

Tree Structures

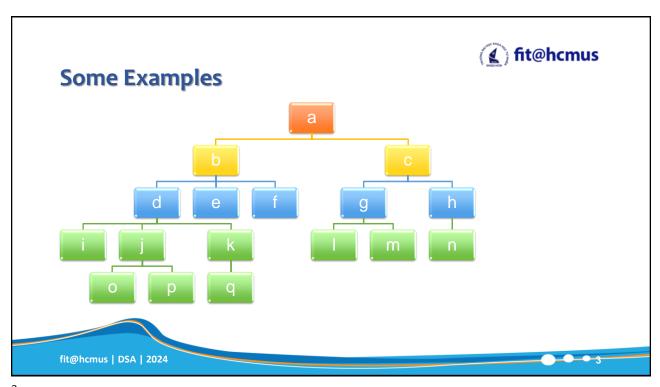
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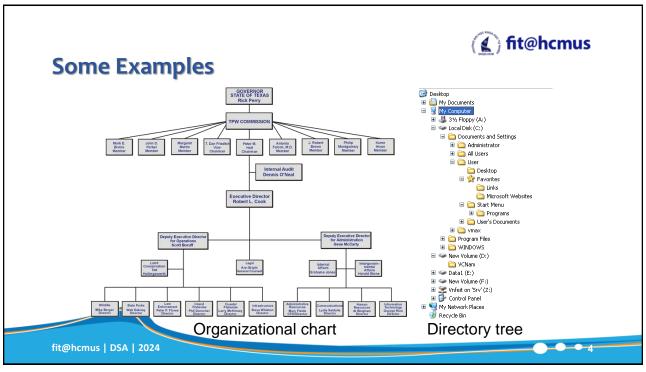
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- Terminologies
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- Tree representation
- Binary tree
- Binary search tree
- AVL tree
- o 2-3 tree, 2-3-4 tree

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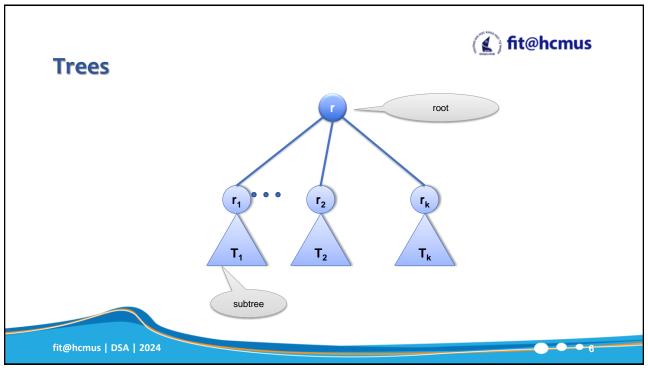


Trees

- Used to represent relationships
- o *hierarchical* in nature
 - "Parent-child" relationship exists between nodes in tree.
 - · Generalized to ancestor and descendant
 - Lines between the nodes are called edges
- A subtree in a tree is any node in the tree together with all of its descendants

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Terminologies

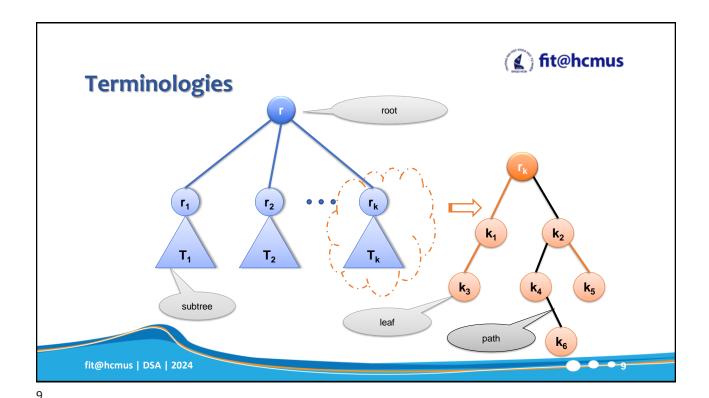
- o node: an item/element in a tree.
- parent (of node *n*): The node **directly above** node *n* in the tree.
- o child (of node *n*): The node **directly below** node *n* in the tree.
- o root: The only node in the tree with no parent.
- leaf: A node with no children.
- o path: A sequence of nodes and edges connecting a node with the nodes below it.

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Terminologies

- siblings: Nodes with common parent.
- o ancestor (of node *n*): a node on the path from the root to *n*.
- o descendant (of node *n*): a node on the path from node *n* to a leaf.
- o subtree (of node n): A tree that consists of a child (if any) of n and the child's descendants.



Terminologies



- o degree/order
 - Order of node *n*: number of children of node *n*.
 - Order of a tree: the maximum order of nodes in that tree.
- depth/level (of node n)
 - If *n* is the root of *T* , it is at level 1.
 - If *n* is not the root of *T* , its level is 1 greater than the level of its parent.

```
if node n is root:
    level(n) = 1
Otherwise:
    level(n) = 1 + level(parent(n))
```

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Terminologies

- Height of tree: number of nodes in the longest path from the root to a leaf.
- Height of a tree T in terms of the levels of its nodes
 - If T is empty, its height is 0.
 - If T is not empty, its height is equal to the maximum level of its nodes.

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Terminologies



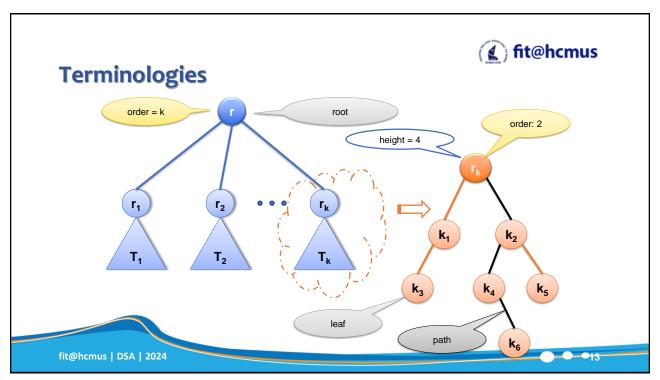
```
• Height of tree T:
```

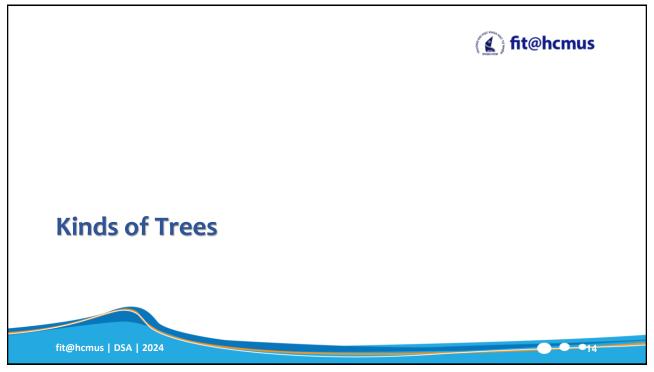
```
if T is empty:  \label{eq:height} \begin{array}{l} \text{height}(\mathtt{T}) \; = \; 0 \\ \\ \text{Otherwise:} \\ \\ \text{height}\; (\mathtt{T}) \; = \; \max\{\text{level}(\mathtt{N_i})\}, \; \mathtt{N_i} \in \mathtt{T} \end{array}
```

Height of tree T:

```
if T is empty:
   height(T) = 0
Otherwise:
   height(T) = 1 + max{height(T<sub>i</sub>)}, T<sub>i</sub> is a subtree of T
```









General Tree

- Set T of one or more nodes such that T is partitioned into disjoint subsets
 - A single node r , the root
 - Sets that are general trees, called subtrees of r

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n-ary Tree



- set T of nodes that is either empty or partitioned into disjoint subsets:
 - A single node r , the root
 - n possibly empty sets that are n-ary subtrees of r



Binary Tree

- Set T of nodes that is either empty or partitioned into disjoint subsets
 - Single node r , the root
 - Two possibly empty sets that are binary trees, called left and right subtrees of r

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Traversal

- Visit each node in a tree exactly once.
- Many operations need using tree traversals.
- The basic tree traversals:
 - Pre-order
 - In-order
 - Post-order

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Pre-order Traversal

```
PreOrder(root)
{
   if root is empty
      Do_nothing;
   Visit root; //Print, Add, ...
   //Traverse every Child<sub>i</sub>.
   PreOrder(Child<sub>0</sub>);
   PreOrder(Child<sub>1</sub>);
   ...
   PreOrder(Child<sub>k-1</sub>);
```



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Post-order Traversal

```
PostOrder(root)
{
    if root is empty
        Do_nothing;
    //Traverse every Child;
    PostOrder(Child_0);
    PostOrder(Child_1);
    ...
    PostOrder(Child_k-1);
    Visit at root; //Print, Add, ...
}
```

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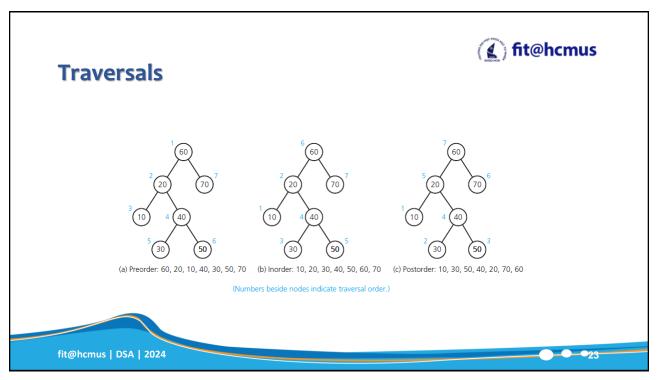
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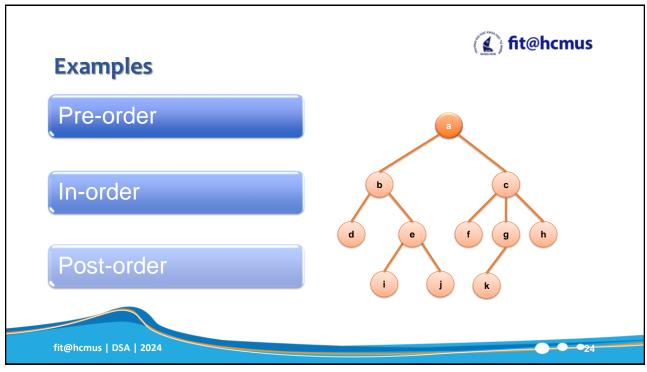
In-order Traversal

