

RANDOM PROCESSES

outline:

1. geometric random variable
2. exponential random variable
3. Stochastic process
4. poisson process
5. discrete time Markov chain
6. Chapman-Kolmogorov equation
7. continuous time Markov chain
8. Chapman-Kolmogorov equation
9. Kolmogorov differential equation
10. birth-death process

1. geometric random variable X

$$P(X=k) = (1-p)^{k-1}p$$

1st 2nd ... kth
fail fail ... success

e.g.

$$\begin{aligned}P(X=1) &= p \\P(X=2) &= (1-p)p \\P(X=3) &= (1-p)^2p\end{aligned}$$

$$E(X) = \frac{1}{p}$$

memoryless (Markovian) property

$$P(X=m+n | X>m) = P(X=n)$$

Proof:

$$\begin{aligned}P(X=m+n | X>m) &= \frac{P(X=m+n \cap X>m)}{P(X>m)} \\&= \frac{P(X=m+n)}{P(X>m)} \\&= \frac{(1-p)^{m+n-1}p}{(1-p)^m} \\&= (1-p)^{n-1}p = P(X=n)\end{aligned}$$

2. exponential random variable X

$X = \exp(\lambda)$, λ is the rate

$$\begin{aligned}\text{cdf: } F_X(x) &= P(X \leq x) \\&= \begin{cases} 1 - e^{-\lambda x}, & 0 \leq x < \infty \\ 0, & x < 0 \end{cases}\end{aligned}$$

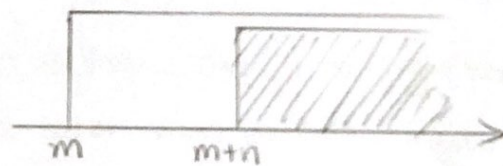
$$P(X>x) = 1 - P(X \leq x) = e^{-\lambda x}, x \geq 0.$$

$$\text{pdf: } f_X(x) = \begin{cases} \lambda e^{-\lambda x}, & x > 0 \\ 0, & x \leq 0 \end{cases}$$

$$\text{mean: } E(X) = \frac{1}{\lambda}$$

memoryless property

$$\begin{aligned}P(X>x+y | X>x) &= P(X>y), \\P(X \leq x+y | X>x) &= P(X \leq y), \\x, y &\geq 0\end{aligned}$$



$$\begin{aligned}\Rightarrow P(X>m+n | X>m) &= P(X>n), \\P(X \leq m+n | X>m) &= P(X \leq n), \\m, n &\geq 1\end{aligned}$$

3. Stochastic process

def: a collection of random variable $\{X(t): t \in T\}$.

T - index set

t - index, of interpreted as time

T is a countable set - discrete time process

T is an interval of \mathbb{R} - continuous time process

state space S - the set of all values $X(t)$ may assume

chain - discrete state space

4. Poisson process

def: a collection of Poisson r.v. $\{X(t): t > 0\}$.

$$P(X(t) = k) = \frac{e^{-\lambda t} (\lambda t)^k}{k!},$$

$k = 0, 1, 2, \dots$

mean: $E(X(t)) = \lambda t$

Poisson process is a continuous time, discrete state space process (continuous time chain).

superposition: the superposition of Poisson processes with rates $\lambda_1, \lambda_2, \dots, \lambda_n$ is also a Poisson process (with rate $\sum_{i=1}^n \lambda_i$).

decomposition: the original Poisson process (with rate λ) is branched out into n streams, with rates $p_1 \lambda, p_2 \lambda, \dots, p_n \lambda$, respectively.

