuset control group:

```
# mount -t tmpfs cgroup_root /sys/fs/cgroup
```

tmpfs is a file system that keeps all files in virtual memory. Everything in tmpfs is temporary in the sense that no files will be created on your hard drive. If you unmount a tmpfs instance, everything stored therein is lost:

```
# mkdir /sys/fs/cgroup/cpuset
```

```
# mount -t cgroup -ocpuset cpuset /sys/fs/cgroup/cpuset
```

---

```
# cd /sys/fs/cgroup/cpuset
# mkdir Charlie
# cd Charlie
# ls
cgroup.clone_children  cpuset.cpu_exclusive  cpuset.mem_hardwall
cpuset.memory_spread_page  cpuset.sched_load_balance  tasks
cgroup.event_control  cpuset.cpus  cpuset.memory_migrate
cpuset.memory_spread_slab  cpuset.sched_relax_domain_level
cgroup.procs  cpuset.mem_exclusive  cpuset.memory_pressure
cpuset.mems  notify_on_release
```

Assign CPU and memory limits to this cgroup:

```
# /bin/echo 2-3 > cpuset.cpus
# /bin/echo 0 > cpuset.mems
# /bin/echo $$ > tasks
```

The following command shows `/Charlie` as the `cpuset` cgroup:

```
# cat /proc/self/cgroup
11:name=systemd:/user/1000.user/c2.session
10:hugetlb:/user/1000.user/c2.session
9:perf_event:/user/1000.user/c2.session
8:blkio:/user/1000.user/c2.session
7:freezer:/user/1000.user/c2.session
6:devices:/user/1000.user/c2.session
5:memory:/user/1000.user/c2.session
4:cpuacct:/user/1000.user/c2.session
3:cpu:/user/1000.user/c2.session
2:cpuset:/Charlie
```

## Attaching processes to cgroups

Add the process ID `PID{X}` to the `tasks` file as shown in the following:

```
# /bin/echo PID > tasks
```

Note that it is `PID`, not `PIDs`.



You can only attach one task at a time. If you have several tasks to attach, you have to do it one after another:

```
# /bin/echo PID1 > tasks
# /bin/echo PID2 > tasks
...
# /bin/echo PIDn > tasks
```

Attach the current shell task by echoing 0:

```
# echo 0 > tasks
```

## Docker and cgroups

cgroups are managed as part of the libcontainer project under Docker's GitHub repo (<https://github.com/opencontainers/runc/tree/master/libcontainer/cgroups>). There is a cgroup manager that manages the interaction with the cgroup APIs in the kernel.

The following code shows the lifecycle events managed by the manager:

```
type Manager interface {
    // Apply cgroup configuration to the process with the specified pid
    Apply(pid int) error
    // Returns the PIDs inside the cgroup set
    GetPids() ([]int, error)
    // Returns statistics for the cgroup set
    GetStats() (*Stats, error)
    // Toggles the freezer cgroup according with specified state
    Freeze(state configs.FreezerState) error
    // Destroys the cgroup set
    Destroy() error
    // Paths maps cgroup subsystem to path at which it is mounted.
    // Cgroups specifies specific cgroup settings for the various
    // subsystems
    // Returns cgroup paths to save in a state file and to be able to
    // restore the object later.
    GetPaths() map[string]string
    // Set the cgroup as configured.
    Set(container *configs.Config) error
}
```

## Using AppArmor to secure Docker containers

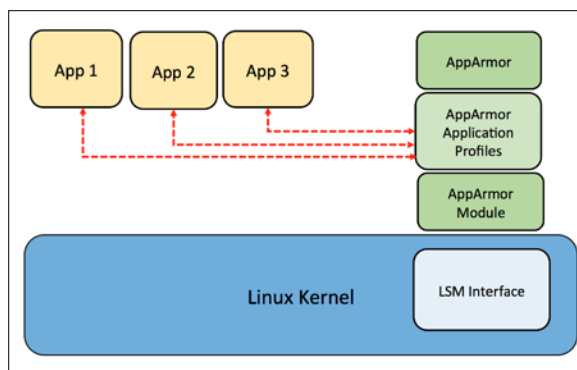
AppArmor is a **Mandatory Access Control (MAC)** system that is a kernel enhancement to confine programs to a limited set of resources. AppArmor's security model is to bind access control attributes to programs rather than to users.

AppArmor confinement is provided via profiles loaded into the kernel, typically on boot. AppArmor profiles can be in one of two modes: enforcement or complain.

Profiles loaded in enforcement mode will result in enforcement of the policy defined in the profile, as well as reporting policy violation attempts (either via syslog or auditd).

Profiles in complain mode will not enforce policy but instead report policy violation attempts.

AppArmor differs from some other MAC systems on Linux: it is path-based, it allows mixing of enforcement and complain-mode profiles, it uses include files to ease development, and it has a far lower barrier to entry than other popular MAC systems. The following figure shows the AppArmor application profiles linked to apps:



AppArmor is an established technology first seen in Immunix and later integrated into Ubuntu, Novell/SUSE, and Mandriva. Core AppArmor functionality is in the mainline Linux kernel from 2.6.36 onwards; work is ongoing by AppArmor, Ubuntu, and other developers to merge additional AppArmor functionality into the mainline kernel.

You can find more information about AppArmor at <https://wiki.ubuntu.com/AppArmor>.

## AppArmor and Docker

Applications running inside Docker can leverage AppArmor for defining policies. These profiles can either be created manually or loaded using a tool called bane.



On Ubuntu 14.x, make sure systemd is installed for the following commands to work.

The following steps show how to use this tool:

1. Download the bane project for GitHub:

```
$ git clone https://github.com/jfrazelle/bane
```

Make sure this is done in the directory in your GOPATH. For example, we used /home/ubuntu/go and the bane source was downloaded in /home/Ubuntu/go/src/github.com/jfrazelle/bane.

2. Install toml parser needed by bane to be compiled:

```
$ go get github.com/BurntSushi/toml
```

3. Go to the /home/Ubuntu/go/src/github.com/jfrazelle/bane directory and run the following command:

```
$ go install
```

4. You will find the bane binary in /home/Ubuntu/go/bin.

5. Use a .toml file to create a profile:

```
Name = "nginx-sample"
[Filesystem]
# read only paths for the container
ReadOnlyPaths = [
    "/bin/**",
    "/boot/**",
    "/dev/**",
    "/etc/**",
    ...
]
AllowExec = [
    "/usr/sbin/nginx"
```

```

]
# denied executable files
DenyExec = [
    "/bin/dash",
    "/bin/sh",
    "/usr/bin/top"
]

```

6. Execute bane to load the profile. `sample.toml` is a file in the directory `/home/Ubuntu/go/src/github.com/jfrazelle/bane`:

```

$ sudo bane sample.toml

# Profile installed successfully you can now run the profile
with # `docker run --security-opt="apparmor:docker-nginx-
sample"`

```

This profile will make a whole lot of paths read only and allows only nginx execution in the container we are going to create. It disables TOP, PING, and so on.

7. Once the profile is loaded you can create a nginx container:

```

$ docker run --security-opt="apparmor:docker-nginx-sample" -p
80:80 --rm -it nginx bash

```

Note, if AppArmor is not able to find the file, copy the file into the `/etc/apparmor.d` directory and reload the AppArmor profiles:

```

$ sudo invoke-rc.d apparmor reload

```

Create the nginx container with the AppArmor profile:

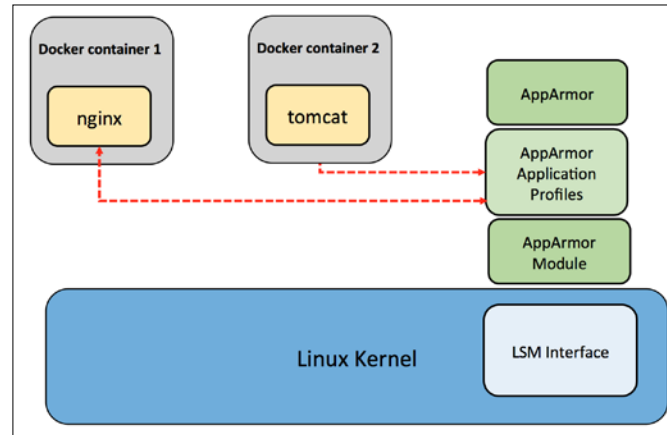
```

ubuntu@ubuntu:~/go/src/github.com$ docker run --security-
opt="apparmor:docker-nginx-sample" -p 80:80 --rm -it nginx
bash

root@84d617972e04:/# ping 8.8.8.8
ping: Lacking privilege for raw socket.

```

The following figure shows how an nginx app running inside a container uses AppArmor application profiles:



## Docker security benchmark

The following tutorial shows some of the important guidelines that should be followed in order to run Docker containers in secured and production environments. It is referred from the CIS Docker Security Benchmark [https://benchmarks.cisecurity.org/tools2/docker/CIS\\_Docker\\_1.6\\_Benchmark\\_v1.0.0.pdf](https://benchmarks.cisecurity.org/tools2/docker/CIS_Docker_1.6_Benchmark_v1.0.0.pdf).

## Audit Docker daemon regularly

Apart from auditing your regular Linux filesystem and system calls, audit Docker daemon as well. Docker daemon runs with root privileges. It is thus necessary to audit its activities and usage:

```
$ apt-get install auditd
Reading package lists... Done
Building dependency tree
Reading state information... Done
The following extra packages will be installed:
  libauparse0
Suggested packages:
  audispd-plugins
The following NEW packages will be installed:
  auditd libauparse0
```

```

0 upgraded, 2 newly installed, 0 to remove and 50 not upgraded.
Processing triggers for libc-bin (2.21-0ubuntu4) ...
Processing triggers for ureadahead (0.100.0-19) ...
Processing triggers for systemd (225-1ubuntu9) ...