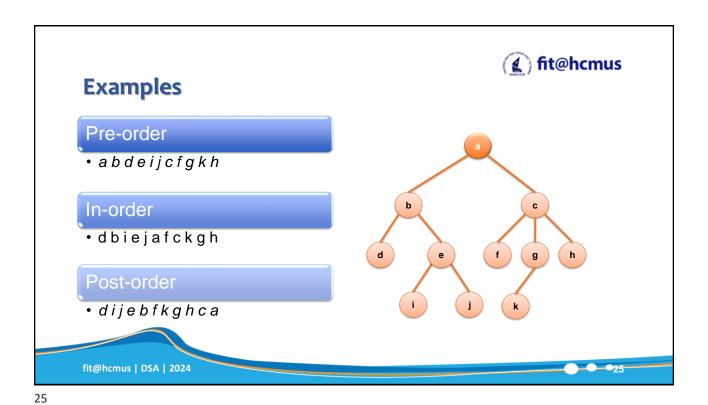
```
(1) fit@hcmus
```

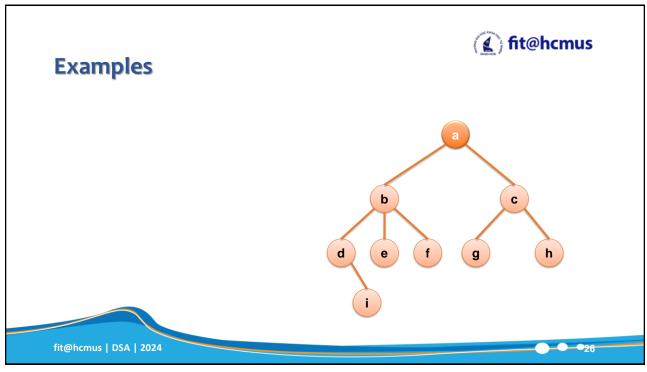
```
InOrder(root)
{
   if root is empty
        Do_nothing;
   //Traverse the child at the first position
   InOrder(Child<sub>0</sub>);
   Visit at root;
   //Traverse other children
   InOrder(Child<sub>1</sub>);
   InOrder(Child<sub>2</sub>);
   ...
   InOrder(Child<sub>k-1</sub>);
}
```

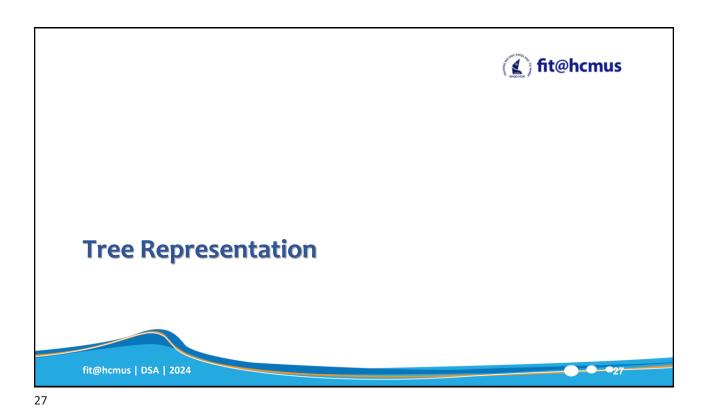
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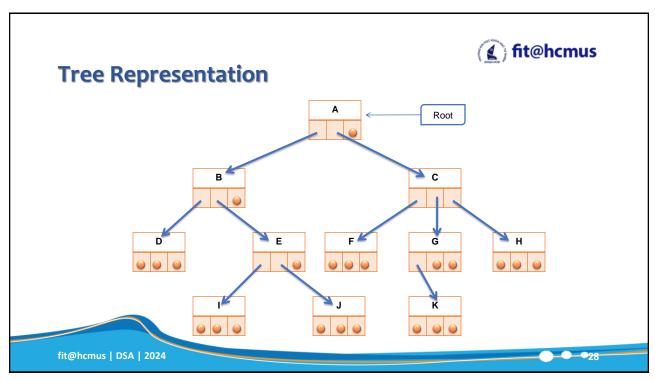


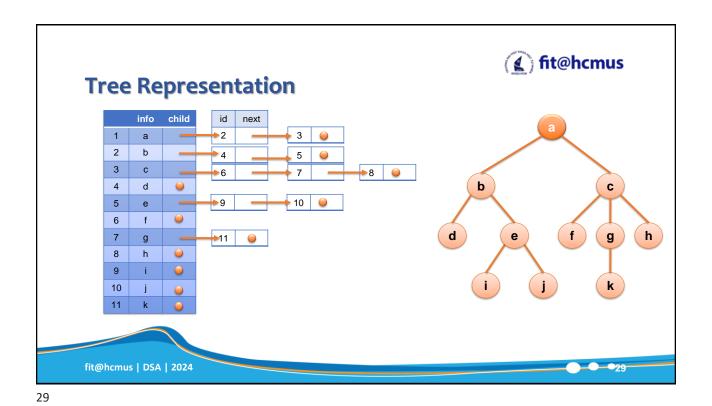




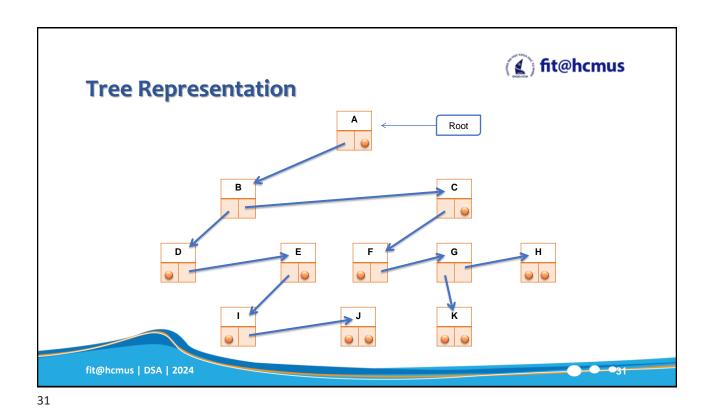


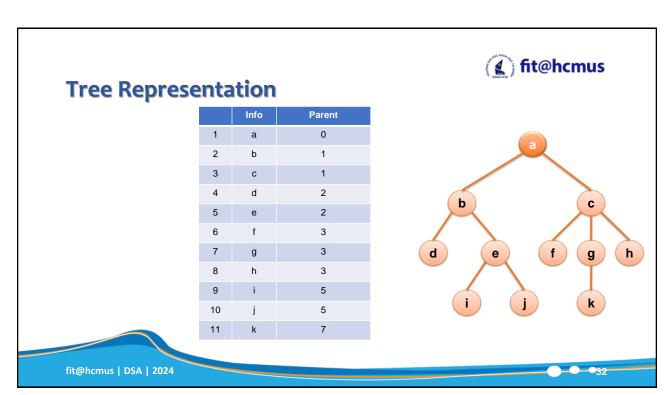


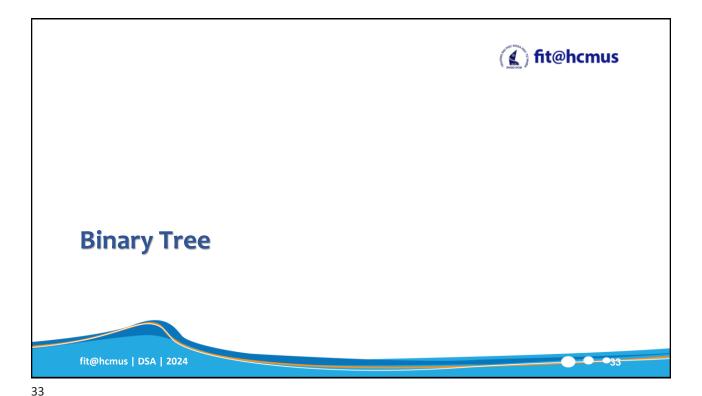




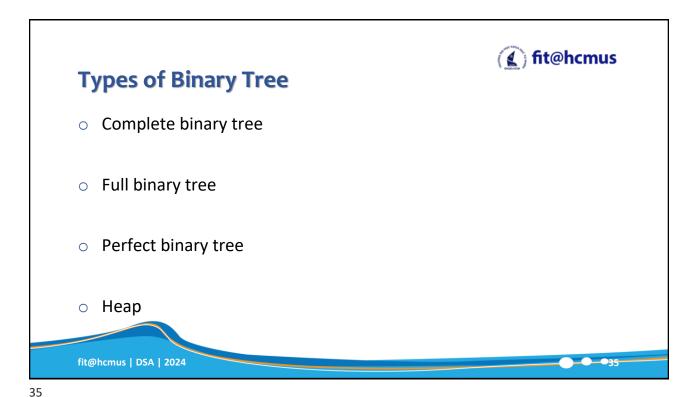
fit@hcmus **Tree Representation** Next Sibling **Eldest Child** b fit@hcmus | DSA | 2024

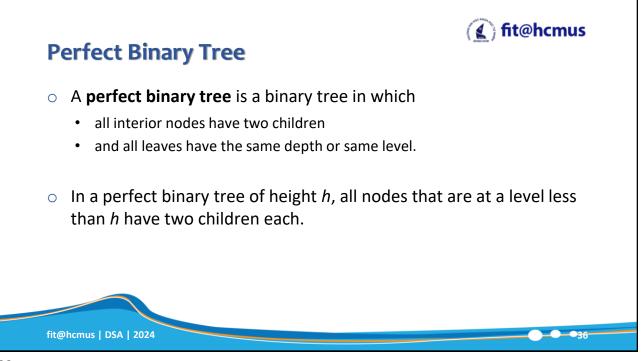






Set T of nodes that is either empty or partitioned into disjoint subsets.
 Single node r, the root
 Two possibly empty sets that are binary trees, called left and right subtrees of r.
 Other definition: A rooted binary tree has a root node and every node has at most two children.

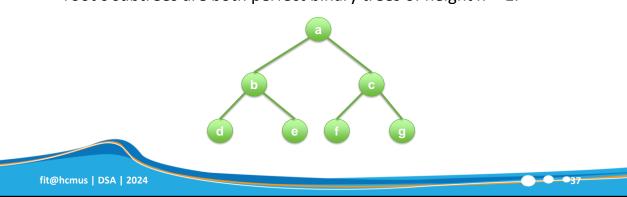






Perfect Binary Tree

- If T is empty, T is a perfect binary tree of height 0.
- If T is not empty and has height h > 0, T is a perfect binary tree if its root's subtrees are both perfect binary trees of height h 1.



