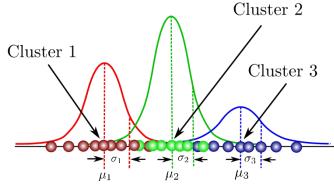
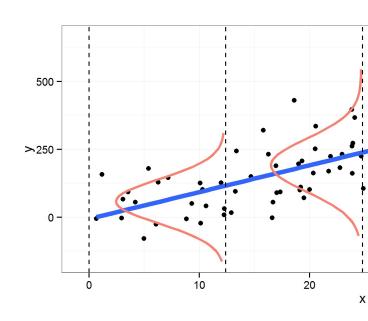
Graphical Models

Zach Wood-Doughty and Bryan Pardo CS 349 Fall 2021

Probabilistic Models



- Some models we've considered have a probabilistic interpretation
 - Linear Regression
 - Gaussian Mixture Models
- No formal language to talk about models
 - We've described the models and given intuition
- Example: Gaussian Mixture Models
 - Assume that we first select a cluster
 - We then generate an example (features) given the cluster
- How can we describe this model formally?



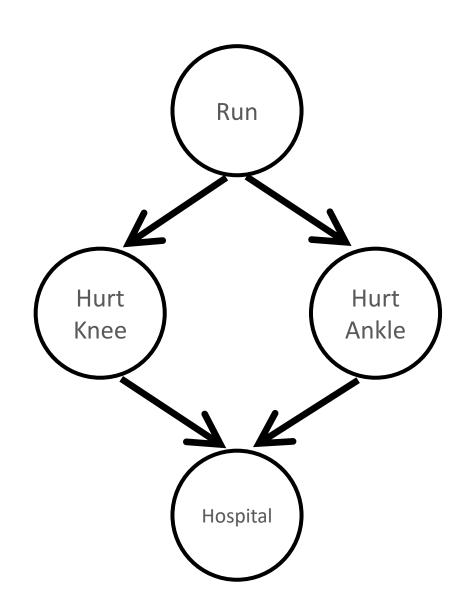
Example Probabilistic System

- A collection of related binary random variables
- Each day with some probability, a runner Avery:
 - Goes for a run
 - Sprains an ankle
 - Injuries their knee
 - Goes to the hospital
- Given a sprained ankle, what's the probability Avery goes to the hospital?
- What is the probability that Avery injuries their knee and goes to the hospital?
- etc

Example

- How do we answer these questions?
 - What is the structure of these variables?
 - What probabilities do I need to compute?
 - Are any of the variables independent of each other?
- How can we represent the variables in a way that answers these questions?

Graphical Models

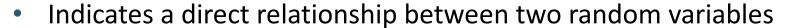


Graphical Models

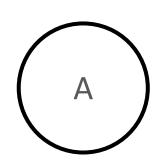
- Combination of probability theory and graph theory
 - Combines uncertainty (probability) and complexity (graphs)
 - Represent a complex system as a graph
 - Gives modularity
 - Standard algorithms for solving graph problems
- Many ML models can be framed as graphical models
 - Logistic regression, linear Regression, GMMs, etc.

Representation

- A probabilistic system is encoded as a graph
- Nodes
 - Random variables
 - Could be discrete (this lecture) or continuous
- Edges
 - Connections between two nodes

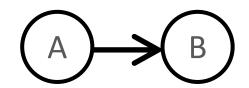


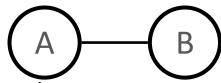
- Note: the lack of an edge is very important
 - No direct relationship



Graph Types

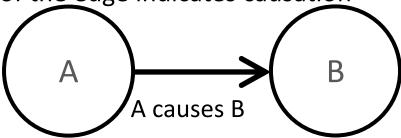
- Edge type determines graph type
- Directed (acyclic) graphs
 - Edges have directions (A -> B)
 - Assume DAGs (no cycles)
 - Typically called Bayesian Networks
 - Popular in Al and stats
- Undirected graphs
 - Edges don't have directions (A B)
 - Typically called Markov Random Fields (MRFs)
 - Popular in physics and vision