```

Remove the audit log file, if it exists:

```

$ cd /etc/audit/
$ ls
audit.log
$ nano audit.log
$ rm -rf audit.log

```

Add the audit rules for the Docker service and audit the Docker service:

```

$ nano audit.rules
-w /usr/bin/docker -k docker
$ service auditd restart
$ ausearch -k docker
<no matches>
$ docker ps
CONTAINER ID      IMAGE               COMMAND             CREATED           STATUS            PORTS
NAMES
$ ausearch -k docker
----
time->Fri Nov 27 02:29:50 2015
type=PROCTITLE msg=audit(1448620190.716:79):
proctitle=646F636B6572007073
type=PATH msg=audit(1448620190.716:79): item=1 name="/lib64/ld-linux-
x86-64.so.2" inode=398512 dev=08:01 mode=0100755 ouid=0 ogid=0 rdev=00:00
nametype=NORMAL
type=PATH msg=audit(1448620190.716:79): item=0 name="/usr/bin/docker"
inode=941134 dev=08:01 mode=0100755 ouid=0 ogid=0 rdev=00:00
nametype=NORMAL
type=CWD msg=audit(1448620190.716:79):  cwd="/etc/audit"
type=EXECVE msg=audit(1448620190.716:79): argc=2 a0="docker" a1="ps"
type=SYSCALL msg=audit(1448620190.716:79): arch=c000003e syscall=59
success=yes exit=0 a0=ca1208 a1=c958c8 a2=c8

```

## Create a user for the container

Currently, mapping the container's root user to a non-root user on the host is not supported by Docker. The support for user namespace would be provided in future releases. This creates a serious user isolation issue. It is thus highly recommended to ensure that there is a non-root user created for the container and the container is run using that user.

As we can see in the following snippet, by default, the `centos` Docker image has a `user` field as blank, which means, by default, the container will get a root user during runtime, which should be avoided:

```
$ docker inspect centos
[
  {
    "Id":
      "e9fa5d3a0d0e19519e66af2dd8ad6903a7288de0e995b6eafbcb38aebf2b606d",
    "RepoTags": [
      "centos:latest"
    ],
    "RepoDigests": [],
    "Parent":
      "c9853740aa059d078b868c4a91a069a0975fb2652e94cc1e237ef9b961afa572",
    "Comment": "",
    "Created": "2015-10-13T23:29:04.138328589Z",
    "Container":
      "eaa200e2e187340f0707085b9b4eab5658b13fd190af68c71a60f6283578172f",
    "ContainerConfig": {
      "Hostname": "7aa5783a47d5",
      "Domainname": "",
      "User": "",
      "Cmd":
        ["cat /etc/passwd"]
    }
  }
]
```

While building the Docker image, we can provide the `test` user, the less-privileged user, in the Dockerfile, as shown in the following snippet:

```
$ cd
$ mkdir test-container
$ cd test-container/
$ cat Dockerfile
FROM centos:latest
```

---

```

RUN useradd test
USER test
root@ubuntu:~/test-container# docker build -t vkohli .
Sending build context to Docker daemon 2.048 kB
Step 1 : FROM centos:latest
--> e9fa5d3a0d0e
Step 2 : RUN useradd test
--> Running in 0c726d186658
--> 12041ebdfd3f
Removing intermediate container 0c726d186658
Step 3 : USER test
--> Running in 86c5e0599c72
--> af4ba8a0fec5
Removing intermediate container 86c5e0599c72
Successfully built af4ba8a0fec5
$ docker images | grep vkohli
vkohli      latest      af4ba8a0fec5      9 seconds ago      172.6 MB

```

When we start the Docker container, we can see that it gets a `test` user, and the `docker inspect` command also shows the default user as `test`:

```

$ docker run -it vkohli /bin/bash
[test@2ff11ee54c5f /]$ whoami
test
[test@2ff11ee54c5f /]$ exit
$ docker inspect vkohli
[
  {
    "Id":
      "af4ba8a0fec558d68b4873e2a1a6d8a5ca05797e0bfbab0772bcedced15683ea",
    "RepoTags": [
      "vkohli:latest"
    ],
    "RepoDigests": [],
    "Parent":
      "12041ebdfd3f38df3397a8961f82c225bddc56588e348761d3e252eec868d129",
    "Comment": "",

```



```
"Created": "2015-11-27T14:10:49.206969614Z",
"Container":
  "86c5e0599c72285983f3c5511fdec940f70cde171f1bfb53fab08854fe6d7b12",
"ContainerConfig": {
  "Hostname": "7aa5783a47d5",
  "Domainname": "",
  "User": "test",
  Contd..
```

## Do not mount sensitive host system directories on containers

If sensitive directories are mounted in read-write mode, it would be possible to make changes to files within those sensitive directories. The changes might bring down security implications or unwarranted changes that could put the Docker host in a compromised state.

If the `/run/systemd` sensitive directory is mounted in the container then we can actually shutdown the host from the container itself:

```
$ docker run -ti -v /run/systemd:/run/systemd centos /bin/bash
[root@laca7fe47882 /]# systemctl status docker
docker.service - Docker Application Container Engine
   Loaded: loaded (/lib/systemd/system/docker.service; enabled)
   Active: active (running) since Sun 2015-11-29 12:22:50 UTC; 21min ago
   Docs: https://docs.docker.com
   Main PID: 758
   CGroup: /system.slice/docker.service
[root@laca7fe47882 /]# shutdown
```

It can be audited by using the following command, which returns the list of current mapped directories and whether they are mounted in read-write mode for each container instance:

```
$ docker ps -q | xargs docker inspect --format '{{.Id }}: Volumes={{.Volumes }} VolumesRW={{.VolumesRW }}'
```

## Do not use privileged containers

Docker supports the addition and removal of capabilities, allowing the use of a non-default profile. This may make Docker more secure through capability removal, or less secure through the addition of capabilities. It is thus recommended to remove all capabilities except those explicitly required for your container process.

As seen in the following, when we run the container without the privileged mode, we are unable to change the kernel parameters, but when we run the container in privileged mode using the `--privileged` flag, it is possible to change the kernel parameters easily, which can cause security vulnerability:

```
$ docker run -it centos /bin/bash
[root@7e1b1fa4fb89 /]# sysctl -w net.ipv4.ip_forward=0
sysctl: setting key "net.ipv4.ip_forward": Read-only file system
$ docker run --privileged -it centos /bin/bash
[root@930aaa93b4e4 /]# sysctl -a | wc -l
sysctl: reading key "net.ipv6.conf.all.stable_secret"
sysctl: reading key "net.ipv6.conf.default.stable_secret"
sysctl: reading key "net.ipv6.conf.eth0.stable_secret"
sysctl: reading key "net.ipv6.conf.lo.stable_secret"
638
[root@930aaa93b4e4 /]# sysctl -w net.ipv4.ip_forward=0
net.ipv4.ip_forward = 0
```

So, while auditing, it should be made sure that all the containers should not have the privileged mode set to `true`:

```
$ docker ps -q | xargs docker inspect --format '{{ .Id }}':
Privileged={{ .HostConfig.Privileged }}'
930aaa93b4e44c0f647b53b3e934ce162fbd9ef1fd4ec82b826f55357f6fdf3a:
Privileged=true
```

## Summary

In this chapter, we took a deep dive into Docker security with an overview of cgroups and kernel namespace. We also went over some of the aspects of filesystems and Linux capabilities, which containers leverage in order to provide more features, such as the privileged containers, but at the cost of exposing itself more on the threat side. We also saw how containers can be deployed in a secured environment in AWS ECS (EC2 container service) using proxy containers to restrict vulnerable traffic. AppArmor also provides kernel-enhancement features in order to confine applications to a limited set of resources. Leveraging their benefits to Docker containers helps us to deploy them in a secured environment. Finally, we had a quick dive into Docker security benchmarks and some of the important recommendations that can be followed during auditing and Docker deployment in the production environment.

In the next chapter, we will learn about tuning and troubleshooting in the Docker network using various tools.

# 6

## Next Generation Networking Stack for Docker: libnetwork

In this chapter, we will learn about a new networking stack for Docker: libnetwork, which provides a pluggable architecture with a default implementation for single and multi-host virtual networking:

- Introduction
  - Goal
  - Design
- CNM objects
  - CNM attributes
  - CNM lifecycle
- Drivers
  - Bridge driver
  - Overlay network driver
- Using overlay network with Vagrant
- Overlay network with Docker Machine and Docker Swarm
- Creating an overlay network manually and using it for containers
- Container network interface
- Calico's libnetwork driver

## Goal

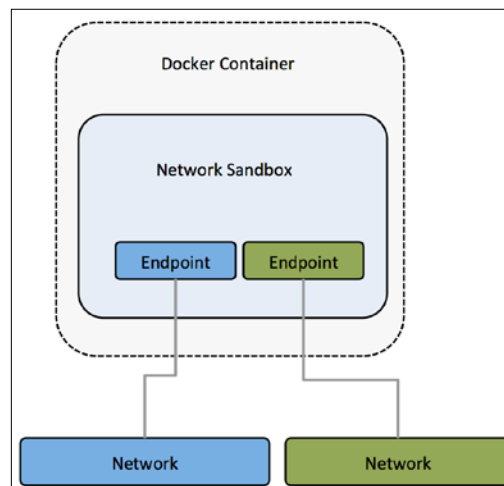
libnetwork which is written in go language is a new way for connecting Docker containers. The aim is to provide a container network model that helps programmers and provides the abstraction of network libraries. The long-term goal of libnetwork is to follow the Docker and Linux philosophy to deliver modules that work independently. libnetwork has the aim to provide a composable need for networking in containers. It also aims to modularize the networking logic in Docker Engine and libcontainer into a single, reusable library by:

- Replacing the networking module of Docker Engine with libnetwork
- Being a model that allows local and remote drivers to provide networking to containers
- Providing a tool dnet for managing and testing libnetwork—still a work in progress (reference from <https://github.com/docker/libnetwork/issues/45>).

