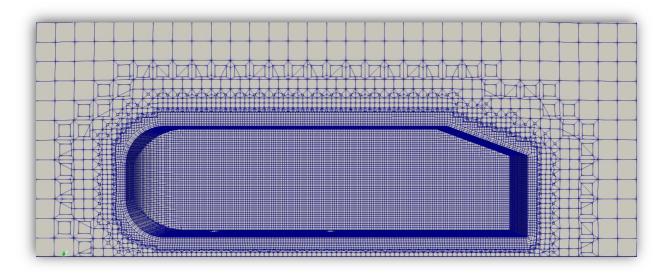


KB6003 Vehicle Aerodynamics

Tutorial 2



Ahmed Body Meshing V2

Date: 19th October 2018

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1 Introduction

This tutorial will looks into generating a refined mesh in OpenFOAM using the "snappyHexMesh" tool. This is an introductive guide and more information can be found at https://cfd.direct/openfoam/user-guide/v6-snappyhexmesh/.

It is advisable to make "reference extrudes" (models/parts) for walls of different mesh areas (such as coarse and fine meshes). These allow easy differentiation of mesh zones using OpenFOAM and obtain co-ordinates (Appendix A) from geometry as well.

- 1.1.1 Creating Reference Extrudes for Outer Walls and Coarse Mesh.
 - 1) On the model, create 5 new variables with the parameters shown in table 1.1.

Name	Value	Name	Value	Name	Value
box_x	1000	box_z	2000	back	5
box y	4000	front	3		

Table 1.1: Variables for reference mesh wall dimensions.

<u>Note:</u> Make sure these variables are above the features that they are to be used on in the "Features" tree.

- 2) Create a sketch on the "Top" plane.
- 3) Sketch a rectangle to enclose the Ahmed body using the "Corner Rectangle" tool.
- 4) You can dimension the square using the variables created in step 1 of this section. The "box_x" variable can be multiplied by the "front" and "back" variable to get dimensions of front and back of the enclosure box from the "Origin". The figure 1.1 below shows shows the completed sketch.

Note: All dimensions are from the "Origin".

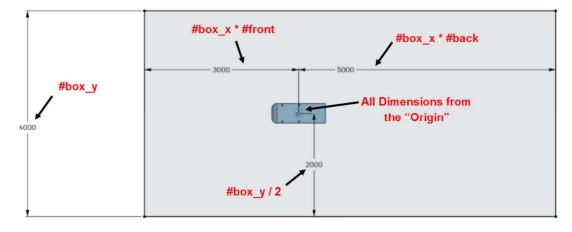


Figure 1.1: Using variables to dimension the rectangle.

5) Extrude the sketch with "Blind" selected from the drop down menu. Input "#box_z" (without quotations) for the depth.

<u>Note:</u> Make sure the "New" tab is selected instead of the "Add" as the extrude should be a new part.

6) The new part ("Part 2") will be opaque but can be made transparent by right clicking on the "Parts" list below "Features" list and clicking "Edit appearance". Move the transparency slider to your liking (as shown in figure 1.2) and click ok.

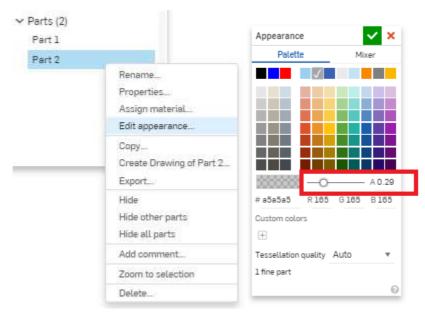


Figure 1.2: Editing appearances of parts.

7) The model should now look similar to figure 1.3 shown below.

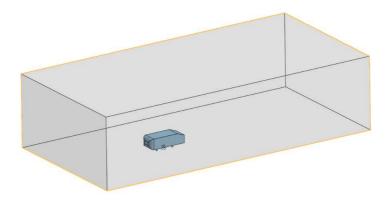


Figure 1.3: Enclosed Ahmed body.

1.1.2 Creating Reference Extrudes for Fine Mesh

Follow from step 2 in section 1.1.1 but with the following fixed dimensions shown in figure 1.4 extruded to a height (z-axis) of 1000 mm. Alternatively, you can create/use variables and assign them to the sketch as well. The finished model should look similar to figure 1.5 shown below.

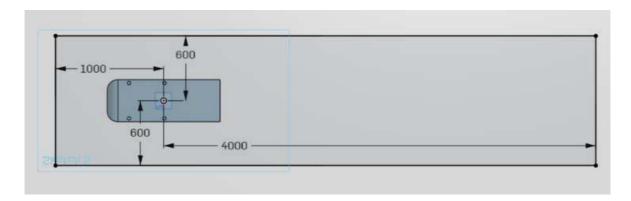


Figure 1.4: Dimensions for the fine mesh reference.

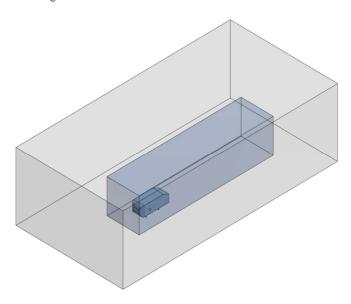


Figure 1.5: Ahmed body with reference extrudes.

1.1 Creating STL files for Meshing

Please export the STL files according to the table 1.2 below. Appendix B shows figures along with filenames for further clarification.

Table 1.2: Parts to export

File Name		Part		
ahmed_body.stl	Con	nbined Ahmed body (not needed if exported		
	prev	viously)		
ref_zone1.stl	The	The reference extrude made in section 1.1.2.		
Format:		STL		
STL Format:		Binary		
Units:		Metre		
Resolution:		Fine		
Options:		Download		

2 OpenFOAM Initial Case Setup

OpenFOAM cases follow a certain file structure and a set of instruction files (dictionaries) to run cases. A standard OpenFOAM case consist of the file structure shown in table 2.1 below.

Folder **Description** Case Main case directory Contains the physical properties and Constant geometries for the case. Also contains the mesh when generated. Contains the mesh after it is generated. polyMesh Contains the geometries (STLs, VTKs, triSurface eMesh, etc.) Contains dictionaries used to control and run the case (such as blockMesh. controlDict. system snappyHexMeshDict, surfaceFeatureExtractDict, meshQualityDict, etc.)

Table 2.1: OpenFOAM case folder structure.

As the case progresses, additional files (such as time directories, post processing, etc. will be added).

The subsequent topics would provide an introduction to modifying various dictionaries and executing them on the Ahmed body generated in tutorial 1.

- 1. Please download the "Start.zip" from; https://github.com/NU-Aero-Lab/OpenFOAM-Cases/tree/master/KB6003/Tutorial2
- 2. Place the case "ahmed1" in "Example1" folder to your OpenFOAM project (running) folder.
- 3. Place the downloaded STL files inside the "<case>/constant/triSurface" folder.

