

# Deep Learning Final Project

## Pokémon Detection & Recognition

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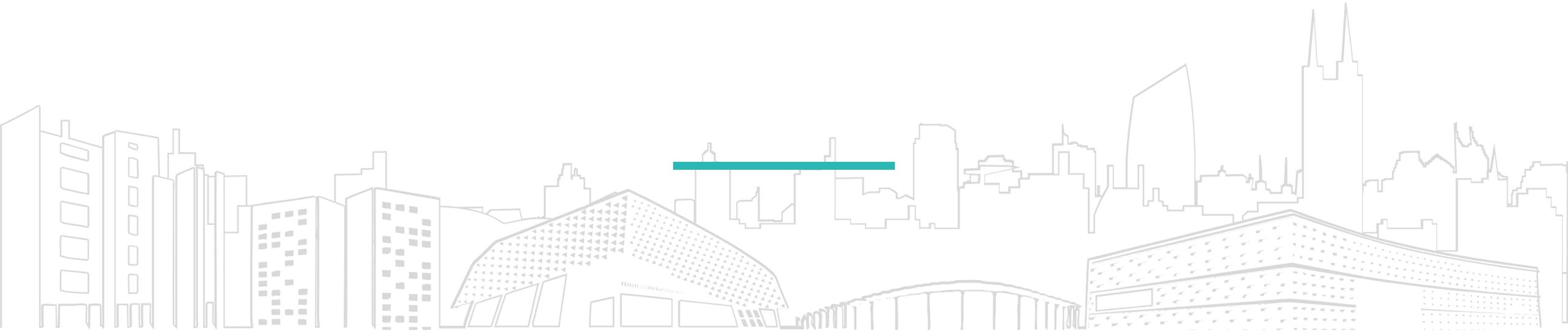
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Conclusion



01

## Introduction & Dataset & Network



# Introduction

- Our chosen topic is about **object detection**
- We have successfully build our own dataset, train the **Pokémon detection model** and deploy it on Jetson Nano, which can be used to boxed the **captured by camera in realtime**
- We have used several **different network architecture** and **quantified** the model
- We have built an **application** that take advantage of this model to capturen and introduce Pokémon
- We have deployed a **Pokémon fusion model** on server to get some interesting generation fusion images of Pokémon



# Framework

- NVIDIA provide a useful framework for deep learning learners
- **Jetson-Inference**
- It contains codes (training, apply, label) for model building and deployment and teach you how to build your own model



