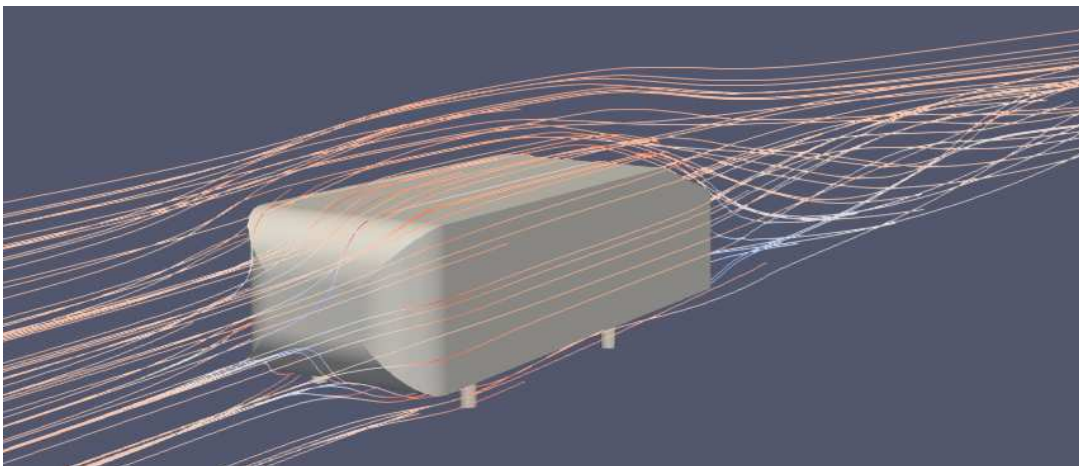




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KB6003 Vehicle Aerodynamics

Tutorial 4



Ahmed Body Solution

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Introduction

OpenFOAM, as described previously, is a powerful utility to solve partial differential equations. It has continuum mechanics, probability, financial and many other applications. It does this via a custom set of solvers. For this tutorial, 'simpleFoam' solver will be used. It is a steady-state solver for incompressible flow with turbulence modelling. A complete list of 'standard' solvers with their description can be seen at <https://www.openfoam.com/documentation/user-guide/standard-solvers.php>.

This tutorial will look into setting up the case for the 'simpleFoam' solver to run (solve) on the previously generated mesh. The subsequent sections will look into the dictionaries that govern the solution, running the solver and some basic post processing.

1.1 simpleFoam







This steady state solver uses the 'simple' (Semi-Implicit Method for Pressure-Linked Equations) to solve the Navier Stokes equations. The algorithm is an iterative process and follows the basic steps described below as per [https://openfoamwiki.net/index.php/OpenFOAM_guide/The SIMPLE algorithm in OpenFOAM](https://openfoamwiki.net/index.php/OpenFOAM_guide/The_SIMPLE_algorithm_in_OpenFOAM).

- 1) *Set the boundary conditions.*
- 2) *Solve the discretized momentum equation to compute the intermediate velocity field.*
- 3) *Compute the mass fluxes at the cells faces.*
- 4) *Solve the pressure equation and apply under-relaxation.*
- 5) *Correct the mass fluxes at the cell faces.*
- 6) *Correct the velocities on the basis of the new pressure field.*
- 7) *Update the boundary conditions.*
- 8) *Repeat till convergence.*

2 Dictionaries for Solution

This sections will look into the dictionaries (controlDict, fvSchemes, fvSolutions, k, p, U, nut, omega, transportProperties and turbulenceProperties) governing the solution. The table 2.1 below shows the location of these dictionaries.

Table 2.1: OpenFOAM case structure (pre-solution).

|  case | Folder | Description |
|--|-------------------------|--|
| | Case | Main case directory |
|  0_orgs | Constant | Contains the physical properties and geometries for the case. Also contains the mesh when generated. |
|  constant | polyMesh | Contains the mesh after it is generated. |
|  polyMesh | triSurface | Contains the geometries (STLs, VTKs, eMesh, etc.) |
|  triSurface | ExtendedFeatureEdgeMesh | Extracted features. |
|  system | system | Contains dictionaries used to control and run the case (such as blockMesh, controlDict, snappyHexMeshDict, surfaceFeatureExtractDict, meshQualityDict, etc.) |

2.1 Fluid Properties (transportProperties)

This dictionary is located in the '<case>/constant' folder and has the properties of the fluid. This should already be set up as a Newtonian fluid with dynamic viscosity (ν) set to 1.5×10^{-5} as shown in figure 2.1 below.

```
/*----- C++ -----*/
|=====|
| \ \ / / | F i e l d | OpenFOAM: The Open Source CFD Toolbox
| \ \ / / | O p e r a t i o n | Version: 4.x
| \ \ / / | A n d | Web: www.OpenFOAM.org
| \ \ / / | M a n i p u l a t i o n |
|=====|
FoamFile
{
    version      2.0;
    format       ascii;
    class        dictionary;
    object       transportProperties;
}
// *****

transportModel Newtonian;

nu              nu [0 2 -1 0 0 0] 1.5e-05;

// *****
```

Figure 2.1: Transport properties.

2.2 Turbulence Model (turbulenceProperties)

This dictionary is located in the '<case>/constant' folder and has the chosen turbulence model. More on this would be covered in subsequent lectures of this module. The model chosen for this simulation is the k-Omega SST model and can be seen in the figure 2.2 below.

```
/*----- C++ -----*/
|=====|
| \ \ / / | F i e l d | OpenFOAM: The Open Source CFD Toolbox
| \ \ / / | O p e r a t i o n | Version: 4.x
| \ \ / / | A n d | Web: www.OpenFOAM.org
| \ \ / / | M a n i p u l a t i o n |
|=====|
FoamFile
{
    version      2.0;
    format       ascii;
    class        dictionary;
    object       turbulenceProperties;
}
// *****

simulationType RAS;

RAS
{
    RASModel      kOmega;

    turbulence     on;

    printCoeffs    on;
}

// *****
```

Figure 2.2: Chosen model.

2.3 controlDict

OpenFOAM sets up databases for its solutions which are governed by 'controlDict'. It controls the time, data input and output of the solution as well as additional libraries loaded at run time. It can be found under '<case>/system/' folder.

Navigate to your Ahmed body 'case/system' and edit the 'controlDict' file to reflect the parameters in the table 2.2 below.

