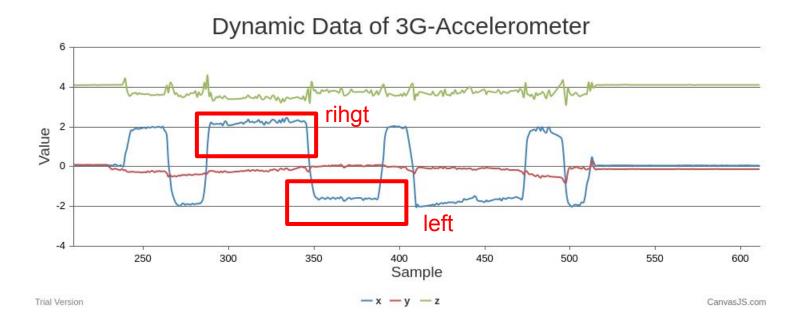
# Pikachu-Volleyball 進度報告

B06901162 電機四 梁瀚中 B06901166 電機四 陳杰民

# Architecture (display) 11111 11111 WIFI WIFI STM32 STM32 player player

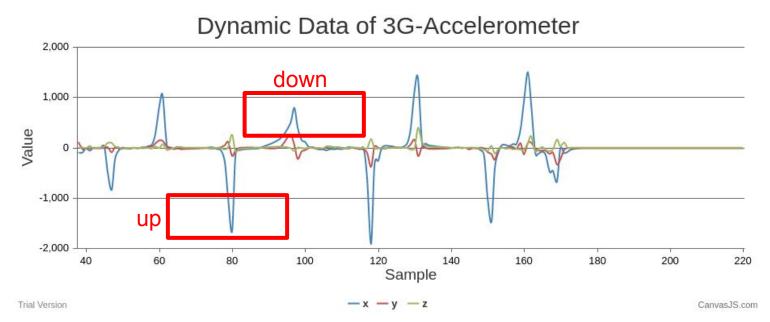
#### STM32

● 使用3軸加速度計的X軸的值來判斷左右。



#### STM32

● 透過gyro得到角速度後累積得到角位移來判斷上下。



#### STM32

● 透過板子上的button來判斷玩家是否殺球。

```
{"right":0,"left":0,"up":0,"down":0,"hit":0}
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["right":0,"left":0,"up":0,"down":0,"hit":0}
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["right":1,"left":0,"up":0,"down":0,"hit":0}
["right":0,"left":0,"up":0,"down":0,"hit":0}
```

### Pikachu Program

- Websocket 只會吃一次tcp receive buffer的資料。
- 如果要讓他吃很多次資料,結果 就連不上了。



## 待解決的問題

- 如何讓javascript 的 websocket 穩定接收來自socket的資料。
- 殺球判斷方式
- 使用者體驗(TCP、UDP、reset function)