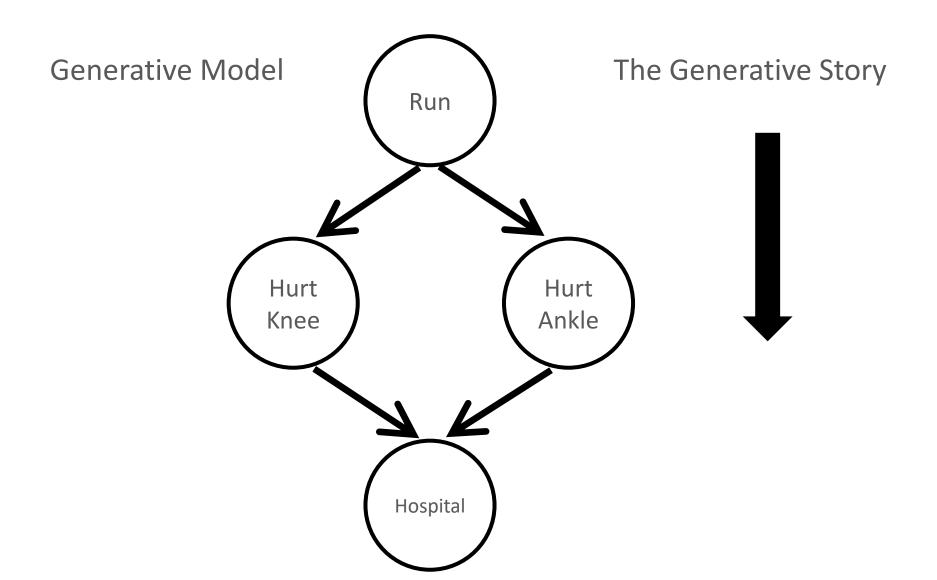
Directed Graphs

• The direction of the edge indicates causation



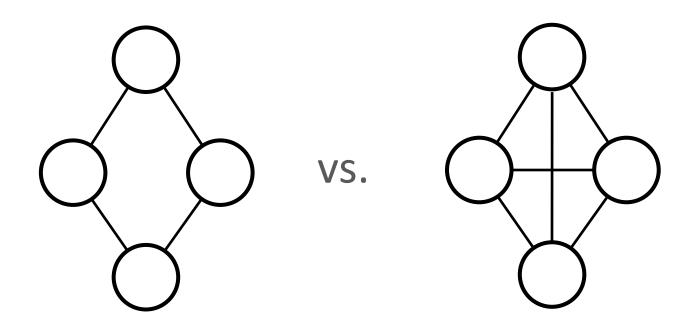
- Causation can be very intuitive
 - We may know which random variable causes the other
 - Use this intuition to create a graph structure

Example



Advantages?

- What have we gained with this representation?
 - We could just draw a graph where everything is connected



Factorization

- Consider the joint probability of our example
 - What is the size of the conditional probability table for the p(R, A, K, H) distribution?
 - What can we do to simplify?

Notice that A and K are independent given R

Run

Hurt
Knee

Hosp

Product Rule

- Can use the product rule to decompose joint probabilities
 - p(a,b,c) = p(c|a,b) p(a,b)
 - p(a,b,c) = p(c|a,b) p(b|a) p(a)
- This is true for any distribution
- Same for K variables

$$p(X_1...X_K) = p(X_K | X_1...X_{K-1})...p(X_2 | X_1)p(X_1)$$

Recall: independence

- The probability I eat pie today is independent of the probability of a blizzard in Japan.
- This is DOMAIN knowledge, typically supplied by the problem designer
- Independence implies:

$$A \perp B \Rightarrow p(A \mid B) = p(A)$$
$$A \perp B \mid C \Rightarrow p(A, B \mid C) = p(A \mid C)p(B \mid C)$$

How does independence help?

$$A \perp B \Rightarrow p(A \mid B) = p(A)$$

Α	В	P(A, B)
F	F	0.56
Т	F	0.24
F	Т	0.14
Т	Т	0.06

$$p(A) = \sum_{B} p(A, B)$$

$$= p(A, B) + p(A, \neg B)$$

$$= 0.24 + 0.06 = 0.3$$

$$p(A|B) = \frac{p(A, B)}{p(B)}$$

$$= \frac{p(A, B)}{\sum_{A} p(A, B)}$$

$$= \frac{p(A, B)}{p(A, B) + p(\neg A, B)}$$

$$= \frac{0.06}{0.06 + 0.14}$$

$$= 0.06/0.2 = 0.3$$

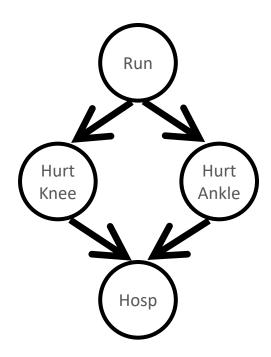
$$A \perp B \mid C \Rightarrow p(A, B \mid C) = p(A \mid C)p(B \mid C)$$