2.1 Modifying Dictionaries

OpenFOAM dictionaries contain instructions to run cases. The following sections would show how to manipulate the extraction of features and generation of a mesh. This section would only concentrate on "blockMesh", "surfaceFeatureExtractDict", "snappyHexMeshDict" and "meshQuality" dictionaries as these govern the mesh generation.

These dictionaries follow a general C++ format with "//" marking comment lines and "/*" and "*/" marking start and end of multiple line comments. The files contain headers, information sections and indentations, which are not mandatory but good programming practices. Furthermore, it would make it easier to debug and for others to understand your code. Figure

2.1 below shows a typical dictionary header. More about dictionaries can be found on https://cfd.direct/openfoam/user-guide/v6-basic-file-format/.

Figure 2.1: OpenFOAM dictionary header.

2.1.1 blockMesh (blockMeshDict)

This dictionary governs the parameters for "blockMesh" tool supplied with OpenFOAM which generates (as the name suggests) a mesh with blocks. This section will look at the generation of a block mesh for the background mesh of the Ahmed body case. More information about "blockMesh" can be found in https://cfd.direct/openfoam/user-guide/v6-blockmesh/.

Please insert the following code to your "blockMeshDict" dictionary in "<case>/system" folder below the header. The lines marked with "//" are comments and do not serve any other functions. A copy of the changed dictionary can be found in GitHub under "end.zip/example1/ahmed1".

```
// Factor for scaling
convertToMeters 1;
// Declaring variables using macro syntax notation which can later
//be used with $variablename
xmin -3;
xmax
// Try to create ymin, ymax, zmin, zmax
// Hint: vertices from geometry generated in section 1.1.1
// Cell spacing
deltax 0.1;
deltay 0.1;
deltaz 0.1;
// Calculate the length by using the above variables and assign to
//new variables
lx #calc "($xmax) - ($xmin)";
// Try to calculate ly and lz
// Calculate the number of cells with above criteria and round
xcells #calc "round($lx/$deltax)";
// Try to calculate ycells and zcells
```

```
// The 8 vertex co-ordinates of the 3D block (geometry) starting
//from 0 vertex number
// Check Appendix D in Tutorial 2 for a visual representation of
//vertices
vertices
    ($xmin $ymin $zmin) // 0 vertex
    ($xmax $ymin $zmin) // 1st vertex
    ($xmax $ymax $zmin) // 2nd vertex
    ($xmin $ymax $zmin) // 3rd vertex
    ($xmin $ymin $zmax) // 4th vertex
    ($xmax $ymin $zmax) // 5th vertex
    ($xmax $ymax $zmax) // 6th vertex
    ($xmin $ymax $zmax) // 7th vertex (8th counting 0)
);
// Defines the block topology
blocks
// Hexahedral (hex) block with vertices in sequential order, number
// of cells in each direction
// ($xcells, etc.) and stretching (simpleGrading) of the mesh (in
// this case uniform)
   hex (0 1 2 3 4 5 6 7) ($xcells $ycells $zcells) simpleGrading (1 1 1)
);
// To be used to define edges joining vertices that are not
// straight. It is assumed straight by default (leave blank)
edges
(
);
// Define the patches for boundary conditions
boundary
    side2 // patch name (user-defined)
        type symmetry; // patch type (refer to Tutorial 2
                        //blockMesh sections for details
        faces
            (3 7 6 2) // list of vertices of the surface patch (face)
        );
    }
    inlet
        type patch;
        faces
            (0 4 7 3)
        );
    }
    name1 // check and re-name the patch appropriately
        type patch;
```

```
faces
              (2 6 5 1)
         );
    side1
         type symmetry;
         faces
              (0 \ 1 \ 5 \ 4)
         );
    }
    top
         type symmetry;
         faces
              (4 5 6 7)
         );
    }
    ground
         type patch;
         faces
              (0 \ 3 \ 2 \ 1)
         );
    }
);
// Incase of multiple blocks() (defined earlier), patches to merge
mergePatchPairs
(
);
```

The patches in the "blockMeshDict" files refers areas of the boundary surface. Some available patches and their descriptions can be found in https://cfd.direct/openfoam/user-guide/v6-boundaries/#x24-1740005.2.1. The table 2.2 below gives the patch descriptions used in this tutorial.

Table 2.2: Patch types used in this tutorial (CFD Direct, 2018).

Patch	Description
patch	Generic type containing no geometric or topological information about the mesh, e.g. used for an inlet or an outlet.
wall	For patch that coincides with a solid wall, required for some physical modelling.
symmetry	For any (non-planar) patch that uses the symmetry plane (slip) condition.

Now "blockMesh" can be executed as follows;

```
# Navigate to your <case> directory (in this case, ahmed)
cd $FOAM_RUN/ahmed1
# Execute blockMesh
blockMesh
```



Figure 2.2: Check patch naming from ParaView.

The generated "blockMesh" and patch names can be checked in ParaView and renamed if needed. This can be done by launching ParaView and ticking and unticking "Mesh Regions" as seen is figure 3.2 and applying.

```
# Launch ParaView with the current
# case
paraFoam -builtin
```

The blockMesh itself can be checked by using the representations provided by ParaView such as "Surface with Edges" and "WireFrame" (figure 2.3).

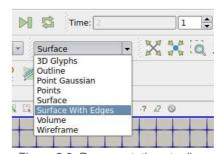


Figure 2.3: Representations toolbar.

2.1.2 surfaceFeatureSDict / surfaceFeatureExtractDict

This dictionary provides parameters for the surface features and their extraction. It is located under "<case>/system" directory. The figure 2.4 shows a typical "surfaceFeatureExtractDict" with comments (in blue followed by "//") describing the code.

```
surfaceFeatureExtractDict
                                                                               Save ≡ 🖨 🗐
                  *----*\ C++ -*-----*\
                           | OpenFOAM: The Open Source CFD Toolbox
| Website: https://openfoam.org
| Version: dev
            O peration
            A nd
            M anipulation |
FoamFile
              2.0; ascii:
   version
   format
               dictionary;
   class
              surfaceFeatureExtractDict;
   // How to obtain raw features (extractFromFile || extractFromSurface)
   extractionMethod
                      extractFromSurface;
   extractFromSurfaceCoeffs
       // Identify a feature when angle between faces < includedAngle
       // - 0 : selects no edges
// - 180: selects all edges
       includedAngle
   // Write options
// Write features to obj format for postprocessing
       writeObj
                              yes;
  Saving file "/home/rav/OpenFOAM/rav-dev/run/Start/ahmed_0/syste... C ▼ Tab Width: 8 ▼ Ln 17, Col 9 ▼ INS
```

Figure 2.4: Example "surfaceFeatureExtractDict".