Table 2.2: Customisation of 'controlDict' for Ahmed body case.

| Parameter | Value | Description |
|-------------------------|------------|--|
| application | simpleFoam | The solver to be used. |
| startFrom | latestTime | The start time of the simulation. This could be a subsequent run hence 'latestTime' resumes from the last time step. |
| startTime | 0 | Initially start at time. |
| stopAt | endTime | When to stop the simulation. |
| endTime | 1000 | End time for simulation (not real time but internal simulation) when 'stopAt' is given an 'endTime'. |
| deltaT | 1 | Time steps for the simulation. |
| writeControl | timeStep | Data output writing clock (runtime, CPU time, clock time, etc.) |
| writeInterval | 1 | Interval for data writing. |
| purgeWrite | 0 | Overwrite (cyclic) time directories (value represents number of directories to keep). |
| writeFormat | ascii | Format of data files. |
| writePrecision | 8 | Precision to decimal places |
| writeCompression | off | To compress with gzip when data is written (on/off). <u>Tip:</u> yes/no, true/false can be used as well. |

| | | |
|--------------------------|---------------|---|
| timeFormat | general | Format for naming time directories. 'general' uses scientific format if exponent is less than -4 or greater than the 'timePrecision' value. |
| timePrecision | 6 | Precision to number of decimal places (default is 6) |
| runTimeModifiable | True | Re-reads the dictionary during the start of each simulation time step. Enabling this allows users to change parameters while during simulation. Eg: Stop simulation after finishing current step (instead of terminating with 'Ctrl+c'). |
| functions { ... } | <leave blank> | Dictionary for functions (such as probes and in-simulation processing). |

The complete version of the controlDict file for the Ahmed body case can be found in 'Tutorial3/end.zip/ahmed3' on Github (<https://github.com/NU-Aero-Lab/OpenFOAM-Cases/tree/master/KB6003/Tutorial3>).

2.4 Numerical Schemes ('fvSchemes')

This dictionary sets the numerical schemes for terms used and calculated in the simulation. It is located under '<case>/systems' folder and is further divided by keywords representing terms of particular type such as;

- timeScheme: first and second time derivatives, e.g. $\partial/\partial t, \partial^2/\partial t^2$
- gradSchemes: gradient ∇
- divSchemes: divergence $\nabla \cdot$
- laplacianSchemes: Laplacian ∇^2
- interpolationSchemes: cell to face interpolations of values.
- snGradSchemes: component of gradient normal to a cell face.
- wallDist: distance to wall calculation, where required.

More information can be found on: <https://cfd.direct/openfoam/user-guide/v6-fvschemes/>

Navigate to your Ahmed body case and edit the 'fvSchemes' file to reflect the parameters in the table 2.3 below.

Table 2.3: Customisation of 'fvSchemes' for Ahmed body case.

| Parameter | Value | Description |
|--------------------------------------|-------------------------------------|--|
| ddtSchemes | | Time schemes ($\partial/\partial t$). |
| default | steadyState | Equates time derivative to zero. Note: Make sure the solver is compatible. i.e. running a transient scheme on a steady state solver (such as 'simpleFoam') would give incorrect results. |
| gradSchemes | | Gradient terms. |
| default | Gauss linear | This scheme gives more accurate results than Gauss upwind. |
| grad(U) | cellLimited Gauss linear 1 | Overridden to clip each component of the gradient equally. |
| divSchemes | | Divergence terms. |
| default | none | |
| div(phi,U) | bounded Gauss linearUpWindV grad(U) | Second order, upwind-biased, bounded, with discretisation of the velocity gradient specified. |
| div(phi,k) | bounded Gauss upwind | First-order bounded. |
| div(phi,omega) | bounded Gauss upwind | First-order bounded. |
| div((nuEff*dev2(T(grad(U))))) | Gauss linear | Second order, unbounded. |
| laplacianSchemes | | Laplacian terms. |

| | | |
|-----------------------------|------------------------|---|
| default | Gauss linear corrected | Second order, unbounded with correction (see 'snGradSchemes'). |
| interpolationSchemes | | Interpolated values of cell centres to face centres. |
| default | linear | Second order, unbounded. |
| snGradSchemes | | Surface normal gradient terms. Required to evaluate a Laplacian term using Gaussian intergration. |
| default | corrected | Non-orthogonal correction to maintain second-order accuracy. |
| wallDist | | Calculates distance to walls and normal to walls fields. |
| method | meshWave | Method for calculating distance to nearest patch for all cells and boundary. |
| correctWalls | true | Correction distance from near-wall cells to boundary. |

The complete version of the controlDict file for the Ahmed body case can be found in 'Tutorial3/end.zip/ahmed3' on Github (<https://github.com/NU-Aero-Lab/OpenFOAM-Cases/tree/master/KB6003/Tutorial3>).

More information on 'fvSolution' can be found on <https://cfd.direct/openfoam/user-guide/v6-fvSchemes>.

2.5 Solutions and Algorithm Control (fvSolution)

The equations solvers and the algorithms along with tolerances are controlled via this dictionary. It is located under '<case>/systems' folder. More information on 'fvSolution' can be found on <https://cfd.direct/openfoam/user-guide/v6-fvSolution/>.

Navigate to your Ahmed body case and edit the 'fvSolutions' file to reflect the parameters in the table 2.4 below.

Table 2.4: Customisation of 'fvSolutions' for Ahmed body case.

| Parameter | Value | | | | Description |
|---------------------------------|-------------|--------------|------|-------|---|
| solvers | p | U | k | omega | Solvers used and parameters for each discretised equation |
| solver | GAMG | smoothSolver | | | GAMG: generalised geometric-algebraic multi-grid. smoothSolver: solver that uses a smoother. |
| smoother | GaussSeidel | | | | Option for solvers using smoother. |
| tolerance | 1e-7 | 1e-8 | 1e-8 | 1e-8 | Tolerance level at which the solution is deemed of sufficient accuracy. |
| relTol | 0.01 | 0.1 | 0.1 | 0.1 | Relative improvements from initial to final solution. |
| nSweeps | <N/A> | 1 | 1 | 1 | Number of sweeps before residual is recalculated (default 1). |
| phi | | | | | The phi term. |
| \$p | <blank> | | | | |
| SIMPLE | | | | | The solver algorithm used |
| nNonOrthogonalCorrectors | 0 | | | | Used to update the explicit non-orthogonal correction of the Laplacian terms. |

| | | | | | | |
|--------------------------|------|-----|---------|---|-------|---|
| consistent | yes | | | | | |
| residualControl | p | U | nuTilda | k | omega | |
| | 1e-4 | | | | | Simulation deemed as converged when residuals falls below this value. |
| potentialFlow | | | | | | Potential flow algorithm controls |
| nNonOrthogonalCorrectors | 10 | | | | | See ‘SIMPLE’ |
| relaxationFactors | | | | | | Under-relaxation of field factors. |
| equations | U | k | omega | | | |
| | 0.9 | 0.7 | 0.7 | | | |
| cache | | | | | | Cache-ing |
| grad(U) | | | | | | Instant solving speed boost but a slight increase in memory usage. |

The complete version of the controlDict file for the Ahmed body case can be found in 'Tutorial3/end.zip/ahmed3' on Github (<https://github.com/NU-Aero-Lab/OpenFOAM-Cases/tree/master/KB6003/Tutorial3>).

2.6 Boundary conditions in Polymesh

At this stage, the solution is almost ready to be run. The few additional steps below are required prior to initiating the solution. This is due to method of mesh generation used i.e. not overwriting the mesh generation steps.

The mesh generated in the previous tutorial is in multiple stages with the final folder containing the generated mesh in full. This needs to be moved to the '<case>/constant/polyMesh'.

