

$$1. (a) \quad X[n] = 2\cos\left(\frac{\pi q n}{3}\right) = e^{j\left(\frac{\pi q}{3}\right)} + e^{-j\left(\frac{\pi q}{3}\right)}$$

$$X(\omega) = \sum_{n=-\infty}^{\infty} X[n] e^{-j\omega n} = \sum_{n=-\infty}^{\infty} (e^{j\left(\frac{\pi q}{3}\right)} + e^{-j\left(\frac{\pi q}{3}\right)}) e^{-j\omega n}$$

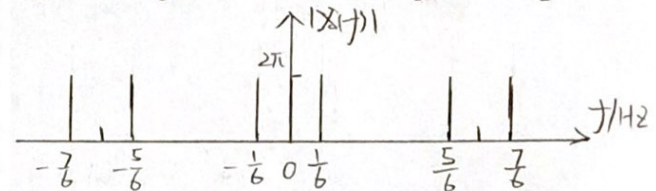
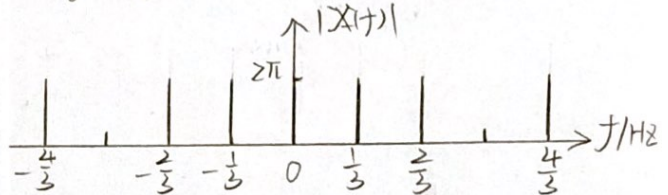
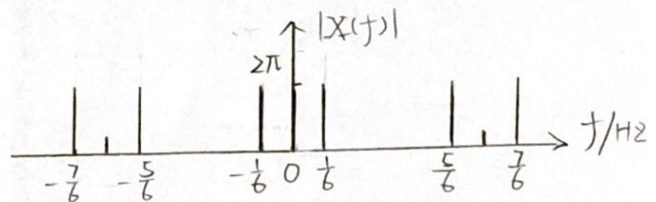
$$= \sum_{n=-\infty}^{\infty} (e^{j\left(\frac{\pi q}{3} - \omega\right)n} + e^{-j\left(\frac{\pi q}{3} + \omega\right)n})$$

$$= 2\pi \sum_{k=-\infty}^{\infty} [\delta(\omega - \frac{\pi q}{3} - 2\pi k) + \delta(\omega + \frac{\pi q}{3} - 2\pi k)]$$

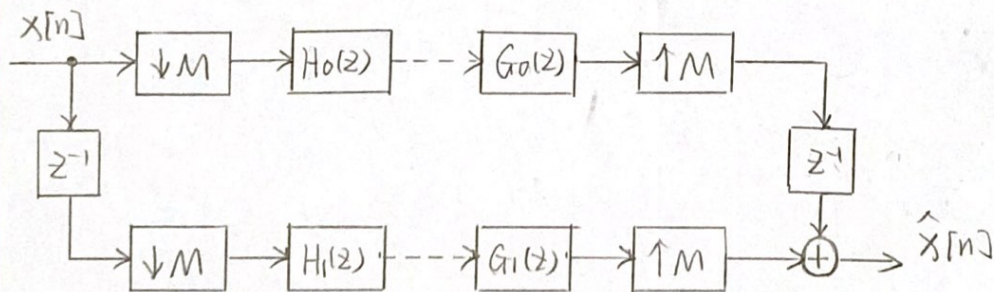
$$q=1: \quad f_1 = \frac{\omega}{2\pi} = \frac{\frac{\pi}{3}}{2\pi} = \frac{1}{6}$$

$$q=2: \quad f_2 = \frac{\omega}{2\pi} = \frac{\frac{2}{3}\pi}{2\pi} = \frac{1}{3}$$

$$q=5: \quad f_5 = \frac{\omega}{2\pi} = \frac{\frac{5}{3}\pi}{2\pi} = \frac{5}{6}$$



(b)