## Design

libnetwork implements a **container network model (CNM)**. It formalizes the steps required to provide networking for containers, while providing an abstraction that can be used to support multiple network drivers. Its endpoint APIs are primarily used for managing the corresponding object and book-keeps them in order to provide a level of abstraction as required by the CNM model.

The CNM is built on three main components. The following figure shows the network sandbox model of libnetwork:



## CNM objects

Let's discuss the CNM objects in detail.

### Sandbox

This contains the configuration of a container's network stack, which includes management of routing tables, the container's interface, and DNS settings. An implementation of a sandbox can be a Linux network namespace, a FreeBSD jail, or other similar concept. A sandbox may contain many endpoints from multiple networks. It also represents a container's network configuration such as IP-address, MAC address, and DNS entries. libnetwork makes use of the OS-specific parameters to populate the network configuration represented by sandbox. libnetwork provides a framework to implement sandbox in multiple operating systems. Netlink is used to manage the routing table in namespace, and currently two implementations of sandbox exist, `namespace_linux.go` and `configure_linux.go`, to uniquely identify the path on the host filesystem.

A sandbox is associated with a single Docker container. The following data structure shows the runtime elements of a sandbox:

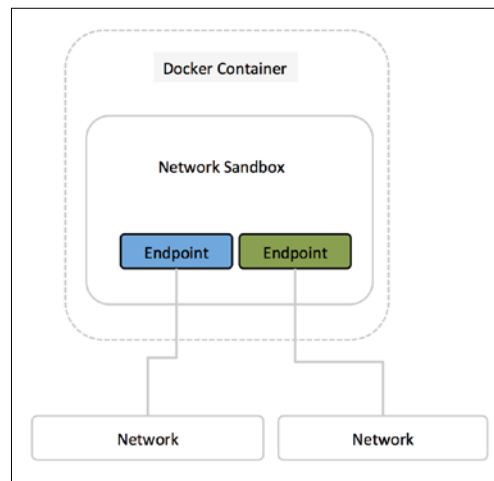
```
type sandbox struct {
    id            string
    containerID   string
    config        containerConfig
    osSbox        osl.Sandbox
    controller    *controller
    refCnt        int
    endpoints     epHeap
    epPriority     map[string]int
    joinLeaveDone  chan struct{}
    dbIndex       uint64
    dbExists      bool
    isStub        bool
    inDelete      bool
    sync.Mutex
}
```

A new sandbox is instantiated from a network controller (which is explained in more detail later):

```
func (c *controller) NewSandbox(containerID string, options
...SandboxOption) (Sandbox, error) {
    ...
}
```

## Endpoint

An endpoint joins a sandbox to the network and provides connectivity for services exposed by a container to the other containers deployed in the same network. It can be an internal port of Open vSwitch or a similar veth pair. An endpoint can belong to only one network but may only belong to one sandbox. An endpoint represents a service and provides various APIs to create and manage the endpoint. It has a global scope but gets attached to only one network, as shown in the following figure:



An endpoint is specified by the following data structure:

```
type endpoint struct {
    name          string
    id            string
    network       *network
    iface         *endpointInterface
    joinInfo      *endpointJoinInfo
    sandboxID     string
    exposedPorts  []types.TransportPort
    anonymous     bool
    generic       map[string]interface{}
    joinLeaveDone  chan struct{}
    prefAddress   net.IP
    prefAddressV6 net.IP
    ipamOptions   map[string]string
    dbIndex       uint64
    dbExists      bool
    sync.Mutex
}
```

An endpoint is associated with a unique ID and name. It is attached to a network and a sandbox ID. It is also associated with an IPv4 and IPv6 address space. Each endpoint is associated with an `endpointInterface` struct.

## Network

A network is a group of endpoints that are able to communicate with each other directly. It provides the required connectivity within the same host or multiple hosts, and whenever a network is created or updated, the corresponding driver is notified. An example is a VLAN or Linux bridge, which has a global scope within a cluster.

Networks are controlled from a network controller, which we will discuss in the next section. Every network has a name, address space, ID, and network type:

```
type network struct {
    ctrlr      *controller
    name       string
    networkType string
    id         string
    ipamType   string
    addrSpace  string
    ipamV4Config []*IpamConf
    ipamV6Config []*IpamConf
    ipamV4Info  []*IpamInfo
    ipamV6Info  []*IpamInfo
    enableIPv6  bool
    postIPv6    bool
    epCnt       *endpointCnt
    generic     options.Generic
    dbIndex     uint64
    svcRecords  svcMap
    dbExists    bool
    persist     bool
    stopWatchCh chan struct{}
    drvOnce     *sync.Once
    internal    bool
    sync.Mutex
}
```



## Network controller

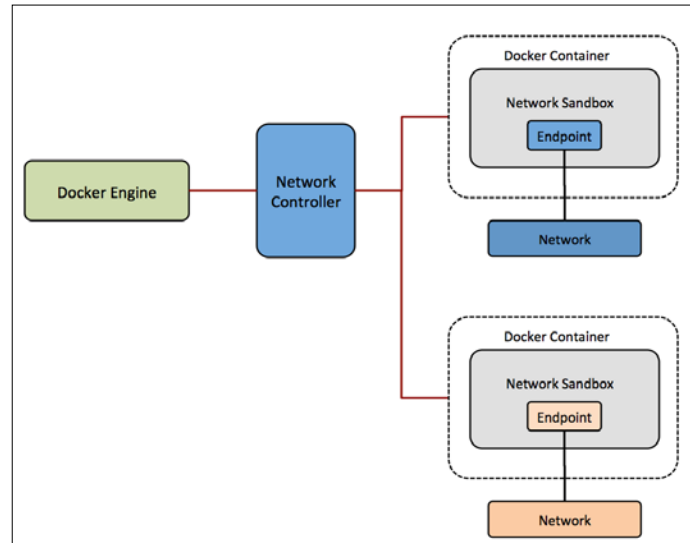
A network controller object provides APIs to create and manage a network object. It is an entry point in the libnetwork by binding a particular driver to a given network, and it supports multiple active drivers, both in-built and remote. Network controller allows users to bind a particular driver to a given network:

```
type controller struct {
    id            string
    drivers       driverTable
    ipamDrivers   ipamTable
    sandboxes     sandboxTable
    cfg           *config.Config
    stores        []datastore.DataStore
    discovery     hostdiscovery.HostDiscovery
    extKeyListener net.Listener
    watchCh       chan *endpoint
    unWatchCh     chan *endpoint
    svcDb         map[string]svcMap
    nmap          map[string]*netWatch
    defOsSbox     osl.Sandbox
    sboxOnce      sync.Once
    sync.Mutex
}
```

Each network controller has reference to the following:

- One or more drivers in the data structure driverTable
- One or more sandboxes in the data structure
- DataStore
- ipamTable

The following figure shows how **Network Controller** sits between the **Docker Engine** and the containers and networks they are attached to:



## CNM attributes

There are two types of attributes, as follows:

- **Options:** They are not end-user visible but are the key-value pairs of data to provide a flexible mechanism to pass driver-specific configuration from user to driver directly. libnetwork operates on the options only if the key matches a well-known label as a result value is picked up, which is represented by a generic object.
- **Labels:** They are a subset of options that are end-user variables represented in the UI using the `-labels` option. Their main function is to perform driver-specific operations and they are passed from the UI.

## CNM lifecycle

Consumers of the container network model interact through the CNM objects and its APIs to network the containers that they manage.

Drivers register with network controller. Built-in drivers register inside of libnetwork, while remote drivers register with libnetwork via a plugin mechanism (WIP). Each driver handles a particular network type.

A network controller object is created using the `libnetwork.New()` API to manage the allocation of networks and optionally configure a driver with driver-specific options.

The network is created using the controller's `NewNetwork()` API by providing a name and `networkType`. The `networkType` parameter helps to choose a corresponding driver and binds the created network to that driver. From this point, any operation on the network will be handled by that driver.

The `controller.NewNetwork()` API also takes in optional options parameters that carry driver-specific options and labels, which the drivers can make use for its purpose.

`network.CreateEndpoint()` can be called to create a new endpoint in a given network. This API also accepts optional options parameters that vary with the driver.

Drivers will be called with `driver.CreateEndpoint` and it can choose to reserve IPv4/IPv6 addresses when an endpoint is created in a network. The driver will assign these addresses using the `InterfaceInfo` interface defined in the driver API. The IPv4/IPv6 addresses are needed to complete the endpoint as a service definition along with the ports the endpoint exposes. A service endpoint is a network address and the port number that the application container is listening on.

`endpoint.Join()` can be used to attach a container to an endpoint. The `Join` operation will create a sandbox if it doesn't exist for that container. The drivers make use of the `sandbox` key to identify multiple endpoints attached to the same container.

There is a separate API to create an endpoint and another to join the endpoint.

An endpoint represents a service that is independent of the container. When an endpoint is created, it has resources reserved for the container to get attached to the endpoint later. It gives a consistent networking behavior.

`endpoint.Leave()` is invoked when a container is stopped. The driver can clean up the states that it allocated during the `Join()` call. `libnetwork` will delete the sandbox when the last referencing endpoint leaves the network.

`libnetwork` keeps holding on to IP addresses as long as the endpoint is still present. These will be reused when the container (or any container) joins again. It ensures that the container's resources are re-used when they are stopped and started again.

