view frames Result Recorded at time: 694.947 world Broadcaster: /virtual\_joint\_broadcaster\_0 Broadcaster: /kinect tf pub Average rate: 10000.000 Hz Average rate: 10.728 Hz Most recent transform: 0.000 (694.947 sec old) Most recent transform: 694.980 (-0.033 sec old) Buffer length: 0.000 sec Buffer length: 1.305 sec panda\_link0 kinect\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.725 Hz Average rate:  $1\overline{0}000.\overline{00}0$  Hz Most recent transform: 694.930 (0.017 sec old) Most recent transform: 0.000 (694.947 sec old) Buffer length: 0.000 sec Buffer length: 1.380 sec panda link1 panda\_link0\_sc Broadcaster: /robot\_state\_publisher Broadcaster: /robot state publisher Average rate:  $1\overline{0}000.\overline{00}0$  Hz Average rate: 50.725 Hz Most recent transform: 0.000 (694.947 sec old) Most recent transform: 694.930 ( 0.017 sec old) Buffer length: 0.000 sec Buffer length: 1.380 sec panda\_link1\_sc panda link2 Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate:  $1\overline{0}000.\overline{00}0$  Hz Average rate: 50.725 Hz Most recent transform: 694.930 (0.017 sec old) Most recent transform: 0.000 (694.947 sec old) Buffer length: 0.000 sec Buffer length: 1.380 sec panda\_link2\_sc panda link3 Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.725 Hz Average rate:  $1\overline{0}000.\overline{00}0$  Hz Most recent transform: 0.000 (694.947 sec old) Most recent transform: 694.930 (0.017 sec old) Buffer length: 0.000 sec Buffer length: 1.380 sec panda\_link3\_sc panda link4 Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate: 50.725 Hz \Most recent transform: 694.930 ( 0.017 sec old) Most recent transform: 0.000 (694.947 sec old) Buffer length: 0.000 sec Buffer length: 1.380 sec panda link5 panda\_link4\_sc Broadcaster: /robot\_state\_publisher Average rate: 50.725 Hz Broadcaster: /robot state publisher Average rate:  $1\overline{0}000.\overline{00}0$  Hz Most recent transform: 0.000 (694.947 sec old) Most recent transform: 694.930 (0.017 sec old) Buffer length: 1.380 sec Buffer length: 0.000 sec panda link6 panda\_link5\_sc Broadcaster: /robot\_state\_publisher Average rate: 50.725 Hz Broadcaster: /robot\_state\_publisher Average rate:  $1\overline{0}000.\overline{00}0$  Hz Most recent transform: 694.930 (0.017 sec old) Most recent transform: 0.000 (694.947 sec old) Buffer length: 1.380 sec Buffer length: 0.000 sec panda link7 panda\_link6\_sc Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate:  $1\overline{0}000.\overline{00}0$  Hz Most recent transform: 0.000 (694.947 sec old) Most recent transform: 0.000 (694.947 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec panda\_link8 panda\_link7\_sc Broadcaster: /robot\_state\_publisher Average rate:  $1\overline{0}000.\overline{00}0$  Hz Most recent transform: 0.000 (694.947 sec old) Buffer length: 0.000 sec panda hand Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate:  $1\overline{0}000.\overline{00}0$  Hz Average rate:  $1\overline{0}000.000$  Hz Average rate: 50.725 Hz Average rate: 50.725 Hz Most recent transform: 0.000 (694.947 sec old) Most recent transform: 694.930 (0.017 sec old) Most recent transform: 694.930 (0.017 sec old) Most recent transform: 0.000 (694.947 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 1.380 sec Buffer length: 1.380 sec panda\_hand\_sc panda\_hand\_tcp panda\_leftfinger panda\_rightfinger