

Mass properties of R1_Housing_Sim
Configuration: Default
Coordinate system: housing_frame

Density = 2182.1051 kilograms per cubic meter

Mass (user-overridden) = 0.04 kilograms

Volume = 1.833e-05 cubic meters

Surface area = 0.03605391 square meters

Center of mass: (meters)

X = -0.0103579

Y = 0

Z = 0.01892497

Principal axes of inertia and principal moments of inertia: (kilograms * square meters)

taken at the center of mass.

Ix = (-0.00042485, 0.99999991, 1.788e-05) Px = 4.241e-05

Iy = (-0.9984924, -0.00042519, 0.05488842) Py = 4.339e-05

Iz = (0.05488842, 5.46e-06, 0.99849249) Pz = 7.789e-05

Moments of inertia: (kilograms * square meters)

taken at the center of mass and aligned with the output coordinate system.

Lxx = 4.349e-05 Lxy = 0 Lxz = -1.89e-06

lyx = 0 lyy = 4.241e-05 lyz = 0

Lzx = -1.89e-06 Lzy = 0 Lzz = 7.779e-05

Moments of inertia: (kilograms * square meters)

taken at the output coordinate system.

lxx = 5.782e-05 lxy = 0 lxz = -9.73e-06

lyx = 0 lyy = 6.103e-05 lyz = 0

lzx = -9.73e-06 lzy = 0 lzz = 8.208e-05