

HW4 Report

語言環境: python3 + PIL 執行: python3 hw4.py

檔案:

程式 ----- hw4.py morph.py

圖檔 ----- binarized.bmp dilation.bmp erosion.bmp
opening.bmp closing.bmp rightUp.bmp

hw4.py:

```
1 from PIL import Image
2 import numpy
3 import morph
4
5 im = Image.open('binarized.bmp')
6 (width,height), data_array = im.size, numpy.array(im)
7 pic = morph.PIC.imToPic(data_array)
8 Image.fromarray(pic.dilation(morph.tffft).toDataArray(), 'L').save('dilation.bmp')
9 print('dilation completed!')
10 Image.fromarray(pic.erosion(morph.tffft).toDataArray(), 'L').save('erosion.bmp')
11 print('erosion completed!')
12 Image.fromarray(pic.opening(morph.tffft).toDataArray(), 'L').save('opening.bmp')
13 print('opening completed!')
14 Image.fromarray(pic.closing(morph.tffft).toDataArray(), 'L').save('closing.bmp')
15 print('closing completed!')
16 Image.fromarray(pic.hitAndMiss(morph.J, morph.K).toDataArray(), 'L').save('rightUp.bmp')
```

將 binarized.bmp 讀入，並以此資料陣列創建一 morph.PIC 物件 pic

再用 morph.PIC 的成員函式作出對應的新 PIC 物件

最後用.toDataArray()成員函式得到其資料陣列

並用 Image.fromarray 和 save 存檔

morph.py:

```
5 class PIC:
6     def __init__(self, row, column, points, compl=None):
7         self.row, self.col = row, column
8         self.Ws, self.Bs = points, compl
9     def toDataArray(self):
10         ret = numpy.zeros((self.row, self.col), dtype=numpy.uint8)
11         for r,c in self.Ws: ret[r][c] = W
12         return ret
13     def getmmMM(self):
14         mr, mc, Mr, Mc = None, None, None, None
15         for i,j in self.Ws:
16             if mr==None or mr>i: mr = i
17             if mc==None or mc>j: mc = j
18             if Mr==None or Mr<i: Mr = i
19             if Mc==None or Mc<j: Mc = j
20         return mr,mc,Mr,Mc
```

PIC 物件有 row 和 col 存放此圖片之大小

Ws 和 Bs 皆是 set 類別，各存放一些(r,c)表示為白色或黑色的點座標

getmmMM 返回白色點座標中的(最小 row, 最小 col, 最大 row, 最大 col)

```

43 @staticmethod
44 def imToPic(data_array):
45     r, c = len(data_array), len(data_array[0])
46     return PIC(r, c, set([(i, j) for i in range(r) for j in range(c) if data_array[i][j]==W]))
47
48 LFFFL = PIC(5, 5, [(-2,-1),(-2,0),(-2,1),(-1,-2),(-1,-1),(-1,0),(-1,1),(-1,2),\
49 (0,-2),(0,-1),(0,0),(0,1),(0,2),(1,-2),(1,-1),(1,0),(1,1),(1,2),(2,-1),(2,0),(2,1)])
50 J = PIC(2, 2, [(0,0), (1,0), (0,-1)])
51 K = PIC(2, 2, [(0,1), (-1,0), (-1,1)])

```

imToPic 接收影像資料陣列並回傳對應的 PIC 物件

此外 **morph.py** 定義了三個全域的 PIC 物件:

```

21 tffft -> 3-5-5-5-3 的 kernel      J -> J kernel      K -> K kernel
22 def dilation(self, pic):
23     whole = set([(i,j) for i in range(self.row) for j in range(self.col)])
24     tmp = set([(r1+r2,c1+c2) for r1,c1 in self.Ws for r2,c2 in pic.Ws])
25     return PIC(self.row, self.col, whole.intersection(tmp))
26 def erosion(self, pic):
27     new = self.complement().dilation(pic.reflection()).complement()
28     #i+mr2>=mr1      j+mc2>=mc1
29     #i+Mr2<=Mr1      j+Mc2<=Mc1
30     (mr1,mc1,Mr1,Mc1), (mr2,mc2,Mr2,Mc2) = self.getnumMM(), pic.getnumMM()
31     inBound = set([(i,j) for i in range(mr1-mr2, Mr1-Mr2+1) for j in range(mc1-mc2, Mc1-Mc2+1)])
32     new.Ws = inBound.intersection(new.Ws)
33     return new
34 def opening(self, pic):
35     return self.erosion(pic).dilation(pic)
36 def closing(self, pic):
37     return self.dilation(pic).erosion(pic)
38 def complement(self):
39     if self.Bs == None:
40         whole = set([(i,j) for i in range(self.row) for j in range(self.col)])
41         self.Bs = whole.difference(self.Ws)
42     return PIC(self.row, self.col, self.Bs, self.Ws)
43 def reflection(self):
44     return PIC(self.row, self.col, set([(-i,-j) for i,j in self.Ws]))
45 def hitAndMiss(self, pic1, pic2):
46     tmp1, tmp2 = self.erosion(pic1), self.complement().erosion(pic2)
47     return PIC(self.row, self.col, tmp1.Ws.intersection(tmp2.Ws))

```

dilation 裡面的交集是為了去除界外的點

erosion 利用公式轉換為先取互補與對稱之膨脹再做互補，最後的交集是為了去除掉 -----因為界外而在 **dilation** 時被扣掉最後又在 **complement** 時補回來的點

complement 先檢查是否已做過，若有則沿用之前存下的資料，若無則在規定的範圍內找尋不在原本 **Ws** 裡面的點

其他都是代公式

原圖:

binarized.bmp



結果:



dilation.bmp



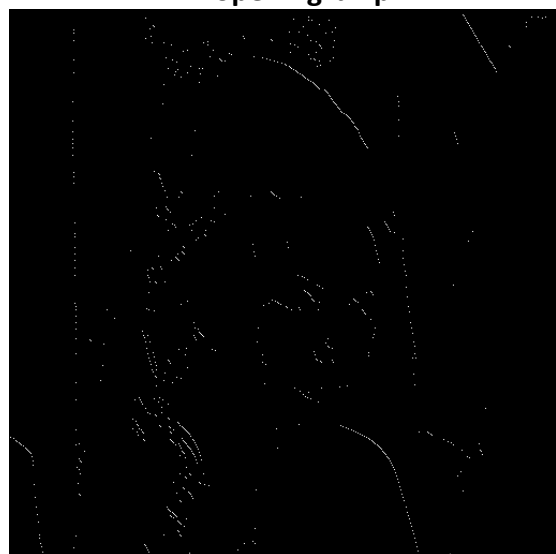
erosion.bmp



opening.bmp



closing.bmp



rightUp.bmp