1) Add the following lines to the body which instruct to extract using the "extractFromSurface" method with "includeAngle" and to write the extraction to ".emesh" and ".obj" files. These can be found in "triSurface" and "extendedFeatureEdgeMesh" folders in "Constant" directory. A copy of the changed dictionary can be found in GitHub under "end.zip/example1/ahmed1".

```
ahmed_body.stl
{
    extractionMethod extractFromSurface;

    extractFromSurfaceCoeffs
    {
        includedAngle 150;
     }

writeObj yes;
}
```

Repeat the above code for any other STL files in lines below.

2) Save file ("Ctrl+s" or click save) and exit.

To execute "surfaceFeatureExtract";

```
# Extract surface features using instructions in
# surfaceFeatureExtractDict
surfaceFeatureExtract -dict system/surfaceFeatureExtractDict
```

Similar to post "blockMesh", open ParaView using the same command but instead of loading the case (clicking "Apply"), delete it.

Now click "Open" () or go to "File>Open ..." and open the ahmed_body.stl" file from the "<ase>/constant/triSurface" directory. Please select "Apply" from the "Properties" tab to display.

You may note that the starting edge of the slanted back is missing as shown in figure 2.5.

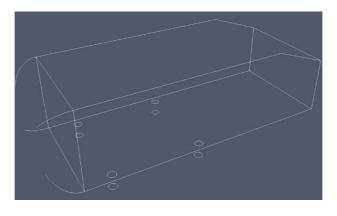


Figure 2.5: Extracted feature edges from the Ahmed body.

2.1.3 Refinement Using ParaView (paraFoam)

This is an alternative method to selecting/generating refinement zones/features. It can be useful when you would want to manually insert uncaptured features as in the case of section 2.1.2. In this particular case, the starting edge of the slanted back is not picked up by the "includeAngle" set in section 2.1.2. This can be manually added as shown below and the mesh could later be refined in this region.

1) Open ParaView by typing "paraFoam" in a terminal window. If you are not opening it from a specific OpenFOAM directory, you will be presented with several warnings and a prompt "Would you like to open ParaView anyway <Y | n>:"

Please type "y" (without quotations) and "Enter" (return) to launch ParaView. You will be presented with a screen as shown in figurer 2.6 below.

If you are opening ParaView from the <case> folder, then instead of loading the case (clicking "Apply"), delete it.

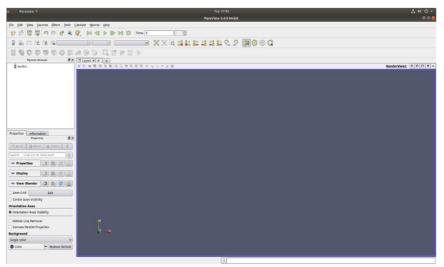


Figure 2.6: ParaView

2) Click "Open" () or go to "File>Open ..." and open the ahmed_body.stl" file. Please select "Apply" from the "Properties" tab to display the STL file.



Figure 2.7: Import the ahmed_body.stl file to ParaView.

3) The view can be manipulated with using the mouse and the view controls in the "Camera Controls" toolbar shown in figure 2.8.



Figure 2.8: Camera controls toolbar.

4) To extract edges, click on the "ahmed_body.stl" in the "Pipeline Browser". Then on the menu bar, go to "Filters>Alphabetical>Feature Edges". Click "Apply" on the properties window.

This should show some prominent edges of the Ahmed body outlined. The eye next to "ahmed_body.stl" can be used to hide the solid to view the lines only as shown in figure 2.9 below.

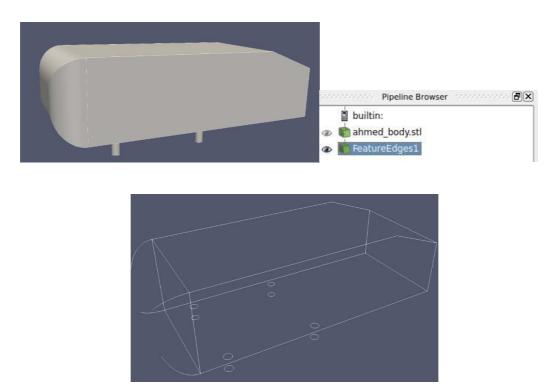


Figure 2.9: Extract feature edges from the Ahmed body.

5) As mentioned in the beginning of the section, the edge at the start of the slanted back is missing. This is due to the "Feature Angle" being set to 30 deg. by default. The feature edges are defined as "edges that are used by two polygons whose dihedral angle is greater than the feature angle." (

https://www.paraview.org/Wiki/ParaView/Users Guide/List of filters)

Since the angle between the two planes around this edge is 20 deg., the "Feature Angle" needs to be less than 20 deg.

6) Replace the default "Feature Angle" by a value lower than 20 (19, 18, 17, ...,2) and click apply to show the missing edge as show in figure 2.10.

Note: Lower the angle value, more feature edges would be captured.

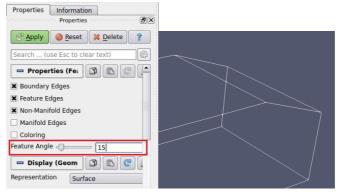


Figure 2.10: Change "Feature Angle" to show edge.

7) Select "Select Cells on (s)" tool () under the "Layout" tab and click on the edge to be extracted.

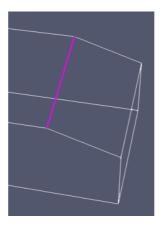


Figure 2.11: Selecting the edge for extraction.

8) Now click the "Extract Selection" under "Data Analysis" toolbar as shown in figure 2.12 and click "Apply" on the "Properties" tab.

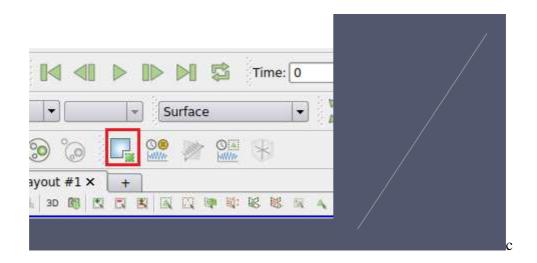
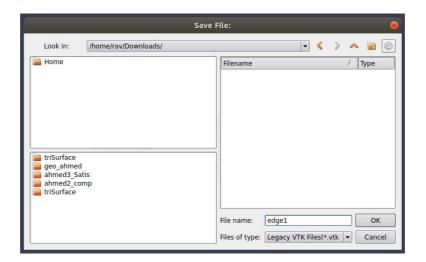


Figure 2.12: Extracting the edge using the "Extract Selection" tool.

- 9) Make sure only the extract selection ("ExtractSelection1" in this case) is selected and visible on the "Pipeline Browser". Click on "Save" () or from menu, select "File>Save Data ...".
- 10) Select the "Legacy VTK Files(*.vtk)" from the "Files of type" dropdown and name it "edge1". Save it with rest of the STL files of this tutorial.

Note: Please make sure "Ascii" is selected as the "File Type" in the following window.