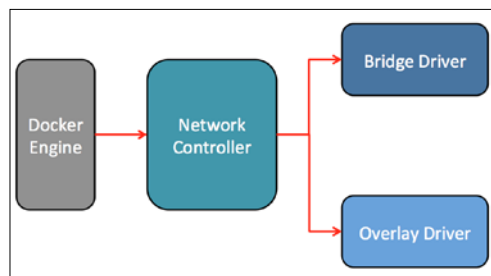
`endpoint.Delete()` is used to delete an endpoint from a network. This results in deleting the endpoint and cleaning up the cached `sandbox.Info`.

`network.Delete()` is used to delete a network. Delete is allowed if there are no endpoints attached to the network.

## Driver

A driver owns a network and is responsible for making the network work and manages it. Network controller provides an API to configure the driver with specific labels/options that are not directly visible to the user but are transparent to libnetwork and can be handled by drivers directly. Drivers can be both in-built (such as bridge, host, or overlay) and remote (from plugin providers) to be deployed in various use cases and deployment scenarios.

The driver owns the network implementation and is responsible for managing it, including **IP Address Management (IPAM)**. The following figure explains the process:



The following are the in-built drivers:

- **Null:** In order to provide backward compatibility with old `docker --net=none`, this option exists primarily in the case when no networking is required.
- **Bridge:** It provides a Linux-specific bridging implementation driver.
- **Overlay:** The overlay driver implements networking that can span multiple hosts network encapsulation such as VXLAN. We will be doing a deep-dive on two of its implementations: basic setup with Consul and Vagrant setup to deploy the overlay driver.
- **Remote:** It provides a means of supporting drivers over a remote transport and a specific driver can be written as per choice.

## Bridge driver

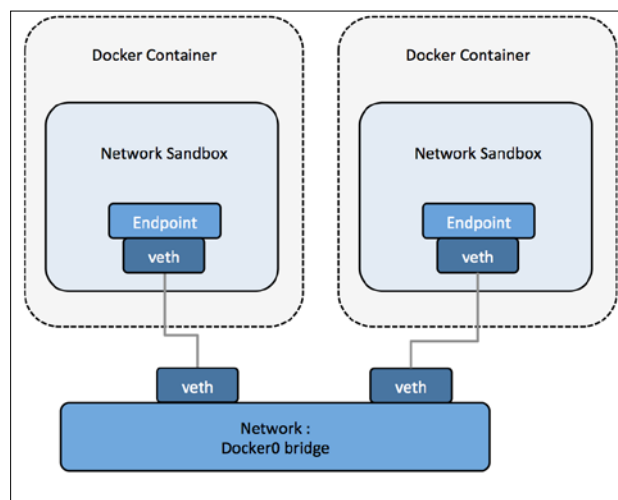
A bridge driver represents a wrapper on a Linux bridge acting as a network for libcontainer. It creates a veth pair for each network created. One end is connected to the container and the other end is connected to the bridge. The following data structure represents a bridge network:

```
type driver struct {  
    config      *configuration  
    etwork      *bridgeNetwork  
    natChain    *iptables.ChainInfo  
    filterChain *iptables.ChainInfo  
    networks    map[string]*bridgeNetwork  
    store       datastore.DataStore  
    sync.Mutex  
}
```

Some of the actions performed in a bridge driver:

- Configuring IPTables
- Managing IP forwarding
- Managing Port Mapping
- Enabling Bridge Net Filtering
- Setting up IPv4 and IPv6 on the bridge

The following diagram shows how the network is represented using `docker0` and `veth` pairs to connect endpoints with the `docker0` bridge:



## Overlay network driver

Overlay network in libnetwork uses VXLAN along with a Linux bridge to create an overlaid address space. It supports multi-host networking:

```
const (
    networkType = "overlay"
    vethPrefix  = "veth"
    vethLen     = 7
    vxlanIDStart = 256
    vxlanIDEnd   = 1000
    vxlanPort    = 4789
    vxlanVethMTU = 1450
)

type driver struct {
    eventCh      chan serf.Event
    notifyCh     chan ovNotify
    exitCh       chan chan struct{}
    bindAddress  string
    neighIP     string
    config       map[string]interface{}
    peerDb       peerNetworkMap
    serfInstance *serf.Serf
    networks     networkTable
    store        datastore.DataStore
    ipAllocator  *idm.Idm
    vxlanIdm     *idm.Idm
    once         sync.Once
    joinOnce     sync.Once
    sync.Mutex
}
```

## Using overlay network with Vagrant

Overlay network is created between two containers, and VXLAN tunnel connects the containers through a bridge.

## Overlay network deployment Vagrant setup

This setup has been deployed using the Docker experimental version, which keeps on updating regularly and might not support some of the features:

1. Clone the official libnetwork repository and switch to the docs folder:
 

```
$ git clone
$ cd libnetwork/docs
```

2. The Vagrant script pre-exists in the repository; we will deploy the three-node setup for our Docker overlay network driver testing by using the following command:

```
$ vagrant up
Bringing machine 'consul-server' up with 'virtualbox'
provider...
Bringing machine 'net-1' up with 'virtualbox' provider...
Bringing machine 'net-2' up with 'virtualbox' provider...
==> consul-server: Box 'ubuntu/trusty64' could not be found.
Attempting to find and install...
    consul-server: Box Provider: virtualbox
    consul-server: Box Version: >= 0
==> consul-server: Loading metadata for box 'ubuntu/trusty64'
    consul-server: URL: https://atlas.hashicorp.com/ubuntu/
trusty64
==> consul-server: Adding box 'ubuntu/trusty64'
(v20151217.0.0) for
provider: virtualbox
    consul-server: Downloading:
https://atlas.hashicorp.com/ubuntu/boxes/trusty64/versions/201
51217.0.0/providers/virtualbox.box
==> consul-server: Successfully added box 'ubuntu/trusty64'
(v20151217.0.0) for 'virtualbox'!
==> consul-server: Importing base box 'ubuntu/trusty64'...
==> consul-server: Matching MAC address for NAT networking...
==> consul-server: Checking if box 'ubuntu/trusty64' is up to
date...
==> consul-server: Setting the name of the VM:
libnetwork_consul-server_1451244524836_56275
==> consul-server: Clearing any previously set forwarded
ports...
==> consul-server: Clearing any previously set network
interfaces...
==> consul-server: Preparing network interfaces based on
configuration...
    consul-server: Adapter 1: nat
    consul-server: Adapter 2: hostonly
```

```

==> consul-server: Forwarding ports...
      consul-server: 22 => 2222 (adapter 1)
==> consul-server: Running 'pre-boot' VM customizations...
==> consul-server: Booting VM...
==> consul-server: Waiting for machine to boot. This may take
a few minutes...
consul-server:
101aac79c475b84f6aff48352ead467d6b2b63ba6b64cc1b93c630489f7e3f
4c
==> net-1: Box 'ubuntu/vivid64' could not be found. Attempting
to find and install...
      net-1: Box Provider: virtualbox
      net-1: Box Version: >= 0
==> net-1: Loading metadata for box 'ubuntu/vivid64'
      net-1: URL: https://atlas.hashicorp.com/ubuntu/vivid64
\=> net-1: Adding box 'ubuntu/vivid64' (v20151219.0.0) for
provider: virtualbox
      net-1: Downloading:
https://atlas.hashicorp.com/ubuntu/boxes/vivid64/versions/2015
1219.0.0/providers/virtualbox.box
contd...

```

3. We can list the deployed machine by Vagrant as follows:

```

$ vagrant status
Current machine states:
consul-server      running (virtualbox)
net-1              running (virtualbox)
net-2              running (virtualbox)

This environment represents multiple VMs. The VMs are all listed
above with their current state. For more information
about a specific VM, run `vagrant status NAME`.

```

4. The setup is complete thanks to the Vagrant script; now, we can SSH to the Docker hosts and start the testing containers:

```

$ vagrant ssh net-1
Welcome to Ubuntu 15.04 (GNU/Linux 3.19.0-42-generic x86_64)
* Documentation:https://help.ubuntu.com/
System information as of Sun Dec 27 20:04:06 UTC 2015
System load:  0.0                Users logged in:      0

```



```
Usage of /:    4.5% of 38.80GB   IP address for eth0:
10.0.2.15

Memory usage: 24%              IP address for eth1:
192.168.33.11

Swap usage:    0%              IP address for docker0:
172.17.0.1

Processes:     78

Graph this data and manage this system at:
https://landscape.canonical.com/

Get cloud support with Ubuntu Advantage Cloud Guest:
http://www.ubuntu.com/business/services/cloud
```

5. We can create a new Docker container, and inside the container we can list the contents of the `/etc/hosts` file in order to verify that it has the overlay bridge specification, which was previously deployed, and it automatically connects to it on the launch:

```
$ docker run -it --rm ubuntu:14.04 bash
Unable to find image 'ubuntu:14.04' locally
14.04: Pulling from library/ubuntu
6edcc89ed412: Pull complete
bdf37643ee24: Pull complete
ea0211d47051: Pull complete
a3ed95caeb02: Pull complete
Digest: sha256:d3b59c1d15c3cfb58d9f2eaab8a232f21fc670c67c11f582bc4
8fb32df17f3b3
Status: Downloaded newer image for ubuntu:14.04

root@65db9144c65b:/# cat /etc/hosts
172.21.0.4    2ac726b4ce60
127.0.0.1    localhost
::1 localhost ip6-localhost ip6-loopback
fe00::0 ip6-localnet
ff00::0 ip6-mcastprefix
ff02::1 ip6-allnodes
ff02::2 ip6-allrouters
172.21.0.3    distracted_bohr
172.21.0.3    distracted_bohr.multihost
172.21.0.4    modest_curie
172.21.0.4    modest_curie.multihost
```

6. Similarly, we can create the Docker container in the other host `net-2` as well and can verify the working of the overlay network driver as both the containers will be able to ping each other in spite of being deployed on different hosts.