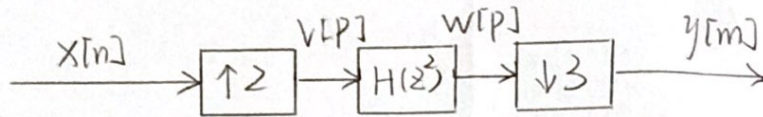
$$H_0(z) = P_0(z^2) + z^{-1}P_1(z^2)$$

$$H_1(z) = P_0(z^2) - z^{-1}P_1(z^2)$$

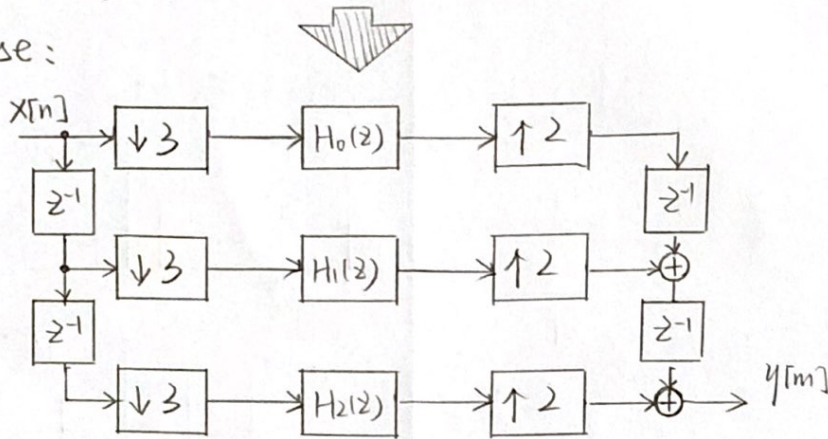
$$G_0(z) = P_0(z^2) + z^{-1}P_1(z^2)$$

$$G_1(z) = -P_0(z^2) + z^{-1}P_1(z^2)$$

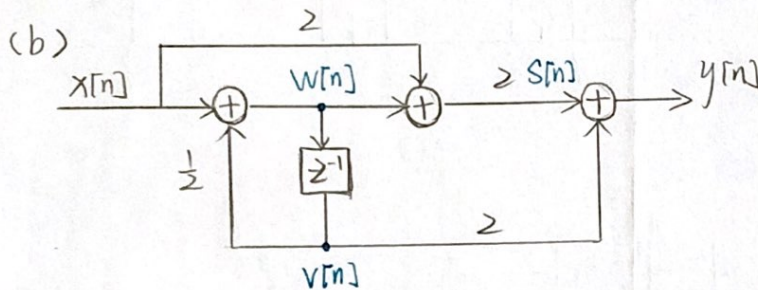
2. (a) $\frac{I}{D} = \frac{2}{3}$



polyphase:



The subfilters are working at the lowest sampling frequency.



$$W(z) = X(z) + \frac{1}{2} V(z), \quad V(z) = z^{-1} W(z),$$

$$\Rightarrow W(z) = X(z) + \frac{1}{2} z^{-1} W(z), \quad X(z) = \left(1 - \frac{1}{2} z^{-1}\right) W(z)$$

$$S(z) = W(z) + 2X(z)$$

$$\begin{aligned} Y(z) &= 2V(z) + 2S(z) = 2z^{-1}W(z) + 2W(z) + 4X(z) \\ &= (2z^{-1} + 2)W(z) + (4 - 2z^{-1})W(z) \\ &= 6W(z) \end{aligned}$$

$$\frac{Y(z)}{X(z)} = \frac{6}{1 - \frac{1}{2} z^{-1}}$$

$$\cos \omega_0 t = \frac{1}{2} (e^{j\omega_0 t} + e^{-j\omega_0 t}), \quad \sin \omega_0 t = \frac{1}{2j} (e^{j\omega_0 t} - e^{-j\omega_0 t})$$

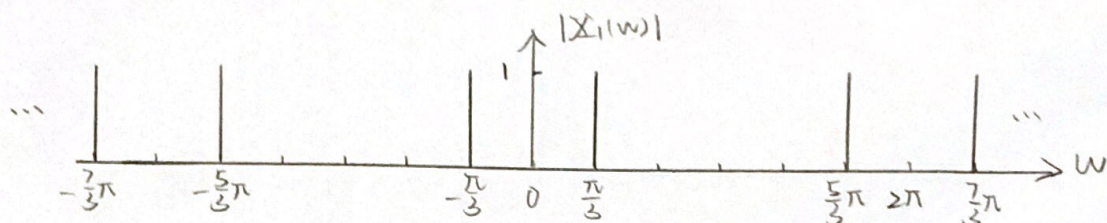
$$\Rightarrow \mathcal{F}[\cos \omega_0 t] = \pi [\delta(\omega + \omega_0) + \delta(\omega - \omega_0)]$$

$$\mathcal{F}[\sin \omega_0 t] = j\pi [\delta(\omega + \omega_0) - \delta(\omega - \omega_0)]$$