Image Classification



Object Detection



Semantic Segmentation



Pose Estimation



Mono Depth

# Dataset

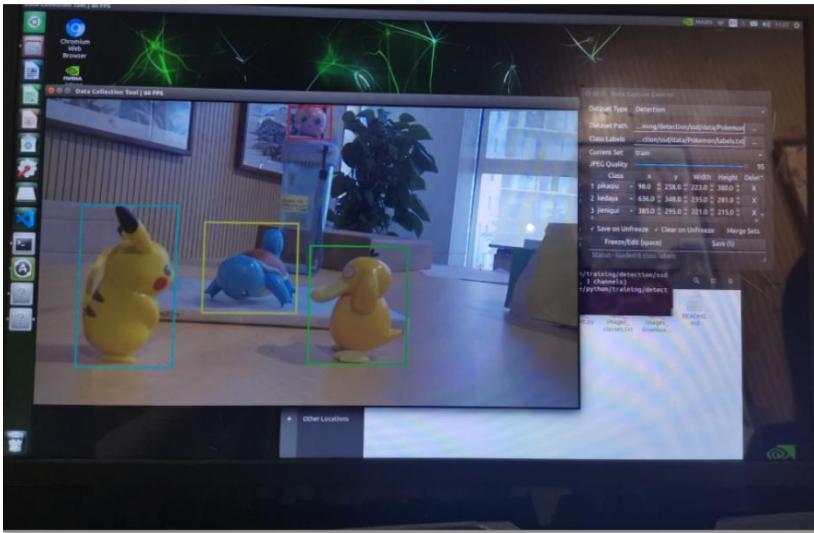
## Kaggle Pokémon Dataset

### 7,000 Labeled Pokemon

7000 hand-cropped and labeled Pokemon images for classification



### Handcraft Dataset

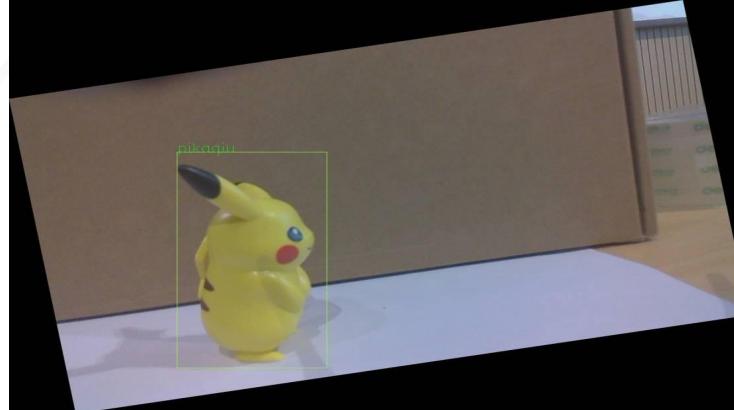


# Data Augmentation

We use several data augmentation methods:



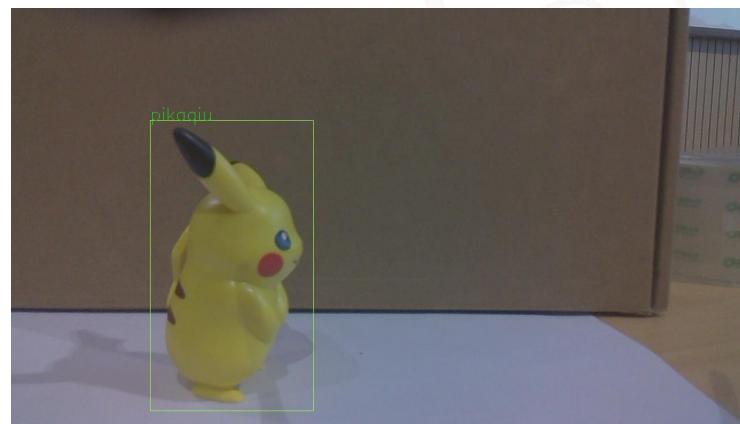
Original



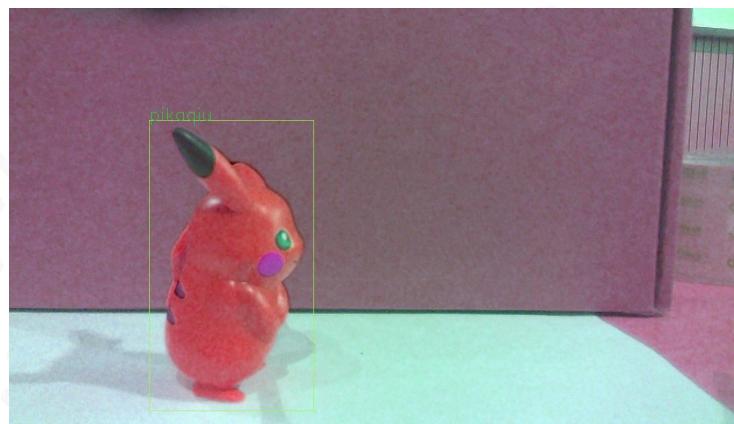
Rotation



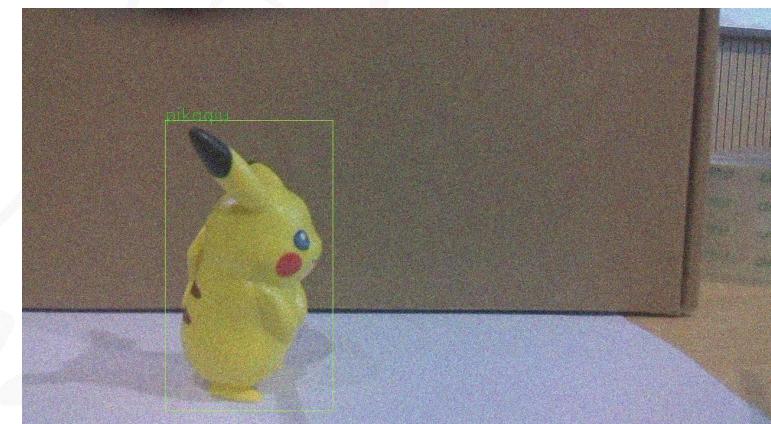
Mirror



Lower Illumination



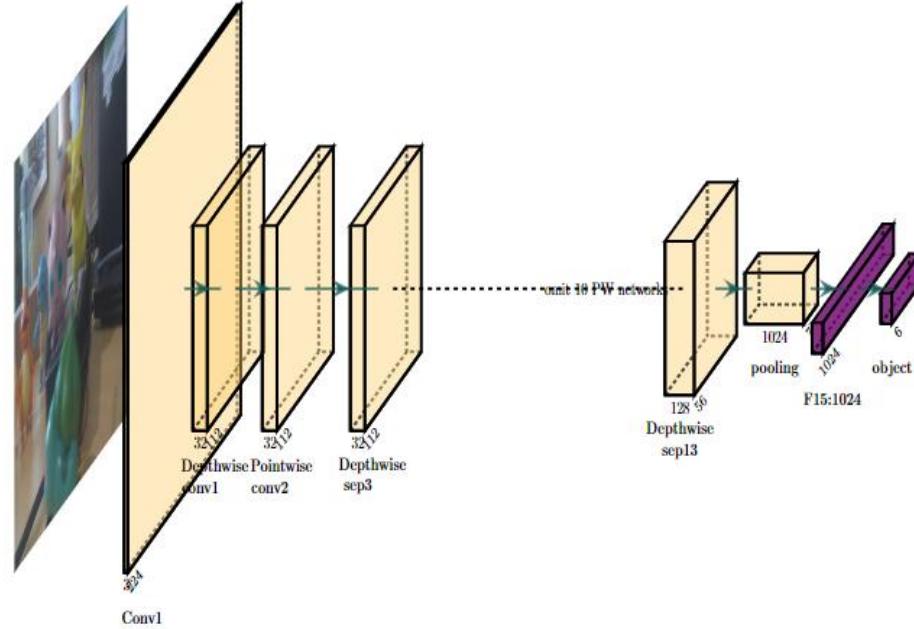
RGB to HSV



Add Noise

# Network Architecture

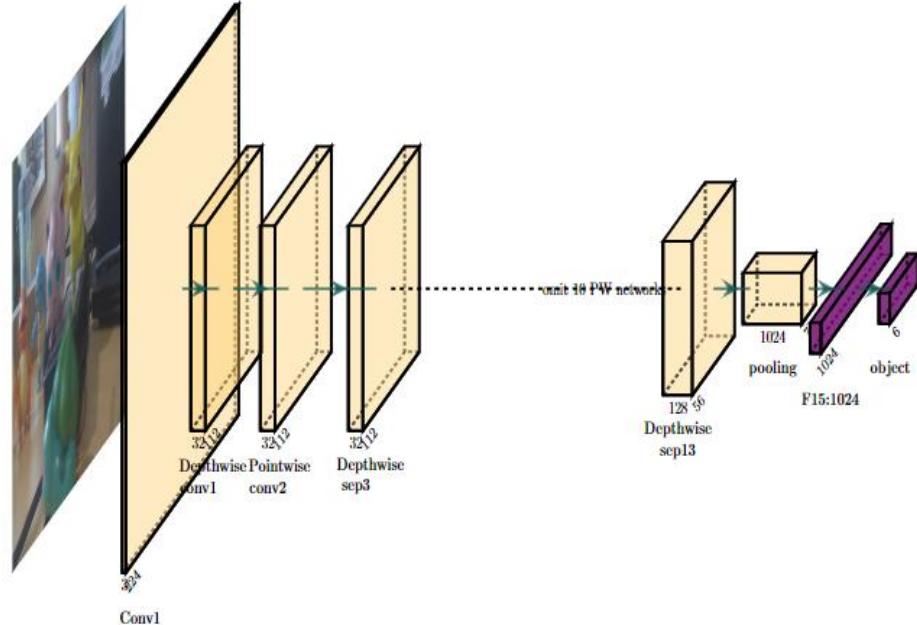
## Mobile-V2



Input	Operator	$t$	$c$	$n$	$s$
$224^2 \times 3$	conv2d	—	32	1	2
$112^2 \times 32$	bottleneck	1	16	1	1
$112^2 \times 16$	bottleneck	6	24	2	2
$56^2 \times 24$	bottleneck	6	32	3	2
$28^2 \times 32$	bottleneck	6	64	4	2
$14^2 \times 64$	bottleneck	6	96	3	1
$14^2 \times 96$	bottleneck	6	160	3	2