In the previous example, we started the Docker container with the default options and they got automatically added to a multi-host network of type overlay.

We can also create a separate overlay bridge and add containers to it manually using the `--publish-service` option, which is part of Docker experimental:

```
vagrant@net-1:~$ docker network create -d overlay tester
447e75fd19b236e72361c270b0af4402c80e1f170938fb22183758c444966427
vagrant@net-1:~$ docker network ls
```

NETWORK ID	NAME	DRIVE
447e75fd19b2	tester	overlay
b77a7d741b45	bridge	bridge
40fe7cfeee20	none	null
62072090b6ac	host	host

The second host will also see this network and we can create containers added to the overlay network in both of these hosts by using the following option in the Docker command:

```
$ docker run -it --rm --publish-service=bar.testester.overlay
ubuntu:14.04 bash
```

We will be able to verify the working of the overlay driver as both the containers will be able to ping each other. Also, tools such as `tcpdump`, `wireshark`, `smartsniff`, and so on can be used to capture the vXLAN package.

## Overlay network with Docker Machine and Docker Swarm

This section explains the basics of creating a multi-host network. The Docker Engine supports multi-host networking through the overlay network driver. Overlay drivers need the following pre-requisites to work:

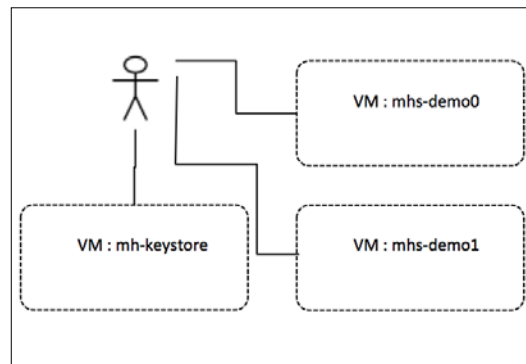
- 3.16 Linux kernel or higher
- Access to a key-value store
- Docker supports the following key-value stores: Consul, etcd, and ZooKeeper

- A cluster of hosts connected to the key-value store
- Docker Engine daemon on each host in the cluster

This example uses Docker Machine and Docker Swarm to create the multi-network host.

Docker Machine is used to create the key-value store server and the cluster. The cluster created is a Docker Swarm cluster.

The following diagram explains how three VMs are set up using Docker Machine:



## Prerequisites

- Vagrant
- Docker Engine
- Docker Machine
- Docker Swarm

## Key-value store installation

An overlay network requires a key-value store. The key-value store stores information about the network state such as discovery, networks, endpoints, IP addresses, and so on. Docker supports various key-value stores such as Consul, etcd, and Zoo Keeper. This section has been implemented using Consul.

The following are the steps to install key-value store:

1. Provision a VirtualBox virtual machine called `mh-keystore`.

When a new VM is provisioned, the process adds the Docker Engine to the host. Consul instance will be using the consul image from the Docker Hub account (<https://hub.docker.com/r/progrium/consul/>):

```
$ docker-machine create -d virtualbox mh-keystore
Running pre-create checks...
Creating machine...
(mh-keystore) Creating VirtualBox VM...
(mh-keystore) Creating SSH key...
(mh-keystore) Starting VM...
Waiting for machine to be running, this may take a few minutes...
Machine is running, waiting for SSH to be available...
Detecting operating system of created instance...
Detecting the provisioner...
Provisioning with boot2docker...
Copying certs to the local machine directory...
Copying certs to the remote machine...
Setting Docker configuration on the remote daemon...
Checking connection to Docker...
Docker is up and running!
To see how to connect Docker to this machine, run: docker-
machine env mh-keystore
```

2. Start the `progrium/consul` container created previously running on the `mh-keystore` virtual machine:

```
$ docker $(docker-machine config mh-keystore) run -d \
> -p "8500:8500" \
> -h "consul" \
> progrium/consul -server -bootstrap

Unable to find image 'progrium/consul:latest' locally
latest: Pulling from progrium/consul
3b4d28ce80e4: Pull complete
...
d9125e9e799b: Pull complete
```

```
Digest:
sha256:8cc8023462905929df9a79ff67ee435a36848ce7a10f18d6d0faba9
306b97274
```

```
Status: Downloaded newer image for progrium/consul:latest
032884c7834ce22707ed08068c24c503d599499f1a0a58098c31be9cc84d8e
6c
```

A bash expansion `$(docker-machine config mh-keystore)` is used to pass the connection configuration to the `Docker run` command. The client starts a program from the `progrium/consul` image running in the `mh-keystore` machine. The container is called `consul` (flag `-h`) and is listening on port 8500 (you can choose any other port as well).

3. Set the local environment to the `mh-keystore` virtual machine:

```
$ eval "$(docker-machine env mh-keystore)"
```

4. Execute the `docker ps` command to make sure the Consul container is up:

```
$ docker ps
```

CONTAINER ID	IMAGE	COMMAND
032884c7834c	progrium/consul	"/bin/start -server -"
seconds ago		47
STATUS	PORTS	
Up 46 seconds	53/tcp, 53/udp, 8300-8302/tcp, 8301-8302/udp, 8400/tcp, 0.0.0.0:8500->8500/tcp	
NAMES		
sleepy_austin		

Output has been formatted to fit in the page.

## Create a Swarm cluster with two nodes

In this step, we will use Docker Machine to provision two hosts for your network. We will create two virtual machines in VirtualBox. One of the machines will be Swarm master, which will be created first.

As each host is created, options for the overlay network driver will be passed to the Docker Engine using Swarm using the following steps:

1. Create a Swarm master virtual machine `mhs-demo0`:

```
$ docker-machine create \
-d virtualbox \
--swarm --swarm-master \
```

---

```
--swarm-discovery="consul://$(docker-machine ip mh-keystore):8500" \
--engine-opt="cluster-store=consul://$(docker-machine ip mh-keystore):8500" \
--engine-opt="cluster-advertise=eth1:2376" \
mhs-demo0
```

At creation time, you supply the engine daemon with the `--cluster-store` option. This option tells the engine the location of the key-value store for the overlay network. The bash expansion `$(docker-machine ip mh-keystore)` resolves to the IP address of the Consul server you created in step 1 of the preceding section. The `--cluster-advertise` option advertises the machine on the network.

2. Create another virtual machine `mhs-demo1` and add it to the Docker Swarm cluster:

```
$ docker-machine create -d virtualbox \
    --swarm \
    --swarm-discovery="consul://$(docker-machine ip mh-keystore):8500" \
    --engine-opt="cluster-store=consul://$(docker-machine ip mh-keystore):8500" \
    --engine-opt="cluster-advertise=eth1:2376" \
mhs-demo1
```

```
Running pre-create checks...
```

```
Creating machine...
```

```
(mhs-demo1) Creating VirtualBox VM...
```

```
(mhs-demo1) Creating SSH key...
```

```
(mhs-demo1) Starting VM...
```

```
Waiting for machine to be running, this may take a few minutes...
```

```
Machine is running, waiting for SSH to be available...
```

```
Detecting operating system of created instance...
```

```
Detecting the provisioner...
```

```
Provisioning with boot2docker...
```

```
Copying certs to the local machine directory...
```

```
Copying certs to the remote machine...
```

```
Setting Docker configuration on the remote daemon...
```

```
Configuring swarm...
Checking connection to Docker...
Docker is up and running!
To see how to connect Docker to this machine, run: docker-
machine env mhs-demo1
```

3. List virtual machines using Docker Machine to confirm that they are all up and running:

```
$ docker-machine ls
```

NAME	ACTIVE	DRIVER	STATE	URL
SWARM		DOCKER	ERRORS	
mh-keystore	*	virtualbox	Running	
tcp://192.168.99.100:2376				v1.9.1
mhs-demo0	-	virtualbox	Running	
tcp://192.168.99.101:2376		mhs-demo0 (master)		v1.9.1
mhs-demo1	-	virtualbox	Running	
tcp://192.168.99.102:2376		mhs-demo0		v1.9.1

At this point, virtual machines are running. We are ready to create a multi-host network for containers using these virtual machines.

## Creating an overlay network

The following command is used to create an overlay network:

```
$ docker network create --driver overlay my-net
```

We will only need to create the network on a single host in the Swarm cluster. We used the Swarm master but this command can run on any host in the Swarm cluster:

1. Check that the overlay network is running using the following command:

```
$ docker network ls
```

```
bd85c87911491d7112739e6cf08d732eb2a2841c6calefcc04d0b20bbb832a33
rdual-ltm:overlay-tutorial rdua$ docker network ls
```

NETWORK ID	NAME	DRIVER
bd85c8791149	my-net	overlay
fff23086faa8	mhs-demo0/bridge	bridge
03dd288a8adb	mhs-demo0/none	null
2a706780454f	mhs-demo0/host	host

---

f6152664c40a	mhs-demo1/bridge	bridge
ac546be9c37c	mhs-demo1/none	null
c6a2de6ba6c9	mhs-demo1/host	host

Since we are using the Swarm master environment, we are able to see all the networks on all the Swarm agents: the default networks on each engine and the single overlay network. In this case, there are two engines running on mhs-demo0 and mhs-demo1.

Each NETWORK ID is unique.

