

## Motions during Interpolation

Notes for motions during interpolation motion.

### Acceleration and Deceleration

Acceleration and deceleration (linear/S-curve) are available in the linear interpolation motion.  
Acceleration and deceleration are not available in the circular interpolation motion.

### Error Stop

If any one axis in the interpolation axes stops in error, all interpolation axes stops as well.  
Confirm the error stop in "MTR\_FINISH\_STATUS" of the MtnGetStatus function. (except 0)  
For the axis which is the error stop factor, the factor bit is "1" and for the other interpolation axes, bit 15 is "1".  
<Error stop>  
Error stop is the case that an axis stops for the factor in bit 16 through bit3 of MTR\_FINISH\_STATUS of the MtnGetStatus function.

### SD signal input

If the SD input status of any one axis in the interpolation axes becomes on, in error, all interpolation axes decelerate or deceleration stop.  
→ Refer to the [MtnSetPulseOut](#) function for the SD signal function.

### Idling Control

If any one axis in the interpolation axes is in the idling range, acceleration motion is not available.  
→ Refer to the [MtnSetLimitConfig](#) function for idling.

### Correction Function

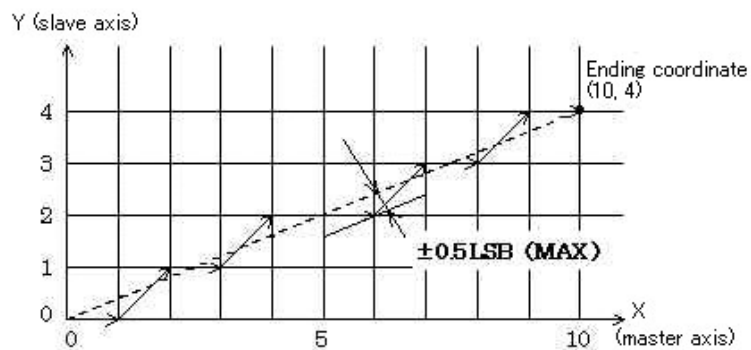
The [backlash correction/slip collection](#) control is not available during interpolation.

### Continuous Execution of Interpolation Motion

The interpolation motion can be executed consecutively using the [pre-registar](#).  
It consecutively operates different configurations of linear interpolation or circular interpolation.  
Refer to "[Startup by Stopping Another Axis](#)" for the configuration example of continuous execution of interpolation motion using the pre-register.

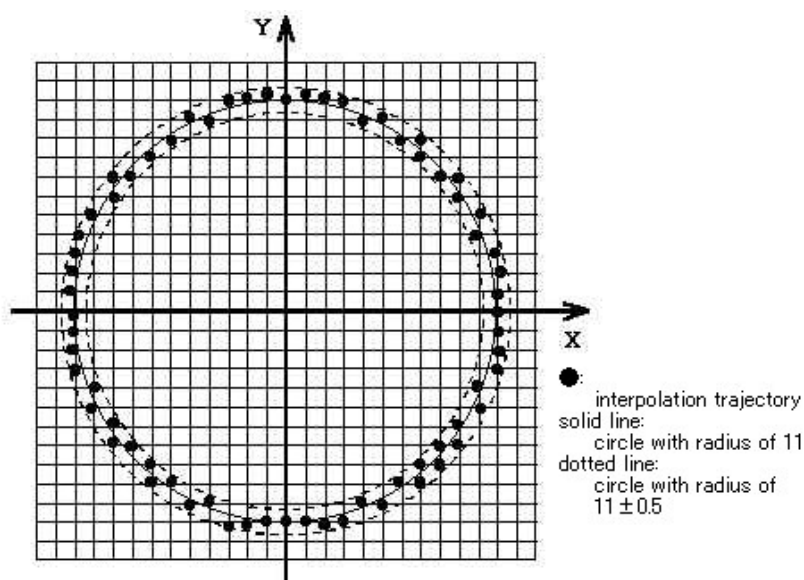
### Linear Interpolation Precision

The position error for specified line in the linear interpolation is  $\pm 0.5\text{LSB}$  within all interpolation range.



### Circular Interpolation Precision

The position error for specified arc curve in the circular interpolation is  $\pm 0.5\text{LSB}$  within all interpolation range. The following figures shows the example of drawing a true circle with radius of 11.



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