$7^2 \times 160$	bottleneck	6	320	1	1
$7^2 \times 320$	conv2d 1x1	—	1280	1	1
$7^2 \times 1280$	avgpool $7 \times 7$	—	—	1	—
$1 \times 1 \times 1280$	conv2d 1x1	—	k	—	—

# Network Architecture

## Mobile-V2



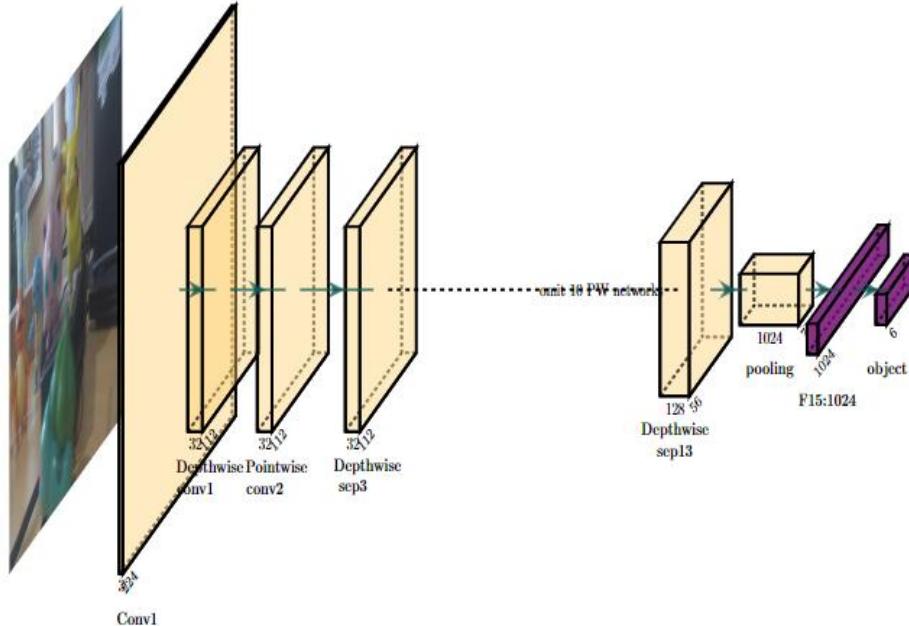
```
class MobileNetV2(nn.Module):
    def __init__(self, class_num=settings.CLASSES_NUM):
        super().__init__()
        self.conv1 = nn.Sequential(
            nn.Conv2d(3, 32, 3, stride=2, padding=1, bias=False),
            nn.BatchNorm2d(32),
            nn.ReLU6(inplace=True)
        )
        self.bottleneck1 = self.make_layer(1, 32, 16, 1, 1)
        self.bottleneck2 = self.make_layer(2, 16, 24, 2, 6)
        self.bottleneck3 = self.make_layer(3, 24, 32, 2, 6)
        self.bottleneck4 = self.make_layer(4, 32, 64, 2, 6)
        self.bottleneck5 = self.make_layer(3, 64, 96, 1, 6)
        self.bottleneck6 = self.make_layer(3, 96, 160, 2, 6)
        self.bottleneck7 = self.make_layer(1, 160, 320, 1, 6)
        self.conv2 = nn.Sequential(
            nn.Conv2d(320, 1280, 1, bias=False),
            nn.BatchNorm2d(1280),
            nn.ReLU6(inplace=True)
        )
        self.avgpool = nn.AdaptiveAvgPool2d(1)
        self.conv3 = nn.Conv2d(1280, class_num, 1, bias=False)
```