2. Switch to each Swarm agent in turn and list the networks:

```
$ eval $(docker-machine env mhs-demo0)
```

```
$ docker network ls
```

NETWORK ID	NAME	DRIVER
bd85c8791149	my-net	overlay
03dd288a8adb	none	null
2a706780454f	host	host
fff23086faa8	bridge	bridge

```
$ eval $(docker-machine env mhs-demo1)
```

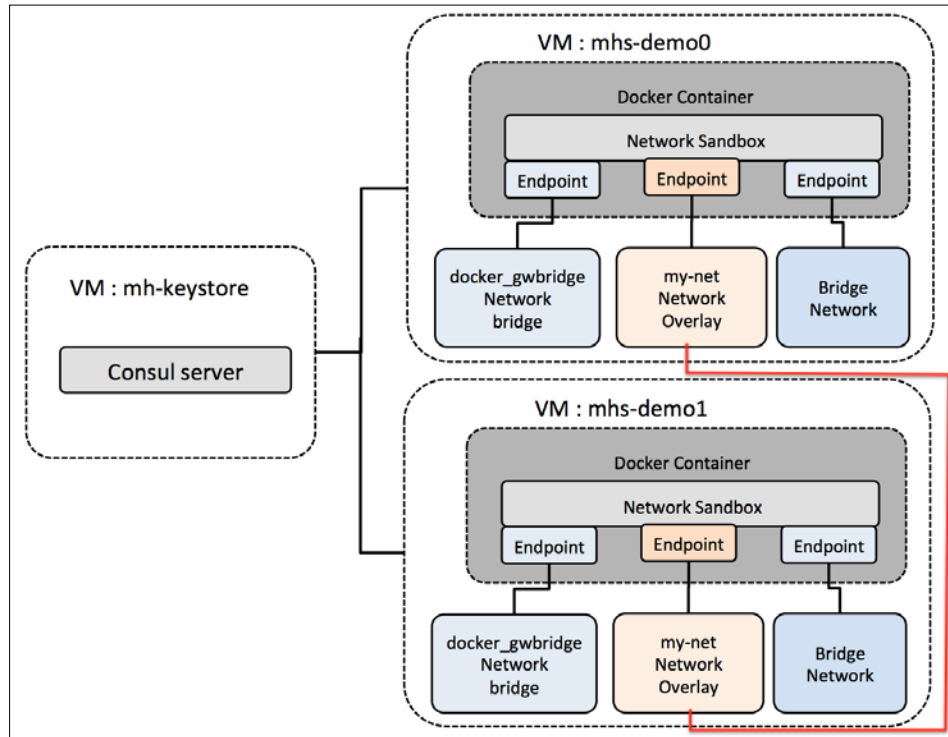
```
$ docker network ls
```

NETWORK ID	NAME	DRIVER
bd85c8791149	my-net	overlay
358c45b96beb	docker_gwbridge	bridge
f6152664c40a	bridge	bridge
ac546be9c37c	none	null
c6a2de6ba6c9	host	host

Both agents report they have the my-net network with the overlay driver. We have a multi-host overlay network running.



The following figure shows how two containers will have containers created and tied together using the overlay my-net:



## Creating containers using an overlay network

The following are the steps for creating containers using an overlay network:

1. Create a container **c0** on **mhs-demo0** and connect to the **my-net** network:

```
$ eval $(docker-machine env mhs-demo0)
```

```
root@843b16belae1:/#
```

```
$ sudo docker run -i -t --name=c0 --net=my-net debian  
/bin/bash
```

Execute `ifconfig` to find the IP address of `c0`. In this case, it is `10.0.0.4`:

```
root@843b16belael:/# ifconfig
eth0      Link encap:Ethernet  HWaddr 02:42:0a:00:00:04
          inet addr:10.0.0.4  Bcast:0.0.0.0  Mask:255.255.255.0
          inet6 addr: fe80::42:aff:fe00:4/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1450  Metric:1
          RX packets:17 errors:0 dropped:0 overruns:0 frame:0
          TX packets:17 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:1474 (1.4 KB)  TX bytes:1474 (1.4 KB)

eth1      Link encap:Ethernet  HWaddr 02:42:ac:12:00:03
          inet addr:172.18.0.3  Bcast:0.0.0.0  Mask:255.255.0.0
          inet6 addr: fe80::42:acff:fe12:3/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:8 errors:0 dropped:0 overruns:0 frame:0
          TX packets:8 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:648 (648.0 B)  TX bytes:648 (648.0 B)

lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          inet6 addr: ::1/128 Scope:Host
          UP LOOPBACK RUNNING  MTU:65536  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
```

2. Create a container, `c1` on `mhs-demo1`, and connect to the `my-net` network:

```
$ eval $(docker-machine env mhs-demo1)

$ sudo docker run -i -t --name=c1 --net=my-net debian /bin/bash
Unable to find image 'ubuntu:latest' locally
latest: Pulling from library/ubuntu
0bf056161913: Pull complete
```

```
1796d1c62d0c: Pull complete
e24428725dd6: Pull complete
89d5d8e8bafb: Pull complete
Digest:
sha256:a2b67b6107aa640044c25a03b9e06e2a2d48c95be6ac17fb1a387e7
5eebafd7c
Status: Downloaded newer image for ubuntu:latest
root@2ce83e872408:/#
```

3. Execute `ifconfig` to find the IP address of `c1`. In this case, it is `10.0.0.3`:

```
root@2ce83e872408:/# ifconfig
eth0      Link encap:Ethernet  HWaddr 02:42:0a:00:00:03
          inet addr:10.0.0.3  Bcast:0.0.0.0
Mask:255.255.255.0
          inet6 addr: fe80::42:aff:fe00:3/64 Scope:Link
UP BROADCAST RUNNING MULTICAST  MTU:1450  Metric:1
RX packets:13 errors:0 dropped:0 overruns:0 frame:0
TX packets:7 errors:0 dropped:0 overruns:0 carrier:0
collisions:0 txqueuelen:0
RX bytes:1066 (1.0 KB)  TX bytes:578 (578.0 B)

eth1      Link encap:Ethernet  HWaddr 02:42:ac:12:00:02
          inet addr:172.18.0.2  Bcast:0.0.0.0
Mask:255.255.0.0
          inet6 addr: fe80::42:acff:fe12:2/64 Scope:Link
UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
RX packets:7 errors:0 dropped:0 overruns:0 frame:0
TX packets:7 errors:0 dropped:0 overruns:0 carrier:0
collisions:0 txqueuelen:0
RX bytes:578 (578.0 B)  TX bytes:578 (578.0 B)

lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          inet6 addr: ::1/128 Scope:Host
UP LOOPBACK RUNNING  MTU:65536  Metric:1
RX packets:0 errors:0 dropped:0 overruns:0 frame:0
TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
collisions:0 txqueuelen:0
RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
```

4. Ping c1 (10.0.0.3) from c0 (10.0.0.4) and vice versa:

```
root@2ce83e872408:/# ping 10.0.0.4
PING 10.0.0.4 (10.0.0.4) 56(84) bytes of data.
64 bytes from 10.0.0.4: icmp_seq=1 ttl=64 time=0.370 ms
64 bytes from 10.0.0.4: icmp_seq=2 ttl=64 time=0.443 ms
64 bytes from 10.0.0.4: icmp_seq=3 ttl=64 time=0.441 ms
```

## Container network interface

**Container network interface (CNI)** is a specification that defines how executable plugins can be used to configure network interfaces for Linux application containers. The official GitHub repository of CNI explains how a go library explains the implementing specification.

The container runtime first creates a new network namespace for the container in which it determines which network this container should belong to and which plugins to be executed. The network configuration is in the JSON format and defines on the container startup which plugin should be executed for the network. CNI is actually an evolving open source technology that is derived from the rkt networking protocol. Each CNI plugin is implemented as an executable and is invoked by a container management system, docker, or rkt.

After inserting the container in the network namespace, namely by attaching one end of a veth pair to a container and attaching the other end to a bridge, it then assigns an IP to the interface and sets up routes consistent with IP address management by invoking an appropriate IPAM plugin.

The CNI model is currently used for the networking of kubelets in the Kubernetes model. Kubelets are the most important components of Kubernetes nodes, which takes the load of running containers on top of them.

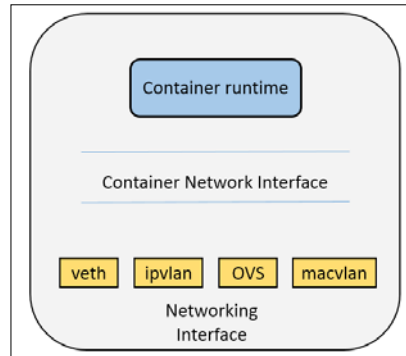
The package CNI for kubelet is defined in the following Kubernetes package:

Constants

```
const (
    CNIPluginName      = "cni"
    DefaultNetDir      = "/etc/cni/net.d"
    DefaultCNIDir      = "/opt/cni/bin"
    DefaultInterfaceName = "eth0"
```

```
VendorCNIDirTemplate = "%s/opt/%s/bin"
)
func ProbeNetworkPlugins
func ProbeNetworkPlugins(pluginDir string) []network.NetworkPlugin
```

The following figure shows the CNI placement:



## CNI plugin

As per the official GitHub repository (<https://github.com/appc/cni>), the parameters that the CNI plugin need in order to add a container to the network are:

- **Version:** The version of CNI spec that the caller is using (container call invoking the plugin).
- **Container ID:** This is optional, but recommended, and defines that there should be a unique ID across an administrative domain while the container is live. For example, the IPAM system may require that each container is allocated a unique ID so that it can be correlated properly to a container running in the background.
- **Network namespace path:** This represents the path to the network namespace to be added, for example, `/proc/[pid]/ns/net` or a `bind-mount/link` to it.
- **Network configuration:** It is the JSON document that describes a network to which a container can be joined and is explained in the following section.
- **Extra arguments:** It allows granular configuration of CNI plugins on a per-container basis.
- **Name of the interface inside the container:** It is the name that gets assigned to the container and complies with Linux restriction, which exists for interface names.

The results achieved are as follows:

- **IPs assigned to the interface:** This is either an IPv4 address or an IPv6 address assigned to the network as per requirements.
- **List of DNS nameservers:** This is a priority-ordered address list of DNS name servers.

