

```

int trigPin = 11;  // Trigger
int echoPin = 12;  // Echo
int ledPin = 13;   // LED
long duration, cm, inches;

void setup() {
  //Serial Port begin
  Serial.begin (9600);
  //Define inputs and outputs
  pinMode(trigPin, OUTPUT);
  pinMode(echoPin, INPUT);
  pinMode(ledPin, OUTPUT);
}

void loop() {
  // The sensor is triggered by a HIGH pulse of 10 or more microseconds.
  // Give a short LOW pulse beforehand to ensure a clean HIGH pulse:
  digitalWrite(trigPin, LOW);
  delayMicroseconds(5);
  digitalWrite(trigPin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigPin, LOW);

  // Read the signal from the sensor: a HIGH pulse whose
  // duration is the time (in microseconds) from the sending
  // of the ping to the reception of its echo off of an object.
  duration = pulseIn(echoPin, HIGH);

  // Convert the time into a distance
  cm = (duration/2) / 29.1;  // Divide by 29.1 or multiply by 0.0343
  inches = (duration/2) / 74;  // Divide by 74 or multiply by 0.0135

  Serial.print(inches);
  Serial.print("in, ");
  Serial.print(cm);
  Serial.print("cm");
  Serial.println();

  if (cm <= 10) {
    digitalWrite(ledPin, HIGH);
  } else {
    digitalWrite(ledPin, LOW);
  }
}

```

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    delay(250);  
}
```