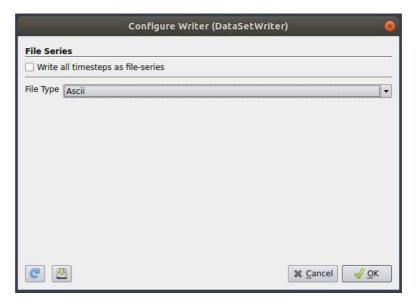


Figure 2.13: Save edge as a .vtk file.

2.1.3.1 Making the VTK File Compatible with "surfaceFeatureConvert"

The "surfaceFeatureConvert" command will be used to convert the VTK file to OpenFOAM's eMesh format. The VTK file generated in section 2.1.3 may contain additional data (such as Metadata) which will output errors when converting. The following modifications to the VTK file would enable smooth conversion;

- 1) Open the VTK file generated in section 2.1.3 in the text editor.
- 2) Remove the line containing "METADATA" to "DATA" (highlighted in figure 2.14 below) and save it.

Note: Do NOT change any formats or other fields such as co-ordinates, etc.

```
edge1.vtk
# vtk DataFile Version 4.2
vtk output
ASCII
DATASET UNSTRUCTURED_GRID
POINTS 2 float
0.313388 -0.1945 0.338 0.313388 0.1945 0.338
CELLS 1 3
2 0 1
CELL_TYPES 1
CELL_DATA 1
FIELD FieldData 1
vtkOriginalCellIds 1 1 vtkIdType
1349
POINT_DATA 2
FIFLD FieldData 1
vtkOriginalPointIds 1 2 vtkIdType
1348 1349
```

Figure 2.14: Removing additional information from the VTK file.

To generate the edge.eMesh file from the VTK file, please execute the following command;

```
# Convert edge1.vtk to eMesh format surfaceFeatureConvert constant/triSurface/edge1.vtk constant/triSurface/edge1.eMesh
```

2.1.4 snappyHexMeshDict

This dictionary controls the generation of 3D meshes consisting of hexahedral and split-hexahedral cells from tri-surfaces, STLs or Wavefront Object (.obj) format. Due to the length of this dictionary, it has not been included in the tutorial handout. A copy of the changed dictionary can be found in GitHub under "end.zip/example1/ahmed1". Comments (following "//") have been added to explain each parameter.

2.1.4.1 The Four Parts of snappyHexMeshDict

A typical snappyHexMeshDict file consist of 4 main parts, namely "castellatedMesh", "snapControls" ("snap"), "addLayers" and "Advanced" parameters (such as meshQualityControls and writeFlags).

The "<u>castellatedMesh</u>" refines the background mesh close to the features and surfaces which enables easy snapping (figure 2.15). The sizes defined in here are relative to the background mesh (in this case, blockMesh created in section 2.1.1).

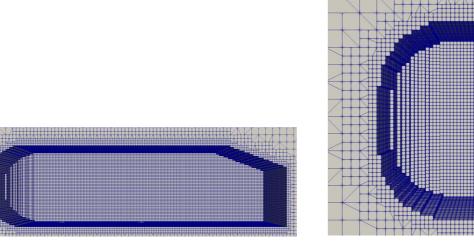


Figure 2.15: Castellated mesh

The "snap" ("snapControls"/snapping) attempts fit the mesh onto the input geometry (figure 2.16). This is an iterative process and if attempts fail to meet defined mesh quality, it would be re-attempted using reformed parameters.

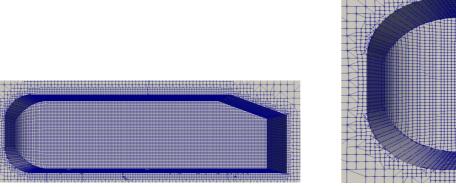


Figure 2.16: Snapping phase.

The "<u>addLayers</u>" (addLayersControls), as the name suggests, adds layers to the defined surfaces (figure 2.17). These fill any voids and irregularities created by shrinking the mesh near surfaces.

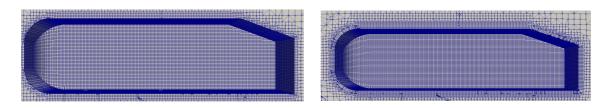


Figure 2.17a: Side view before layers

Figure 2.17b: Side view with layers

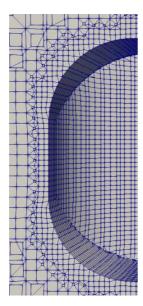
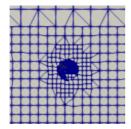


Figure 2.17c: Side view before layers (zoomed in)

Figure 2. 17d: Side view with layers (zoomed in)



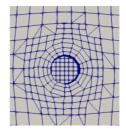


Figure 2.17e: Support (bottom view) before layers

Figure 2. 17f: Support (bottom view) with layers

Figure 2.17: Adding layers to mesh

The first few lines of the body of "snappyHexMeshDict" indicates which phase of meshing to run. These can be enabled or disabled by setting them to "true" or "false" respectively (figure 2.18). These phases can be run together, individually or re-run (together or individually) after corrections. The output can be viewed in stages in ParaView as shown in figure 2.15-2.17 by following instructions in section 3.1.2.



Figure 2.18: Which steps to run in snappHexMesh.

The Advances parameters contain parameters such as "meshQualityControls" (see section 2.1.5), "writeFlags" (information for post processing), debug flags amongst others.

The table 2.3 below will outline some important fields "snappyHexMeshDict" file.

Table 2.3: Changes to "snappyHexMeshDict" dictionary.

Parameter	Value	Description
geometry	ahmed_body.stl, ref_zone1.stl	STL Files for meshing.
castellatedMesh		
maxGlobalCells	2000000	Number of overall cells
nCellsBetweenLevels	2 (default is 3)	Number of buffer layers of cells when transitioning through levels of refinement
features	eMesh files generated by "surfaceFeatureExtract"	Feature edge refinement
level	0 for STLs, 4 for edge1	Level of refinement (see Appendix C for levels of refinement)
refinementSurfaces		Surface refinement of custom STLs name in "geometry" section.
level	(2, 2), Try more refinement later.	Level of refinement, min and max for cells intersecting the surface.
resolveFeatureAngles	30	Angle above which max refinement is added.
planarAngle	30	Angle used to detect opposite surfaces.
Region-wise Refinement	Regions from Custom STLs (names assigned in "geometry" used)	Regions for refinement with level (x y) where x is distance, y is level of refinement from surface to distance x.
refinementRegions	Box_stl: mode inside, levels (1E15 1) Ahmed1/2: mode distance, levels (0.06 4) Try more refinement later.	Refinement levels for cells in relation to surface.
LocationinMesh	(2 0 1)	Location (co-ordinates) inside the enclosure to be meshed. This must not lie/intersect the body.
snapControls		

nSolverIter	300	Number of mesh displacement relaxation iterations. Higher values result in better fitted mesh but will take more time.
nFeatureSnapIter	20	Iterations for feature edge snapping. Increase for better feature edge quality.
addLayersControls		
nSurfaceLayers	3	Number of layers
expansionRatio	1.2	Factor to increasing from layer to layer.
finalLayerThickness	0.8	Thickness of the layer furthest from the wall.
minThickness	0.001	Minimum thickness of layers (relative or absolute)
featureAngle	330	Angles above which mesh is collapsed.
nRelaxIter (slipfeature)	10	Max. number of snapping relaxation iterations. Improves the quality of the body fitted mesh.
nSmoothNormals	1	Number of smoothing iterations of interior mesh movement direction.
//Advanced		
meshQualityControls	Quality parameters for the mesh	Can be in a different file with #include notation
relaxed	maxNonOrtho 75;	Max non-orthogonality allowed.

