

Commitment Statement

By uploading this manuscript I certify that

(1) the manuscript is submitted with the full knowledge and consent of all co-authors (if any), and that I will undertake to keep my co-authors informed of all correspondence about the manuscript.

(2) contents of this manuscript are original and it is not being submitted simultaneously for consideration towards publication in another conference or journal. I understand that all submissiona will be checked by the iThenticate tool for plagiarism and excessive reuse of authors own existing material. In cases of plagiarism or excessive reuse, all results will be reported to the IEEE for further investigation.

(3) in the event that the manuscript is accepted, the authors will provide a final version that will fundamentally correspond, in length and contents, to the submitted version, except for parts that might be added or modified to comply with the reviewers' suggestions. It is considered unethical to shorten or otherwise alter the final version in ways that make it weaker than what was approved by the reviewers.

(4) none of the authors are on the IEEE Restricted Author List.

I also understand that

(1) by submitting my manuscript through the RAS conference paper management system, I am permitting the RAS society access to my contact information and research interests. I agree that this data may only be used by the RAS designated users to contact me regarding future events sponsored by the society and to assist its editorial board to identify qualified reviewers for peer review of submissions to its conferences.

(2) if my manuscript is accepted by the conference, I or one of my co-authors or colleagues will attend the conference to present the paper and will comply with the conference registration policy.

(3) failure to comply with above may lead to the Robotics and Automation Society preventing me and my co-authors from submitting manuscripts to future events.

Joshua Goh, April 24, 2020