- Random variable X is conditionally independent of Y given Z if the probability of each is independent given Z
- p(x,y|z) = p(x|z)p(y|z)
- p(x|z, y) = p(x|z)
- Example
 - X: I need an umbrella and Y: the ground is wet
 - Not independent!
 - If ground is wet, it's probably raining and I'll need an umbrella
 - I am told it is raining; knowing this, the probability that I need an umbrella is independent of the ground being wet
 - I gain no new information knowing that the ground is wet
 - P(x | z, y) = p(x, z)

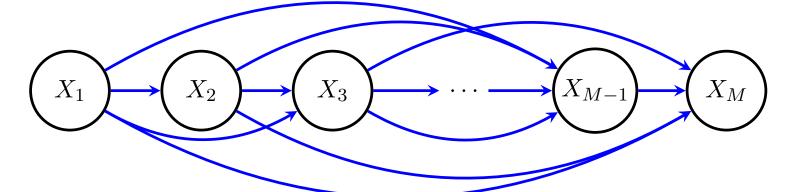
Factorization

- For any graphical model we can write the joint distribution using conditional probabilities
 - We just need conditional probabilities for a node given its parents

$$p(\mathbf{x}) = \prod_{k=1}^{K} p(\mathbf{x}_k | \text{parents}_k)$$



Counting parameters in CPTs



X ₁	X ₂	:	X _M	P(X)
F	I	L	I	0.001
Т	F	I	F	0.014
F	Τ	Щ	F	0.004
Т	Τ	I	F	0.002

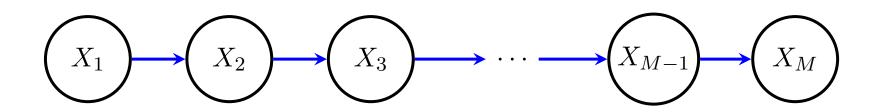
P(X ₁)
.5

X ₁	P(X ₂ X ₁)
F	0.5
Т	0.3

X ₁	X ₂	P(X ₃ X ₂ , X ₁)
F	Ŀ	0.4
Т	F	0.3
F	Т	0.2
Т	Т	0.7

$$p(\mathbf{x}) = \prod_{k=1}^{K} p(\mathbf{x}_k | \text{parents}_k)$$

Counting parameters in CPTs



X ₁	X ₂		X _M	P(X)
I	I	IЪ	F	0.001
Τ	F	F	F	0.014
F	Τ	F	F	0.004
Т	Т	F	F	0.002

$$p(\mathbf{x}) = \prod_{k=1}^{K} p(\mathbf{x}_k | \text{parents}_k)$$

X ₁	P(X ₂ X ₁)
F	0.5
Т	0.3

X ₁	X ₂	P(X	3 X ₂ , X ₁)
F	F	0.4	
Т	F	0.4	
F	Т	0.2	
Т	Т	0.2	
1	'	X_2	P(X ₃ X ₂)

F

0.4

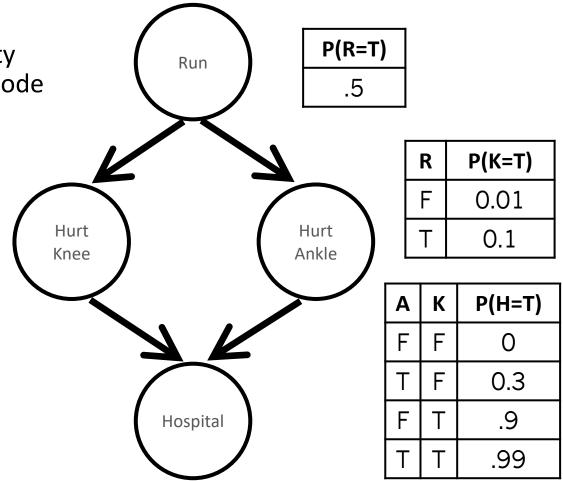
0.2

Conditional Probability Tables

 The CPTs specify the conditional probability distribution at each node

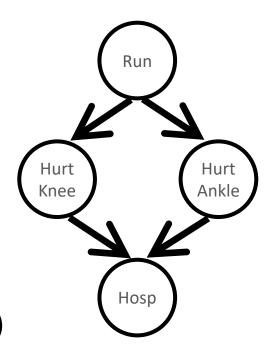
CPTs reflect local information only

R	P(A=T)
F	0.05
Т	0.2



Factorization

- Consider the joint probability of our example
 - The full p(R, A, K, H) is complex
 - What can we do to simplify?
 - Notice that A and K are independent given R
- Factor the joint probability according to the graph
 - $p(R, A, K, H) = p(H \mid A, K) p(A \mid R) p(K \mid R) p(R)$
 - This is much simpler to compute, with fewer conditional probabilities track.