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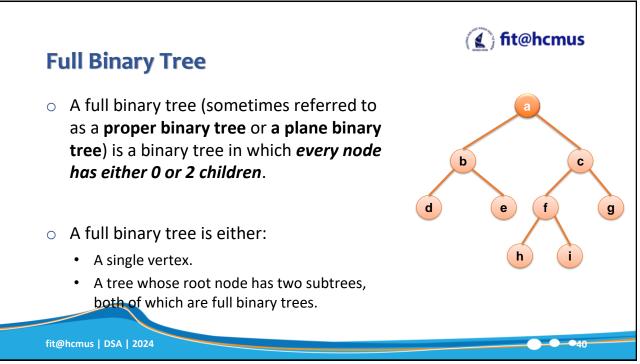


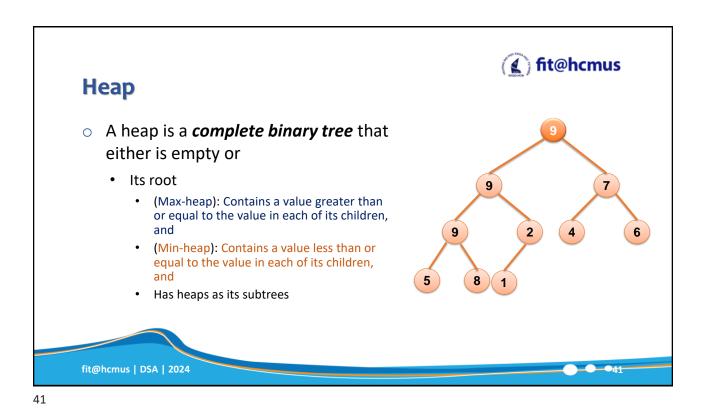
Complete Binary Tree

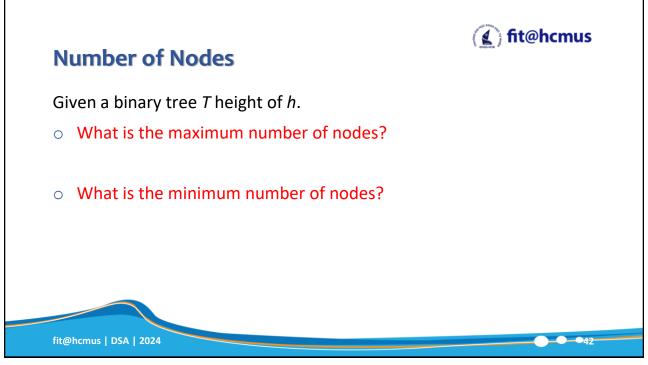
- O A complete binary tree of height h is a binary tree that is **perfect** down to level h-1, with level h filled in from left to right.
- In a complete binary tree every level, except possibly the last, is completely filled, and all nodes in the last level are as far left as possible.
- Other definition: A complete binary tree is a perfect binary tree whose rightmost leaves (perhaps all) have been removed.

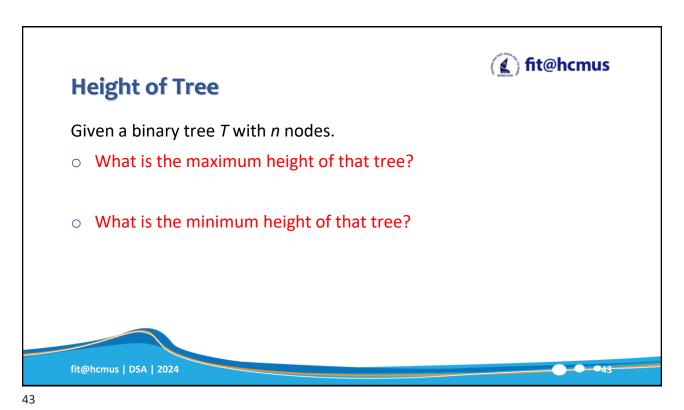


Complete Binary Tree A binary tree is complete if All nodes at level h - 2 and above have two children each, and When a node at level h - 1 has children, all nodes to its left at the same level have two children each, and When a node at level h - 1 has one child, it is a left child









Binary Search Tree

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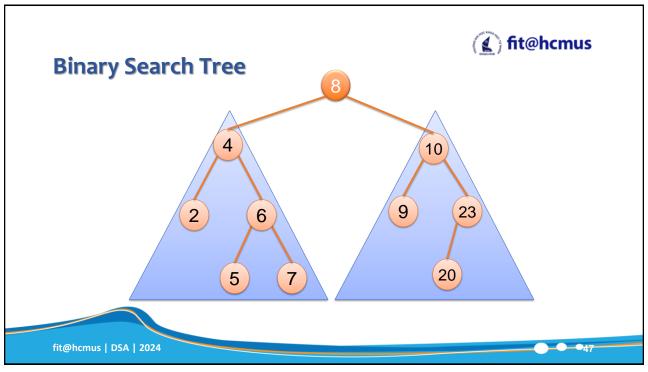
Binary Search Tree

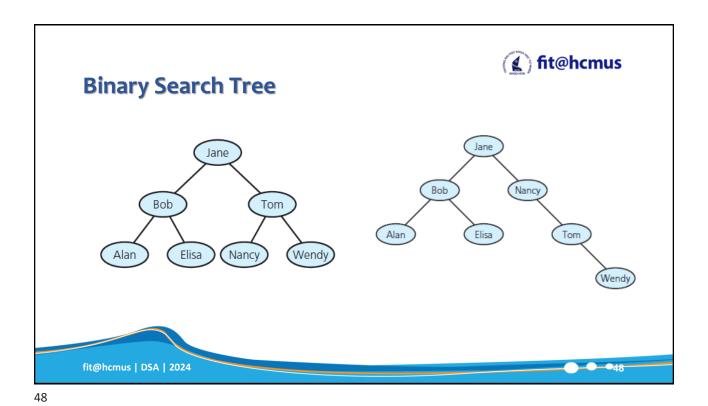
- A binary search tree is a binary tree in which each node n has properties:
 - n's value greater than all values in left subtree T_L
 - n's value less than all values in right subtree T_R
 - Both T_R and T_L are binary search trees.

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Operations

Insert (a key)
Search (a key)
Remove (a key)
Traverse
Sort (based on key value)
Rotate (Left rotation, Right rotation)



Insertion

```
Insert (root, Data)
{
    if (root is NULL) {
        Create a new_Node containing Data
        This new_Node becomes root of the tree
    }
    //Compare root's key with Key
    if root's Key is less than Data's Key
        Insert Key to the root's RIGHT subtree
    else if root's Key is greater than Data's Key
        Insert Key to the root's LEFT subtree
    else
        Do nothing //Explain why?
}
```



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Insertion

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Beginning with an empty binary search tree, what binary search tree is formed when you insert the following values in the order given?

15, 20, 40, 25, 70, 90, 80, 55, 60, 65, 30, 75

9, 1, 4, 2, 3, 9, 5, 8, 6, 7, 4





Insertion

Beginning with an empty binary search tree, what binary search tree is formed when you insert the following values in the order given?

- W, T, N, J, E, B, A
- W, T, N, A, B, E, J
- A, B, W, J, N, T, E
- B, T, E, A, N, W, J

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Search

```
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```