Before moving, the 'ground' parameter in the 'boundary' dictionary inside the last time-step '4/polyMesh' needs to be changed from 'patch' to 'slip' as no boundary conditions would be applied to the ground.

Once changed, please enter the following CLI command to move the final mesh and delete the intermediate stages;

```
# Remove existing 'polyMesh' in 'constant' directory
rm -rf constant/polyMesh/

# Copy the desired mesh to the 'polyMesh' in 'constant' directory
# *Please Note: There are spaces before and after '-r' and before 'constant/'
cp -r 4/polyMesh/ constant/
```

```
# Remove intermediate stages (steps) of mesh generation
foamListTimes -rm
```

2.7 The “0_org” Folder

This folder contains the initial conditions for the solution such as the velocity, the interactions with walls, etc. It is located in the main ‘<case>’ folder and contains the ‘k’. ‘nut’. ‘omega’, ‘p’ and ‘U’ dictionaries. It describes the dimensions, fields (internal and boundary) along with their parameters where the said conditions are applied.

Navigate to your Ahmed body case and edit the files under the ‘0_org’ folder to reflect the parameters in the table 2.5 overleaf.

2.7.1 Estimating the Initial Conditions for k and omega

The initial values for ‘k’ and ‘omega’ can be estimated using calculators such as <https://www.cfd-online.com/Tools/turbulence.php>.

Please navigate to the link above and enter the selected ‘Freestream velocity’ (33 m/s in this case), the ‘Turbulence intensity/level Tu’ as 1% and ‘Eddy viscosity ratio μ_t / μ ’ as 1.

Select the ‘Turbulence variables (k, ϵ , ω) from turbulence intensity (Tu), eddy viscosity ratio (μ_t/μ), freestream velocity (U_∞) and kinematic viscosity (ν)’ option and click ‘Convert’.

This should now present you with values for ‘k’ and ‘omega’ to be included in the ‘k’ and ‘omega’ dictionaries in section 2.7.

2.7.2 Dimensions for dictionaries

The ‘dimensions’ in the ‘k’. ‘nut’, ‘omega’, ‘p’ and ‘U’ are the properties represented by chosen units. By default, OpenFOAM uses the SI units and the dimensions can be adjusted by changing the dimensions array. The references for dimensions can be seen in figure 2.3 below.

| No. | Property | SI unit | USCS unit |
|-----|--------------------|---------------|---------------------|
| 1 | Mass | kilogram (kg) | pound-mass (lbm) |
| 2 | Length | metre (m) | foot (ft) |
| 3 | Time | second (s) | second (s) |
| 4 | Temperature | Kelvin (K) | degree Rankine (°R) |
| 5 | Quantity | mole (mol) | mole (mol) |
| 6 | Current | ampere (A) | ampere (A) |
| 7 | Luminous intensity | candela (cd) | candela (cd) |

Figure 2.3: Dimension reference for OpenFOAM.

Table 2.5: Customisation of '0_org' folder dictionaries for Ahmed body case.

| Parameter | Value | | | | | Description |
|----------------------|---------------------|---------------------|---------------------|---------------------|------------------|--|
| Dictionary: | k | nut | omega | p | U | The respective dictionary for k-Omega model. |
| dimensions | [0 2 -2 0 0 0 0] | [0 2 -1 0 0 0 0] | [0 0 -1 0 0 0 0] | [0 2 -2 0 0 0 0] | [0 1 -1 0 0 0 0] | Add dimensions (see section 2.7.1). |
| internalField | uniform 0.4335 | uniform 0 | uniform 2890 | uniform 0 | uniform 17 0 0 | The initial values of the internal field. |
| boundaryField | <See below> | | | | | |
| inlet | | | | | | Inlet patch. |
| type | fixedValue | calculated | fixedValue | zeroGradient | fixedValue | Type of the value i.e. fixed, calculated, function, slip, etc. |
| value | uniform 0.4335 | calculated | uniform 2890 | <N/A> | uniform 17 0 0 | The value, see section 2.7.2. |
| outlet | | | | | | Outlet patch. |

| | | | | | | |
|-------------------|----------------|------------|--------------|------------|----------------|--|
| type | inletOutlet | calculated | inletOutlet | fixedValue | inletOutlet | Type of the value i.e. fixed, calculated, function, etc. |
| inletValue | uniform 0.4335 | <N/A> | uniform 2890 | <N/A> | uniform 0 0 0 | Add dimensions (see section 2.7.1). |
| value | uniform 0.4335 | uniform 0 | uniform 2890 | uniform 0 | uniform 17 0 0 | Add dimensions (see section 2.7.1). |
| ground | | | | | | Ground patch. |
| type | slip | | | | | Slip as no boundary conditions applied. |
| side.* | | | | | | Sides patch (both). |

| | | | | | | |
|---------------|-----------------|------------------|-------------------|--------------|---------------|--|
| type | symmetry | | | | | Patch which uses the symmetry plane (slip) condition. |
| Top | | | | | | Top patch. |
| type | symmetry | | | | | Patch which uses the symmetry plane (slip) condition. |
| ahmed1 | | | | | | The main body. |
| type | kqRWallFunction | nutkWallFunction | omegaWallFunction | zeroGradient | fixedValue | Wall functions applied with fixed and zeroGradient conditions applied. |
| value | uniform 0.4335 | uniform 0 | uniform 2890 | <N/A> | uniform 0 0 0 | Values. |

| | | | | | | |
|---------------|-----------------|------------------|-------------------|--------------|---------------|--|
| ahmed2 | | | | | | The supports. |
| type | kqRWallFunction | nutkWallFunction | omegaWallFunction | zeroGradient | fixedValue | Wall functions applied with fixed and zeroGradient conditions applied. |
| value | uniform 0.4335 | uniform 0 | uniform 2890 | <N/A> | uniform 0 0 0 | Values. |

The complete version of the controlDict file for the Ahmed body case can be found in 'Tutorial3/end.zip/ahmed3' on Github (<https://github.com/NU-Aero-Lab/OpenFOAM-Cases/tree/master/KB6003/Tutorial3>).

Finally, the finished dictionaries in '0_org' needs to be copied to the '0' (initial) folder. This can be done via the following CLI commands;

```
# Copy 0_org folder to the 0 folder
cp -r 0_org 0
```

You should now be able to run the simulation using the CLI detailed in section 4. However, it is advisable to add the residuals plot to monitor your simulation as described in section 3.

3 Plotting Residuals

Although not a mandatory step, it is advisable to plot residuals for observation during the simulation. This would let one ascertain if the solution is converging or not. A solution not converging could mean incorrect solution set-up or a low quality mesh. These plots are crucial for longer simulations (spanning hours, days and more) as errors could be spotted and rectified at an earlier stage. The figure 3.1 below shows some examples of residual plots.