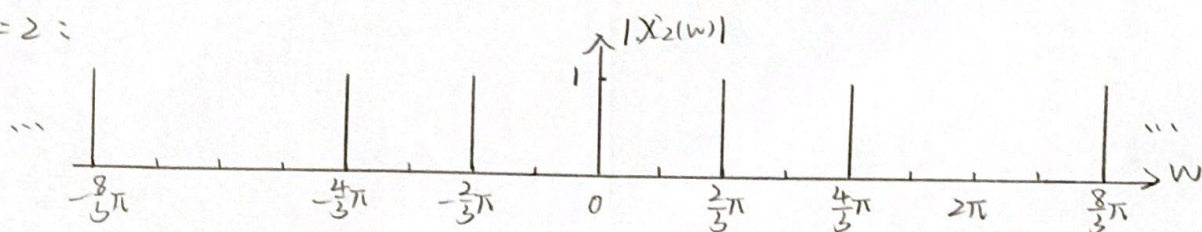
$$x[n] = 2\cos\left(\frac{1}{3}\pi q n\right) = e^{j(\frac{1}{3}\pi q n)} + e^{-j(\frac{1}{3}\pi q n)}$$

$$\begin{aligned} X(\omega) &= \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n} = \sum_{n=-\infty}^{\infty} (e^{j(\frac{1}{3}\pi q - \omega)n} + e^{-j(\frac{1}{3}\pi q + \omega)n}) \\ &= 2\pi \sum_{k=-\infty}^{\infty} [\delta(\omega + \frac{1}{3}\pi q - 2k\pi) + \delta(\omega - \frac{1}{3}\pi q - 2k\pi)] \end{aligned}$$

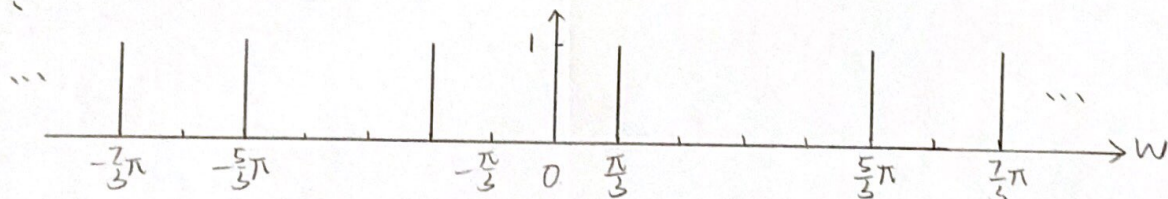
$$q=1:$$



$$q=2:$$



$$q=5:$$



$$\mathcal{F}[\delta(t)] = \int_{-\infty}^{+\infty} \delta(t) e^{-j\omega t} dt = e^{-j\omega t} \Big|_0 = 1,$$

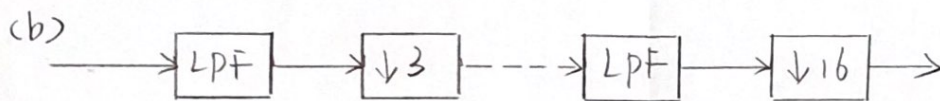
$$\mathcal{F}^{-1}[1(t)] = \frac{1}{2\pi} \int_{-\infty}^{+\infty} 1 \cdot e^{j\omega t} d\omega = \delta(t),$$

$$\Rightarrow \int_{-\infty}^{+\infty} e^{j\omega t} d\omega = 2\pi \delta(t)$$

3. (a) parameters used to specify LPF:

- ① passband freq $\omega_p = 2\pi \frac{F_p}{F_T}$,
- ② stopband freq $\omega_s = 2\pi \frac{F_s}{F_T}$,
- ③ passband ripple $\delta_p = 0.5(1 - 10^{-\frac{\alpha_p}{20}})$,
- ④ stopband ripple $\delta_s = 10^{-\frac{\alpha_s}{20}}$.
- ⑤ filter order $N = \frac{-10 \log_{10}(\delta_p \delta_s) - 13}{14.6 \times (\omega_s - \omega_p) / 2\pi}$.

$\Rightarrow \delta_p \delta_s \downarrow \rightarrow N \uparrow$; N is inversely proportional to the size of ripples.
 $(\omega_s - \omega_p) \downarrow \rightarrow N \uparrow$; N is inversely proportional to the transition bandwidth.
 $F_T \downarrow \rightarrow N \downarrow$. N is proportional to the sampling freq.



$$\delta_p = 0.01, \delta_s = 0.001, F_T = 48 \times 10^3 \text{ Hz}$$

Stage 1: $D_1 = 3, \delta_{p1} = \frac{1}{2} \delta_p = 0.005, \delta_{s1} = \delta_s = 0.001$.