# Network Architecture



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## Mobile-V2



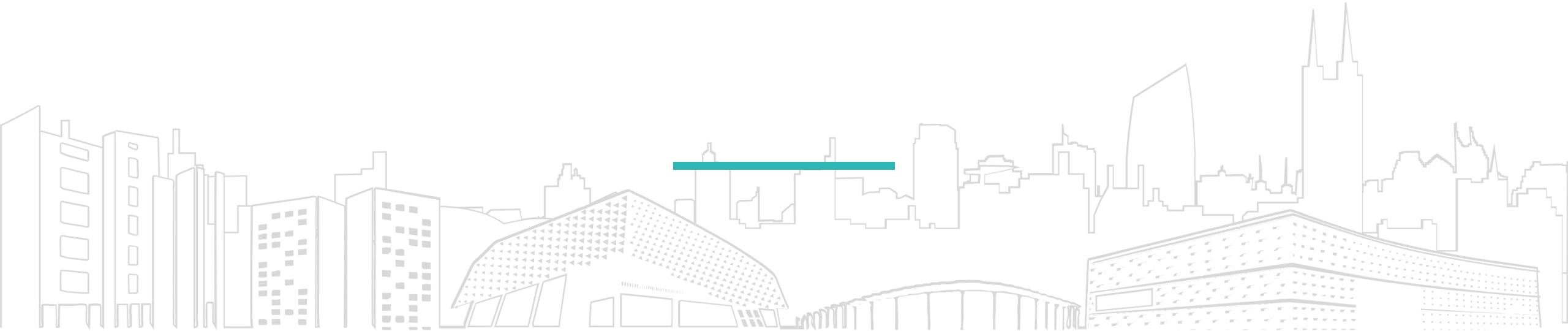
```
def make_layer(self, repeat, in_channels, out_channels, stride, t):
    layers = []
    layers.append(BottleNeck(in_channels, out_channels, stride, t))
    while repeat-1:
        layers.append(BottleNeck(out_channels, out_channels, 1, t))
        repeat -= 1
    return nn.Sequential(*layers)
def forward(self, x):
    x = self.conv1(x)
    x = self.bottleneck1(x)
    x = self.bottleneck2(x)
    x = self.bottleneck3(x)
    x = self.bottleneck4(x)
    x = self.bottleneck5(x)
    x = self.bottleneck6(x)
    x = self.bottleneck7(x)
    x = self.conv2(x)
    x = self.avgpool(x)
    x = self.conv3(x)
    x = x.flatten(1)
    return x
```

[https://blog.csdn.net/qq\\_38675397/article/details/104236588?spm=1001.2101.3001.6650.1&utm\\_medium=distribute.pc\\_relevant.none-task-blog-2%7Edefault%7ECTRLIST%7Edefault-1-104236588-blog-114368032.pc\\_relevant\\_downloadblacklistv1&depth\\_1-utm\\_source=distribute.pc\\_relevant.none-task-blog-2%7Edefault%7ECTRLIST%7Edefault-1-104236588-blog-114368032.pc\\_relevant\\_downloadblacklistv1&utm\\_relevant\\_index=2](https://blog.csdn.net/qq_38675397/article/details/104236588?spm=1001.2101.3001.6650.1&utm_medium=distribute.pc_relevant.none-task-blog-2%7Edefault%7ECTRLIST%7Edefault-1-104236588-blog-114368032.pc_relevant_downloadblacklistv1&depth_1-utm_source=distribute.pc_relevant.none-task-blog-2%7Edefault%7ECTRLIST%7Edefault-1-104236588-blog-114368032.pc_relevant_downloadblacklistv1&utm_relevant_index=2)



02

## Experiment & Quantization



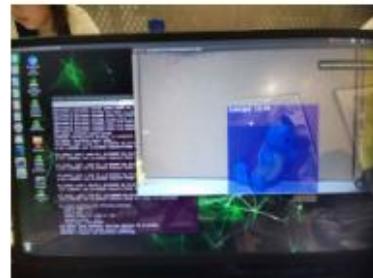
# Experiment

## Training details

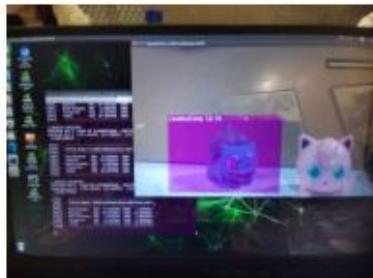
- We trained **400** epochs on a **Tesla-V100 GPU** and the batch size is **4**
- The initial learning rate is  $10^{-3}$  which will reduce **99%** every epoch
- The **Adam optimizer** is adapted and it cost nearly **5 minutes** for a single epoch