```
Search (root, Data)
{
    if (root is NULL) {
        return NOT_FOUND;
}
    //Compare root's key with Key
    if root's Key is less than Data's Key
        Search Data in the root's RIGHT subtree
    else if root's Key is greater than Data's Key
        Search Data in the root's LEFT subtree
    else
        return FOUND //Explain why?
```



Deletion

- When we delete a node, three possibilities arise.
- Node to be deleted:
 - is leaf:
 - Simply remove from the tree.
 - has only one child:
 - · Copy the child to the node and delete the child
 - has two children:
 - Find in-order successor (predecessor) **S_Node** of the node.
 - Copy contents of **S Node** to the node and delete the **S Node**.

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Traversals



Pre-order:

Node - Left - Right

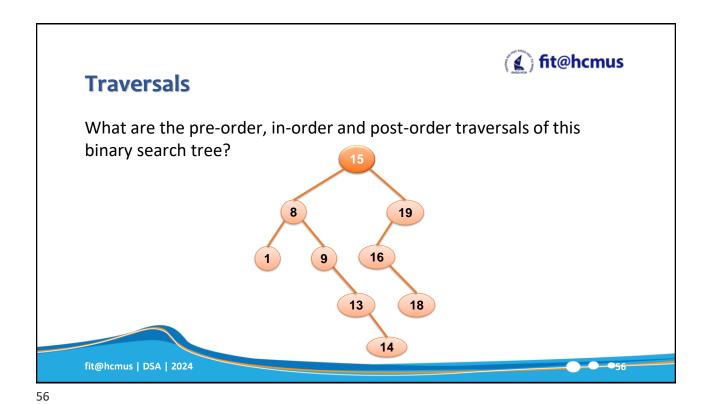
o In-order:

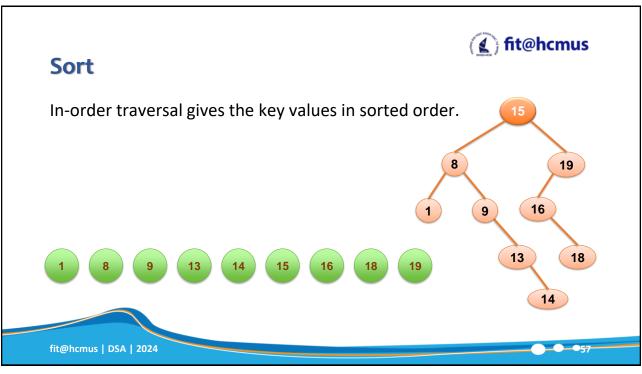
Left - Node - Right

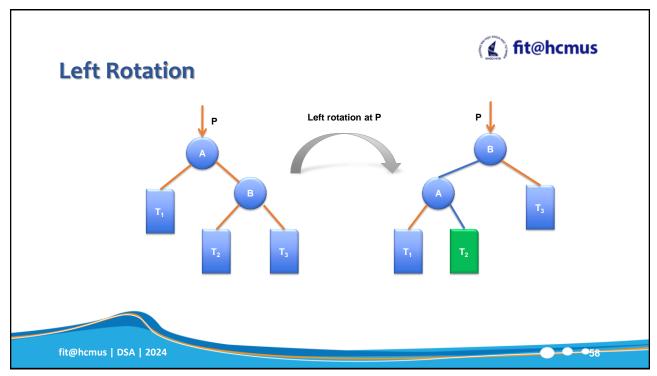
Post-order:

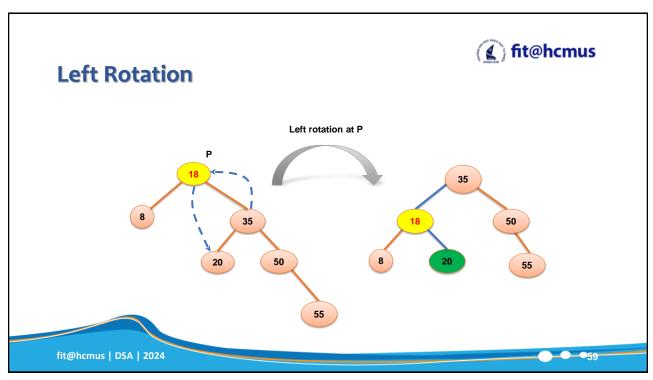
Left - Right - Node

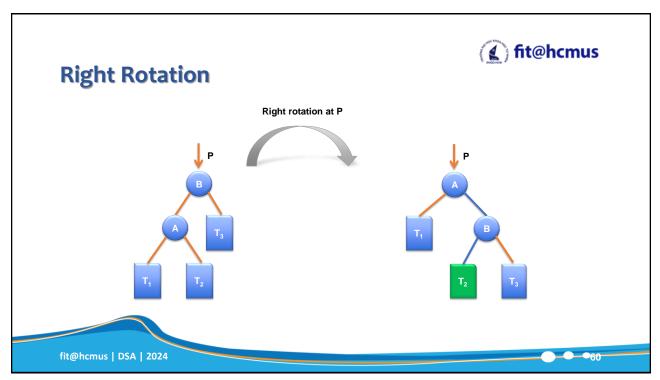


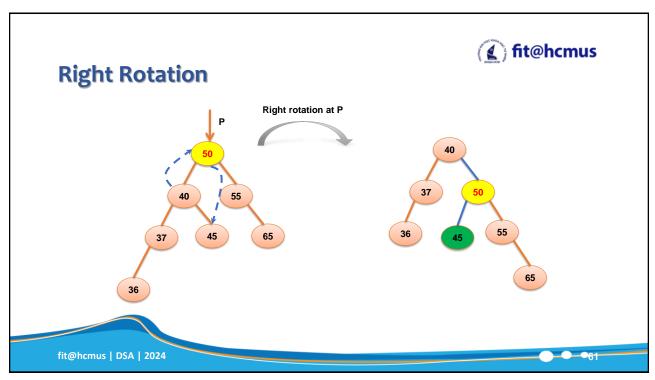














Efficiency of Binary Search Tree Operations

Operation	Average case	Worst case
Retrieval	$O(\log n)$	O(<i>n</i>)
Insertion	$O(\log n)$	O(<i>n</i>)
Removal	$O(\log n)$	O(<i>n</i>)
Traversal	O(<i>n</i>)	O(<i>n</i>)

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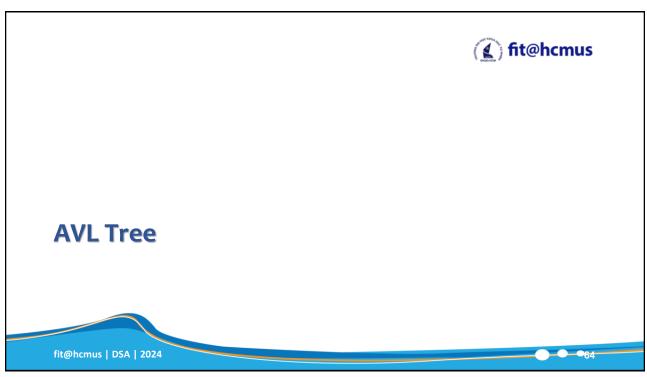


Very Bad Binary Search Tree

Beginning with an empty binary search tree, what binary search tree is formed when inserting the following values in the order given?

2, 4, 6, 8, 10, 12, 14, 18, 20









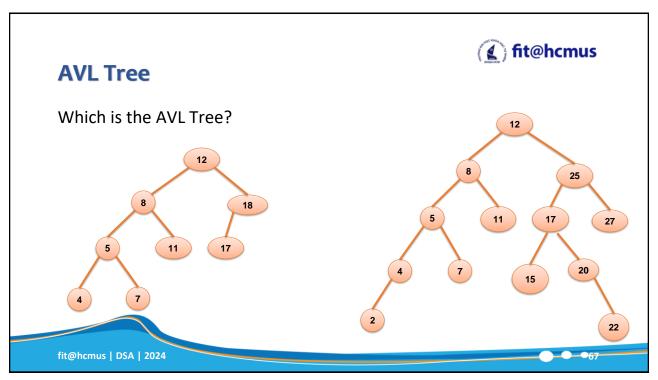
AVL Tree

- o Named for inventors, (Georgii) Adelson-Velsky and (Evgenii) Landis
- Invented in 1962 (paper "An algorithm for organization of information").
- AVL Tree is a self-balancing binary search tree where