passband freq: $0 \sim 450 \text{ Hz}$,

stopband freq: $450 \sim (48\text{K}/3) - 450 = 15550 \text{ Hz}$,

$$\Delta F_1 = (15550 - 450) / 48 \times 10^3 = 0.31458$$

$$N_1 = \frac{-10 \log_{10}(\delta_{p1} \delta_{s1}) - 13}{14.6 \times \Delta F_1} + 1 = 9.17 \approx 10$$

Stage 2: $D_2 = 16, \delta_{p2} = \frac{1}{2} \delta_p = 0.005, \delta_{s2} = \delta_s = 0.001$

passband freq: $0 \sim 450 \text{ Hz}$,

stopband freq: $450 \sim 500 \text{ Hz}$,

input sampling freq: $F_{T2} = F_T / 3 = 16 \times 10^3 \text{ Hz}, F_s = \frac{F_T}{20} = \frac{16 \times 10^3}{32}$

$$\Delta F_2 = (500 - 450) / 16 \times 10^3 = 0.003125, = 500 \text{ Hz},$$

$$N_2 = \frac{-10 \log_{10}(\delta_{s2} \delta_{p2}) - 13}{14.6 \times \Delta F_2} + 1 = 877.9 \approx 878$$

$$N_1 = 10, N_2 = 878$$

$$\frac{(N+1)}{2} \times F_i \text{ multiplications/sec}$$

$$N \times F_i \text{ additions/sec}$$

$$\Rightarrow \text{Stage 1: } \frac{10+1}{2} \times 48 \times 10^3 = 264 \times 10^3 \text{ multiplications/sec}$$

$$10 \times 48 \times 10^3 = 48 \times 10^4 \text{ additions/sec ;}$$

$$\text{Stage 2: } \frac{878+1}{2} \times 16 \times 10^3 = 7032 \times 10^3 = 7.032 \times 10^6 \text{ multiplications/sec}$$

$$878 \times 16 \times 10^3 = 1.4048 \times 10^7 \text{ additions/sec.}$$

$$4. \quad x[n] = s[n] + w[n], \quad s[n] - 0.4s[n-1] = v[n], \quad \sigma_v^2 = 0.36$$

$$(a) \quad T_{dx}(z) = T_{ss}(z) = \sigma_v^2 H(z) H(z^{-1}), \quad H(z) = \frac{1}{1 - 0.4z^{-1}}$$

$$= \frac{0.36}{(1 - 0.4z^{-1})(1 - 0.4z)} = \frac{0.36}{0.84} \cdot \frac{1}{1 - 0.4z^{-1}}$$

$$T_{xx}(z) = T_{dx}(z) + T_{ww}(z) = T_{dx}(z) + 1$$

$$= \frac{(1 - 0.4z^{-1})(1 - 0.4z) + 0.36}{(1 - 0.4z^{-1})(1 - 0.4z)} = \frac{1.52 - 0.4(z^{-1} + z)}{(1 - 0.4z^{-1})(1 - 0.4z)}$$

$$r_{dx}[k] = \frac{3}{7} \times (0.4)^{|k|}, \quad r_{xx}[k] = r_{dx}[k] + r_{ww}[k]$$

$$= \frac{3}{7} (0.4)^{|k|} + \delta[k]$$

$$(b) \quad \begin{bmatrix} r_{xx}[0] & r_{xx}[-1] \\ r_{xx}[1] & r_{xx}[0] \end{bmatrix} \begin{bmatrix} h[0] \\ h[1] \end{bmatrix} = \begin{bmatrix} r_{ss}[0] \\ r_{ss}[1] \end{bmatrix}$$

$$\begin{bmatrix} \frac{10}{7} & \frac{6}{35} \\ \frac{6}{35} & \frac{10}{7} \end{bmatrix} \begin{bmatrix} h[0] \\ h[1] \end{bmatrix} = \begin{bmatrix} \frac{3}{7} \\ \frac{6}{35} \end{bmatrix}$$