## Network configuration

The network configuration is in the JSON format that can be stored on disk or generated from other sources by container runtime. The following fields in the JSON have importance, as explained in the following:

- **cniVersion (string):** It is Semantic Version 2.0 of the CNI specification to which this configuration meets.
- **name (string):** It is the network name. It is unique across all containers on the host (or other administrative domain).
- **type (string):** Refers to the filename of the CNI plugin executable.
- **ipMasq (boolean):** Optional, sets up an IP masquerade on the host as it is necessary for the host to act as a gateway to subnets that are not able to route to the IP assigned to the container.
- **ipam:** Dictionary with IPAM-specific values.
- **type (string):** Refers to the filename of the IPAM plugin executable.
- **routes (list):** List of subnets (in CIDR notation) that the CNI plugin should make sure are reachable by routing through the network. Each entry is a dictionary containing:
  - **dst (string):** A subnet in CIDR notation
  - **gw (string):** It is the IP address of the gateway to use. If not specified, the default gateway for the subnet is assumed (as determined by the IPAM plugin).

An example configuration for plugin-specific OVS is as follows:

```
{
  "cniVersion": "0.1.0",
  "name": "pci",
  "type": "ovs",
  // type (plugin) specific
  "bridge": "ovs0",
  "vxlanID": 42,
  "ipam": {
```

```
    "type": "dhcp",
    "routes": [ { "dst": "10.3.0.0/16" }, { "dst": "10.4.0.0/16" } ]
  }
}
```

## IP allocation

The CNI plugin assigns an IP address to the interface and installs necessary routes for the interface, thus it provides great flexibility for the CNI plugin and many CNI plugins internally have the same code to support several IP management schemes.

To lessen the burden on the CNI plugin, a second type of plugin, **IP address management plugin (IPAM)**, is defined, which determines the interface IP/subnet, gateway, and routes and returns this information to the main plugin to apply. The IPAM plugin obtains information via a protocol, `ipam` section defined in the network configuration file, or data stored on the local filesystem.

## IP address management interface

The IPAM plugin is invoked by running an executable, which is searched in a predefined path and is indicated by a CNI plugin via `CNI_PATH`. The IPAM plugin receives all the system environment variables from this executable, which are passed to the CNI plugin.

IPAM receives a network configuration file via `stdin`. Success is indicated by a zero return code and the following JSON, which gets printed to `stdout` (in the case of the `ADD` command):

```
{
  "cniVersion": "0.1.0",
  "ip4": {
    "ip": <ipv4-and-subnet-in-CIDR>,
    "gateway": <ipv4-of-the-gateway>, (optional)
    "routes": <list-of-ipv4-routes> (optional)
  },
  "ip6": {
    "ip": <ipv6-and-subnet-in-CIDR>,
    "gateway": <ipv6-of-the-gateway>, (optional)
    "routes": <list-of-ipv6-routes> (optional)
  },
  "dns": <list-of-DNS-nameservers> (optional)
}
```

The following is an example of running Docker networking with CNI:

1. First, install Go Lang 1.4+ and jq (command line JSON processor) to build the CNI plugins:

```
$ wget https://storage.googleapis.com/golang/go1.5.2.linux-amd64.tar.gz
$ tar -C /usr/local -xzf go1.5.2.linux-amd64.tar.gz
$ export PATH=$PATH:/usr/local/go/bin
$ go version
go version go1.5.2 linux/amd64
$ sudo apt-get install jq
```

2. Clone the official CNI GitHub repository:

```
$ git clone https://github.com/appc/cni.git
Cloning into 'cni'...
remote: Counting objects: 881, done.
remote: Total 881 (delta 0), reused 0 (delta 0), pack-reused 881
Receiving objects: 100% (881/881), 543.54 KiB | 313.00 KiB/s, done.
Resolving deltas: 100% (373/373), done.
Checking connectivity... done.
```

3. We will now create a `netconf` file in order to describe the network:

```
mkdir -p /etc/cni/net.d
root@rajdeepd-virtual-machine:~# cat >/etc/cni/net.d/10-mynet.conf <<EOF
>{
>  "name": "mynet",
>  "type": "bridge",
>  "bridge": "cni0",
>  "isGateway": true,
>  "ipMasq": true,
>  "ipam": {
>    "type": "host-local",
>    "subnet": "10.22.0.0/16",
>    "routes": [
>      { "dst": "0.0.0.0/0" }
>    ]
>  }
```



```
> }  
>}  
> EOF
```

4. Build the CNI plugins:

```
~/cni$ ./build  
Building API  
Building reference CLI  
Building plugins  
  flannel  
  bridge  
  ipvlan  
  macvlan  
  ptp  
  dhcp  
  host-local
```

5. Now we will execute the `priv-net-run.sh` script in order to create the private network with the CNI plugin:

```
~/cni/scripts$ sudo CNI_PATH=$CNI_PATH ./priv-net-run.sh  
ifconfig  
  
eth0      Link encap:Ethernet  HWaddr 8a:72:75:7d:6d:6c  
          inet addr:10.22.0.2  Bcast:0.0.0.0  Mask:255.255.0.0  
          inet6 addr: fe80::8872:75ff:fe7d:6d6c/64 Scope:Link  
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1  
          RX packets:1 errors:0 dropped:0 overruns:0 frame:0  
          TX packets:1 errors:0 dropped:0 overruns:0 carrier:0  
          collisions:0 txqueuelen:0  
          RX bytes:90 (90.0 B)  TX bytes:90 (90.0 B)  
  
lo        Link encap:Local Loopback  
          inet addr:127.0.0.1  Mask:255.0.0.0  
          inet6 addr: ::1/128 Scope:Host  
          UP LOOPBACK RUNNING  MTU:65536  Metric:1  
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0  
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0  
          collisions:0 txqueuelen:0  
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
```

- Run a Docker container with the network namespace, which was set up previously using the CNI plugin:

```
~/cni/scripts$ sudo CNI_PATH=$CNI_PATH ./docker-run.sh --rm
busybox:latest /bin/ifconfig

eth0      Link encap:Ethernet  HWaddr 92:B2:D3:E5:BA:9B
          inet addr:10.22.0.2  Bcast:0.0.0.0  Mask:255.255.0.0
          inet6 addr: fe80::90b2:d3ff:fee5:ba9b/64 Scope:Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:2 errors:0 dropped:0 overruns:0 frame:0
          TX packets:2 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:180 (180.0 B)  TX bytes:168 (168.0 B)

lo        Link encap:Local Loopback
          inet addr:127.0.0.1  Mask:255.0.0.0
          inet6 addr: ::1/128 Scope:Host
          UP LOOPBACK RUNNING  MTU:65536  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:0
          RX bytes:0 (0.0 B)  TX bytes:0 (0.0 B)
```

## Project Calico's libnetwork driver

Calico provides a scalable networking solution for connecting containers, VMs, or bare metal. Calico provides connectivity using the scalable IP networking principle as a layer 3 approach. Calico can be deployed without overlays or encapsulation. The Calico service should be deployed as a container on each node and provides each container with its own IP address. It also handles all the necessary IP routing, security policy rules, and distribution of routes across a cluster of nodes.

The Calico architecture contains four important components in order to provide a better networking solution:

- Felix, the Calico worker process, is the heart of Calico networking, which primarily routes and provides desired connectivity to and from the workloads on host. It also provides the interface to kernels for outgoing endpoint traffic.

- BIRD, the route distribution open source BGP, exchanges routing information between hosts. The kernel endpoints, which are picked up by BIRD, are distributed to BGP peers in order to provide inter-host routing. Two BIRD processes run in the calico-node container, IPv4 (bird) and one for IPv6 (bird6).
- Confd, a templating process to auto-generate configuration for BIRD, monitors the etcd store for any changes to BGP configuration such as log levels and IPAM information. Confd also dynamically generates BIRD configuration files based on data from etcd and triggers automatically as updates are applied to data. Confd triggers BIRD to load new files whenever a configuration file is changed.
- calicoctl, the command line used to configure and start the Calico service, even allows the datastore (etcd) to define and apply security policy. The tool also provides the simple interface for general management of Calico configuration irrespective of whether Calico is running on VMs, containers, or bare metal. The following commands are supported at calicoctl:

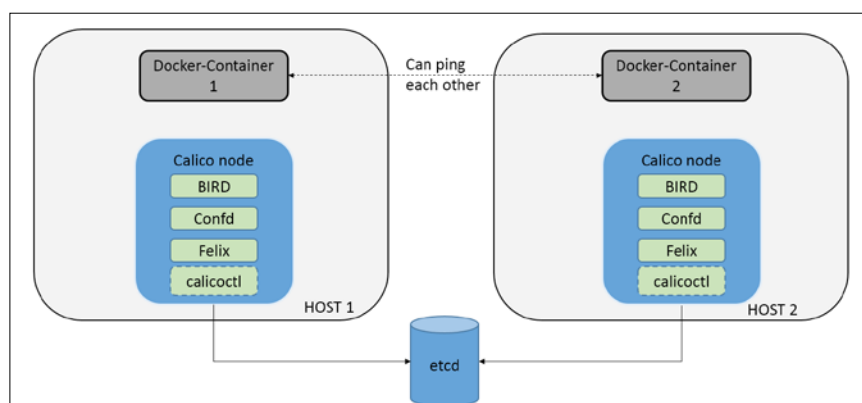
```
$ calicoctl
Override the host:port of the ETCD server by setting the
environment variable ETCD_AUTHORITY [default: 127.0.0.1:2379]
Usage: calicoctl <command> [<args>...]

status          Print current status information
node            Configure the main calico/node container and
establish Calico networking
container       Configure containers and their addresses
profile         Configure endpoint profiles
endpoint        Configure the endpoints assigned to existing
containers
pool            Configure ip-pools
bgp             Configure global bgp
ipam            Configure IP address management
checksystem     Check for incompatibilities on the host
system
diags           Save diagnostic information
version         Display the version of calicoctl
config          Configure low-level component configuration
See 'calicoctl <command> --help' to read about a specific
subcommand.
```