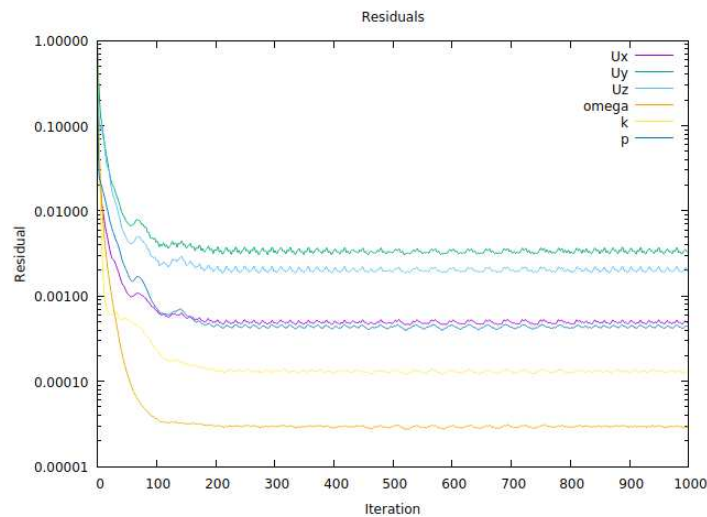


Figure 3.1a: None convergence

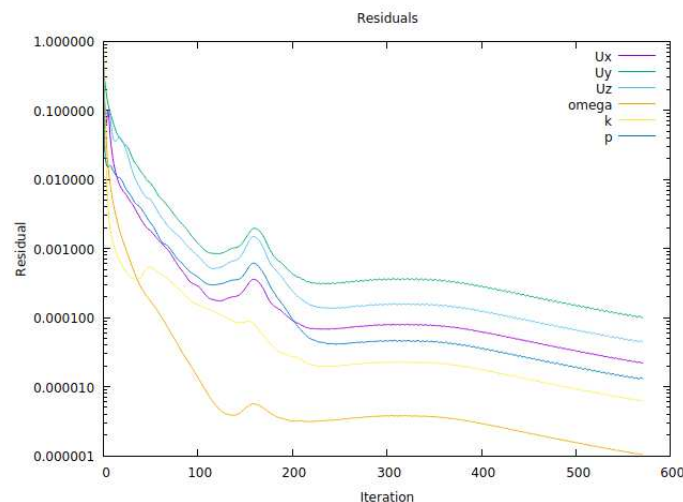


Figure 3.1b: Convergence

Figure 3.1: Residual plots.

In order to plot residuals, a residual script must be created and then initiated during runtime. To create the script, follow the steps below;

- 1) Open a 'Terminal' in your main case directory either by;
 - a. Navigating to the folder in 'File Manager', right clicking on an empty space and selecting 'Open in Terminal'.

- b. Navigate using CLI to the case folder;

```
cd $FOAM_RUN/<case>
```

- 2) Create a text file called 'residuals' in the case folder by typing;

```
gedit residuals .
```

The above CLI tells 'gedit' (the text editor, similar to 'Notepad' in Windows) to create a blank file called 'residuals' in the current ('.') directory.

Tip: alternatively, the text editor could be opened via GUI, then the file saved in the case folder after editing.

- 3) Insert the following code into the blank 'residuals' file.

```
set logscale y
set title "Residuals"
set ylabel 'Residual'
set xlabel 'Iteration'
plot "< cat log.simplefoam | grep 'Solving for Ux' | cut -d ' ' -f9 | tr -d ',' title 'Ux' with lines,\
"< cat log.simplefoam | grep 'Solving for Uy' | cut -d ' ' -f9 | tr -d ',' title 'Uy' with lines,\
"< cat log.simplefoam | grep 'Solving for Uz' | cut -d ' ' -f9 | tr -d ',' title 'Uz' with lines,\
"< cat log.simplefoam | grep 'Solving for omega' | cut -d ' ' -f9 | tr -d ',' title 'omega' with lines,\
"< cat log.simplefoam | grep 'Solving for k' | cut -d ' ' -f9 | tr -d ',' title 'k' with lines,\
"< cat log.simplefoam | grep 'Solving for p' | cut -d ' ' -f9 | tr -d ',' title 'p' with lines
pause 2
reread
```

- 4) Change the LOGNAME and PAUSETIME to the logname and the pause time (refreshing time of the graph) of your choosing (such as 'log.simplefoam' and '2').

Note: It is advisable to associate logs with tasks such as solver used (log.simpleFoam), stage (log.SnappyHexMesh), etc. This will make debugging easier.

- 5) Click 'Save' or press 'Ctrl+s' and quit the program.

Note: If the 'Terminal' does not return to normal state, please type 'Ctrl+c' on it. This will terminate the gedit. Please ensure you have saved the file before this.

4 Running the Solver (Solution)

The solution is now ready to be run. It can be done using the following CLI commands;

```
# Run the potential solver to get an initial solution
potentialFoam -initialiseUBCs -noFunctionObjects

# Run the simpleFoam solver and generate 'log.simplefoam' then show the tail of the log file
simpleFoam > log.simplefoam | tail -f log.simplefoam

# Plot residuals (open a new Terminal)
gnuplot -residuals
```

After running the potential solver, you can open ParaView and check the initial solution which is similar to the figure 4.1 below. The main simulation (step 0) should start off from this solution.

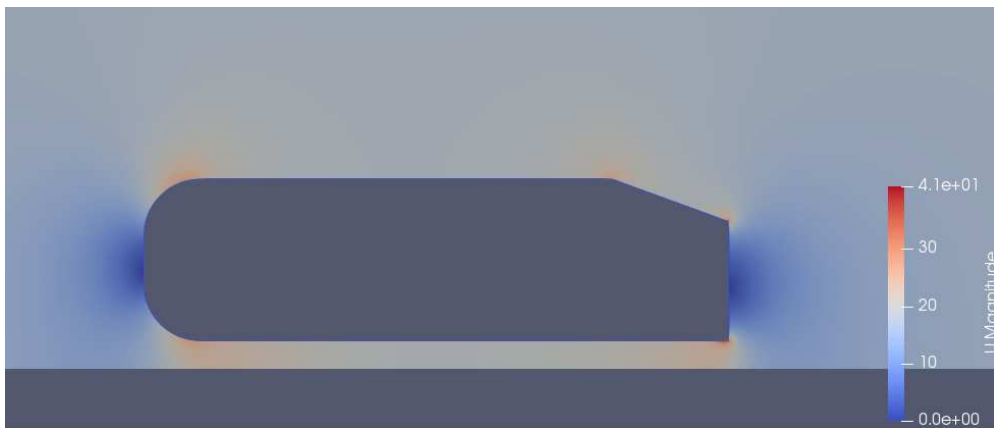


Figure 4.1: Initial potential solution.

5 Initial Post Processing

This section will look into visualising simulation data in ParaView and where needed, extract data from the finished simulation for further analysis. This tutorial will cover some basic post processing such as general visualisation, tracing streamlines and wall shear stress.

In order to proceed, please open ParaView from the simulated case by typing;

```
ParaFoam -builtin
```

Note: There is a space before '-builtin'.