5. Discrete-Time Markov Chain

def: DTMC $\{X_n: n \in \mathbb{N}\}$ with countable state space S has the following Markov property:

$$P(X_n = j \mid X_{n-1} = i, X_{n-2} = i_2, \dots, X_0 = i_0) = P(X_n = j \mid X_{n-1} = i)$$

⇒ given the current state $X_{n-1} = i$, the future $X_n = j$ is independent of the past ($X_{n-2} = i_2, \dots, X_0 = i_0$).

n-step transition probability

$$P_{ij}(m, m+n) = P(X_{m+n} = j \mid X_m = i)$$

homogeneous

for all $i, j \in S$ and $m, n \in \mathbb{N}$, the transition probability $P_{ij}(m, m+n)$ is independent of m and only depend on n :

$$P_{ij}(m, m+n) = P_{ij}(n)$$

$$P_{ij} \equiv P_{ij}(1) = P(X_n = j \mid X_{n-1} = i)$$

transition probability matrix TPM

$$P = [P_{ij}] = \begin{bmatrix} P_{00} & P_{01} & P_{02} & \dots \\ P_{10} & P_{11} & P_{12} & \dots \\ P_{20} & P_{21} & P_{22} & \dots \\ \dots & \dots & \dots & \dots \end{bmatrix}$$

$$0 \leq P_{ij} \leq 1, \quad i, j \in \mathbb{N}$$

$$\sum_j P_{ij} = 1, \quad i \in \mathbb{N}$$

sojourn time

def: given a state i of a DTMC $\{X_n \in S: n \in \mathbb{N}\}$, the sojourn time T_i of state i is the discrete r.v. that gives the # of time steps DTMC resides in state i before transiting to a different state.

T_i is a geometric r.v. with success probability $(1 - p_{ii})$.

$$P(T_i = n) = p_{ii}^{n-1} (1 - p_{ii})$$

$$\text{mean: } E(T_i) = \frac{1}{1 - p_{ii}}$$

$$p_{ii} = 0 \Rightarrow E(T_i) = 1$$

$$p_{ii} = 1 \Rightarrow E(T_i) = \infty$$

Example 5.1:

a machine has 2 states: working (state 0) and breakdown (state 1). The state is examined every hour.

the system can be formulated as a homogeneous DTMC $\{X_n \in S: n \in \mathbb{N}\}$, where $S = \{0, 1\}$ and the time constants t_0, t_1, t_2, \dots , correspond to 0, 1h, 2h, \dots , respectively.

let a = probability that machine is failed in a given hour = p_{01} .
 b = probability that the failed machine gets repaired in a given hour = p_{10} .

TPM:

$$P = \begin{bmatrix} p_{00} & p_{01} \\ p_{10} & p_{11} \end{bmatrix} = \begin{bmatrix} 1-a & a \\ b & 1-b \end{bmatrix}, \quad 0 \leq a, b \leq 1$$

case 1: $a = b = 0$

$$P = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

mean sojourn time:

$$E(T_i) = (1 - p_{ii})^{-1} \cdot E(T_0) = \infty = E(T_i).$$

case 2: $a = b = 1$

$$P = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$E(T_i) = (1 - p_{ii})^{-1} \cdot E(T_0) = 1 = E(T_i).$$

case 3: $a, b \in (0, 1)$

$$P = \begin{bmatrix} 1-a & a \\ b & 1-b \end{bmatrix}$$

$$E(T_i) = (1 - p_{ii})^{-1} \cdot E(T_0) = a^{-1},$$

$$E(T_i) = b^{-1}.$$

6. Chapman-Kolmogorov equation

for $m, n \geq 0$, $i, j \in S$:

$$\begin{aligned} P_{ij}(m+n) &= P(X_{m+n}=j \mid X_0=i) \\ &= \sum_{k \in S} P(X_{m+n}=j, X_m=k \mid X_0=i) \\ &= \sum_{k \in S} P(X_{m+n}=j \mid X_m=k, X_0=i) \\ &\quad \cdot P(X_m=k \mid X_0=i) \\ &= \sum_{k \in S} P(X_{m+n}=j \mid X_m=k) P(X_m=k \mid X_0=i) \\ &= \sum_{k \in S} P_{kj}(n) P_{ik}(m) \end{aligned}$$

$$\Rightarrow P(m+n) = P(m)P(n).$$

n -step transition probabilities:

$$p(n) = [P_{ij}(n)], \quad p(0) = I,$$

let $m=n-1$, $n \geq 1$.