 - for ALL nodes, the difference between height of the left subtrees and the right subtrees cannot be more than one. (height invariant, or balance invariant).

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AVL Tree

- A balanced binary search tree
 - · Maintains height close to the minimum
 - After insertion or deletion, check the tree is still AVL tree determine whether any node in tree has left and right subtrees whose heights differ by more than 1
- Can search AVL tree almost as efficiently as minimum-height binary search tree.

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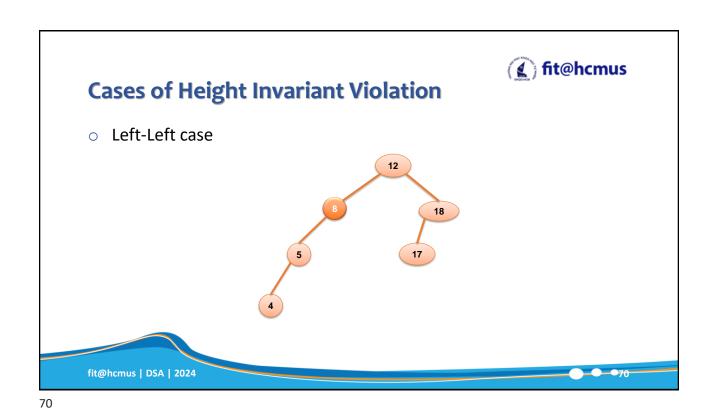
Cases of Height Invariant Violation

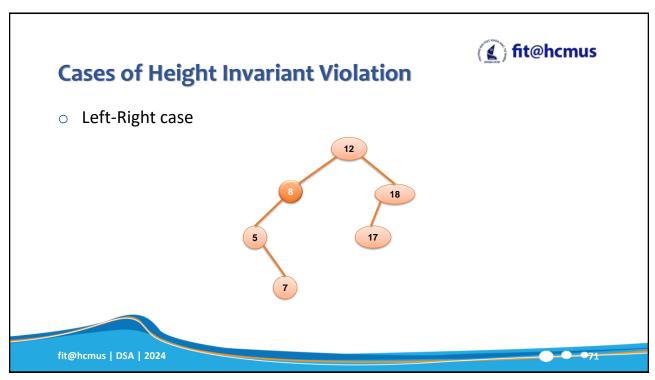


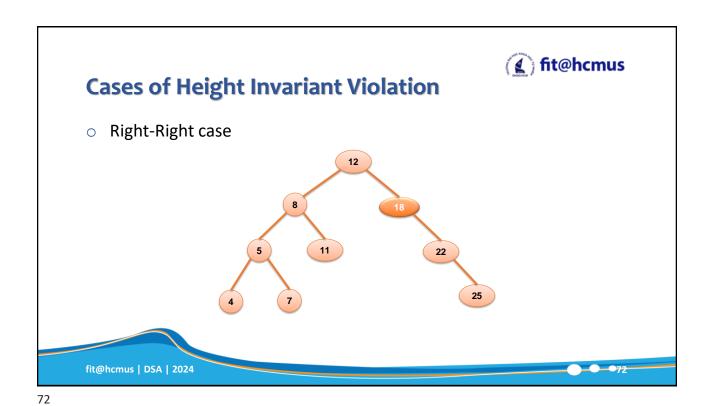
- Left-Left case
- Left-Right case
- Right-Right case
- Right-Left case

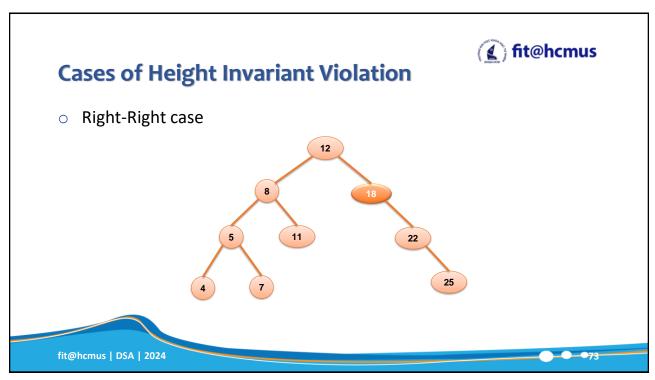
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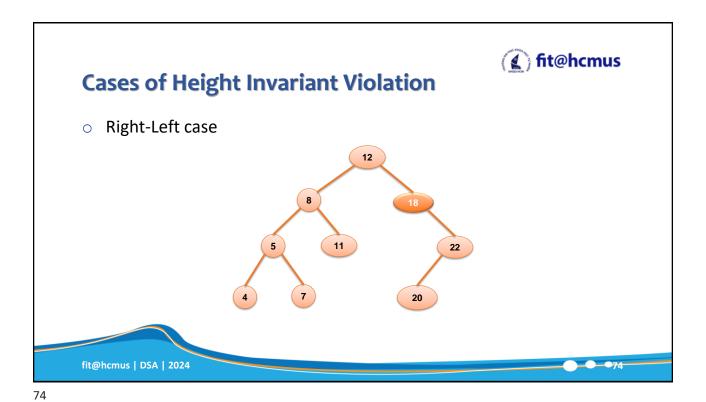
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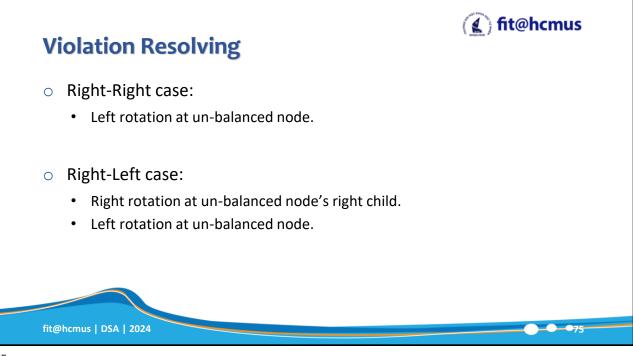


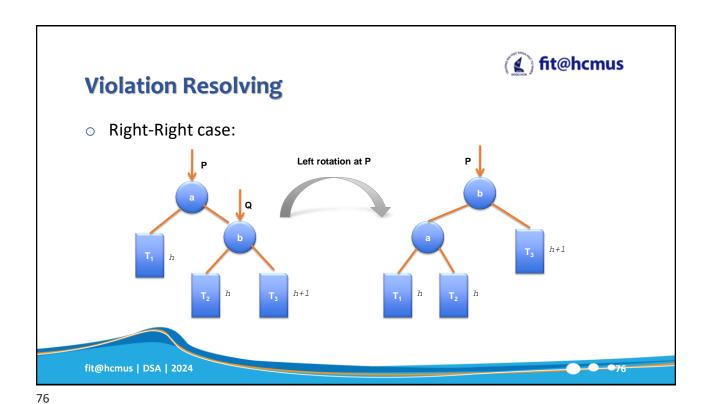












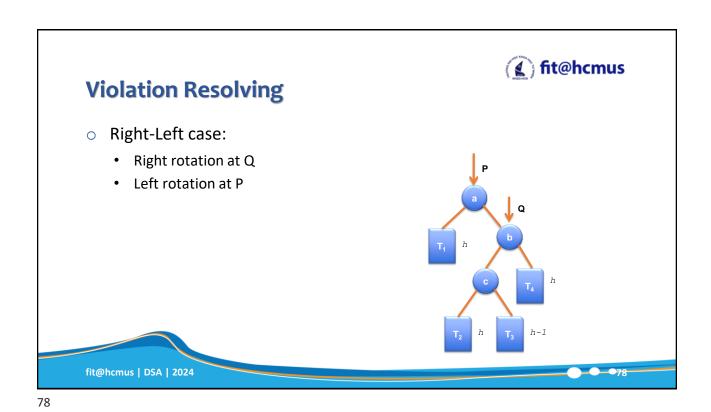
Violation Resolving

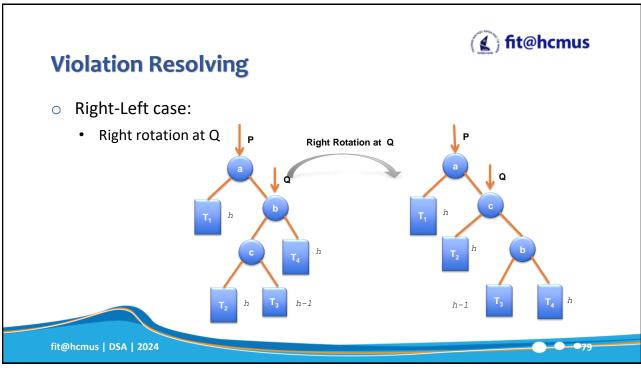
Right-Right case:

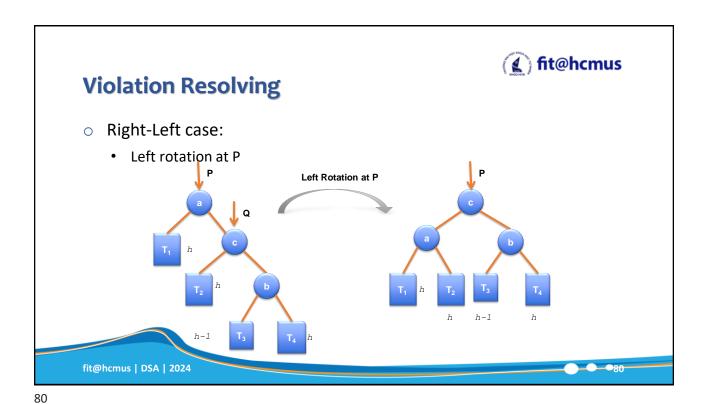
Left rotation at P

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Violation Resolving

Right rotation at Q

Right station at Q

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Right station at Q

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Right station at Q

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Right station at Q

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Right station at Q

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Right station at Q

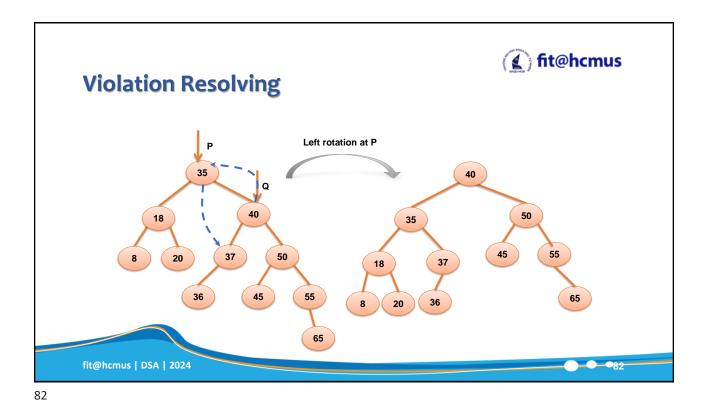
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Violation Resolving

