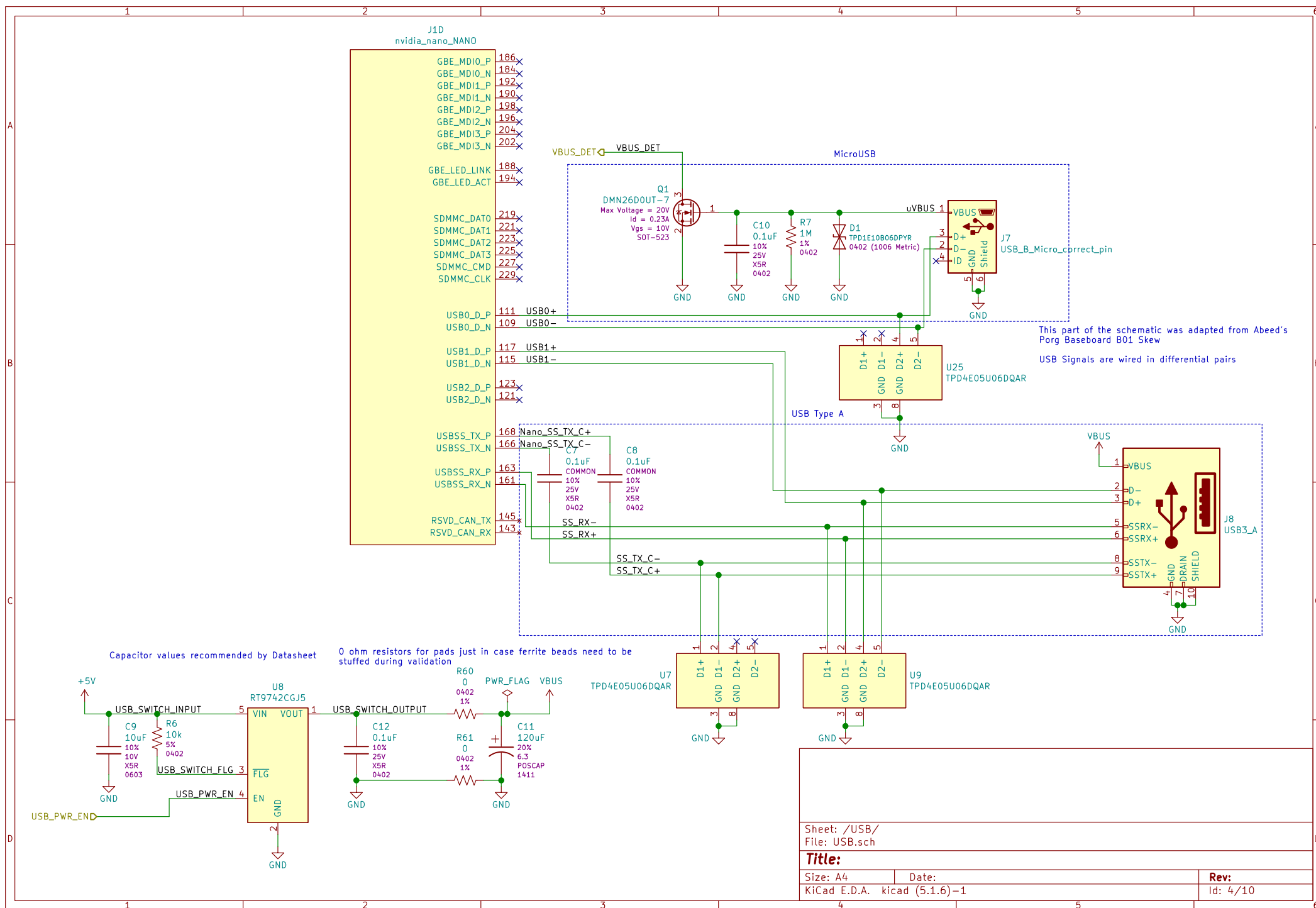
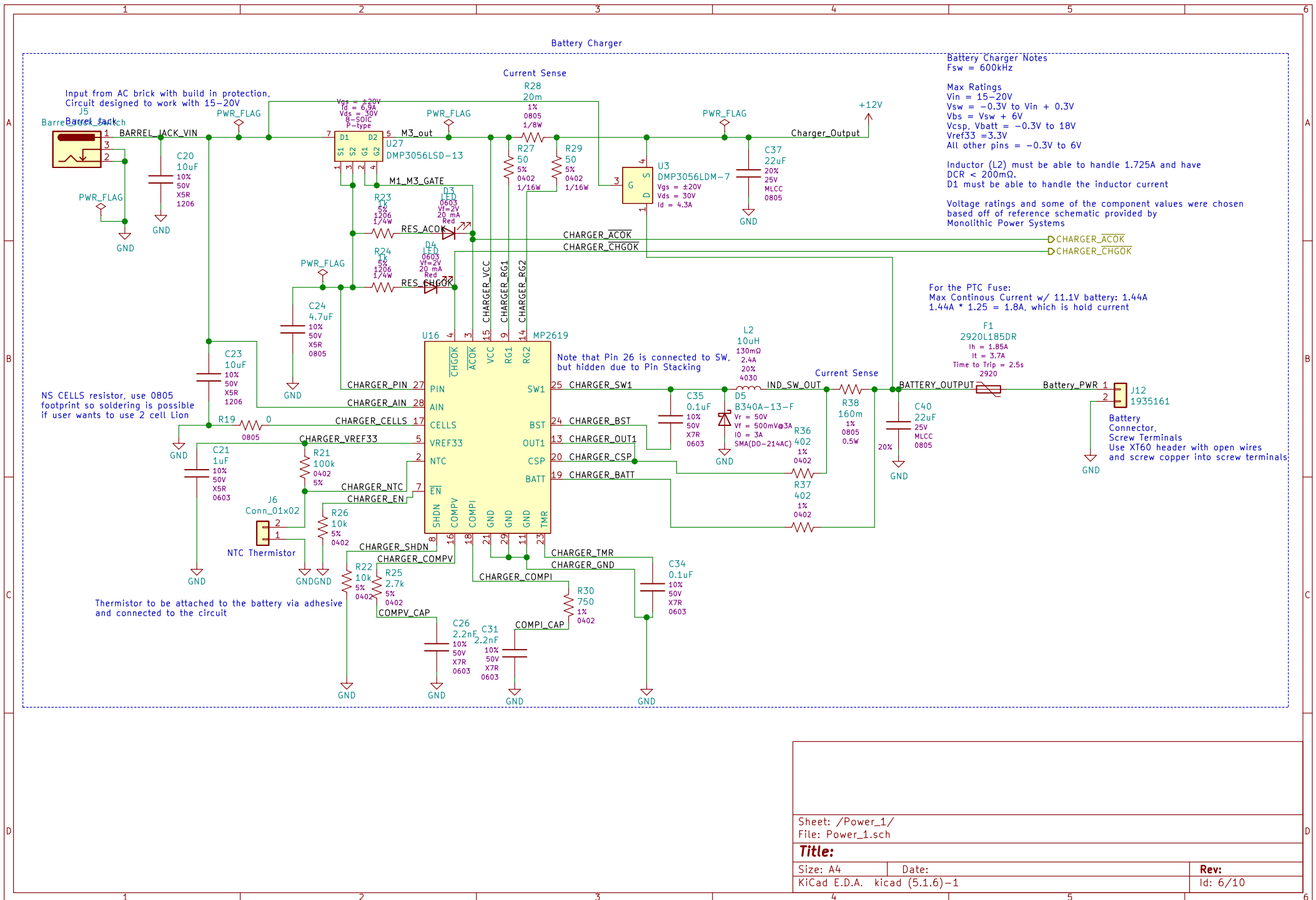


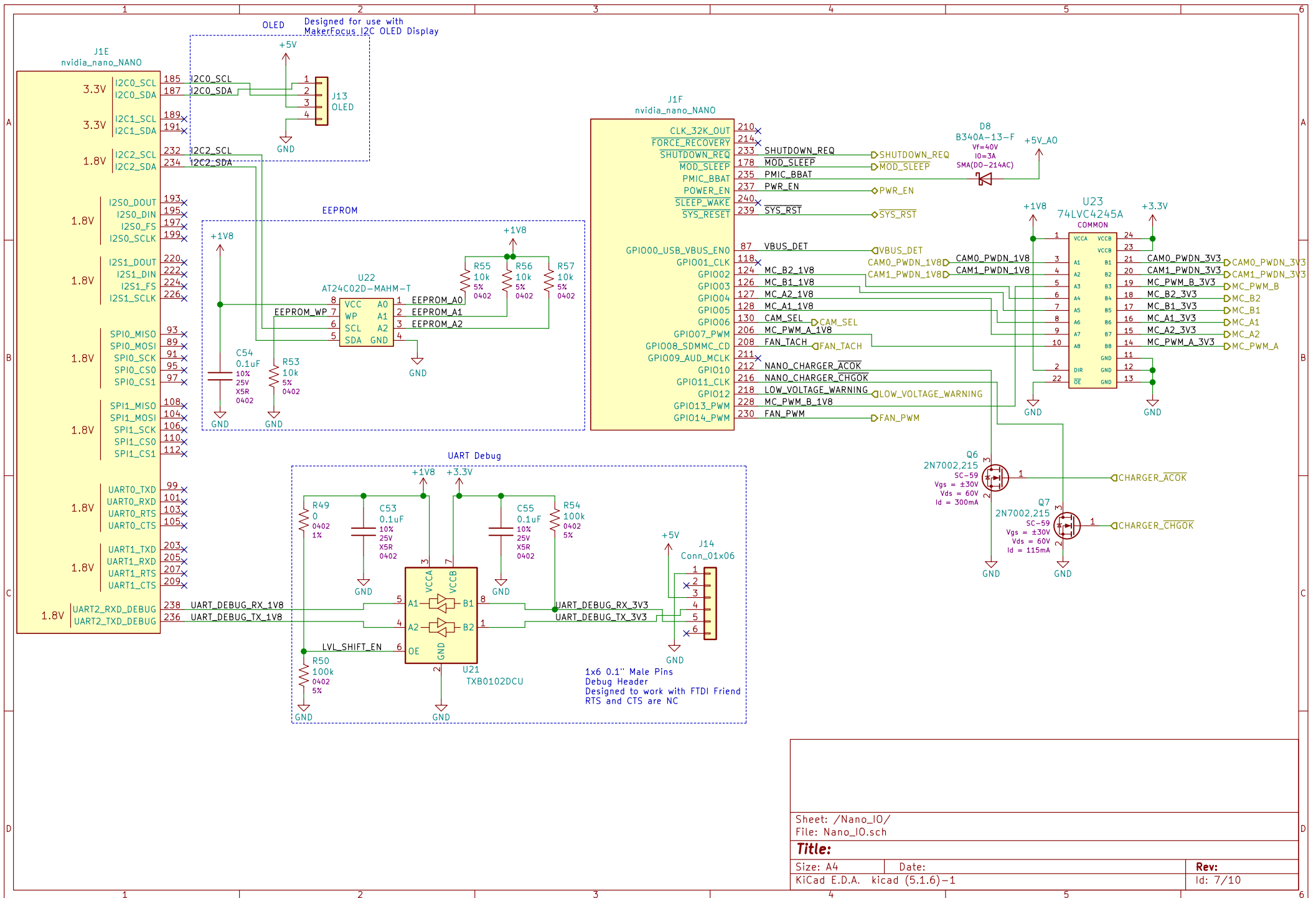
Motor controller and