$$P_{ij}(m+n) = \sum_{k \in S} P_{ik}(m) P_{kj}(n)$$

$$\Rightarrow P_{ij}(n) = \sum_{k \in S} P_{ik}(n-1) P_{kj}(1)$$

$$\text{or } P(n) = p(n-1) \cdot p, \quad n \geq 1$$

$$\Rightarrow P(n) = p^n, \quad n \geq 1$$

State Probabilities

assume $S = \{0, 1, 2, \dots\}$.

$$p_j(n) = P(X_n=j), \quad n=0, 1, 2, \dots, \\ j=0, 1, 2, \dots,$$

by total probability theorem:

$$\begin{aligned} p_j(n) &= P(X_n=j) \\ &= \sum_{i \in S} P(X_n=j, X_0=i) \\ &= \sum_{i \in S} P(X_n=j \mid X_0=i) P(X_0=i) \\ &= \sum_{i \in S} P_i(0) P_{ij}(n), \quad j=0, 1, 2, \dots \end{aligned}$$

$$\text{let } \pi(n) = [p_0(n) \ p_1(n) \ p_2(n) \ \dots].$$

$\pi(n)$ gives the pmf of r.v. X_n .

$\pi(0)$ gives the initial r.v. X_0 .

$$\pi(n) = \pi(0)P(n) = \pi(0)P^n, \\ n=0, 1, 2, \dots$$

thus, knowing $\pi(0)$ and P , we can compute $\pi(n)$.

Steady State analysis

assume the following limiting probabilities exist and are unique

$$\lim_{n \rightarrow \infty} P_j(n), \quad j = 0, 1, \dots$$

$$\lim_{n \rightarrow \infty} P_{ij}(n), \quad i, j = 0, 1, \dots$$

⇒ for any j :

$$y_j = \lim_{n \rightarrow \infty} P_j(n) = \lim_{n \rightarrow \infty} P_{ij}(n).$$

$$\gamma = \lim_{n \rightarrow \infty} \pi(n) = [\gamma_0 \ \gamma_1 \ \gamma_2 \ \dots]$$

is called the **vector** of the steady-state probabilities.

$$\lim_{n \rightarrow \infty} P^n = \lim_{n \rightarrow \infty} P(n) = \begin{bmatrix} \gamma \\ \gamma \\ \vdots \\ \gamma \end{bmatrix}.$$

$$\begin{aligned} \pi(n) &= \pi(0) P^n = \pi(0) P^{n-1} P \\ &= \pi(n-1) P. \end{aligned}$$

$$\text{So } \lim_{n \rightarrow \infty} \pi(n) = \lim_{n \rightarrow \infty} \pi(n-1) P$$

$$\Rightarrow \gamma = \gamma P,$$

$$\text{with } \sum_j \gamma_j = 1, \quad \gamma_j \geq 0, \quad j \geq 0.$$

therefore, we can compute γ .

Example 6.1

TPM: $P = \begin{bmatrix} 1-a & a \\ b & 1-b \end{bmatrix}$,
 $0 \leq a, b \leq 1$

case 1: $a = b = 0$

$$P = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I.$$

$$P(n) = P^n = I.$$

$$\pi(n) = \pi(0) P(n) = \pi(0) P^n = \pi(0)$$

⇒ if the initial state $X_0 = 0$,

then $\pi(0) = [1 \ 0] = \pi(n)$,

the system will remain forever in state 0;

if $X_0 = 1$, then $\pi(0) = [0 \ 1]$,

the system will remain forever in state 1.

case 2: $a = b = 1$

$$P = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}.$$

$$P^2 = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I.$$

$$P^3 = P^2 P = P.$$

$$P^4 = P^3 P = P^2 = I, \dots$$

⇒ $P^n = \begin{cases} I, & \text{if } n \text{ is even} \\ P, & \text{if } n \text{ is odd} \end{cases}$

Suppose $X_0 = [1 \ 0] = \pi(0)$,

$$\pi(n) = \pi(0) P^n = \begin{cases} \pi(0) I, & \text{even} \\ \pi(0) P, & \text{odd} \end{cases}$$

$$= \begin{cases} [1 \ 0], & \text{if } n \text{ is even} \\ [0 \ 1], & \text{if } n \text{ is odd} \end{cases}$$

the system will be in state 0 after even # of steps, and in state 1 after odd # of steps.