The complete mesh quality file can be put in a separate meshQualityDict file and the "#includ "meshQualityDict" can be used as shown in the "ahmed1" example.

2.1.5 meshQuality (meshQualityDict)

This dictionary defines parameters to ensure the quality of the mesh generated is satisfactory. If the mesh does not comply with the requirements of this dictionary, it would be re-iterated with additional (defined) settings.

In this particular case, the following parameters in table 2.4 have been changed. The rest are included from the default "meshQualityDict" supplied with OpenFOAM by the line "#includeEtc "caseDicts/mesh/generation/meshQualityDict". A copy of the changed dictionary can be found in GitHub under "end.zip/example1/ahmed1".

Table 2.4: Changes to "meshQualityDict" dictionary.

Parameter	Value	Description
maxNonOrtho	75	Max non-orthogonality allowed.
maxBoundarySkewness	4	Maximum boundary face skewness allowed
minFaceWeight	0.02	Minimum face interpolation weight

To generate the "snappyHexMesh", execute the following command;

```
# Mesh using snappyHexMesh
snappyHexMesh -dict system/snappyHexMeshDict
```

<u>Note:</u> controlDict (controls read/write time, etc.), fvSchemes and fvSolutions form a part of the solution and will be explained at a later stage.

3 Checking the Generated Mesh

3.1.1 Using "checkMesh" Command

To check the quality of the mesh and any errors (skewness, non-orthagonality, etc.), the following command can be run.

Checking the mesh using checkMesh
checkMesh

It would give an output similar to figure 3.1 (not exact) below. Any deformations (errors, warnings, etc.) would be highlighted by "*" in the beginning of the line. Higher the numbers of "*" in the beginning of the line indicates the severity.

```
rav@rav-vm: ~/OpenFOAM/rav-dev/run/ahmedb
Checking basic patch addressing...
                                      Patch
                                                                          Points
                                                         Faces
                                      side2
                                                           1600
                                                                              1701
                                      inlet
                                                             800
                                                                               861
                                     outlet
                                                             800
                                                                               861
                                      side1
                                                                              1701
                                                           1600
                                          top
                                                           3200
                                                                              3321
                                     ground
                                                           8502
                                                                              9024
                                     ahmed1
                                                          34452
                                                                             35092
                                                           4318
                                                                              4463
                                     ahmed2
                                                                                558
                                     ahmed3
                                                             496
Checking geometry..
       cking geometry...

Overall domain bounding box (-3 -2 0) (5 2 2)

Mesh has 3 geometric (non-empty/wedge) directions (1 1 1)

Mesh has 3 solution (non-empty) directions (1 1 1)

Boundary openness (-1.9536797e-17 6.0701552e-18 3.344324e-16) OK.

Max cell openness = 3.3226644e-16 OK.

Max aspect ratio = 6.8804802 OK.

Minimum face area = 5.6075054e-06. Maximum face area = 0.010691097. Face area
     magnitudes OK.
       Min volume = 1.6248931e-08. Max volume = 0.0010508195. Total volume = 63.88
8514. Cell volumes OK.
   Mesh non-orthogonality Max: 74.751872 average: 8.0008849

*Number of severely non-orthogonal (> 70 degrees) faces: 24.

Non-orthogonality check OK.

<<Writing 24 non-orthogonal faces to set nonOrthoFaces

Face pyramids OK.

Max skewness = 1.9315824 OK.

Coupled point location match (average 0) OK.
Mesh OK.
End
Finalising parallel run
```

Figure 3.1: Output from "checkMesh".

3.1.2 Using ParaView

ParaView can be used to check the mesh visually once finished by typing the following code;

ParaFoam -builtin

This will launch ParaView with the case ready to be imported as shown in figure 3.2. Please follow the steps below.



Figure 3.2: ParaView with mesh.

- 1) From the "Case Type" dropdown, make sure "Reconstructed Case" is selected.
- 2) Make sure the "internalMesh" is selected in the "Mesh Regions" is selected and click "Apply". You will now see a solid block. To view the internal mesh, a "Clip" or "Slice" can be made.
- 3) Make sure the "<case>.foam" file is selected and click on the "Clip" or "Slice" in the "Common" toolbar (figure 3.3).
- 4) Select "Y Normal" (to get a cross section from the y-axis) and click "Apply".
- 5) Adjust your view by using your mouse or the "Camera Controls" toolbar (figure 2.8).

 <u>Tip:</u> You can unselect the "Show Plane" in the clip/slice "Properties" pane to hide it.
- 6) To view the mesh, change the representation from "Surface" to "Surface with Edges" from the "Representations Toolbar" dropdown (figure 3.4).



Figure 3.3: "Clip" in "Common" toolbar.

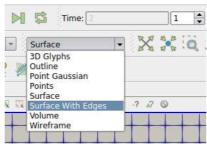


Figure 3.4: Representations toolbar.

You should now see the first step of the meshing process (castellatedMesh). You can check the rest of the mesh by navigating the steps in "VCR Controls" and "Current Time Controls"

(figurer 3.5). You can obtain different views and sections of you mesh and check if it is similar to table 3.1 below as well.



Figure 3.5: "VCR Controls" and "Current Time Controls".

To check the thickness of the layers on the Ahmed body as shown in the last parts of table 3.1;

- 1) Hide the different view/sections created from the pipeline browser by clicking the "eye" next to them.
- 2) Make the "<case>.foam" file visible and select the main geometry ("ahmed1", etc. as named in 2.1.4) and unselect the "internalMesh" then click "Apply". You should now be able to see the Ahmed body.
- 3) Select the "thickness" from "Active Variables Toolbar" (figure 3.6) and this should colour the surface of the Ahmed body with the thickness (the result is shown in table 3.1 and Appendix F).

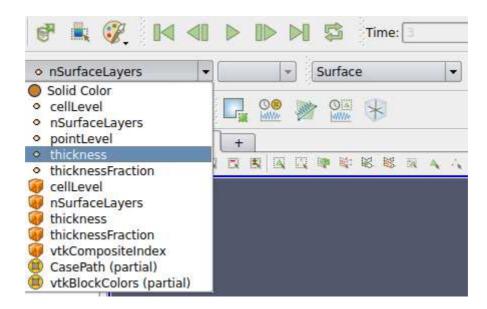


Figure 3.6: Active variables toolbar.