Conditional Probability Tables

- Graph provides a problem structure that indicates relationships
- We use this structure to break down the problem into many local problems
- What is P(A=T | H=T)?
 - Probability of ankle injury, given a trip to the hospital
 - Break down using the network and CPTs

$$p(A = T \mid H = T) = \frac{p(A = T, H = T)}{p(H = T)} = \frac{\sum_{r,k} p(R = r, K = k, A = T, H = T)}{\sum_{r,k,a} p(R = r, K = k, A = a, H = T)}$$

Observed Variables

- Variables are either
 - Observed- we observe values in data
 - Hidden- we cannot see values in data
- Indicate observed variables by shading
- Compute the remaining probabilities given shaded value

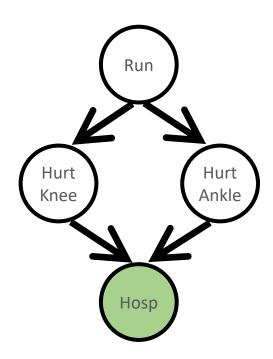


Plate Notation

Plates in graphical models

When many variables have same structure, we replace them

Run

Hosp

Hurt Ankle

Hurt

Knee

with a plate

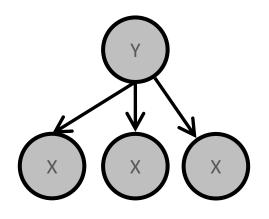
The plate indicates repetition

There are N days

Did Avery go to the hospital on any day?

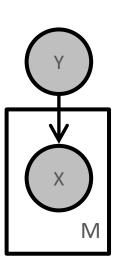
Let's consider a new model

A model where we have label Y and example X



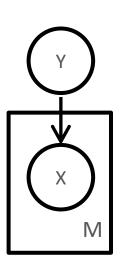
- At test time there's no Y
 - Estimate Y using X
- What model is this?





Naïve Bayes

- Generative Story
 - Generate a label Y
 - Given Y, generate each feature X independently
- Learning
 - We observe X and Y, maximum likelihood solution
- Prediction
 - Compute most likely value for Y given X



Factorization

$$P(y,x) = P(x|y)P(y)$$

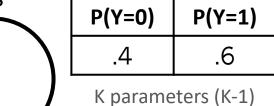
$$= \prod_{i=1}^{M} P(x_i|y)P(y)$$

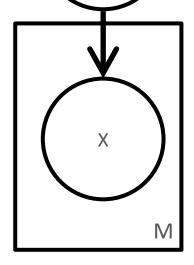
Argmax Derivation

$$\theta_{\text{MAP}} = \arg\max_{\theta} p(\theta \mid X, y)$$

Conditional Probability Tables

• The parameters correspond to CPTs





Υ	P(X=0)	P(X=1)
0	.2	.8
1	.6	.4

KM parameters

M Tables

Argmax Derivation

$$\theta_{\text{MAP}} = \arg \max_{\theta} p(\theta \mid X, y)$$

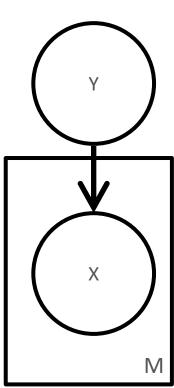
$$= \log p(y \mid \theta) + \log p(\theta) + \sum_{j=1}^{M} \log p(X_j \mid y, \theta)$$

P(Y=0)	P(Y=1)
.4	.6

Υ	P(X=0)	P(X=1)
0	.2	.8
1	.6	.4

Learning

- We assumed both examples (X) and labels (Y) for learning naïve Bayes
 - Maximum likelihood solution
 - Each entry in table are based on counts
- What if we only have X?
 - Can use EM! $\max P(X) = \sum_{y \in Y} P(Y, X)$
 - Unsupervised NB: clustering
 - Some labels: semi-supervised NB



- What is p(x|y)?
 - Probability of generating example x given that it has label y
- How hard is this?
 - Remember that x is a vector
 - Equivalent to $p(X_{i1}, X_{i2}, X_{i3} ... X_{iM} \mid Y_i)$
 - Assuming binary features and binary label, how many parameters do we need?
 - 2 * (2^M-1) parameters!
 - (2^M-1) combinations for x
 - 2 labels