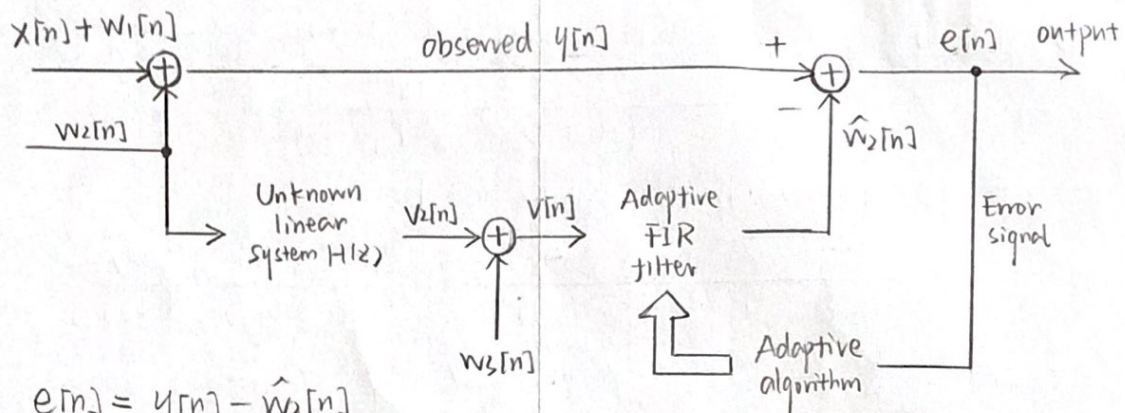
$$\begin{cases} \frac{10}{7} h[0] + \frac{6}{35} h[1] = \frac{3}{7} \\ \frac{6}{35} h[0] + \frac{10}{7} h[1] = \frac{6}{35} \end{cases} \Rightarrow \begin{cases} h[0] + \frac{42}{350} h[1] = \frac{3}{10} \\ h[0] + \frac{350}{42} h[1] = 1 \end{cases}$$

$$\Rightarrow h[1] = \frac{15}{176} \approx 0.0852, \quad h[0] = \frac{51}{176} \approx 0.2898$$

$$\min \varepsilon_2^h = r_{ss}[0] - \begin{bmatrix} r_{ss}[0] & r_{ss}[1] \end{bmatrix} \begin{bmatrix} h[0] \\ h[1] \end{bmatrix}$$

$$= \frac{3}{7} - \left(\frac{3}{7} \times \frac{51}{176} + \frac{6}{35} \times \frac{15}{176} \right) \approx 0.2898.$$

5. adaptive noise-canceling system



$$(a) \quad e[n] = y[n] - \hat{w}_2[n]$$

$$= y[n] - \sum_{k=0}^P h[k] V[n-k], \quad \text{normal equation:}$$

$$V[n] = V_2[n] + w_3[n]$$

$$V_2[n] = \sum_{k=0}^{\infty}$$

$$\sum_{k=0}^{M-1} h[k] r_w[l-k] = r_{vy}[l], \quad l=0,1,\dots,M$$

$$4. (a) \quad T_{ss}(z) = \sigma_V^2 H(z^{-1})H(z)$$

$$= \frac{0.36}{(1-0.4z^{-1})(1-0.4z)} = \frac{0.36}{0.84} \frac{1}{1-0.4z^{-1}} = \frac{3}{7} \frac{1}{1-0.4z^{-1}}$$

$$V_{ss}[m] = \frac{3}{7} (0.4)^{|m|}, \quad V_{xx}[m] = V_{ss}[m] + V_{vv}[m] \\ = \frac{3}{7} (0.4)^{|m|} + \delta[m],$$

$$T_{xx}(z) = T_{ss}(z) + T_{vv}(z) = \frac{0.36}{(1-0.4z^{-1})(1-0.4z)} + 1$$

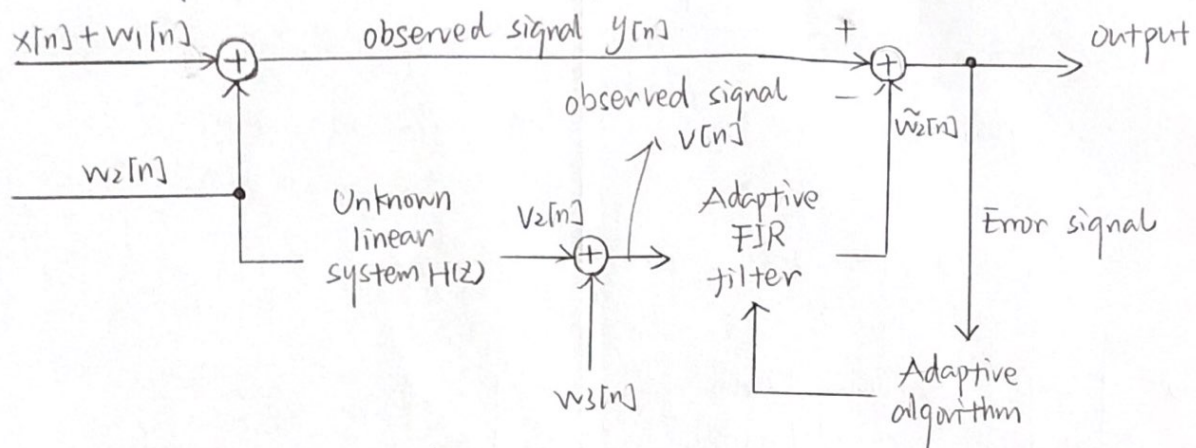
$$(b) \quad \begin{bmatrix} V_{xx}[0] & V_{xx}[1] \\ V_{xx}[-1] & V_{xx}[0] \end{bmatrix} \begin{bmatrix} h[0] \\ h[1] \end{bmatrix} = \begin{bmatrix} V_{ss}[0] \\ V_{ss}[1] \end{bmatrix}$$