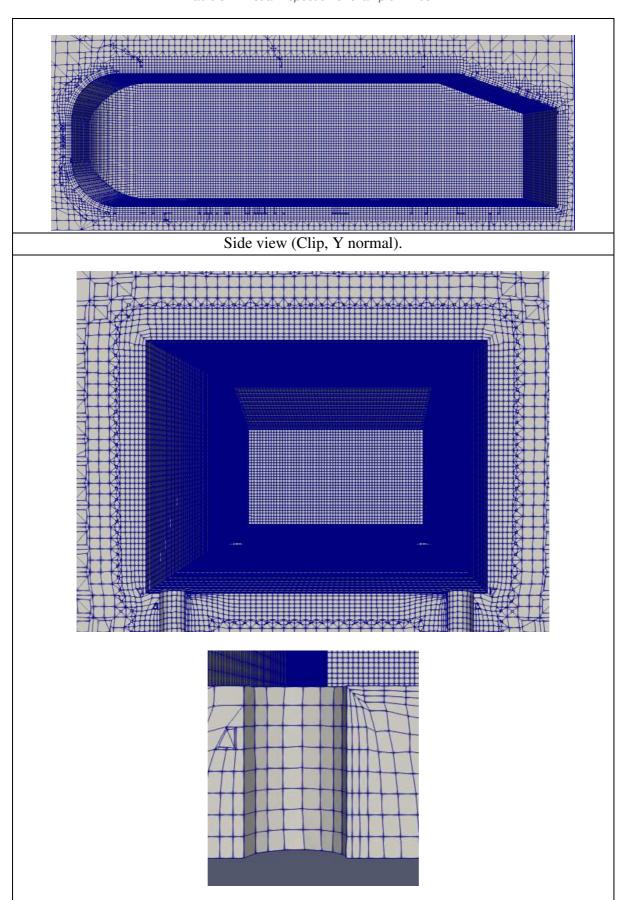
<u>Tip:</u> You can enable the internal mesh, and create different views/sections to see the layer sizing with the colours.

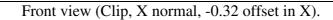
<u>Tip:</u> You can switch back to "Surface" from "Surface with Edges" in the "Representations Toolbar".

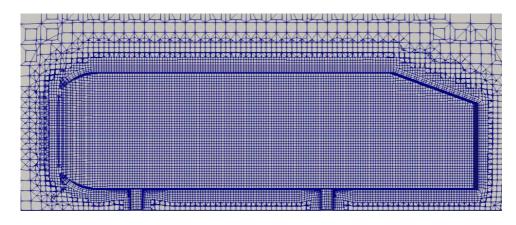
<u>Note:</u> You will have to go through different time steps as this mesh is in its decomposed stage. Eg: In some cases (example 2), last step may only shows the layers of the supports, not the rest of the body as this was the last "addLayers" step.

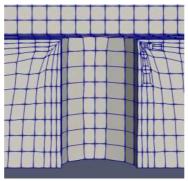
The table 3.1 below shows the generated mesh and some of its imperfections.

Table 3.1: Visual inspection of example 1 mesh.

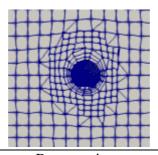






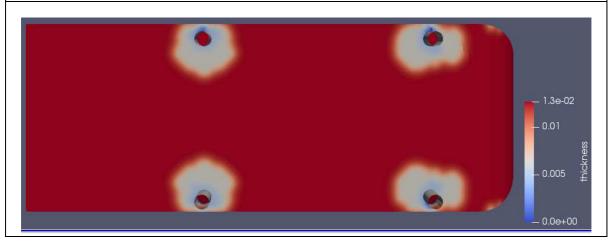


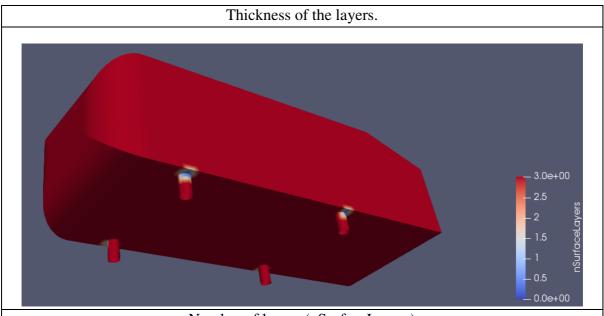
Side view (Clip, Y normal, 0.1635 offset in Y).



Bottom view.

Inflation layers on the main body look deformed from the side and the mesh seems to be collapsing near the supports.





Number of layers (nSurfaceLayers)

Checking for thickness and number of layers confirms the layers have collapsed towards the supports.

4 Example 2: Split Ahmed Body with 2 Step Meshing.

4.1.1 Splitting the Ahmed Body

This section will look at splitting the Ahmed body into different parts; the front, back and the supports. This will be done on Onshape as shown in steps below. These steps will assume that you have completed the first tutorial and hence skips detailed guidance.

- 1) Open the Ahmed body model on Onshape.
- 2) Use the "Parts" tree to make only the Ahmed body visible.
- 3) Use the "Plane" tool (□) and select "Top" plane as the "Entities" with "Offset" selected from the dropdown and value as 50 mm (the distance from top plane to the main Ahmed body). Make sure the direction of the offset is as needed (figure 4.1). Click ok (∨) to create a plane between the main Ahmed body and the supports.

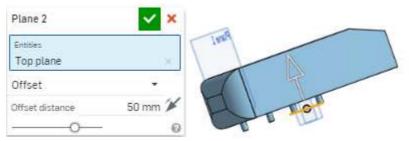


Figure 4.1: Creating a new plane by offsetting "Top" plane.

- 4) Use the "Split" tool (□) with the main Ahmed body selected as the "Parts or surfaces to split" and the "Top" plane as the "Entity to split with". Click ok (☑) to split the legs from the main body.
- 5) Save the main body (without supports) and the supports (all 4 in 1 file) according to the table 4.1 below. Appendix B shows the exported STLs.

File Name	Part
abm.stl	Main Ahmed body
support.stl	Legs of the Ahmed body
Format:	STL
STL Format:	Binary
Units:	Metre
Resolution:	Fine
Options:	Download

Table 4.1: Export parameters for Ahmed body splits.

4.1.2 Generating the Mesh in 2 Steps

This example will use the split body created in section 4.1.1 with hopes of refining the mesh further. The process can be summarised in figure 4.2.