• Left-Left case:

Single rotation

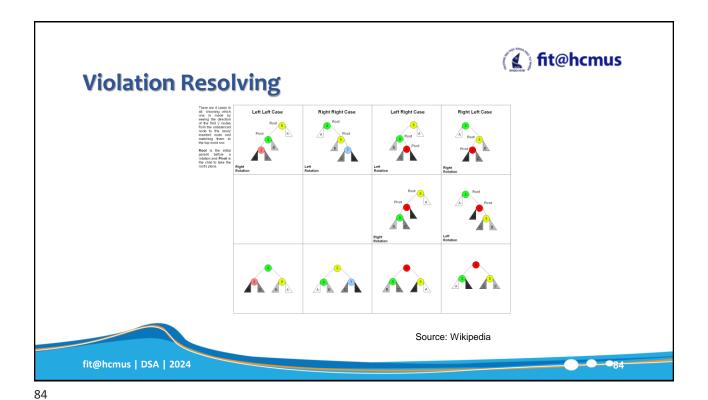
• Right rotation at un-balanced node.

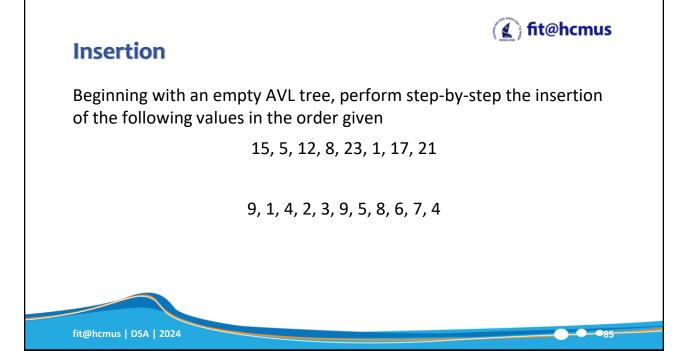
• Left-Right case:

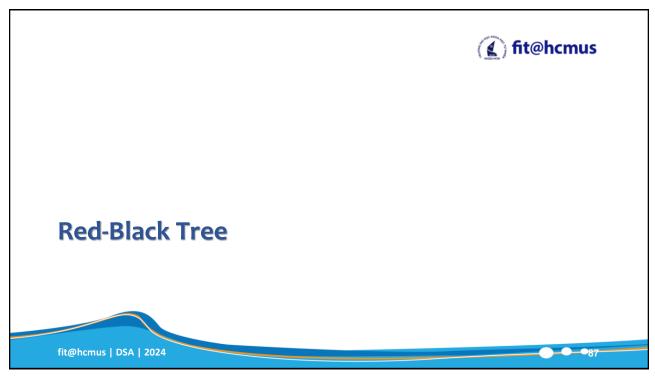
Double rotation

• Left rotation at un-balanced node's left child.

• Right rotation at un-balanced node.







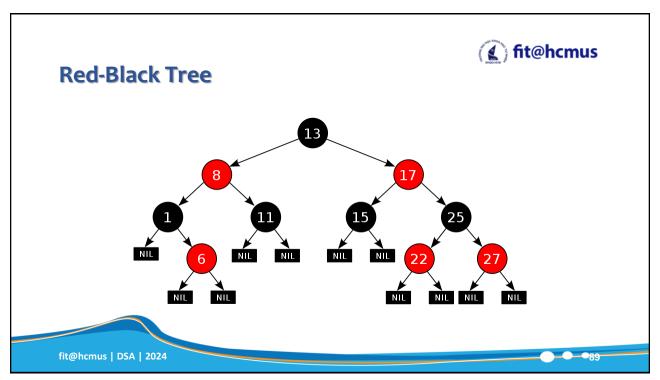
Red-Black Tree

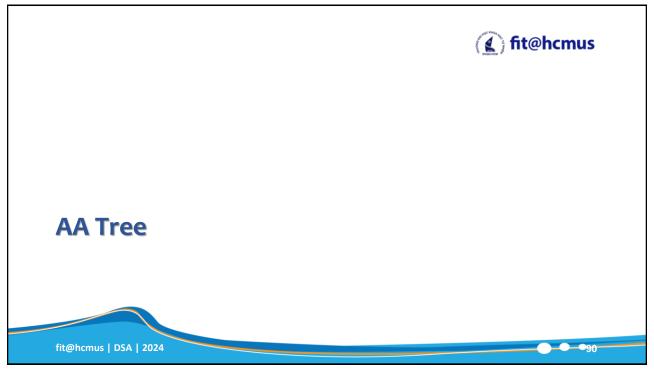


- o Invented in 1972 by Rudolf Bayer.
- Red-Black tree is a binary search tree with the following rules:
 - Every node has a color either red or black.
 - The root of the tree is always **black**.
 - There are no two adjacent red nodes (A red node cannot have a red parent or red child).
 - Every path from a node (including root) to any of its descendants NULL nodes has the same number of **black** nodes.
 - All leaf nodes are black nodes.

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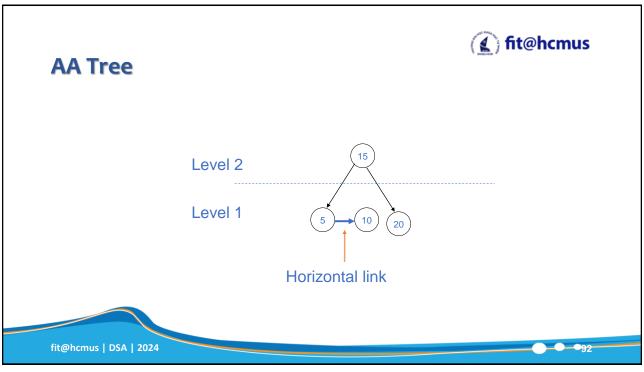
AA Tree

- Invented by Arne Anderson in a work published in 1993 (Balanced Search Tree Made Simple).
- o Two concepts:
 - Level:
 - Number of LEFT links from that nodes to a NULL node.
 - · Horizontal link:
 - The link between parent and its child node having the same level.

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AA Tree

- AA tree is a binary search tree with the following rules:
 - The level of every leaf node is one.
 - The level of every left child is exactly one less than that of its parent.
 - The level of every right child is equal to or one less than that of its parent.

 Horizontal link must be a RIGHT link.
 - The level of every right grandchild is strictly less than that of its grandparent.

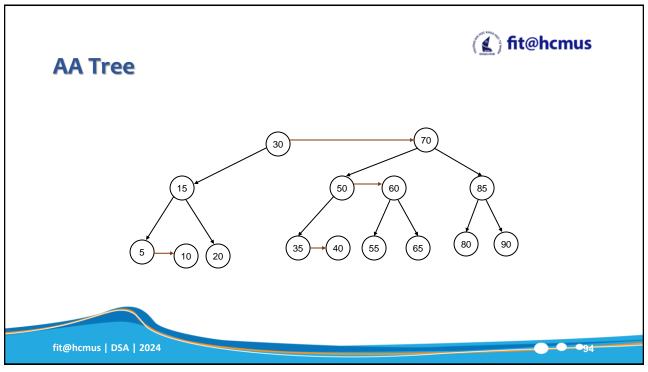
There is no two consecutive horizontal links.

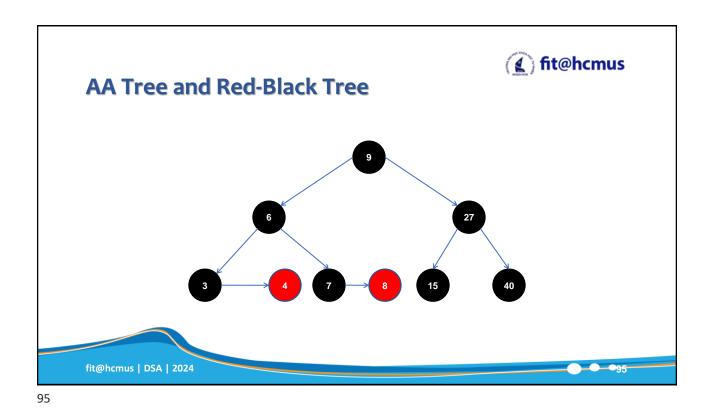
Every node of level greater than one has two children.