$$\begin{bmatrix} \frac{10}{7} & \frac{6}{35} \\ \frac{6}{35} & \frac{10}{7} \end{bmatrix} \begin{bmatrix} h[0] \\ h[1] \end{bmatrix} = \begin{bmatrix} \frac{3}{7} \\ \frac{6}{35} \end{bmatrix}$$

$$\begin{bmatrix} h[0] \\ h[1] \end{bmatrix} = \begin{bmatrix} 0.7102 & -0.0852 \\ -0.0852 & 0.7102 \end{bmatrix} \begin{bmatrix} \frac{3}{7} \\ \frac{6}{35} \end{bmatrix} \\ = \begin{bmatrix} 0.2898 \\ 0.0852 \end{bmatrix}$$

$$\epsilon_m^h = V_{ss}[0] - \begin{bmatrix} V_{ss}[0] & V_{ss}[1] \end{bmatrix} \begin{bmatrix} h[0] \\ h[1] \end{bmatrix} \\ = \frac{3}{7} - \begin{bmatrix} \frac{3}{7} & \frac{6}{35} \end{bmatrix} \begin{bmatrix} 0.2898 \\ 0.0852 \end{bmatrix} = 0.2898$$

5. adaptive noise canceling system:



$x[n]$ is a stationary random process.

$w_1[n]$, $w_2[n]$, $w_3[n]$ are white noise sequence with $\sigma_{w_1}^2 = 0.04$, $\sigma_{w_2}^2 = 0.16$, $\sigma_{w_3}^2 = 1$. $v[n] = v_2[n] + w_3[n]$, $y[n] = x[n] + w_1[n] + w_2[n]$;

$$e[n] = y[n] - \tilde{w}_2[n] = y[n] - \sum_{k=0}^{M-1} h[k] v[n-k]; \quad v_2[n] = \sum_{l=0}^{\infty} h[l] w_2[n-l];$$

normal equation: $y_y[k] = \sum_{k=0}^{M-1} h[k] y_w[n-k]$.

$$y_w[k] = \frac{1}{N} \sum_{n=0}^{N-1} v[n] v[n-k]$$

$$= \frac{1}{N} \sum_{n=0}^{N-1} \left(\sum_{l=0}^{\infty} h[l] w_2[n-l] + w_3[n] \right) \left(\sum_{p=0}^{\infty} h[p] w_2[n-k-p] + w_3[n-k] \right)$$

$$= \frac{1}{N} \sum_{n=0}^{N-1} \left(\sum_{l=0}^{\infty} \sum_{p=0}^{\infty} h[p] h[l] w_2[n-k-p] w_2[n-l] + w_3[n] \sum_{p=0}^{\infty} h[p] w_2[n-k-p] + w_3[n-k] \sum_{l=0}^{\infty} h[l] w_2[n-l] + w_3[n] w_3[n-k] \right)$$

$$E[y_w[k]] = y_{w_3 w_3}[k] + \sum_{l=0}^{\infty} h[l] y_{w_2 w_3}[k-l] + \sum_{p=0}^{\infty} h[p] y_{w_3 w_2}[k+p]$$

$$+ \sum_{l=0}^{\infty} \sum_{p=0}^{\infty} h[p] h[l] y_{w_2 w_2}[k+p-l].$$

$$y_{yy}[k] = \frac{1}{N} \sum_{n=0}^{N-1} y[n] v[n-k] = \frac{1}{N} \sum_{n=0}^{N-1} (x[n] + w_1[n] + w_2[n]) \left(\sum_{l=0}^{\infty} h[l] w_2[n-k-l] + w_3[n-l] \right)$$