5.1 General 'U' Visualisation

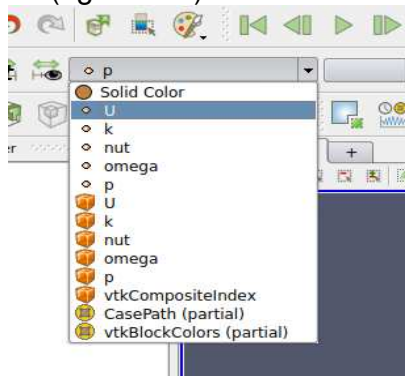
This is a general (basic) view (slice, clip, etc.) of the simulation which would provide information on the intensity of 'U'. It is similar to checking the mesh in tutorial 2 and is outlined in the steps below.

- 1) Make sure the 'internalMesh' and 'Reconstructed Case' is selected from the 'Properties' tab and select 'Apply' (figure 5.2 below).
- 2) Make a 'Slice' or a 'Clip' from the 'Common' toolbar (similar to mesh visualisation in tutorial 2).
- 3) Select the desired normal-to-axis, the co-ordinates and click apply.

Tip: To get a cross section from the middle of the legs, enter 0 or 0.1635 as the 'y' co-ordinate of the clipping.

Tip: For bottom, select 'z-normal' and enter 0.049 as the 'z' co-ordinate with 'Inside Out' selected in clipping.

- 4) Change the active variable to 'U' (velocity) from the 'Active Variable Control' toolbar (figure 5.1).



 U - The general velocity.

 \vec{U} - The velocity per mesh cell.

Figure 5.1: Change the active variable to U.

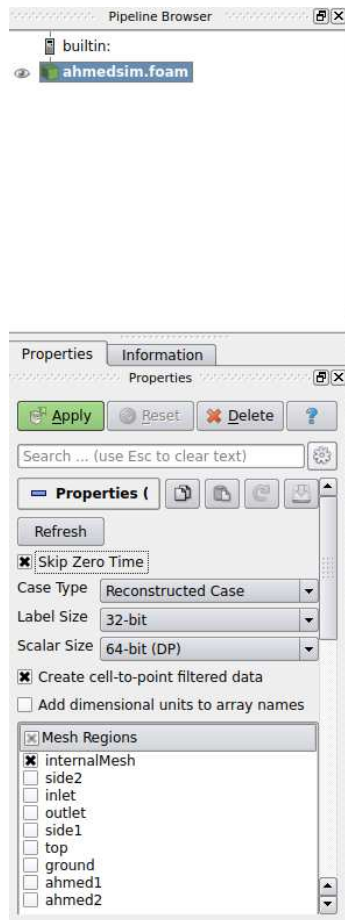


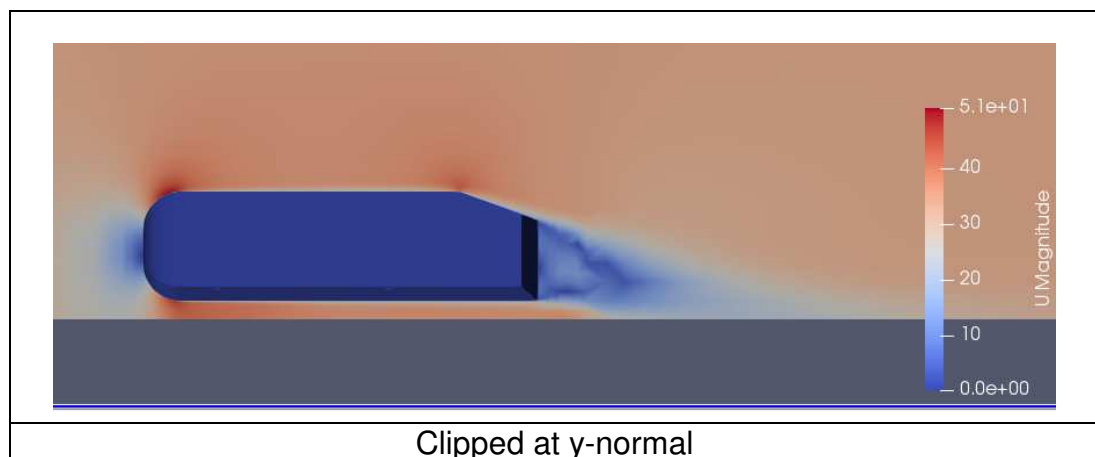
Figure 5.2: Loading the case.

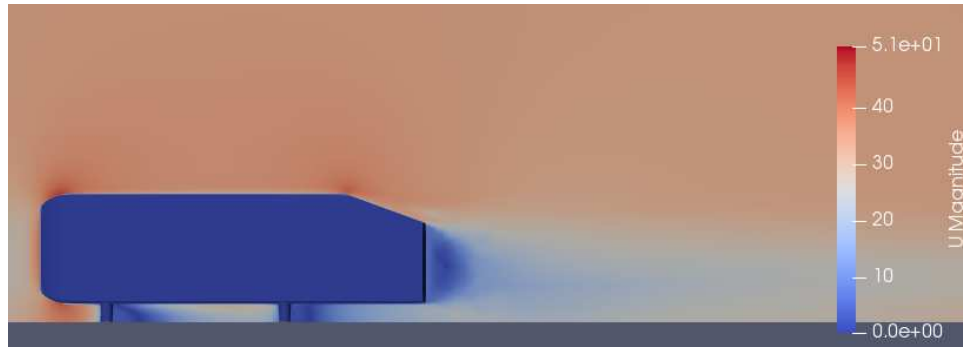
- 5) You can change the representation to 'Surface' or 'Surface with Edges' to suite your view from the 'Representation Toolbar'.
- 6) You can now see the velocity with intensity in different time steps using the 'VCR Controls'.

Tip: You can play the simulation and save the animation as well.

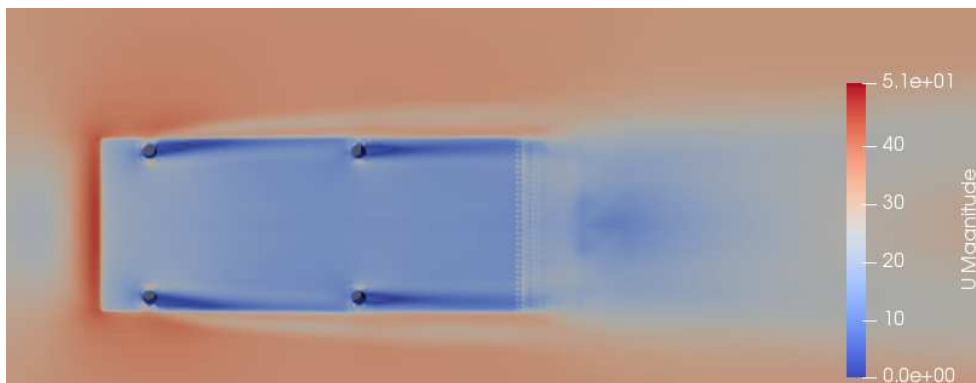
The table 5.1 below shows some of the clippings.

Table 5.1: Clippings of velocity ('U').