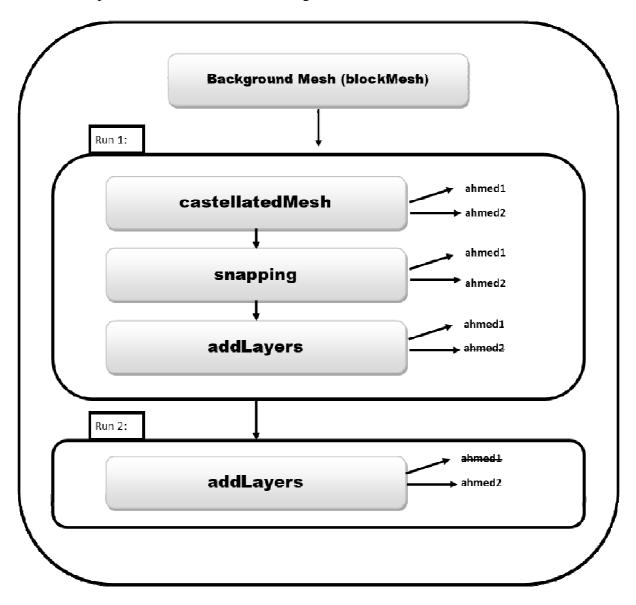


Figure 4.2: Two step meshing process.

Please follow the steps below to generate and check the above mentioned mesh;

- 1) Move the 2 STLs created in section 4.1.1 to the "<case>/constant/triSurface" directory.
- 2) Make sure the "ref_zone1.stl" and edge1.eMesh are in the folder as well.
- 3) Complete the "blockMeshDict" is set as show in section 2 and generate a "blockMesh".
- 4) Add the "abm.stl" and "supports.stl" to "surfaceFeatureExtractDict" and extract the surface features.
- 5) Open the "snappyHexMeshDict" and include the "abm.stl" and "support.stl" to the dictionary. This can be done by modifying the already existing "ahmed_body.stl" lines to "abm.stl". They can then be copied with "abm.stl" replaced by "supports.stl" in the copied lines.
- 6) Similar to the above step, add the 2 new geometries and remove the old one from;

- a. "Explicit feature edge refinement"
- b. "Surface based refinement"
- c. "Region-wise refinement"
- d. "Settings for the layer addition"
- 7) Make sure "castellatedMesh", "snap" and "addLayers" are set to "true" with "nSurfaceLayers" set to 3.
- 8) For "Run 1" set the "nSurfaceLayers" in supports (also called "ahmed2") to "0". Save this dictionary. Run the "snappyHexMesh".
- 9) For "Run 2" set the "nSurfaceLayers" in abm (also called "ahmed1") to "0". Save this dictionary. Run the "snappyHexMesh" again.
 - <u>Note:</u> Copies of the changed dictionaries can be found in GitHub under "end.zip/example2/ahmed2".
- 10) Check the mesh by running the "checkMesh" command.
- 11) Check the mesh visually by section using ParaView.

The table 4.2 below shows the generated mesh and some of its characteristics.

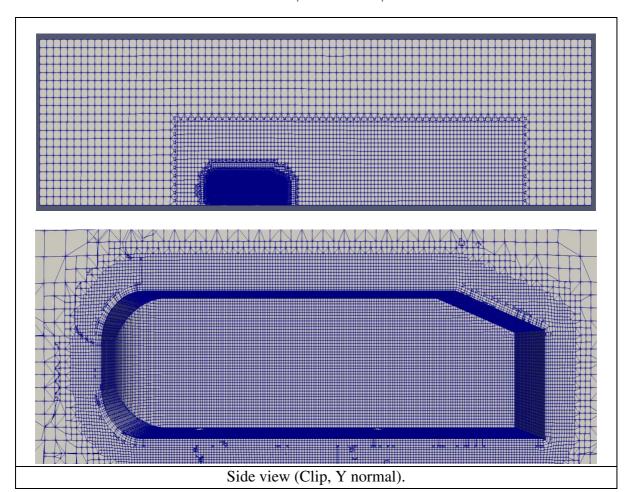
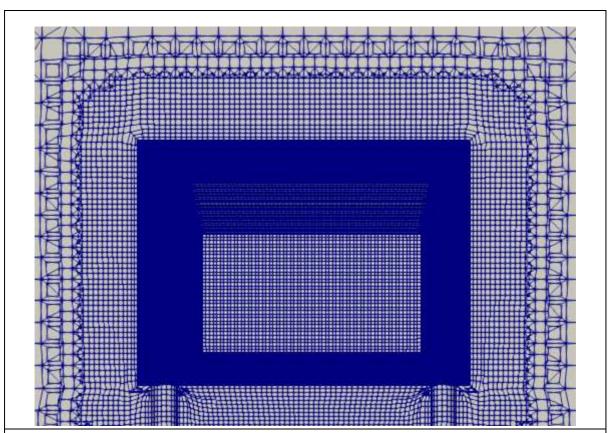
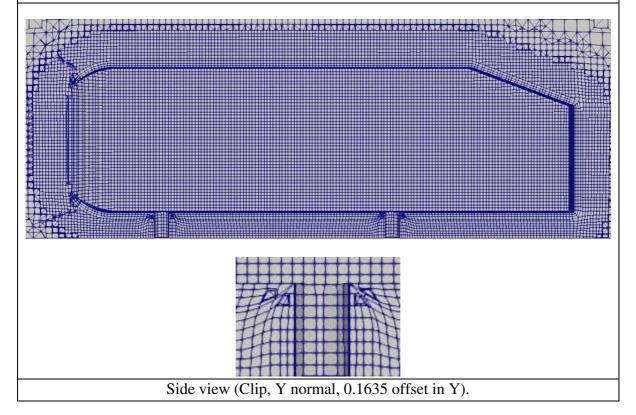
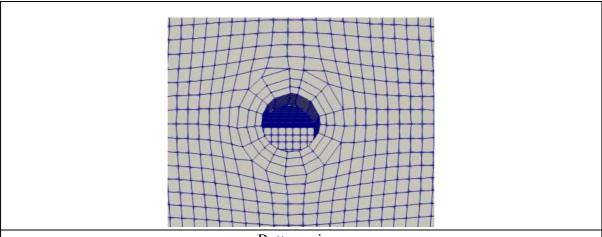


Table 4.2: Visual inspection of example 2 mesh.



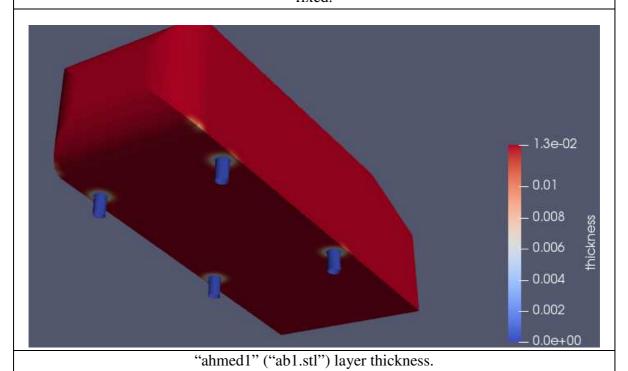
Front view (Clip, X normal, -0.32 offset in X).