$$= \frac{1}{N} \sum_{n=0}^{N-1} \sum_{l=0}^{\infty} (x[n] + w_1[n] + w_2[n]) h[l] w_2[n-k-l] + \frac{1}{N} \sum_{n=0}^{N-1} (x[n] + w_1[n] + w_2[n]) \cdot w_3[n-l].$$

$$E[y_{yy}[k]] = \sum_{l=0}^{\infty} h[l] (y_{x w_2}[k+l] + y_{w_1 w_2}[k+l] + y_{w_2 w_2}[k+l]) + y_{x w_3}[k] + y_{w_1 w_3}[k] + y_{w_2 w_3}[k].$$

$$\Gamma_m h_m = y_y, \quad \Gamma_m[n+1] = \Gamma_m[n] + \frac{1}{2} \Delta[n] S[n] = \Gamma_m[n] - \frac{1}{2} \Delta[n] g[n]$$

$$g[n] = \frac{dE_m}{d h_m} = 2(\Gamma_m h_m - y_y)$$

EE6401

NANYANG TECHNOLOGICAL UNIVERSITY
SEMESTER 1 EXAMINATION 2017-2018
EE6401 – ADVANCED DIGITAL SIGNAL PROCESSING

November/December 2017

Time Allowed: 3 hours

INSTRUCTIONS

1. This paper contains 5 questions and comprises 3 pages.
2. Answer all 5 questions.
3. All questions carry equal marks.
4. This is a closed-book examination.

$$X(\omega) = 2\pi \sum_{k=-\infty}^{\infty} \left(\delta\left(\omega + \frac{q}{3}\pi - 2k\pi\right) + \delta\left(\omega - \frac{q}{3}\pi - 2k\pi\right) \right)$$

1. (a) Find the discrete-time Fourier transform (DTFT) of the signal

$$x[n] = 2 \cos\left(\frac{\pi q n}{3}\right)$$

for $q = 1, 2$ and 5 . Plot these DTFTs and comment on your observations.

(8 Marks)

- (b) For a two-channel alias-free quadrature filter bank, the filters $H_0(z)$, $H_1(z)$, $G_0(z)$ and $G_1(z)$ in the analysis and synthesis sections can be implemented with a two-branch polyphase filter structure. For example, $H_0(z) = P_0(z^2) + z^{-1}P_1(z^2)$, where $P_0(z)$ and $P_1(z)$ are the expressions of the branch filters in the polyphase implementation. Find a computationally efficient polyphase implementation of the two-channel alias-free quadrature filter bank.

(12 Marks)

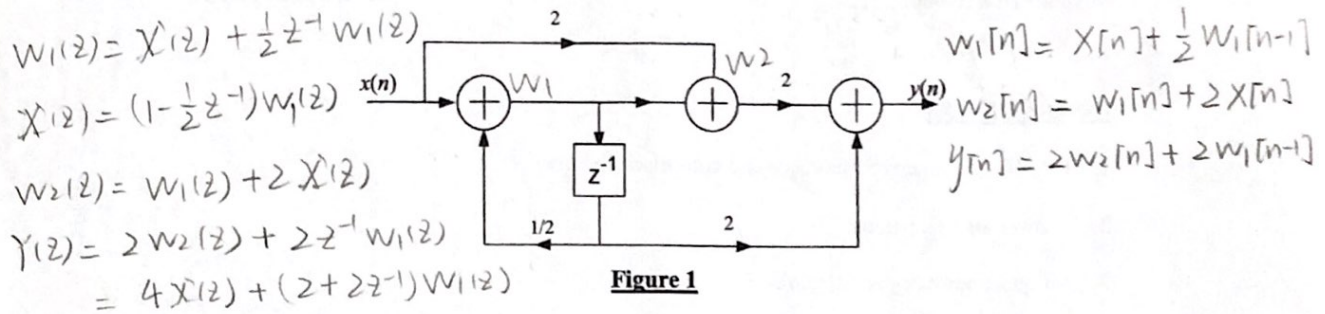
EE6401

2. (a) A sampling rate converter is needed to change its input sampling frequency by $2/3$ times. To minimize the computational costs, *derive* a polyphase structure in its *most efficient* form, and *explain* why the computational complexity is reduced by the polyphase implementation compared to the implementation directly using a finite impulse response (FIR) filter.

(14 Marks)

- (b) Determine the z-transform of the impulse response of the system shown in Figure 1 below.