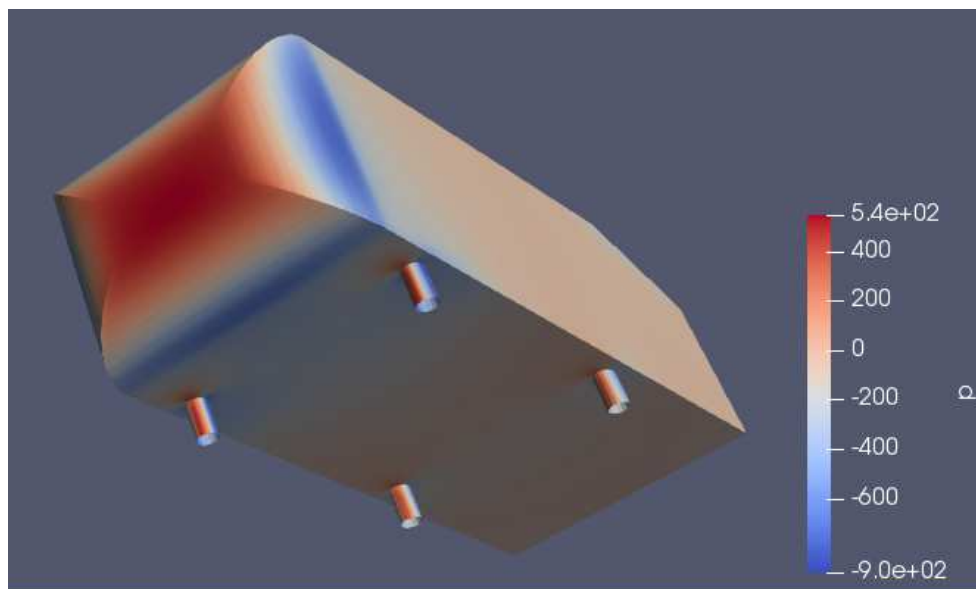




Clipped at y-normal and $y = 0.1635$



Clipped at z-normal and $z = 0.049$ with 'Inside Out' selected.



Pressure on the Ahmed body using 'p' variable with 'ahmed1' and 'ahmed2' 'Mesh Regions' selected (only).

5.2 Trace Streamlines

This section will outline how to trace streamlines and visualise them with the Ahmed body model loaded. Please follow the following steps;

- 1) Ensure that the case is loaded on ParaView with the 'internalMesh' selected in 'Mesh Regions'.
- 2) Hide (visibility) the loaded case.
- 3) Click 'Open' and select the 'ahmed_body.stl' (whole Ahmed body) file and click apply.

You should now see the full Ahmed body.

- 4) Click on the main loaded case (hidden in step 2) and click on the 'Stream Tracer' in the 'Common' toolbar (figure 5.3).



Figure 5.3: Select 'Stream Tracer' from 'Common' toolbar.

- 5) Please input the parameters for the 'Properties' outlined in table 5.2 below.

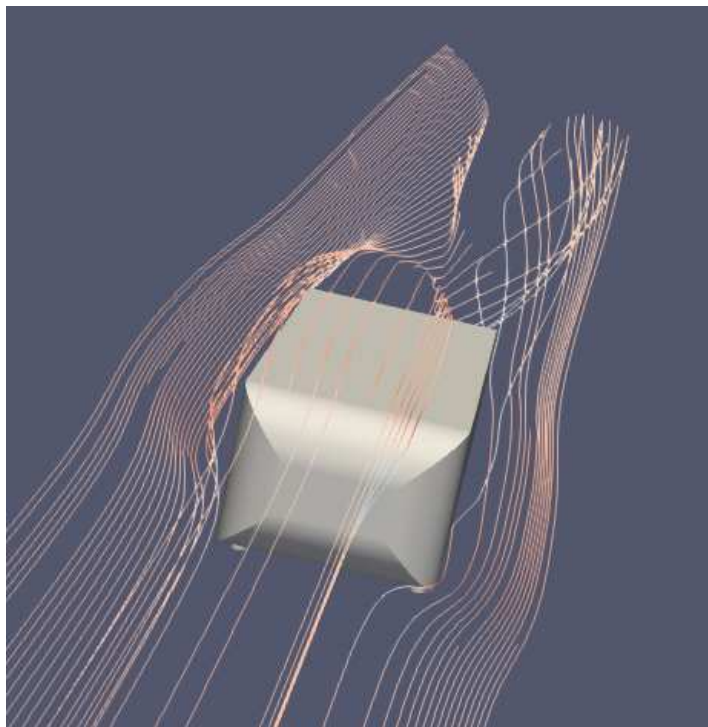
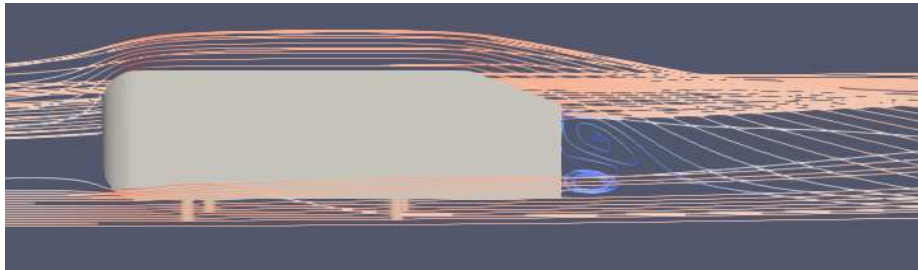
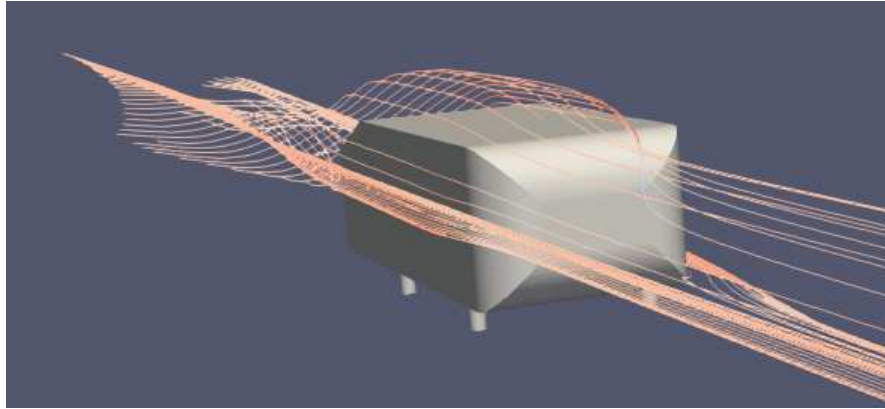
Table 5.2: Streamline parameters.

| Parameter | Value |
|------------------------|---|
| Vectors | U |
| Seed Type | High Resolution Line Source |
| Line Parameters | Point1: -2, -0.3, 0 Point2: 5, 0.3, 0.35 |
| Resolution | 70 |
| Colouring | U |
| Alternatively | |
| Seed Type | Point Source |
| Center | -2, 0, 0.2 |
| Radius | 0.3 |