case 3: $a, b \in (0, 1)$,
 $|1-a-b| < 1$

$$P = \begin{bmatrix} 1-a & a \\ b & 1-b \end{bmatrix}.$$

$$P^n = \begin{bmatrix} \frac{b+ax^n}{a+b} & \frac{a-ax^n}{a+b} \\ \frac{b-bx^n}{a+b} & \frac{a+bx^n}{a+b} \end{bmatrix},$$

where $x = 1-a-b$, $|x| < 1$

$$\lim_{n \rightarrow \infty} P^n = \begin{bmatrix} \frac{b}{a+b} & \frac{a}{a+b} \\ \frac{b}{a+b} & \frac{a}{a+b} \end{bmatrix}$$

⇒ if the initial state is 0,

then $\pi(0) = [1 \ 0]$,

$$\pi(n) = \pi(0) P^n = \begin{bmatrix} \frac{b+ax^n}{a+b} & \frac{a-ax^n}{a+b} \end{bmatrix}$$

if the initial state is 1,

then $\pi(0) = [0 \ 1]$,

$$\pi(n) = \pi(0) P^n = \begin{bmatrix} \frac{b-bx^n}{a+b} & \frac{a+bx^n}{a+b} \end{bmatrix}$$

as $n \rightarrow \infty$, both $\pi(n)$ give:

$$\pi(\infty) = \lim_{n \rightarrow \infty} \pi(n) = \begin{bmatrix} \frac{b}{a+b} & \frac{a}{a+b} \end{bmatrix}$$

the DTMC settles down to a behavior whereby it visits state 0 $\frac{b}{a+b}$ of time, and state 1 $\frac{a}{a+b}$ of time.

⇒ steady-state probability or limiting probability of state 0 and state 1.

7. CTMC

def: a continuous time discrete state space process $\{X(t) : t \geq 0\}$ with state space S is called CTMC if the following Markov property is satisfied:

for all $s \geq 0, u \geq 0, t > s$, and $i, j, X(u) \in S$:

$$\begin{aligned} P(X(t) = j \mid X(s) = i, X(u) = X(u)) \\ \text{for } 0 \leq u < s) \\ = P(X(t) = j \mid X(s) = i). \end{aligned}$$

$P_{ij}(s, t) = P(X(t) = j \mid X(s) = i)$ are called transition probabilities corresponding to states $i, j \in S$ and $t \geq s \geq 0$.

$$P_{ij}(s, s) = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases}$$

A CTMC is said to be homogeneous or to have stationary transition probabilities if:

for each $t \geq s \geq 0$, $P_{ij}(s, t)$ does NOT depend on s , and only depends on $t - s$.

$$\begin{aligned} \Rightarrow P_{ij}(s, t) &= P_{ij}(t - s) \\ &= P(X(u + t - s) = j \mid X(u) = i) \end{aligned}$$

sojourn times in states 4

def: given a state i of a CTMC $\{X(t) : t \geq 0\}$, sojourn time T_i of state i is a continuous r.v. that denotes the span of time.

T_i is an exponential r.v.

$$P(T_i > s + x \mid T_i > s) = h(x),$$

where $h(x)$ is a function of x only.

$$\begin{aligned} P(T_i > s + x \mid T_i > s) \\ = \frac{P(T_i > s + x, T_i > s)}{P(T_i > s)} \\ = \frac{P(T_i > s + x)}{P(T_i > s)} = h(x), \end{aligned}$$

letting $s = 0$ and $P(T_i > 0) = 1$:

$$\begin{aligned} \Rightarrow h(x) &= P(T_i > x) \\ &= e^{-\lambda_i x}, \quad x \geq 0 \end{aligned}$$

if $\lambda_i = 0$: absorbing state;

if $\lambda_i = \infty$: instantaneous state;

if $\lambda_i \in (0, \infty)$: stable state.

8. C-K eqn

def: consider a CTMC $\{X(t): t \geq 0\}$ with state space $\{0, 1, 2, \dots\}$.