Motors chosen were kept consistent with the original Jetbot to ensure software compatibility

MOD_SLEEP pin is 1.8V CMOS and the STBY is on 3.3V logic, so level shift is needed

Sheet: /Motors/		
File: Motors.sch		
Title:		
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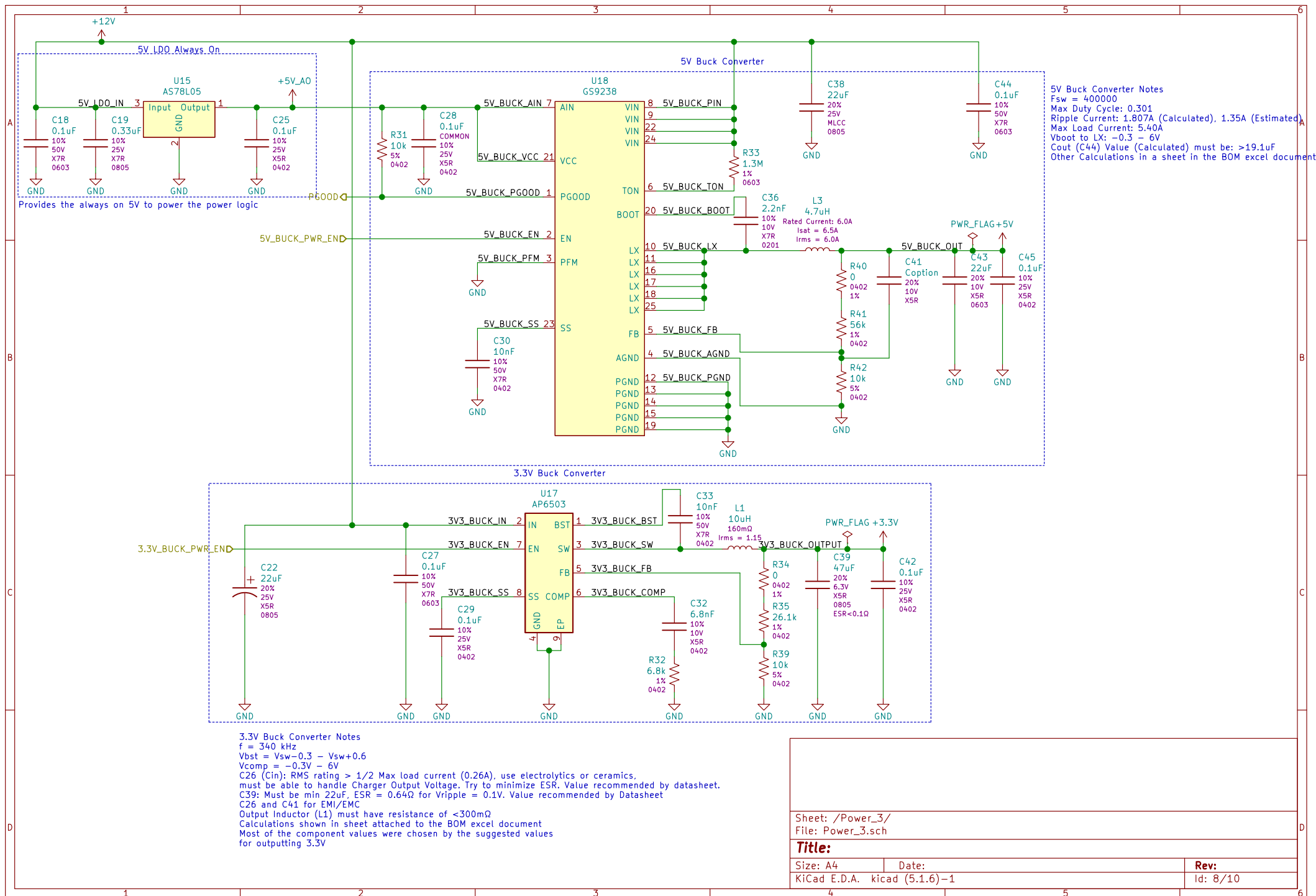