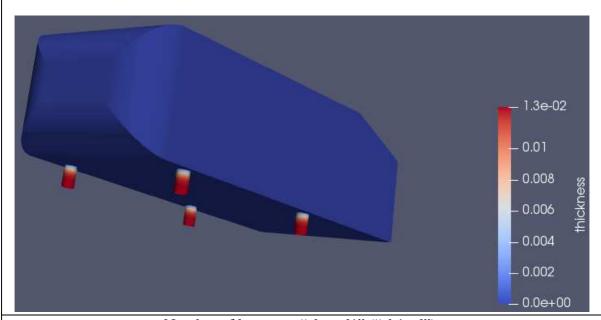




Bottom view.

The inflation layers on the legs are better, some distortion in the geometry, needs to be fixed.





Number of layers on "ahmed1" ("ab1.stl").

When checking for thickness, the layers seem to be thin but not collapsing. Better than in section example 1. Further improvement possible.

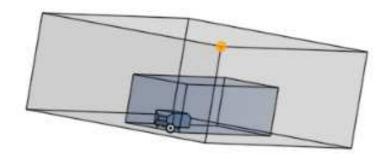
4.2 Other Improvements

Further improvements can be made to the mesh, such as the addition of more refinement zones (such as "ref_zone1.stl") to various interest areas of the body, by splitting the body into several parts and refining these individual parts with different refinement settings (such as levels, etc.).

In your own time, try to improve the above mesh. If you need support, please do not hesitate to e-mail me (<u>r.t.b.ranaweera@northumbria.ac.uk</u>) and CC in Dr. Martin (nick.d.martin@northumbria.ac.uk).

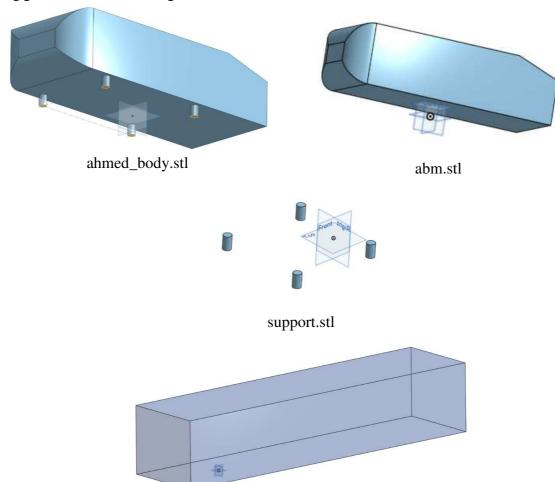
Appendix A: Co-Ordinates from Onshape

Co-ordinates of points (vertices) can be easily obtained from Onshape by clicking on the point/vertex and looking at the bottom left corner of the screen.



Point: X: -3000.000 Y: -2000.000 Z: 2000.000 r

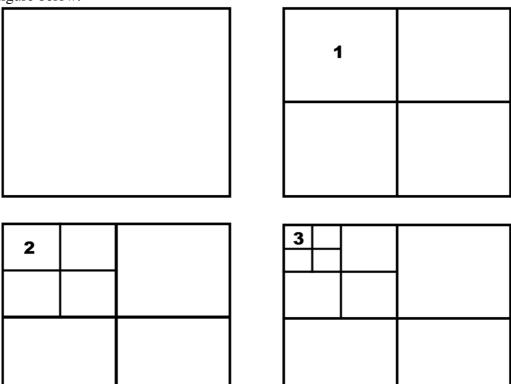
Appendix B: STL Exports



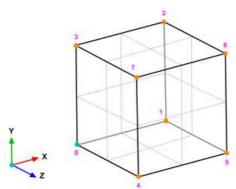
ref_zone1.stl

Appendix C: Refinement Levels

Refinement level is the splitting of a hexahedron into different smaller parts. This is illustrated in the figure below.

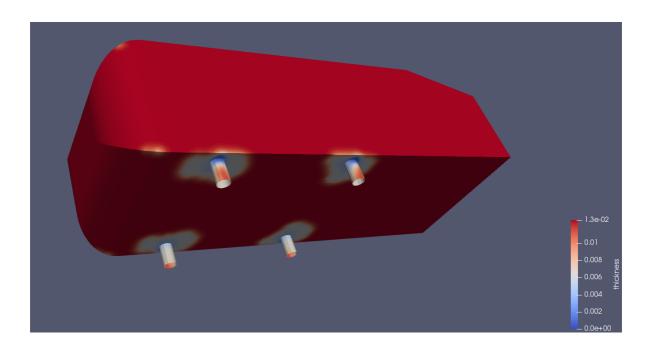


Appendix D: Vertices of a the Geometry

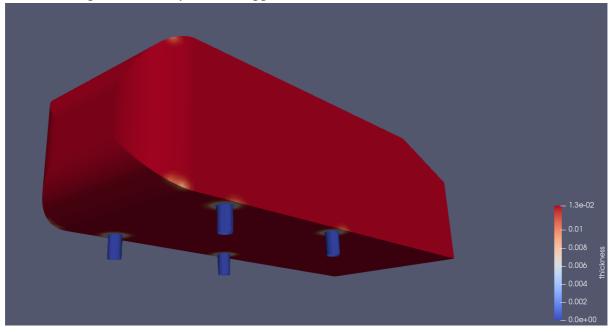


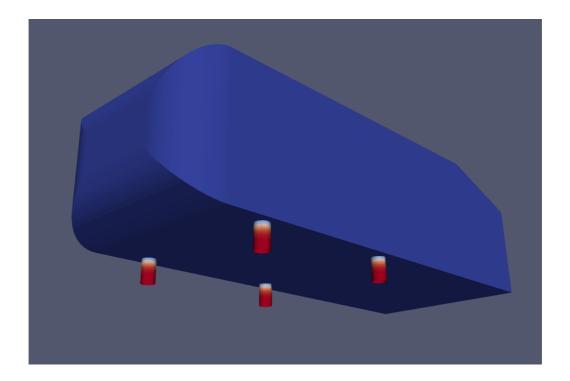
Appendix F: Single Run vs 2 Runs (snappyHexMesh)

Single run:



Two runs (separate "addLayers" for supports):





<u>Note:</u> The images are in 2 different steps (stages) due to layers for supports being applied after meshing of the main body is complete.

Recommended Learning Content

https://cfd.direct/openfoam/user-guide/v6-mesh/

https://www.openfoam.com/documentation/user-guide/mesh.php

http://www.wolfdynamics.com/wiki/meshing_OF_blockmesh.pdf

http://www.wolfdynamics.com/wiki/meshing_OF_SHM.pdf

https://www.youtube.com/watch?v=bRS0n8FuFVY&list=PLoI86R1JVvv-

EN7BsoyomcWJIPaVPXaHO

https://openfoamwiki.net/images/f/f0/Final-AndrewJacksonSlidesOFW7.pdf