As per the official GitHub page of the Calico repository (<https://github.com/projectcalico/calico-containers>), the following integration of Calico exists:

- Calico as a Docker network plugin
- Calico without Docker networking
- Calico with Kubernetes
- Calico with Mesos
- Calico with Docker Swarm

The following figure shows the Calico architecture:



In the following tutorial we will run the manual set up of Calico on a single node machine with Docker 1.9, which finally brings libnetwork out of its experimental version to main release, and Calico can be configured directly without the need of other Docker experimental versions:

1. Get the etcd latest release and configure it on the default port 2379:

```
$ curl -L
https://github.com/coreos/etcd/releases/download/v2.2.1/etcd-
v2.2.1-linux-amd64.tar.gz -o etcd-v2.2.1-linux-amd64.tar.gz
  % Total    % Received % Xferd  Average Speed   Time    Time
Time  Current
                                 Dload  Upload  Total  Spent
Left  Speed
100  606    0  606    0    0   445      0  --:--:--
0:00:01 --:--:--  446
100 7181k 100 7181k    0    0  441k      0  0:00:16
0:00:16 --:--:-- 1387k
$ tar xzvf etcd-v2.2.1-linux-amd64.tar.gz
etcd-v2.2.1-linux-amd64/
```

```
etcd-v2.2.1-linux-amd64/Documentation/  
etcd-v2.2.1-linux-amd64/Documentation/04_to_2_snapshot_migration.  
md  
etcd-v2.2.1-linux-amd64/Documentation/admin_guide.md  
etcd-v2.2.1-linux-amd64/Documentation/api.md  
contd..  
etcd-v2.2.1-linux-amd64/etcd  
etcd-v2.2.1-linux-amd64/etcdctl  
etcd-v2.2.1-linux-amd64/README-etcdctl.md  
etcd-v2.2.1-linux-amd64/README.md
```

```
$ cd etcd-v2.2.1-linux-amd64
```

```
$ ./etcd
```

```
2016-01-06 15:50:00.065733 I | etcdmain: etcd Version: 2.2.1  
2016-01-06 15:50:00.065914 I | etcdmain: Git SHA: 75f8282  
2016-01-06 15:50:00.065961 I | etcdmain: Go Version: go1.5.1  
2016-01-06 15:50:00.066001 I | etcdmain: Go OS/Arch: linux/amd64  
Contd..  
2016-01-06 15:50:00.107972 I | etcdserver: starting server...  
[version: 2.2.1, cluster version: 2.2]  
2016-01-06 15:50:00.508131 I | raft: ce2a822cea30bfca is  
starting a new election at term 5  
2016-01-06 15:50:00.508237 I | raft: ce2a822cea30bfca became  
candidate at term 6  
2016-01-06 15:50:00.508253 I | raft: ce2a822cea30bfca received  
vote from ce2a822cea30bfca at term 6  
2016-01-06 15:50:00.508278 I | raft: ce2a822cea30bfca became  
leader at term 6  
2016-01-06 15:50:00.508313 I | raft: raft.node:  
ce2a822cea30bfca elected leader ce2a822cea30bfca at term 6  
2016-01-06 15:50:00.509810 I | etcdserver: published  
{Name:default ClientURLs:[http://localhost:2379  
http://localhost:4001]} to cluster 7e27652122e8b2ae
```

2. Open the new terminal and configure the Docker daemon with the etcd key-value store by running the following commands:

```
$ service docker stop
```

```
$ docker daemon --cluster-store=etcd://0.0.0.0:2379
```

```
INFO[0000] [graphdriver] using prior storage driver "aufs"
```

```

INFO[0000] API listen on /var/run/docker.sock
INFO[0000] Firewall running: false
INFO[0015] Default bridge (docker0) is assigned with an IP
address 172.16.59.1/24. Daemon option --bip can be used to set
a preferred IP address
WARN[0015] Your kernel does not support swap memory limit.
INFO[0015] Loading containers: start.
.....INFO[0034] Skipping update of resolv.conf file with
ipv6Enabled: false because file was touched by user
INFO[0043] Loading containers: done.
INFO[0043] Daemon has completed initialization
INFO[0043] Docker daemon      commit=a34ald5
execdriver=native-0.2 graphdriver=aufs version=1.9.1
INFO[0043] GET /v1.21/version
INFO[0043] GET /v1.21/version
INFO[0043] GET /events
INFO[0043] GET /v1.21/version

```

3. Now, in the new terminal, start the Calico container in the following way:

```

$ ./calicoctl node --libnetwork
No IP provided. Using detected IP: 10.22.0.1
Pulling Docker image calico/node:v0.10.0
Calico node is running with id:
79e75fa6d875777d31b8aeadd10c2712f54485c031df50667edb4d7d7cb6bb2
6c
Pulling Docker image calico/node-libnetwork:v0.5.2
Calico libnetwork driver is running with id:
bc7d65f6ab854b20b9b855abab4776056879f6edbcde9d744f218e556439997f
$ docker ps

```

CONTAINER ID	IMAGE	COMMAND
CREATED	STATUS	PORTS
NAMES		
7bb7a956af37	calico/node-libnetwork:v0.5.2	"/sbin/start_
"/start.sh"	3 minutes ago	Up 3 minutes
	calico-libnetwork	
13a0314754d6	calico/node:v0.10.0	"/sbin/start_
runit"	3 minutes ago	Up 3 minutes
	calico-node	
1f13020cc3a0	weaveworks/plugin:1.4.1	"/home/weave/
plugin"	3 days ago	Up 3 minutes
	weaveplugin	

4. Create the Calico bridge using the `docker network` command recently introduced in the Docker CLI:

```
$docker network create -d calico net1
```

```
$ docker network ls
```

NETWORK ID	NAME	DRIVER
9b5f06307cf2	docker_gwbridge	bridge
1638f754fbaf	host	host
02b10aaa25d7	weave	weavemesh
65dc3cbcd2c0	bridge	bridge
f034d78cc423	net1	calico

5. Start the busybox container connected to the Calico `net1` bridge:

```
$docker run --net=net1 -itd --name=container1 busybox
```

```
1731629b6897145822f73726194b1f7441b6086ee568e973d8a88b554e838366
```

```
$ docker ps
```

CONTAINER ID	IMAGE	COMMAND
CREATED	STATUS	NAMES
1731629b6897	busybox	"sh"
6 seconds ago	Up 5 seconds	
container1		
7bb7a956af37	calico/node-libnetwork:v0.5.2	"/
start.sh"	6 minutes ago	Up 6 minutes
calico-libnetwork		
13a0314754d6	calico/node:v0.10.0	"/
sbin/start_runit"	6 minutes ago	Up 6 minutes
calico-node		
1f13020cc3a0	weaveworks/plugin:1.4.1	"/
home/weave/plugin"	3 days ago	Up 6 minutes
weaveplugin		

```
$ docker attach 1731
```

```
/ #
```

```
/ # ifconfig
```

```
cali0      Link encap:Ethernet  HWaddr EE:EE:EE:EE:EE:EE
            inet addr:10.0.0.2  Bcast:0.0.0.0
Mask:255.255.255.0

            inet6 addr: fe80::ecee:eeff:feee:eeee/64 Scope:Link
UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
RX packets:29 errors:0 dropped:0 overruns:0 frame:0
```

```
TX packets:8 errors:0 dropped:0 overruns:0 carrier:0
collisions:0 txqueuelen:1000
RX bytes:5774 (5.6 KiB) TX bytes:648 (648.0 B)

eth1    Link encap:Ethernet  HWaddr 02:42:AC:11:00:02
        inet addr:172.17.0.2 Bcast:0.0.0.0
Mask:255.255.0.0
        inet6 addr: fe80::42:acff:fe11:2/64 Scope:Link
        UP BROADCAST RUNNING MULTICAST MTU:1500 Metric:1
        RX packets:21 errors:0 dropped:0 overruns:0 frame:0
        TX packets:8 errors:0 dropped:0 overruns:0 carrier:0
        collisions:0 txqueuelen:0
        RX bytes:4086 (3.9 KiB) TX bytes:648 (648.0 B)

lo      Link encap:Local Loopback
        inet addr:127.0.0.1 Mask:255.0.0.0
        inet6 addr: ::1/128 Scope:Host
        UP LOOPBACK RUNNING MTU:65536 Metric:1
        RX packets:0 errors:0 dropped:0 overruns:0 frame:0
        TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
        collisions:0 txqueuelen:0
        RX bytes:0 (0.0 B) TX bytes:0 (0.0 B)
```

Inside the container we can see that the container is now connected to the Calico bridge and can connect to the other containers deployed on the same bridge.



## Summary

In this chapter, we looked into some of the deeper and more conceptual aspects of Docker networking, one of them being libnetworking, the future Docker network model that is already getting into shape with the release of Docker 1.9. While explaining libnetworking, we also studied the CNM model and its various objects and components with its implementation code snippets. Next, we looked into drivers of CNM, the prime one being the overlay driver, in detail, with deployment as part of the Vagrant setup. We also looked at the stand-alone integration of containers with the overlay network and as well with Docker Swarm and Docker Machine. In the next section, we explained about the CNI interface, its executable plugins, and a tutorial of configuring Docker networking with the CNI plugin.

In the last section, project Calico is explained in detail, which provides a scalable networking solution based out of libnetwork and provides integration with Docker, Kubernetes, Mesos, bare-metal, and VMs primarily.

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