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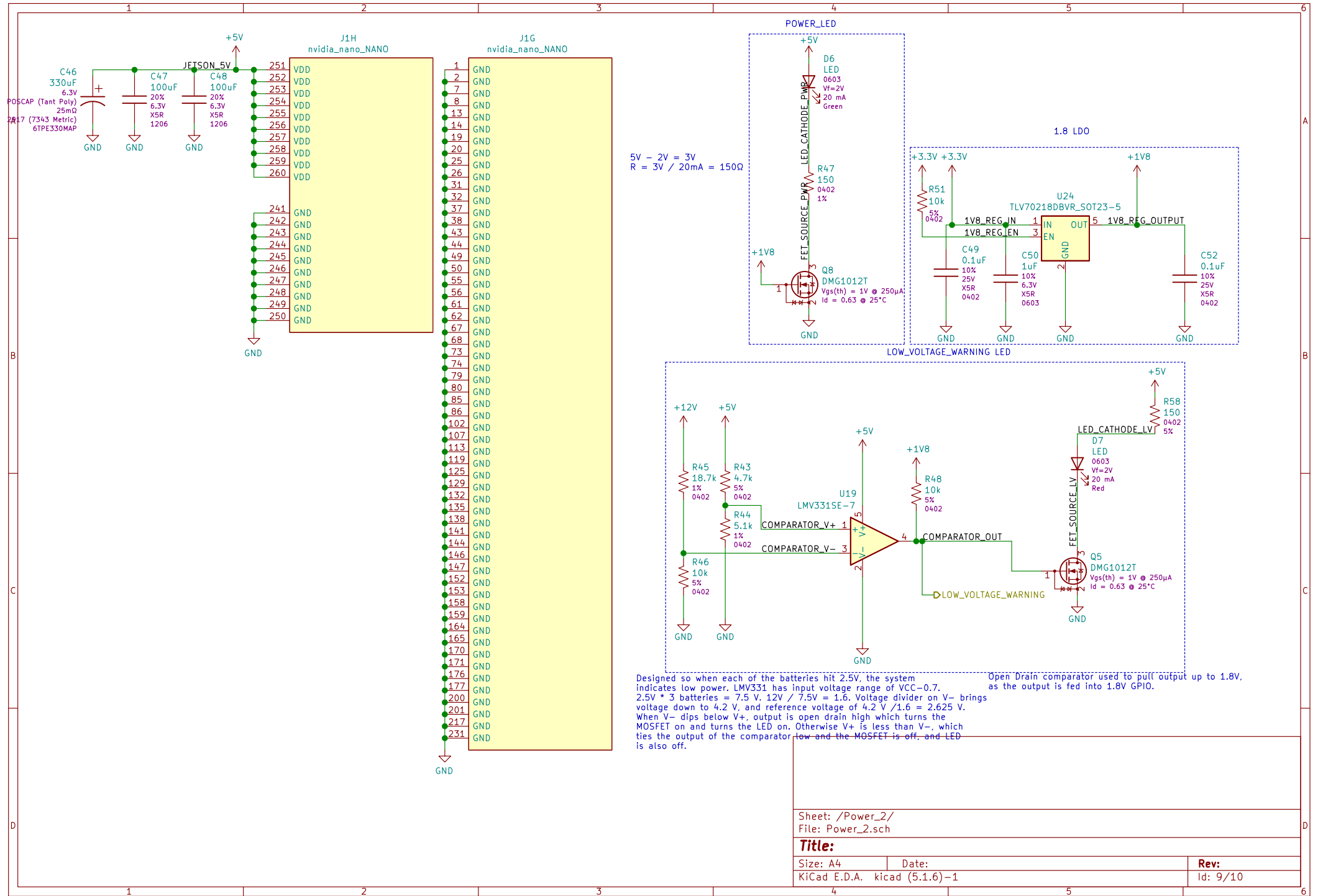
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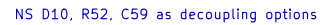
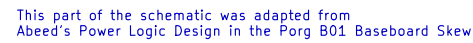
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