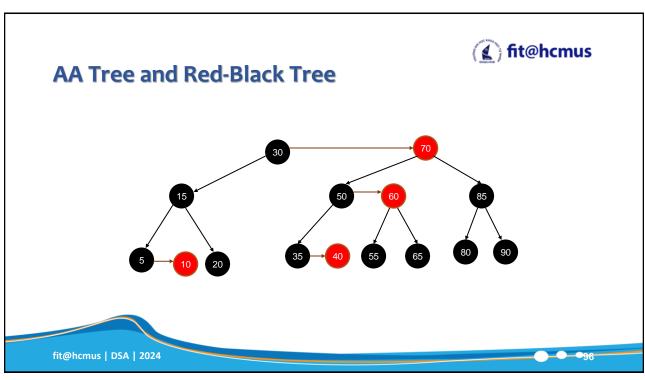
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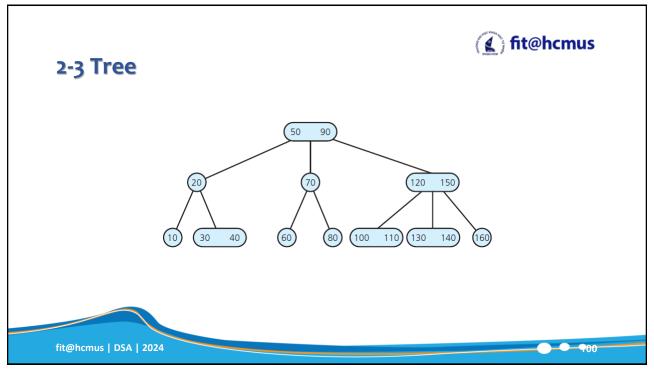
93

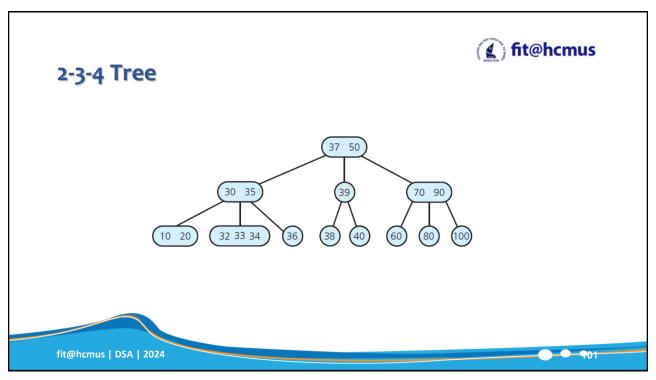












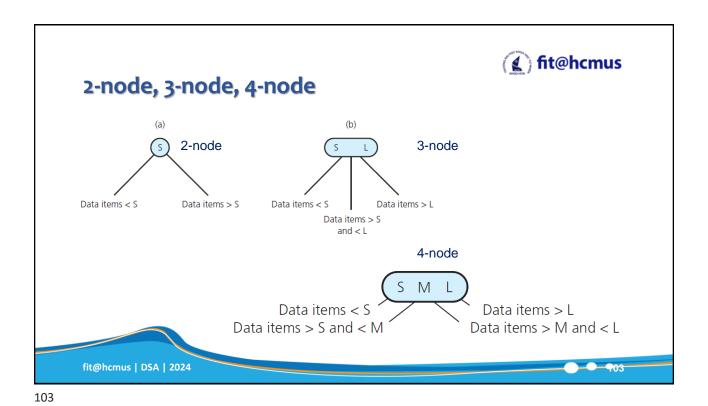


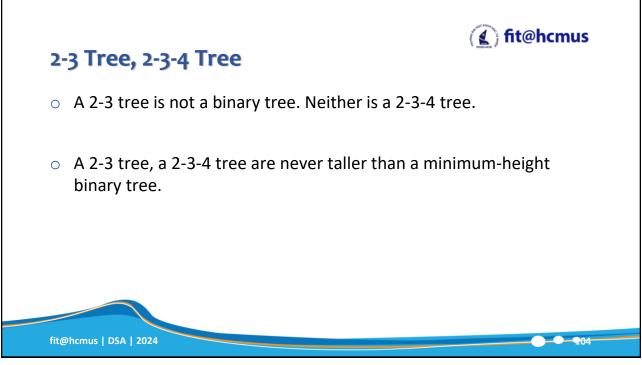
2-node, 3-node, 4-node

- A 2-node (has two children) must contain single data item greater than left child's item(s) and less than right child's item(s).
- O A 3-node (has three children) must contain **two** data items, S and L, such that
 - S is greater than left child's item(s) and less than middle child's item(s);
 - L is greater than middle child's item(s) and less than right child's item(s).
- O A 4-node (has our children) must contain three data items S, M, and L that satisfy:
 - S is greater than left child's item(s) and less than middle-left child's item(s)
 - M is greater than middle-left child's item(s) and less than middle-right child's item(s);
 - Lis greater than middle-right child's item(s) and less than right child's item(s).

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2-3 Tree

- o Invented by John Hopcroft in 1970.
- 2-3 tree is a tree in which
 - Every internal node is either a 2-node or a 3-node.
 - Leaves have no children and may contain either one or two data items.

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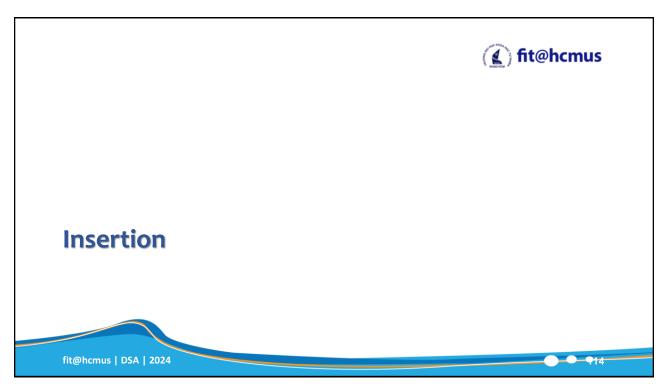
2-3-4 Tree

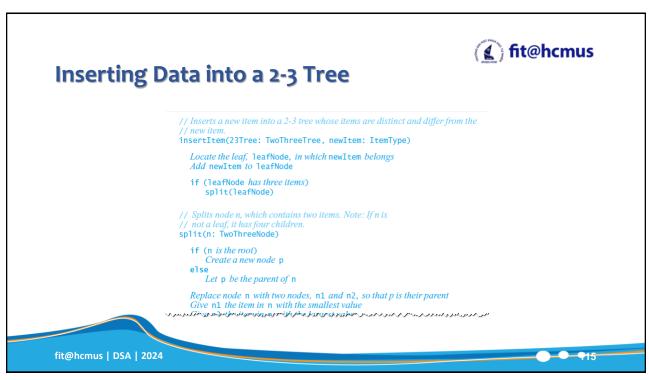


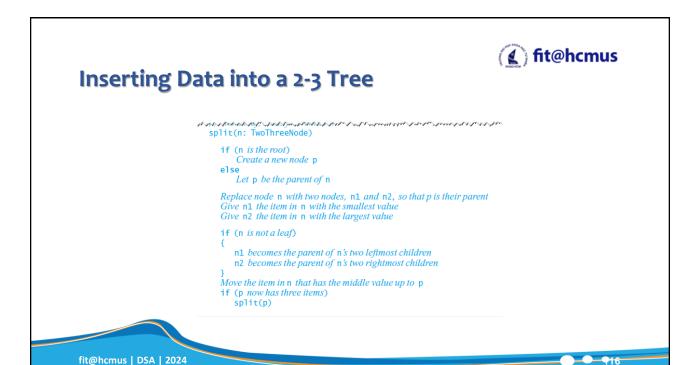
- 2-3-4 tree is a tree in which
 - Every internal node is a 2-node, a 3-node or a 4-node.
 - Leaves have no children and may contain either one, two or three data items.

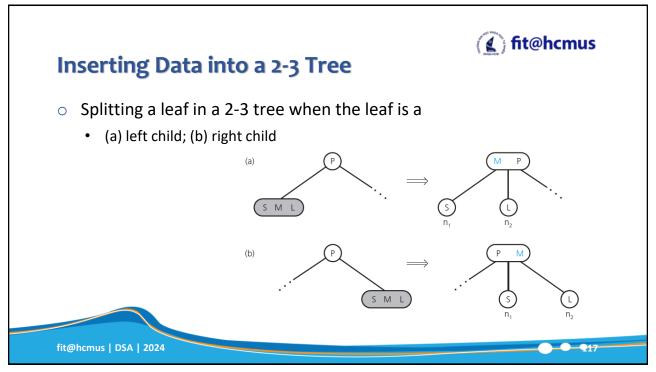
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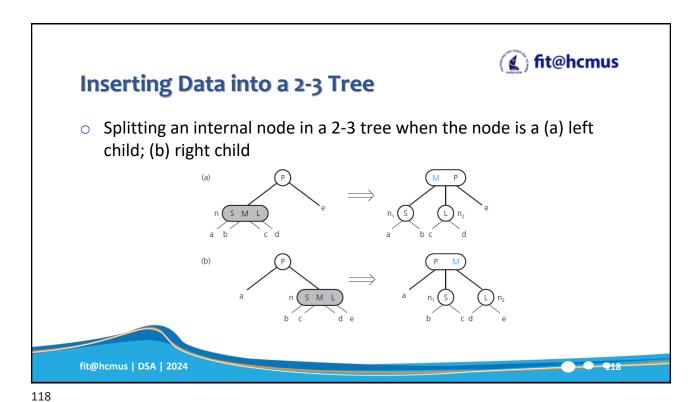


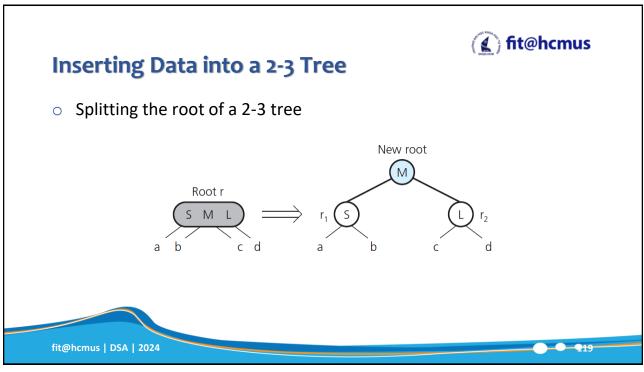


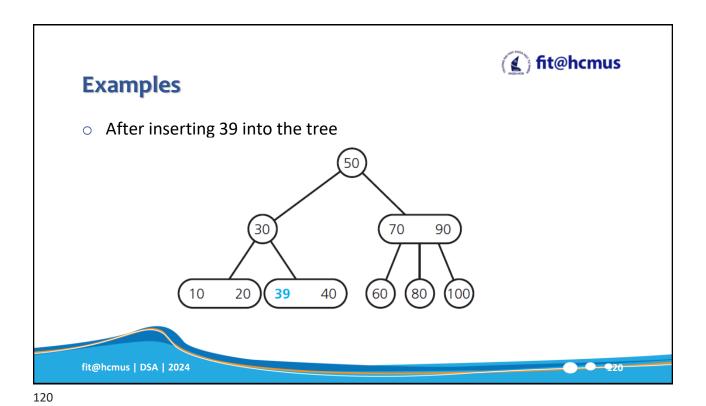