$P_{ij}(s, t) = P(X(t) = j \mid X(s) = i)$
can be expressed as matrix form:

$$H(s, t) = [P_{ij}(s, t)]$$

$$H(s, s) = I$$

for $0 \leq s \leq u \leq t$.

$$\begin{aligned} P_{ij}(s, t) &= P(X(t) = j \mid X(s) = i) \\ &= \sum_{k \in S} P(X(t) = j, X(u) = k \mid X(s) = i) \\ &= \sum_{k \in S} P(X(t) = j \mid X(u) = k, X(s) = i) \\ &\quad \cdot P(X(u) = k \mid X(s) = i) \\ &= \sum_{k \in S} P(X(t) = j \mid X(u) = k) \\ &\quad \cdot P(X(u) = k \mid X(s) = i) \\ &= \sum_{k \in S} P_{ik}(s, u) P_{kj}(u, t) \end{aligned}$$

matrix form:

$$H(s, t) = H(s, u)H(u, t), \\ 0 \leq s \leq u \leq t$$

9. Kolmogorov Differential Eqn

def: let h be an infinitesimal increment in time. $t = t+h, u = t$.

$$H(s, t+h) = H(s, t)H(t, t+h)$$

$$H(s, t+h) - H(s, t) = H(s, t)H(t, t+h) - H(s, t)$$

$$H(s, t+h) - H(s, t) = H(s, t)[H(t, t+h) - I]$$

$$\lim_{h \rightarrow 0} \frac{H(s, t+h) - H(s, t)}{h}$$

$$= H(s, t) \lim_{h \rightarrow 0} \frac{H(t, t+h) - I}{h}$$

$$= H(s, t) Q(t)$$

partial differential eqn:

$$\frac{\partial H(s, t)}{\partial t} = H(s, t) Q(t)$$

with initial state $H(s, s) = I$,
is called the forward
Kolmogorov equation.

$Q(t)$ is called the infinitesimal
generator of the CTMC, and
is also called transition rate
matrix.

take $u = s+h$:

backward Kolmogorov eqn:

$$\frac{\partial H(s, t)}{\partial s} = -Q(s)H(s, t)$$

with initial condition $H(s, s) = I$.

Interpretation of $Q(t)$:

$$Q(t) = \lim_{h \rightarrow 0} \frac{H(t, t+h) - I}{h}$$

$$= [q_{ij}(t)] ,$$

$$q_{ii}(t) = \lim_{h \rightarrow 0} \frac{P_{ii}(t, t+h) - 1}{h}$$

$$q_{ij}(t) = \lim_{h \rightarrow 0} \frac{P_{ij}(t, t+h)}{h}, \quad i \neq j$$

is the rate at which CTMC moves from state i to state j ($i \neq j$) in the time interval $(t, t+h)$.

since $\sum_j P_{ij}(s, t) = 1$:

$$q_{ii}(t) + q_{ij}(t) = \sum_j q_{ij}(t) = 0, \quad \text{for all } i$$

the sum of any row of $Q(t)$ is zero.

Homogeneous CTMC:

def: the transition probabilities $P_{ij}(x, x+t)$ do not depend on x and only depend on t .

$$P_{ij}(t) = P_{ij}(x, x+t) ,$$

$$H(t) = H(x, x+t) = [P_{ij}(t)] ,$$

$$q_{ij} = q_{ij}(x) ,$$

$$Q = Q(x) = [q_{ij}] ,$$

$$H(x+t) = H(x) H(t)$$

$$\frac{dH(t)}{dt} = H(t) Q, \quad H(0) = I$$

solution: $H(t) = \exp(Qt)$

$$= I + Qt + Q^2 \frac{t^2}{2!} + Q^3 \frac{t^3}{3!} + \dots$$

State Probabilities:

assume the state space is $S = \{0, 1, 2, \dots\}$,

$$P_j(t) = P(X(t) = j)$$

$$\text{let } \pi(t) = [P_0(t) \ P_1(t) \ P_2(t) \ \dots]$$

by the total probability thm:

$$P_j(t) = P(X(t) = j)$$

$$= \sum_{i \in S} P(X(t) = j, X(0) = i)$$

$$= \sum_{i \in S} P(X(t) = j | X(0) = i) P(X(0) = i)$$

$$= \sum_{i \in S} P_i(0) P_{ij}(t)$$

matrix form:

$$\pi(t) = \pi(0) H(t)$$

$$= \pi(0) \exp(Qt) ,$$

$$\frac{d\pi(t)}{dt} = \pi(0) \exp(Qt) Q$$

$$= \pi(t) Q .$$

Steady State Analysis: ($t \rightarrow \infty$)

$$\pi_j = \lim_{t \rightarrow \infty} P_j(t), \quad j = 0, 1, \dots$$

is the long-run proportion of residence time in state j , which satisfies:

$$1. \sum_j \pi_j = 1 ;$$

2. unique, independent of the initial state.

$$\pi = [\pi_0 \ \pi_1 \ \pi_2 \ \dots]$$

is the steady-state probability distribution of the CTMC.

to obtain vector π , set:

$$\frac{d\pi(t)}{dt} = 0, \quad \pi(t)Q = 0,$$

hence, π can be obtained as the solution of:

$$\begin{cases} \pi Q = 0 \\ \sum_j \pi_j = 1 \\ \pi_j \geq 0, j=0,1,2,\dots \end{cases}$$

$$\pi Q = 0 \Rightarrow q_{jj}\pi_j + \sum_{k \neq j} q_{kj}\pi_k = 0 = \sum_k q_{jk}\pi_k$$

$$\Rightarrow \pi_j \left(\sum_{k \neq j} q_{jk} \right) = \sum_{k \neq j} q_{kj}\pi_k$$

Example 9.1:

states:

0: set up

1: processing

2: failed, being repaired

transition rate:

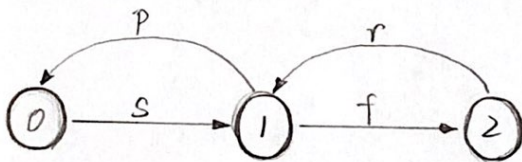
S: setup rate

P: processing rate

f: failure rate

r: repair rate

case 1: the system follows resume policy



$$Q = \begin{bmatrix} q_{00} & q_{01} & q_{02} \\ q_{10} & q_{11} & q_{12} \\ q_{20} & q_{21} & q_{22} \end{bmatrix} = \begin{bmatrix} -S & S & 0 \\ P & -(P+f) & f \\ 0 & r & -r \end{bmatrix}$$

to find the steady-state probability vector $\pi = [\pi_0 \ \pi_1 \ \pi_2]$:

$$\pi Q = 0,$$

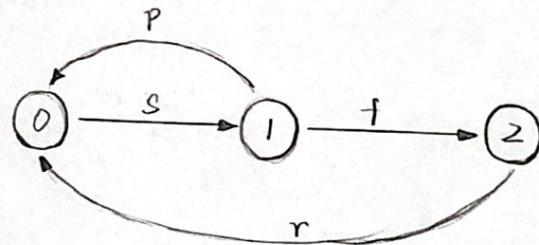
$$\begin{cases} \pi_0 S = \pi_1 P \\ \pi_1 (P+f) = \pi_0 S + \pi_2 r \\ \pi_2 r = \pi_1 f \end{cases},$$

$$\pi_0 + \pi_1 + \pi_2 = 1,$$

$$\Rightarrow \pi_0 = \frac{Pr}{Pr+rs+fs}$$

$$\pi_1 = \frac{rs}{Pr+rs+fs}, \quad \pi_2 = \frac{fs}{Pr+rs+fs}$$

case 2: the system follows discard policy



$$Q = \begin{bmatrix} -S & S & 0 \\ P & -(P+f) & f \\ r & 0 & -r \end{bmatrix}$$

10. Birth-Death Process

a special case of CTMC.

