

```
/*
 * Rui Santos
 * Complete Project Details http://randomnerdtutorials.com
 *
 * Based on the example TinyGPS++ from arduiniana.org
 *
 */

#include <TinyGPS++.h>
#include <SoftwareSerial.h>

static const int RXPin = 4, TXPin = 3;
static const uint32_t GPSBaud = 9600;

// The TinyGPS++ object
TinyGPSPlus gps;

// The serial connection to the GPS device
SoftwareSerial ss(RXPin, TXPin);

void setup(){
  Serial.begin(9600);
  ss.begin(GPSBaud);
}

void loop(){
  // This sketch displays information every time a new sentence is correctly encoded.
  while (ss.available() > 0){
    gps.encode(ss.read());
    if (gps.location.isUpdated()){
      // Latitude in degrees (double)
      Serial.print("Latitude= ");
      Serial.print(gps.location.lat(), 6);
      // Longitude in degrees (double)
      Serial.print(" Longitude= ");
      Serial.println(gps.location.lng(), 6);

      // Raw latitude in whole degrees
      Serial.print("Raw latitude = ");
      Serial.print(gps.location.rawLat().negative ? "-" : "+");
      Serial.println(gps.location.rawLat().deg);
      // ... and billionths (u16/u32)
      Serial.println(gps.location.rawLat().billionths);

      // Raw longitude in whole degrees
      Serial.print("Raw longitude = ");
      Serial.print(gps.location.rawLng().negative ? "-" : "+");
      Serial.println(gps.location.rawLng().deg);
      // ... and billionths (u16/u32)
      Serial.println(gps.location.rawLng().billionths);

      // Raw date in DDMMYY format (u32)
      Serial.print("Raw date DDMMYY = ");
      Serial.println(gps.date.value());

      // Year (2000+) (u16)
      Serial.print("Year = ");
      Serial.println(gps.date.year());
      // Month (1-12) (u8)
      Serial.print("Month = ");
      Serial.println(gps.date.month());
      // Day (1-31) (u8)
      Serial.print("Day = ");
      Serial.println(gps.date.day());
    }
  }
}
```

```
// Raw time in HHMMSSCC format (u32)
Serial.print("Raw time in HHMMSSCC = ");
Serial.println(gps.time.value());

// Hour (0-23) (u8)
Serial.print("Hour = ");
Serial.println(gps.time.hour());
// Minute (0-59) (u8)
Serial.print("Minute = ");
Serial.println(gps.time.minute());
// Second (0-59) (u8)
Serial.print("Second = ");
Serial.println(gps.time.second());
// 100ths of a second (0-99) (u8)
Serial.print("Centisecond = ");
Serial.println(gps.time.centisecond());

// Raw speed in 100ths of a knot (i32)
Serial.print("Raw speed in 100ths/knot = ");
Serial.println(gps.speed.value());
// Speed in knots (double)
Serial.print("Speed in knots/h = ");
Serial.println(gps.speed.knots());
// Speed in miles per hour (double)
Serial.print("Speed in miles/h = ");
Serial.println(gps.speed.mph());
// Speed in meters per second (double)
Serial.print("Speed in m/s = ");
Serial.println(gps.speed.mps());
// Speed in kilometers per hour (double)
Serial.print("Speed in km/h = ");
Serial.println(gps.speed.kmph());

// Raw course in 100ths of a degree (i32)
Serial.print("Raw course in degrees = ");
Serial.println(gps.course.value());
// Course in degrees (double)
Serial.print("Course in degrees = ");
Serial.println(gps.course.deg());

// Raw altitude in centimeters (i32)
Serial.print("Raw altitude in centimeters = ");
Serial.println(gps.altitude.value());
// Altitude in meters (double)
Serial.print("Altitude in meters = ");
Serial.println(gps.altitude.meters());
// Altitude in miles (double)
Serial.print("Altitude in miles = ");
Serial.println(gps.altitude.miles());
// Altitude in kilometers (double)
Serial.print("Altitude in kilometers = ");
Serial.println(gps.altitude.kilometers());
// Altitude in feet (double)
Serial.print("Altitude in feet = ");
Serial.println(gps.altitude.feet());

// Number of satellites in use (u32)
Serial.print("Number os satellites in use = ");
Serial.println(gps.satellites.value());

// Horizontal Dim. of Precision (100ths-i32)
Serial.print("HDOP = ");
Serial.println(gps.hdop.value());
}
```

```
}  
}
```