## Ablation validation

- Our team firstly adopted the **MobileNet-v1+ssd** as the network but get bad results. We compare both methods by both metrics and examples



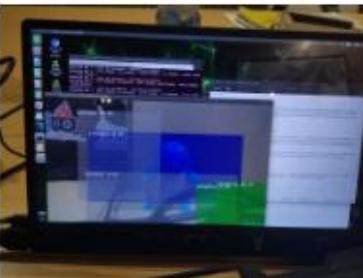
(a) Acceptable result



(b) Wrong tag



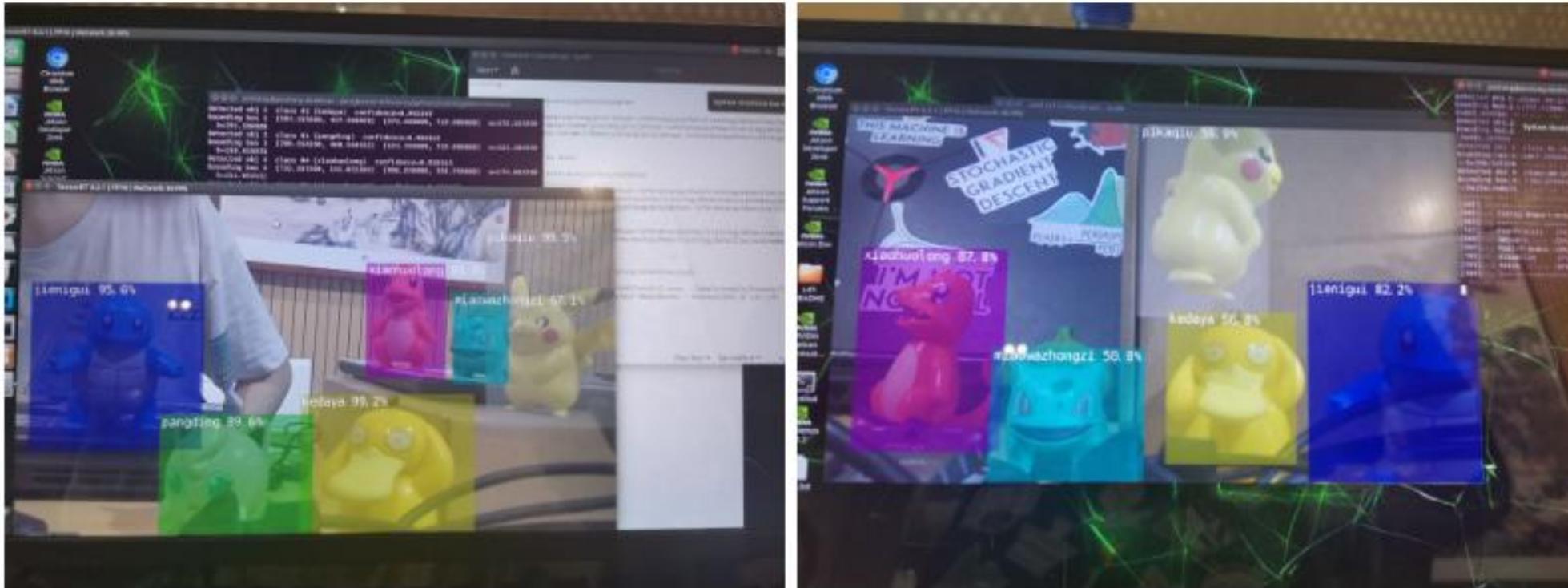
(c) Wrong tag



(d) Bad bounding boxes

# Experiment

## Training result



Mobile-V2 Model Training Result

# Quantization



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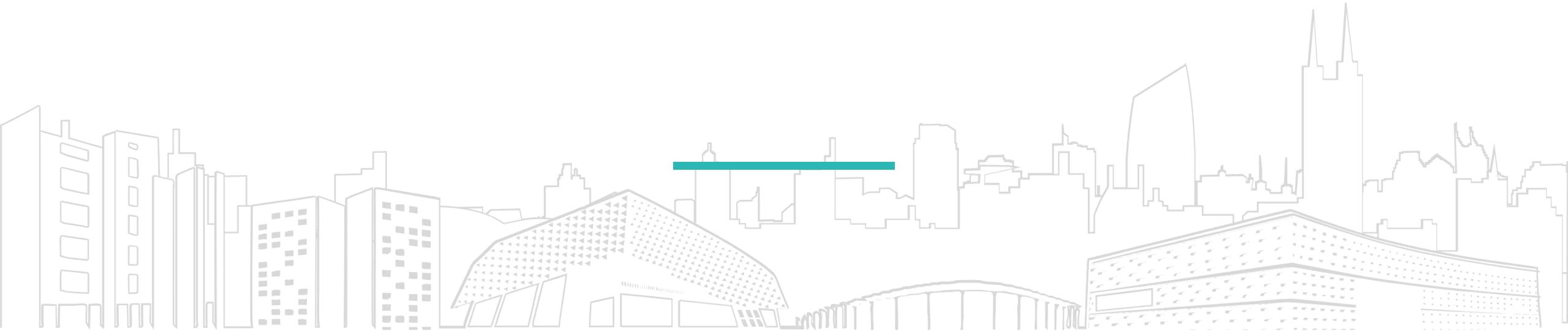
We use ONNXRuntime to do dynamic and static quantization on the model. However, the jetson-inference does not support quantization operator and we cannot validate our quantized model

Quantization method	Function
dynamic quantization	Quantize the learnable weights of the model
static quantization	Quantize model from a small amount of calibration data
QAT	Minimize model quantization error through finetune training