def: a homogeneous CTMC $\{X(t) : t \geq 0\}$ with state space $\{0, 1, 2, \dots\}$ is called a BD process if there exists constants λ_i and μ_i such that the transition rates are given by:

$$q_{i, i+1} = \lambda_i, \quad i = 0, 1, 2, \dots$$

$$q_{i, i-1} = \mu_i, \quad i = 1, 2, 3, \dots$$

$$q_{ij} = 0, \quad |i - j| > 1$$

in state i , λ_i is birth rate, μ_i is death rate

Steady State Analysis:

rate balance eqn:

$$\lambda_0 \pi_0 = \mu_1 \pi_1$$

$$(\mu_k + \lambda_k) \pi_k = \pi_{k-1} \lambda_{k-1} + \pi_{k+1} \mu_{k+1}$$

QUEUEING MODELS

Outline:

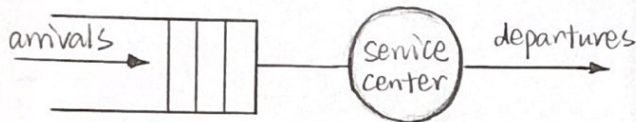
1. Queues
2. Little's result
3. M/M/1
4. M/M/1/N
5. M/M/m
6. M^b/M/1

1. Queues

def: a queue is a system into which customers arrive to receive service.

3 basic elements:

- arrivals
- service mechanism
- queueing discipline



notations:

- A : arrival process
- S : service distribution for the arriving customers
- m : no. of servers
- K : storage space
- L : customer population
- C_1, C_2, \dots : stream of customers
- S_j : service time of C_j
- D_j : waiting time of C_j in queue
- $W_j = D_j + S_j$: waiting time of C_j in system

* in system: either in service or in the queue

2. Little's Result

notations:

- λ : arrival rate
- W : mean waiting time in system
- D : mean waiting time in queue
- L : mean no. of customers in the system
- Q : mean no. of customers in the queue

in the steady state: ($t \rightarrow \infty$)

$$L = \lambda W, \quad Q = \lambda D$$

M: Poisson process with rate λ
arrival / service time / # of service

Little's results:

$$L = \lambda W$$

$$Q = \lambda D$$

Appendix A

M/M/1 Queue with Arrival Rate λ and Service Rate μ :

$$\text{utilization: } \rho = \frac{\lambda}{\mu} = \frac{\text{arrival rate}}{\text{service rate}}$$

$$\text{steady-state probability: } \pi_0 = 1 - \rho$$

$$\pi_k = \rho^k (1 - \rho), \quad k \geq 1$$

$$\text{mean \# of customers in system: } L = \frac{\rho}{1 - \rho} = \frac{\lambda}{\mu - \lambda}$$

$$\text{mean \# of customers in queue: } Q = \frac{\rho^2}{1 - \rho} = \frac{\lambda^2}{\mu(\mu - \lambda)}$$

$$\text{mean waiting-time in system: } W = \frac{1}{\mu(1 - \rho)} = \frac{1}{\mu - \lambda}$$

$$\text{mean waiting-time in queue: } D = D = W - \frac{1}{\mu} = \frac{\lambda}{\mu(\mu - \lambda)}$$

M/M/1/N Queue with Arrival Rate λ and Service Rate μ :

production rate $U\mu$

最多同时服务 $N-1$
($< N$)

$$\rho = \frac{\lambda}{\mu} \quad U = 1 - \pi_0$$

$$\lambda_k = \begin{cases} \lambda, & 0 \leq k \leq N-1 \\ 0, & k \geq N \end{cases}$$

$$\pi_0 = \left(\sum_{k=0}^N \rho^k \right)^{-1} = \frac{1 - \rho}{1 - \rho^{N+1}}$$

$$\pi_k = \rho^k \pi_0 = \frac{\rho^k (1 - \rho)}{1 - \rho^{N+1}}, \quad 0 \leq k \leq N$$

$$L = \frac{\rho[1 - \rho^N - N\rho^N(1 - \rho)]}{(1 - \rho)(1 - \rho^{N+1})} = \sum_{k=1}^N k\pi_k = \pi_1 + 2\pi_2 + 3\pi_3 + \dots$$

$$Q = \frac{\rho^2[1 - \rho^N - N\rho^{N-1}(1 - \rho)]}{(1 - \rho)(1 - \rho^{N+1})}$$

$$W = \frac{1 - \rho^N - N\rho^N(1 - \rho)}{\mu(1 - \rho)(1 - \rho^{N+1})} = \frac{L}{\lambda}$$

$$D = \frac{\rho[1 - \rho^N - N\rho^{N-1}(1 - \rho)]}{\mu(1 - \rho)(1 - \rho^{N+1})} = \frac{Q}{\lambda}$$

