view frames Result Recorded at time: 645.019 world Broadcaster: /robot_state_publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (645.019 sec old) Buffer length: 0.000 sec panda link0 Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: 50.427 Hz Most recent transform: 0.000 (645.019 sec old) Most recent transform: 645.010 (0.009 sec old) Buffer length: 0.000 sec Buffer length: 2.340 sec panda link1 panda_link0_sc Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: 50.427 Hz Most recent transform: 0.000 (645.019 sec old) Most recent transform: 645.010 (0.009 sec old) Buffer length: 0.000 sec Buffer length: 2.340 sec panda_link1_sc panda link2 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: 50.427 Hz Most recent transform: 0.000 (645.019 sec old) Most recent transform: 645.010 (0.009 sec old) Buffer length: 0.000 sec Buffer length: 2.340 sec panda_link2_sc panda link3 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.427 Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (645.019 sec old) Most recent transform: 645.010 (0.009 sec old) Buffer length: 0.000 sec Buffer length: 2.340 sec panda_link3_sc panda_link4 Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: 50.427 Hz Most recent transform: 0.000 (645.019 sec old) \Most recent transform: 645.010 (0.009 sec old) Buffer length: 2.340 sec Buffer length: 0.000 sec panda link5 panda_link4_sc Broadcaster: /robot_state_publisher Broadcaster: /robot state publisher Average rate: 50.427 Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (645.019 sec old) Most recent transform: 645.010 (0.009 sec old) Buffer length: 2.340 sec Buffer length: 0.000 sec panda link6 panda_link5_sc Broadcaster: /robot_state_publisher Average rate: 50.427 Hz Broadcaster: /robot_state_publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 645.010 (0.009 sec old) Most recent transform: 0.000 (645.019 sec old) Buffer length: 0.000 sec Buffer length: 2.340 sec panda link7 panda_link6_sc Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz

Most recent transform: 0.000 (645.019 sec old) Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (645.019 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec panda_link8 panda_link7_sc Broadcaster: /robot_state_publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (645.019 sec old) Buffer length: 0.000 sec panda hand Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: 50.427 Hz Average rate: 50.427 Hz Most recent transform: 0.000 (645.019 sec old) Most recent transform: 0.000 (645.019 sec old) Most recent transform: 645.010 (0.009 sec old) Most recent transform: 645.010 (0.009 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 2.340 sec Buffer length: 2.340 sec panda_hand_sc panda_hand_tcp panda_leftfinger panda_rightfinger