03

## Application & Pokémon Fusion

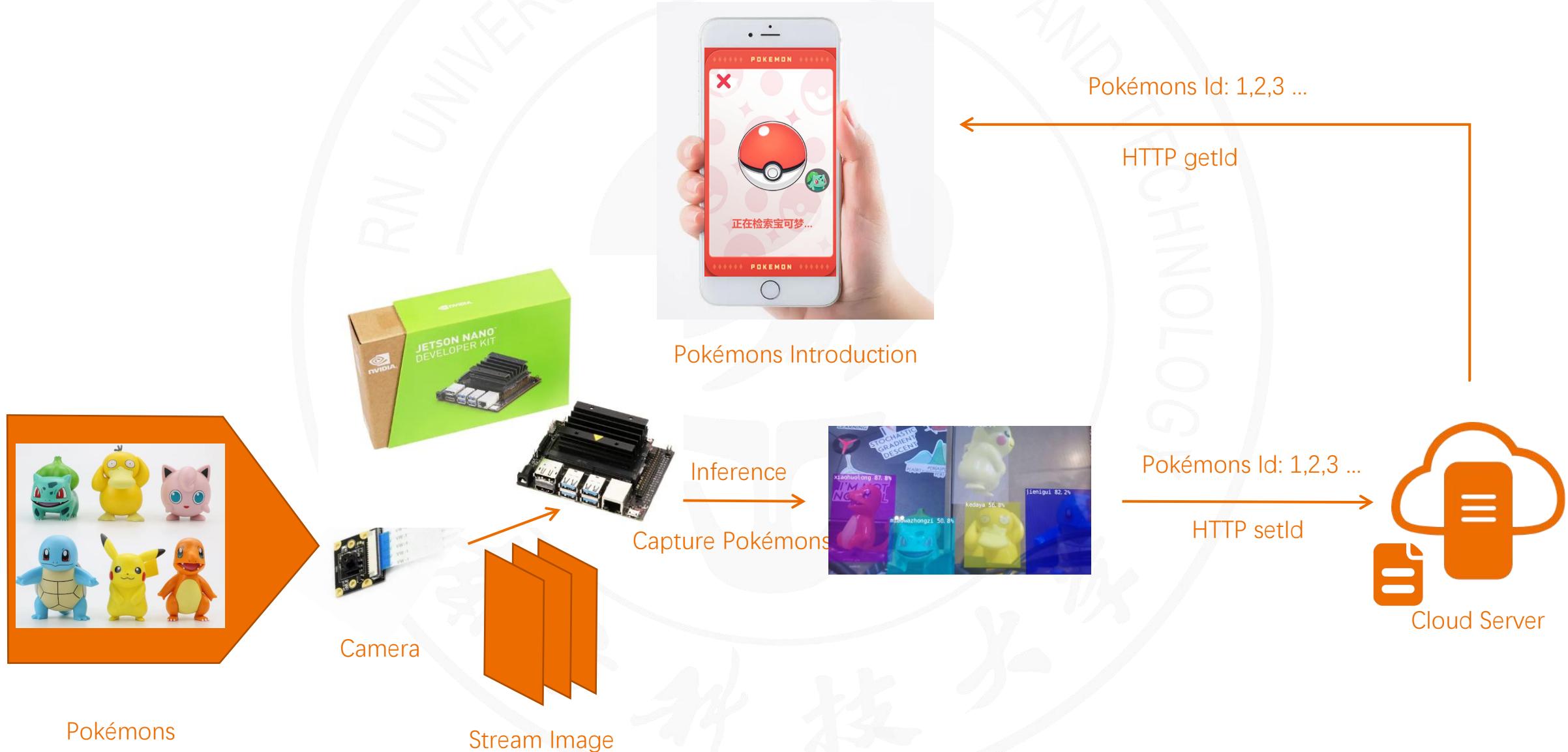


# Pokémon-Library

We build an application which can introduce the Pokémons captured by the camera



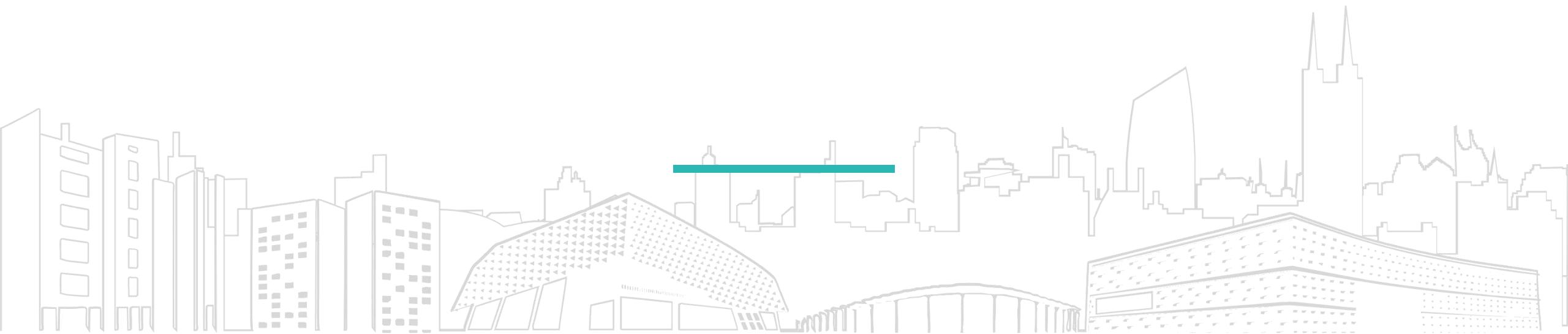
# Application Architecture





04

## Conclusion



# Conclusion

- Configure and deploy the Jetson Nano environment, including pip, python, c++, jetson-inference project etc.
- Run the base image classification and object detection project, use Jetson nano camera to capture in real time.
- Sample own data set and label the data by ourselves.
- Train our own Pokémon detection model, use different network model and compare the result.
- Build a Pokémon application take advantage of our model based on the real requirement (Support Windows and Android platform).

# Conclusion

Name	Contribution	Ratio
唐云龙	Model Selection, Training, Adjust parameters, Dataset Construction	20%
聂雨荷	Environment Deployment, Application Development, PPT writing	20%
云泽彬	Dataset Construction, Report writing	20%
张通	Data Augumentation, Quantization, Dataset construction	20%
郑执	Model Experiment, Report writing	20%

# THANK YOU!

## References

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- Howard, A. G., M. Zhu, B. Chen, D. Kalenichenko, W. Wang, T. Weyand, M. Andreetto, and H. Adam (2017). Mobilenets: Efficient convolutional neural networks for mobile vision applications. arXiv preprint arXiv:1704.04861.
- Sandler, M., A. Howard, M. Zhu, A. Zhmoginov, and L.-C. Chen (2018). Mobilenetv2: Inverted residuals and linear bottlenecks. In Proceedings of the IEEE conference on computer vision and pattern recognition, pp. 4510–45