超过 N , 停止服务

$$\text{Utilization } U = \pi_1 + \pi_2 + \dots + \pi_N$$

$$= 1 - \pi_0$$

$$= \frac{\rho(1 - \rho^N)}{1 - \rho^{N+1}}$$

$$\text{production rate: } (1 - \pi_0)\mu$$

$$\lambda_k = \lambda, \quad k \geq 0$$

$$\mu_k = \begin{cases} k\mu, & 0 \leq k \leq m-1 \\ m\mu, & k \geq m \end{cases}$$

M/M/m Queue with Arrival Rate λ and Service Rate μ :

m servers, 同时服务 m 个

$$\rho = \frac{\lambda}{m\mu}$$

average # of busy servers
in steady state:

$$B = \frac{\lambda}{\mu}$$

mean utilization of each
server:

$$U = \frac{\lambda}{m\mu} = \rho$$

$$\pi_0 = \left[\frac{(m\rho)^m}{m!(1-\rho)} + \sum_{k=0}^{m-1} \frac{(m\rho)^k}{k!} \right]^{-1}$$

$$\pi_k = \pi_0 \begin{cases} \frac{(m\rho)^k}{k!}, & 0 \leq k \leq m-1 \\ \frac{m^m \rho^k}{m!}, & k \geq m \end{cases}$$

$$L = \frac{\rho(m\rho)^m \pi_0}{m!(1-\rho)^2} + \frac{\lambda}{\mu}$$

$$Q = \sum_{k=m}^{\infty} (k-m) \pi_k = \frac{\rho(m\rho)^m \pi_0}{m!(1-\rho)^2}$$

$$W = \frac{L}{\lambda} = \frac{\rho(m\rho)^m \pi_0}{m!\lambda(1-\rho)^2} + \frac{1}{\mu}$$

$$D = W - \frac{1}{\mu} = \frac{\rho(m\rho)^m \pi_0}{m!\lambda(1-\rho)^2}$$

M^b/M/1 Queue with Arrival Rate λ and Service Rate μ :

bulk size: 一个 batch 中有 b 个 work pieces

$$\rho = \frac{b\lambda}{\mu}$$

rate-balance eqn:

$$\pi_0 = 1 - \rho$$

$$\begin{aligned} (\lambda + \mu)\pi_k &= \lambda\pi_{k-b} + \mu\pi_{k+1}, \quad k \geq b \\ (\lambda + \mu)\pi_k &= \mu\pi_{k+1}, \quad 1 \leq k \leq b-1 \\ \lambda\pi_0 &= \mu\pi_1 \end{aligned} \quad \pi_k = \begin{cases} \left(\frac{\lambda + \mu}{\mu} \right)^{k-1} \frac{\lambda}{\mu} \pi_0 & 1 \leq k \leq b \\ \frac{\lambda + \mu}{\mu} \pi_{k-1} - \frac{\lambda}{\mu} \pi_{k-b-1} & k \geq b+1 \end{cases} \quad \text{steady-state probabilities}$$

$$L = \frac{\rho(1+b)}{2(1-\rho)} \quad \text{mean \# of customers in system}$$

$$Q = L - \rho = \frac{\rho(b-1+2\rho)}{2(1-\rho)} \quad \text{mean \# of customers in queue}$$

$$W = \frac{L}{\lambda b} = \frac{1+b}{2\mu(1-\rho)} \quad \text{mean waiting time in system}$$

$$D = W - \frac{1}{\mu} = \frac{b+2\rho-1}{2\mu(1-\rho)} \quad \text{mean waiting time in queue}$$

$$\text{utilization: } U = \rho = \frac{b\lambda}{\mu}$$