Recorded at time: 927.088 world Broadcaster: /static transform publisher 1749073476635198788 Average rate: 10.371 Hz Most recent transform: 927.115 (-0.027 sec old) Buffer length: 2.507 sec ur10/world Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (927.088 sec old) Buffer length: 0.000 sec ur10/base link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (927.088 sec old) Most recent transform: 0.000 (927.088 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec ur10/base_link_inertia ur10/base Broadcaster: /robot state publisher Average rate: 117.424 Hz Most recent transform: 927.078 (0.010 sec old) Buffer length: 2.640 sec ur10/shoulder link Broadcaster: /robot state publisher Average rate: $\overline{1}17.42\overline{4}$ Hz Most recent transform: 927.078 (0.010 sec old) Buffer length: 2.640 sec ur10/upper arm link Broadcaster: /robot state publisher Average rate: $\overline{1}17.42\overline{4}$ Hz Most recent transform: 927.078 (0.010 sec old) Buffer length: 2.640 sec ur10/forearm link Broadcaster: /robot state publisher Average rate: 117.424 Hz Most recent transform: 927.078 (0.010 sec old) Buffer length: 2.640 sec ur10/wrist 1 link Broadcaster: /robot state publisher Average rate: $\overline{1}17.4\overline{24}$ Hz Most recent transform: 927.078 (0.010 sec old) Buffer length: 2.640 sec ur10/wrist 2 link Broadcaster: /robot state publisher Average rate: 117.424 Hz Most recent transform: 927.078 (0.010 sec old) Buffer length: 2.640 sec ur10/wrist 3 link Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (927.088 sec old) Buffer length: 0.000 sec ur10/flange Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (927.088 sec old) Buffer length: 0.000 sec ur10/tool0 Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (927.088 sec old) Buffer length: 0.000 sec ur10/pg70 base link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: 117.424 Hz Average rate: 117.424 Hz Most recent transform: 927.078 (0.010 sec old) Most recent transform: 927.078 (0.010 sec old) Buffer length: 2.640 sec Buffer length: 2.640 sec ur10/pg70 finger left link ur10/pg70 finger right link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{0}0$ Hz Most recent transform: 0.000 (927.088 sec old) Most recent transform: 0.000 (927.088 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec ur10/pg70 fingertip left link ur10/pg70 fingertip right link

view frames Result