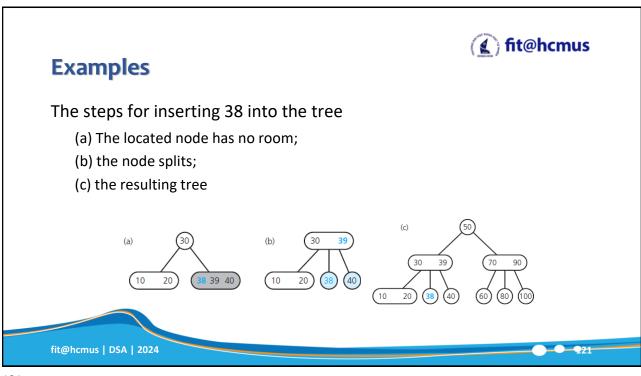


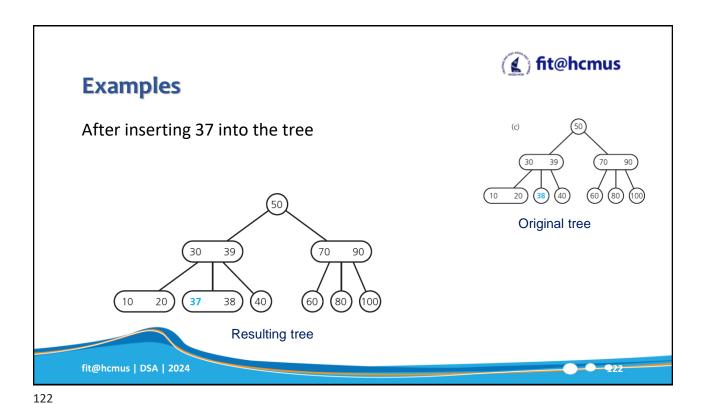


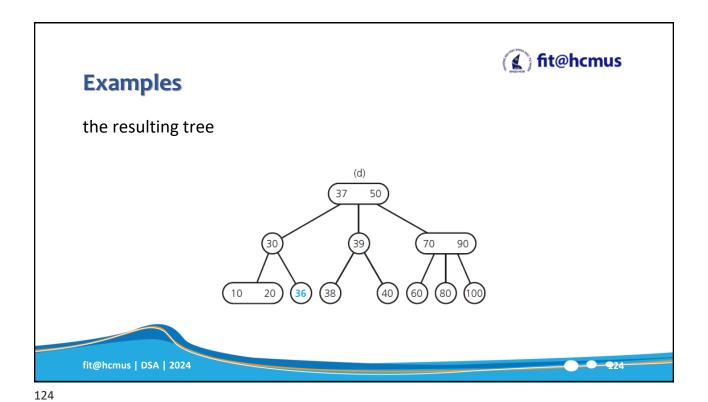


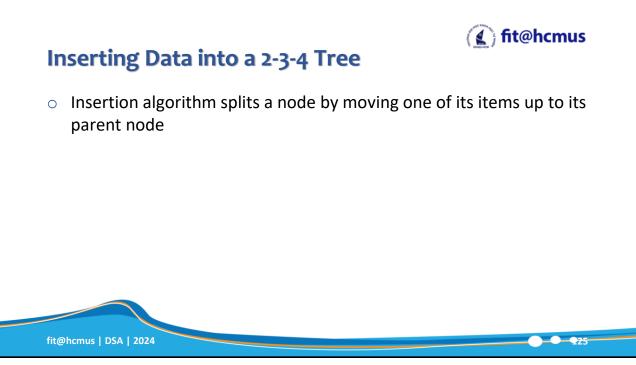


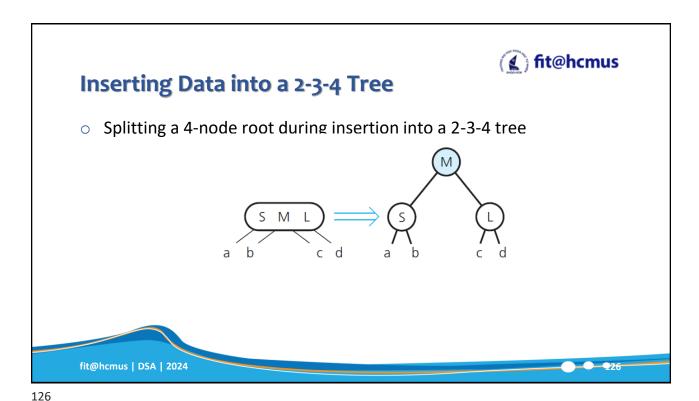


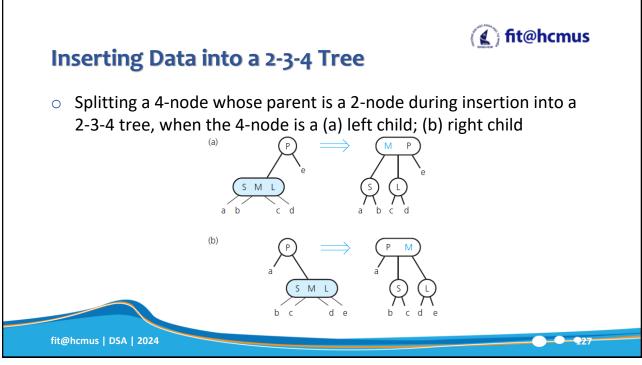








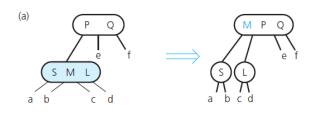






Inserting Data into a 2-3-4 Tree

Splitting a 4-node whose parent is a 3-node during insertion into a
 2-3-4 tree, when the 4-node is a (a) left child



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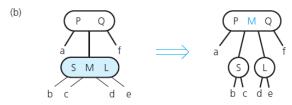


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Inserting Data into a 2-3-4 Tree

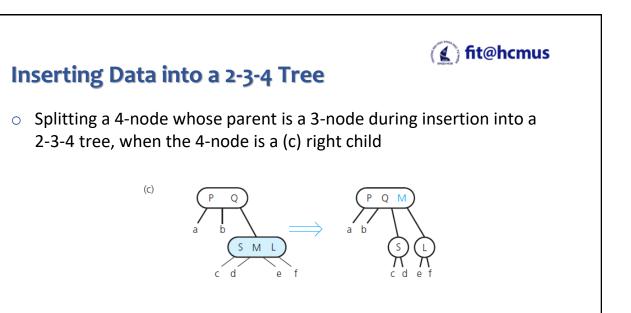


Splitting a 4-node whose parent is a 3-node during insertion into a
 2-3-4 tree, when the 4-node is a (b) middle child

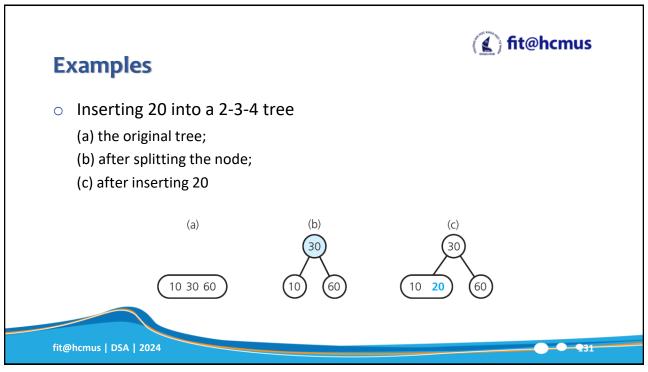


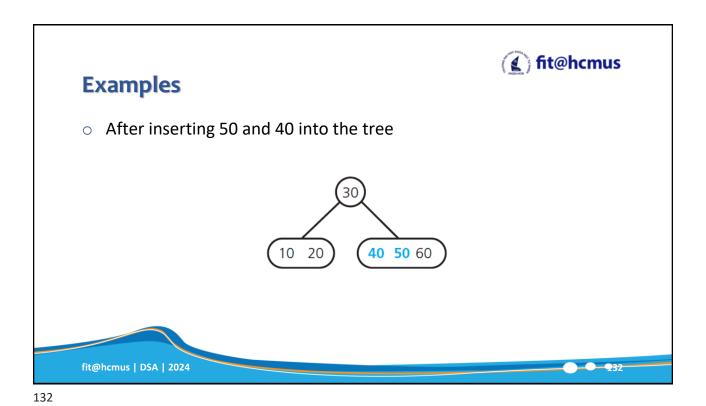
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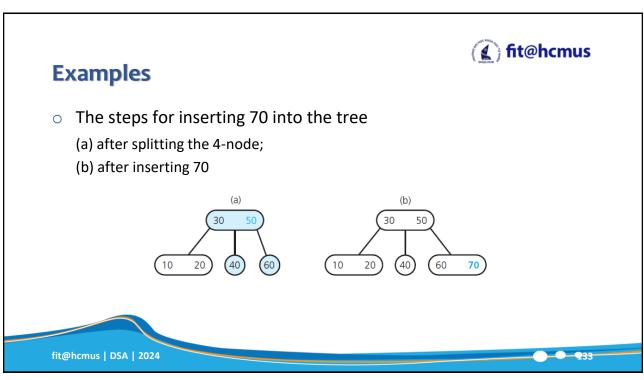
Q Q 29

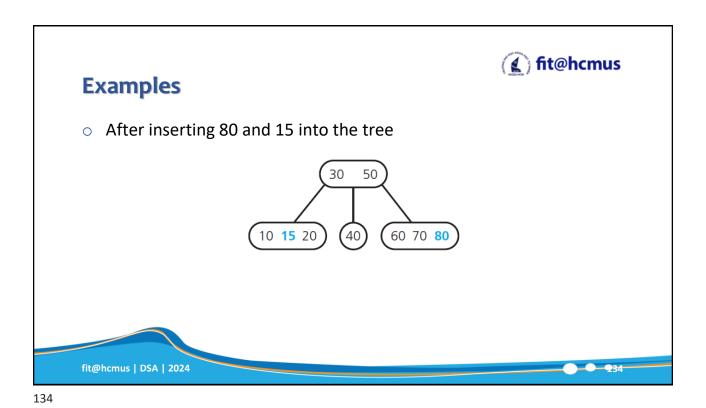


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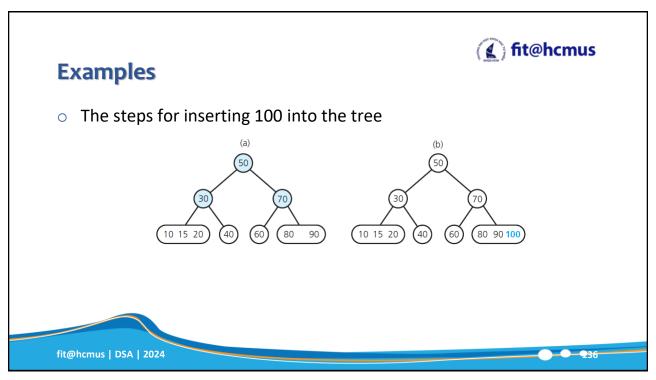


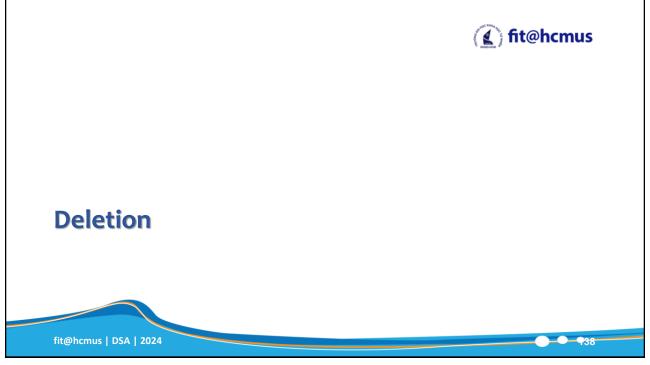


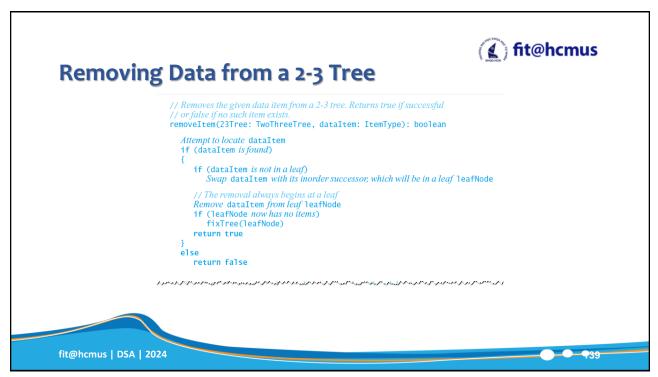
Examples

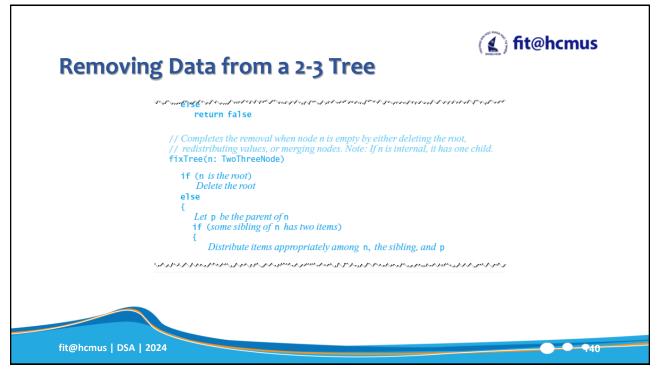
The steps for inserting 90 into the tree

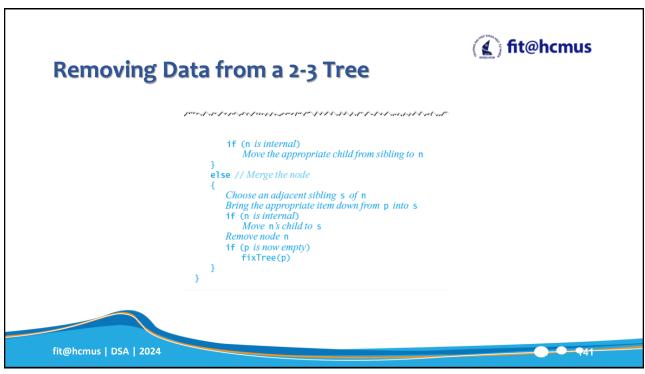
(a)
(b)
(30 50 70
(b)
(30 50 70
(d)
(d)
(d)
(d)
(d)
(e)
(d)
(e)
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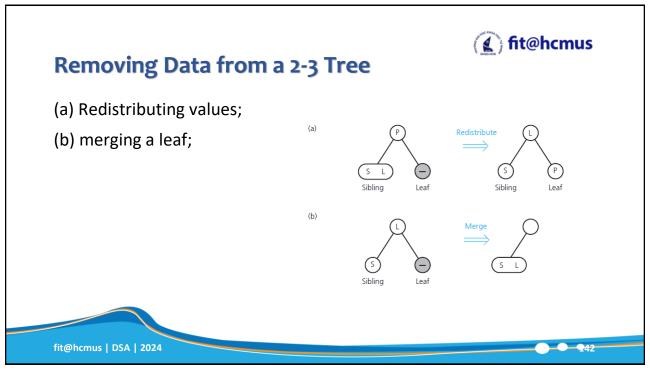


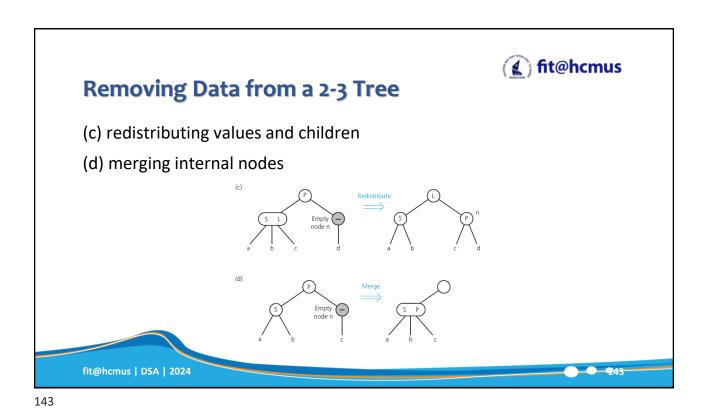


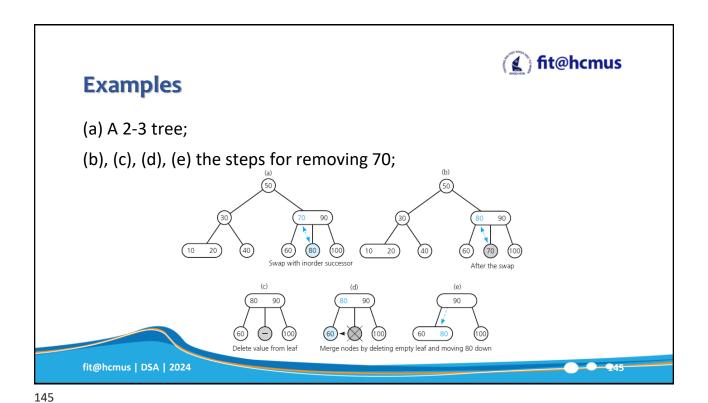


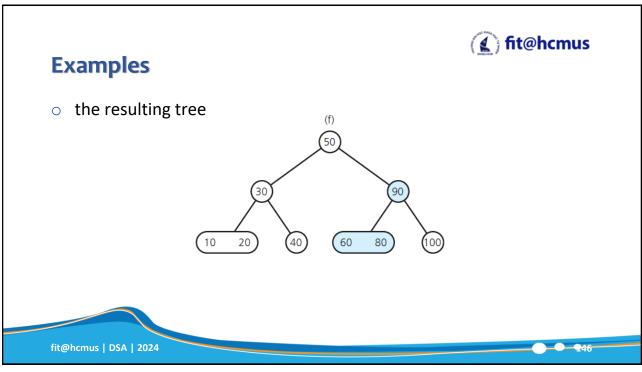


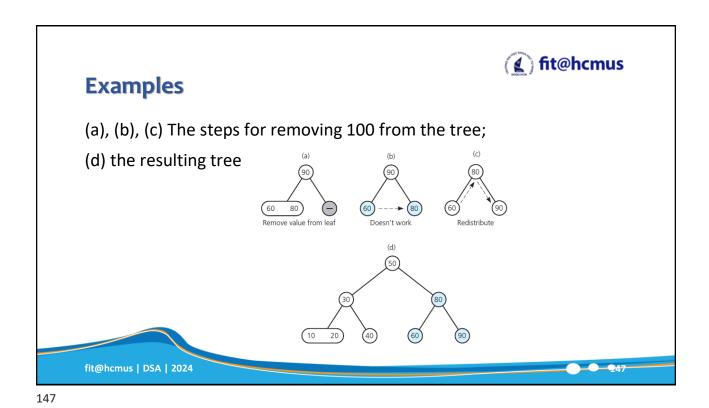


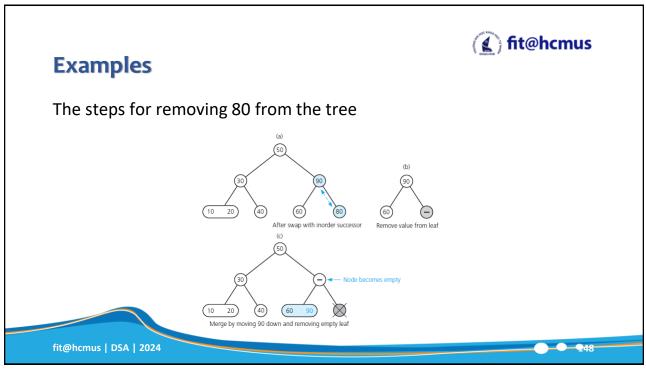


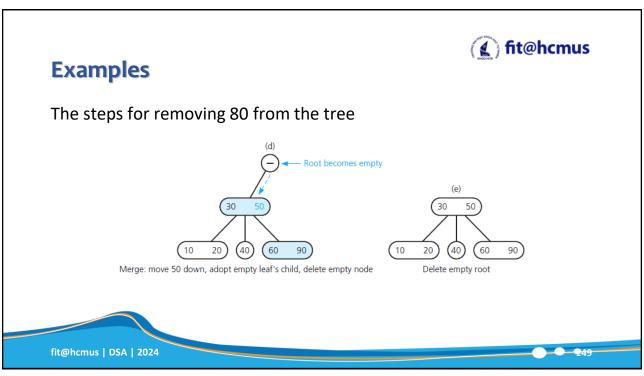


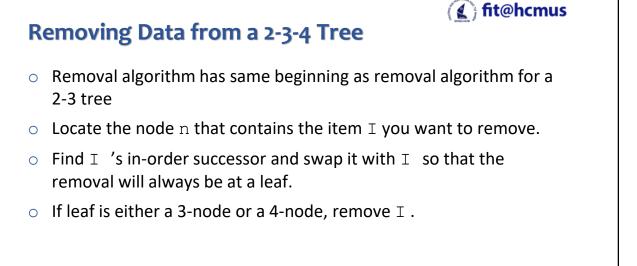












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