- Random variable X is conditionally independent of Y given Z if the probability of each is independent given Z
- p(x,y|z) = p(x|z)p(y|z)
- p(x|z, y) = p(x|z)
- Example
 - X: I need an umbrella and Y: the ground is wet
 - Not independent!
 - If ground is wet, it's probably raining and I'll need an umbrella
 - I am told it is raining; knowing this, the probability that I need an umbrella is independent of the ground being wet
 - I gain no new information knowing that the ground is wet
 - P(x | z, y) = p(x, z)

- Assume each feature in x is independent given y
 - Once I know y each feature in x is independent
- Why is this helpful?

$$p(x_i \mid y_i) = \prod_{j=1}^{M} p(x_{ij} \mid y_i)$$

This is a naïve assumption (it's very unlikely)

- How to estimate $p(X_{ij} | Y_i)$?
 - Lots of data: every time feature x_{ij} occurs with y_i
- How many parameters do I need?
 - Before: 2 * (2^M-1)
 - Now: 2 * M
 - One parameter for each of M features
- It's much easier to learn a smaller number of parameters

Naïve vs. Reality

- Positive: we now can parameterize our model
- Reality: naïve assumption very unlikely to be true
- Example:
 - Document classification: sports vs. finance
 - Each word in a document is a feature
 - Naïve assumption: once I know the topic is sports, every word is conditionally independent
 - Not true! Would be grammatically nonsense.

Naïve Assumptions vs. Reality

- Naïve approach often works well in practice
- Caution: features that are too dependent are difficult for model
 - Create features that are minimally dependent
 - Limits the expressiveness of features

Making more realistic assumptions

- Naïve Bayes makes assumptions
 - Features (X) conditionally independent given label (Y)
- What would be a more realistic assumption?
- How does independence fit in graphical models?

Independence

- The best part of graphical models is what they do not show
- Consider the network
- A and B are independent





- P(A,B) = P(A) P(B)
- Variable independence allows us to build efficient models
 - Recall discussion on Naïve Bayes

Conditional Independence

- Are Knee and Ankle independent?
 - No, but they are conditionally independent given Run
 - P(Knee, Ankle | Run)= p(Knee | Run) p(Ankle | Run)
 - Once we know whether Avery ran, no information about ankle injuries will inform us about knee injuries

Run

Hospital

Hurt

Ankle

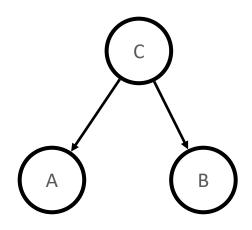
Hurt

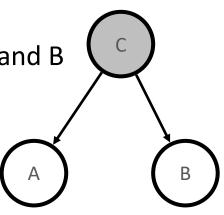
Knee

- How do we know if something is independent?
 - We can read it from the paths of the graph!
 - No mathematical trickery needed

Example 1

- Are A and B independent?
 - Clearly not. Both depend on C
- Are A and B conditionally independent?
 - Yes. Why?
 - The connection of A and B to C is "tail-to-tail"
 - Creates a dependence
 - Conditioning on C "blocks the path" between A and B



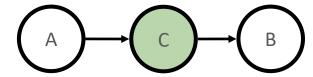


Example 2

- Are A and B independent?
 - No. A cause C which causes B



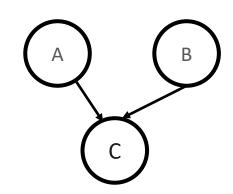
Yes. Why?



- The connection of A and B to C is "head to tail"
 - Creates a dependence
- When we condition on C, it blocks the path between A and B

Example 3

- Are A and B independent?
 - Yes. A and B are generated without common parents
- Are A and B conditionally independent given C?
 - No. Why?
 - The connection of A and B to C is "head-to-head"
 - Creates a dependence when C is observed
 - When C is unobserved, the path is blocked
 - When C is observed, the path becomes unblocked

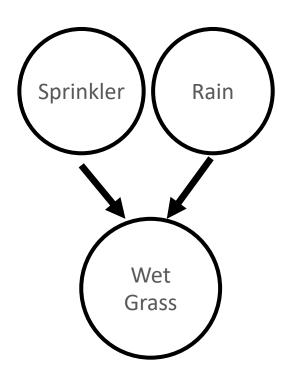


Blocked vs. Unblocked?