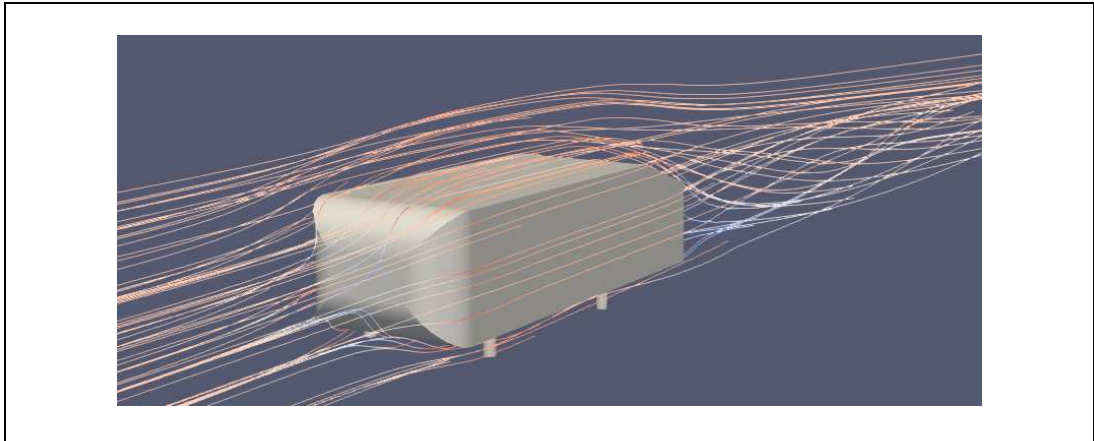
Click 'Apply' and the output should be similar to table 5.3 below.

Table 5.3: Traced streamlines.

| |
|-----------------------------|
| High Resolution Line Source |
|-----------------------------|



Point Source



At this stage, it is advisable to save the ParaView state so that you can return to it at a later stage. To save, click on 'File' and click 'Save State'. Give an appropriate name and click 'OK'.

5.3 Wall Shear Stress

This section will look into extracting the wall shear stresses and imposing them onto the Ahmed body. The wall shear stresses are not saved during simulation. They need to be extracted post-simulation. In order to do this exit ParaView and return to the Terminal with the case path.

Note: Ensure the ParaView state was saved.

Type the following CLI command into the Terminal (from case path);

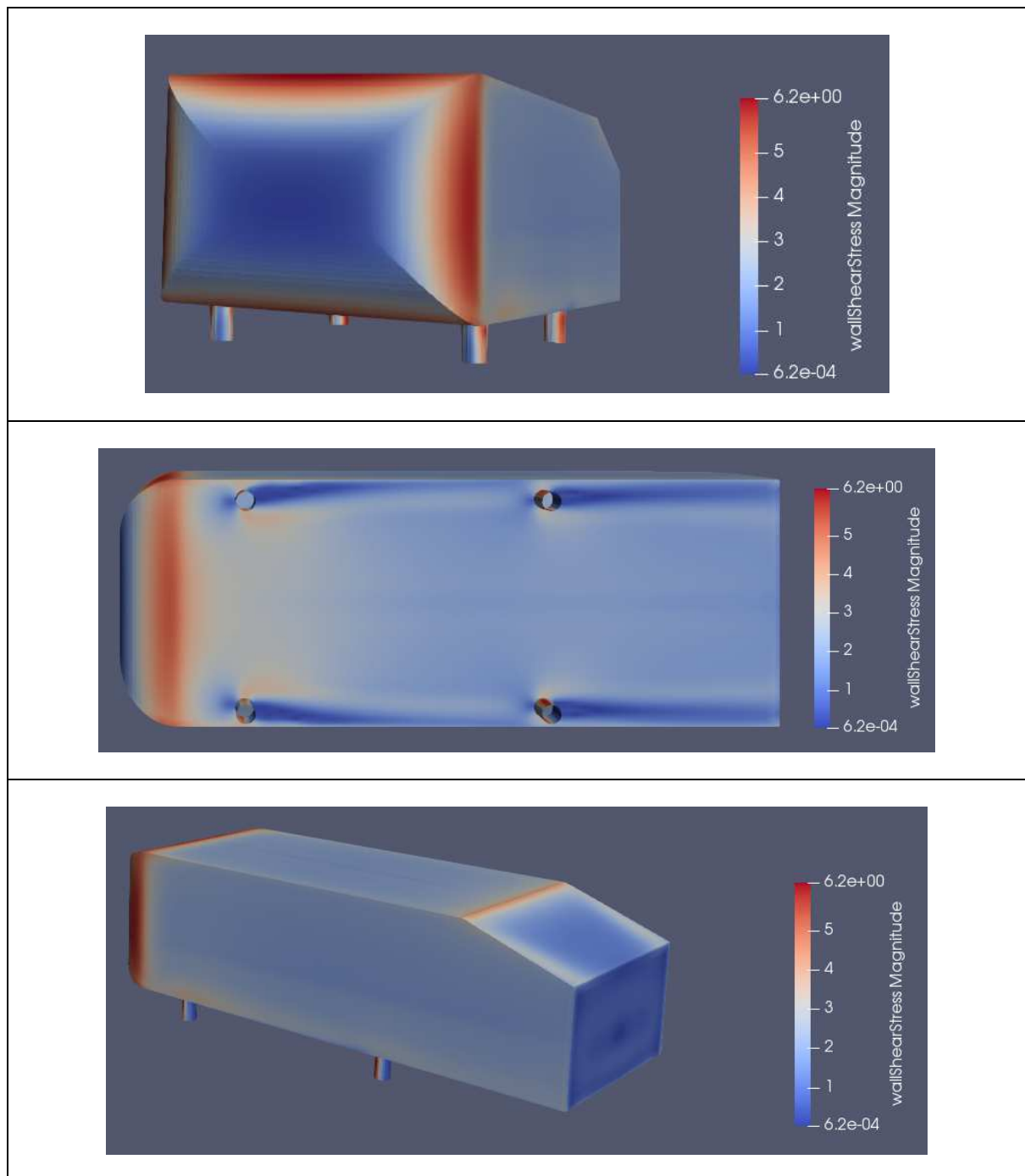
```
# Extract wall shear stress
simpleFoam -postProcess -func wallShearStress -latestTime

# Open ParaView to visualise results
ParaFoam -builtin
```

- 1) When ParaView is open, unselect the 'internalMesh' and select the 'ahmed1' and 'ahmed2' from 'MeshRegions'.
- 2) Make sure you are on the last time step (from 'VCR Control') and that the 'wallShearStress' is selected from the 'Cell Arrays' and click 'Apply'.
- 3) Select the 'wallShearStress' from the 'Active Variables Toolbar'.

Your Ahmed body should now display the wall shear stresses similar to table 5.4 below.

Table 5.4: Wall shear stresses.



5.4 Plotting Surface Streamlines

This section will look into plotting the extracted wall shear stress as streamlines onto the Ahmed body. This would allow a representation similar to that of a flow-visualisation in a wind tunnel. Additionally, it would make regions such as (saddle points, etc). visible.