(6 Marks)



3. (a) List the parameters that are used to specify a low-pass digital filter and generate the filter coefficients. Briefly discuss how these parameters affect the filter order.

$$= (4(1 - \frac{1}{2}z^{-1}) + 2 + 2z^{-1})w1(z)$$

$$= 6w1(z)$$

$$= \frac{6}{1 - \frac{1}{2}z^{-1}} X(z)$$

- (b) The sampling rate of a signal $x[n]$ is to be reduced, by decimation, from 48 kHz to 1 kHz. The highest frequency of interest after decimation is 450 Hz. Assume that an optimal FIR filter is to be used, with an overall passband ripple, $\delta_p = 0.01$, and stopband ripple, $\delta_s = 0.001$. Design an efficient decimator with two-stage FIR filters shown in Figure 2, and calculate the required computational complexity in terms of the number of additions and multiplications per second.

(5 Marks)

$$D = 48$$

Stage 1:

$$F_{T1} = 48 \text{ kHz}, F_1 = \frac{48 \text{ k}}{3} = 16 \text{ kHz}$$

$$F_{sc} = 16 \text{ k} - 450 = 15550 \text{ Hz},$$

$$\Delta F = (F_{sc} - F_{pc})/F_T = (15550 - 450)/48 \text{ k} = 0.31458$$

$$N = \frac{-10 \log_{10}(\delta_s \delta_p) - 13}{14.6 (\omega_s - \omega_p)/2\pi} + 1$$

Stage 2:

$$F_{T2} = F_1 = 16 \text{ kHz}, F_2 = \frac{F_T}{D} = 1 \text{ kHz}, F_{sc} = \frac{F_T}{2D} = \frac{16 \text{ k}}{32} = 500 \text{ Hz}$$

$$\Delta F = (500 - 450)/16 \text{ k}$$

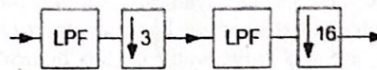


Figure 2

$$D = \frac{F_T}{2F_{sc}}$$

(15 Marks)

$$\begin{aligned} T_{ss}(z) &= \sqrt{1-a^2} H(z) = \frac{0.36}{(1-0.4z^{-1})(1-0.4z)} \\ T_{ww}(z) &= T_{ss}(z) + T_{nw}(z) = \frac{0.36 + 1.16 - 0.4(z^{-1} + z)}{(1-0.4z^{-1})(1-0.4z)} = \frac{1.52 - 0.4(z^{-1} + z)}{(1-0.4z^{-1})(1-0.4z)} \end{aligned}$$

EE6401

4. Consider a signal $x[n] = s[n] + w[n]$ where $\{s[n]\}$ is an $AR(1)$ process that satisfies the difference equation $s[n] = 0.4s[n-1] + v[n]$ where $w[n]$ and $v[n]$ are uncorrelated white noise sequences with variances $\sigma_v^2 = 0.36, \sigma_w^2 = 1$.

(a) Determine the power density spectrum of $x[n]$.

(10 Marks)

(b) Design a Wiener filter of length $M = 2$ to estimate $s[n]$.

(10 Marks)

5. Consider an adaptive noise-canceling system illustrated in Figure 3 where $x[n]$ is a stationary random process and $w_1[n], w_2[n], w_3[n]$ are white noise sequences with variances $\sigma_{w_1}^2 = 0.04, \sigma_{w_2}^2 = 0.16, \sigma_{w_3}^2 = 1$, respectively.

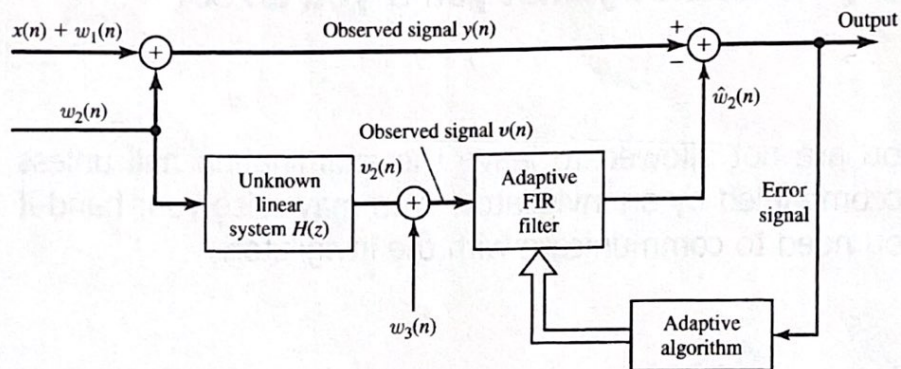


Figure 3

(a) Determine the equations of the overall system.

(10 Marks)

(b) Explain how the Least Mean Square (LMS) Algorithm can be applied in this application.

(10 Marks)

END OF PAPER