- Terminology: y is a descendent of x if there is a path from x to y (following the arrows)
- Tail-to-tail or head-to-tail node only blocks a path when it is observed
- A head-to-head node blocks a path when it is unobserved
 - A head-to-head path will become unblocked if either node, or any of its descendents, is observed

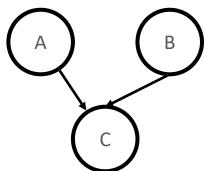
Head-to-head dependence

- Suppose you see the grass outside is wet
- The two causes (sprinkler/rain) compete to explain the grass



Explaining Away

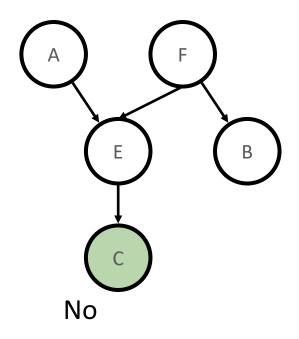
- This makes sense
 - The rain explained the grass, so sprinkler is now less likely
 - The rain explained away the state of the grass
 - Don't "need" to use sprinkler to explain it
- Thus, the observed head-to-head is unblocked
 - Once we know the value of C, we learn something about A and B



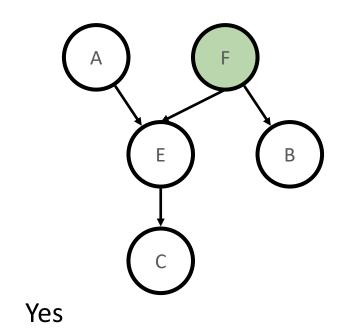
D-Separation

- Two nodes A and B are d-separated given observed node(s) C if all paths between A and B are blocked
 - Blocked paths: two arrows on the path meet head-to-tail or tail-to-tail at a node in set C
 - Or, the arrows meet head-to-head at a node which isn't in C
 - And none of its descendants are either
- If two (sets of) nodes are d-separated they are conditionally-independent!

Are A and B d-separated?

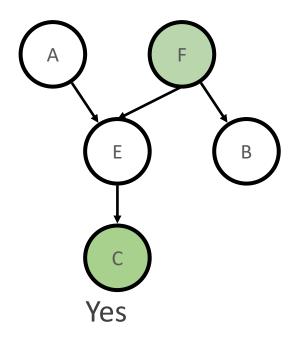


C is a descendent of head to head E

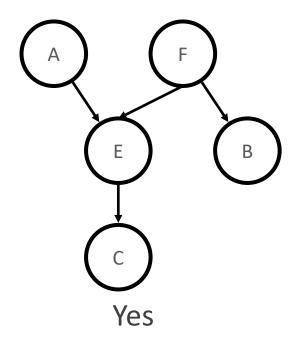


F is a tail to tail node

Are A and B d-separated?



F is a tail-to-tail node



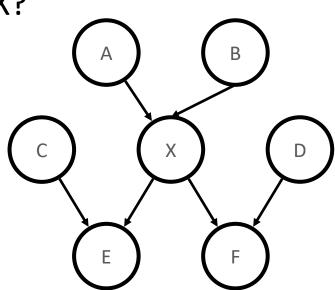
E is head-to-head

Isolating Nodes

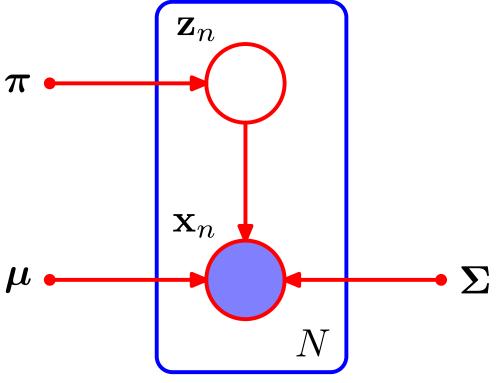
- How do we isolate a variable in the graph?
 - We know how to make it conditionally independent
 - We want to experiment with a variable in isolation
 - We don't want to enumerate all possible values of the whole network

Markov Blanket

- The Markov blanket of a node is the minimal set of nodes that isolates it from the graph
 - A node conditioned on its Markov blanket is independent from all other nodes in the graph
- What nodes are in the blanket for X?
 - Think about d-separation
 - All of them!
 - A Markov blanket depends on the parents, children, and co-parents



Graphical Representation



Graphical representation of a Gaussian mixture model for a set of N i.i.d. data points $\{x_n\}$, with corresponding latent points $\{z_n\}$, where n = 1, ..., N.

Next time:

 How do we connect more complicated graphical models to machine learning algorithms?