In order to do the above, a plugin ('SurfaceLIC') needs to be loaded. This can be done by 'Tools>Manage Plugins', clicking on SurfaceLIC (expand), selecting 'Auto Load'

and clicking on 'Load Selected' (figure 5.4). More on 'SurfaceLIC' can be found under https://www.paraview.org/Wiki/ParaView/Line_Integral_Convolution.

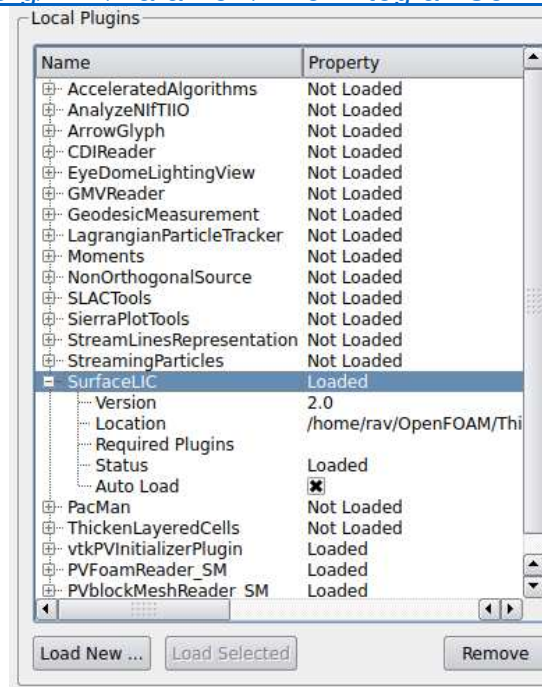


Figure 5.4: Load 'SurfaceLIC' plugin.

Restart ParaView and the plug-in should now be active. Please follow the steps below for surface streamlines.

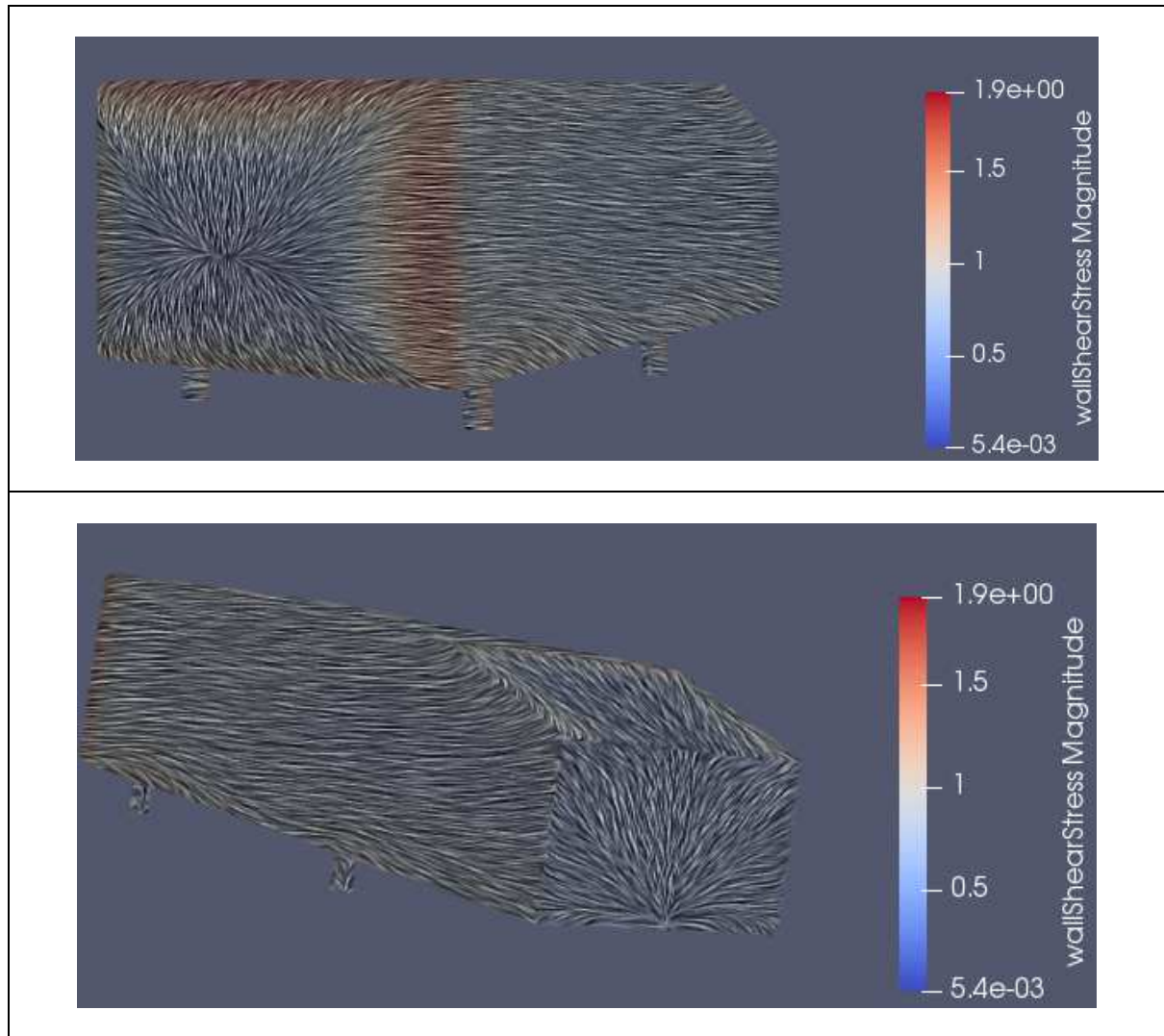
- 1) Once restarted, load the Ahmed body case and select 'ahmed1' and 'ahmed2' in 'Mesh Regions'.

Note: Make sure the 'wallShearStress' is selected in the final step 'Cell Arrays'.

Tip: You can load the previously saved state as well.

- 2) If saved state loaded, open another instance of the Ahmed body case by clicking on 'Open' in ParaView and selecting the '<case name>.foam' file.
- 3) Select 'ahmed1' and 'ahmed2' in 'Mesh Regions' and scroll down to 'Display' section (figure xx).
- 4) Choose the 'Representation as 'Surface LIC' with 'Coloring' selected as 'wallShearStress' (ignore any errors).
- 5) Scroll down to 'SurfaceLIC: Integrators' and select 'wallShearStress' as the 'Vectors' with 'Number Of Steps' as 10.
- 6) Click 'Apply' and the output should look similar to table 5.5 below.

Table 5.5: Surface streamlines ('wallShearStress')



5.5 Wall Distance ('y-plus')

Similar to section 5.3, this needs to be extracted. It can be done using;

```
# Extract wall shear stress
simpleFoam -postProcess -func yPlus -latestTime

# Open ParaView to visualise results
ParaFoam -builtin
```

Similar analysis can be done on this as above and would be discussed along with more post processing methods in the next tutorial.