

Nafis Abeer EC 330 HW 7

- 1) In order for a graph to be bipartite, the graph  $G(V, E)$  has its vertex ( $V$ ) set divided into  $V = L \cup R$  where  $L$  and  $R$  are disjoint and all Edges ( $E$ ) go between  $L$  and  $R$ . Any element of  $L$  does not have an edge connecting to another element in  $L$ . Pseudo code to check for a bipartite:

- will be using a similar idea

- as breadth first search

- will color every vertex white to indicate that they have not been visited.

-  $G.adj[u]$   $u \in V$ , is

used to indicate all adjacent vertices of vertex  $u$ .

- color Red refers to partition 1

- color Blue refers to partition 2

- Run through every vertex

and if it contains neighbors

that has already been assigned

the same color as itself,

return false.

- If end of function is

reached, return true because

no adjacent vertices of

any given vertex was

the same color as itself.

- using an adjacency list

will give a runtime

of  $O(V+E)$ .

```
bool Bipartite(G, s) { // s is starting node
```

```
    for each vertex  $u \in G.V$ 
```

```
         $u.color = white;$ 
```

```
         $s.color = RED;$  // source is red as in partition 1.
```

```
         $Q = \emptyset;$  Enqueue  $(Q, s);$ 
```

```
        while ( $Q \neq \emptyset$ ) {
```

```
             $u = Dequeue(Q);$  // this empties queue over time
```

```
            if ( $\exists v \in G.adj[u] \text{ s.t. } v = u$ ) // if there is a self loop.
```

```
                return false;
```

```
            for each  $v \in G.adj[u]$  { // loop through every neighbor
```

```
                if ( $v.color == white \&\& u.color == RED$ ) {
```

```
                     $v.color = blue;$  // assign the opposite
```

```
                    Enqueue  $(Q, v);$  } // color
```

```
                else if ( $v.color == white \&\& u.color == Blue$ ) {
```

```
                     $v.color = RED;$  // assign the opp. color
```

```
                    Enqueue  $(Q, v);$  } // store in queue
```

```
                else if ( $v.color == u.color$ ) // same partition
```

```
                    return false;
```

```
            }
```

```
        }
```

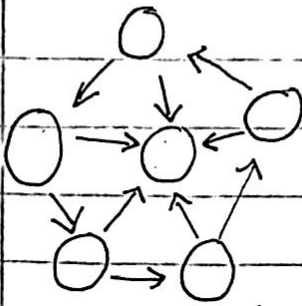
```
        return true;
```

```
    }
```

// in the case v is already the opposite color, the

// for loop just continues

2)



A Eulerian Cycle is impossible as there are

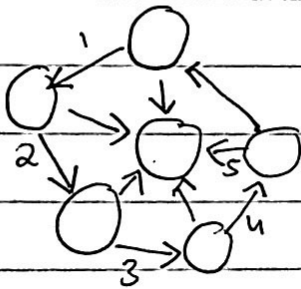
many edges (one for every vertex) that leads to the celebrity, but in order to visit every edge one would have to reach each one of those edges. This is clearly

impossible since you can't leave the celebrity vertex once

you reach it. In a cycle you must be able to come back to the

starting node once you leave it down one edge so it's a closed loop

traced without "lifting off your pencil," you'd have to "lift your pencil" every time you reach celebrity.



A Hamiltonian Path would be possible

by following the numbered edges, but a cycle

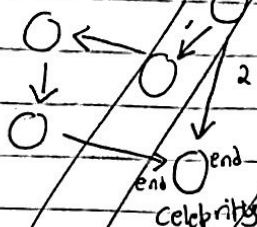
is a "closed loop" that comes back to the starting

node which is clearly impossible because no edge

leads out of a celebrity. A Hamiltonian Cycle for this reason

is impossible.

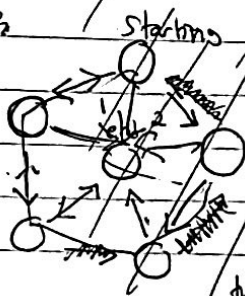
2)



visiting every edge will require 1 to trace back on every edge in a given path

Eulerian cycle (impossible w/ celebrity)

In order to have a Eulerian cycle, the starting node must also be the end node. In the case where a celebrity is present, the celebrity node is always the end node since no edge leads out from it. For this reason it will be impossible to visit every edge because say we go down path 1 from starting node in the case above. We stop at the celebrity and we never get to visit path 2. The same is true for the path 2, as we never visit any edge in path 1.



Hamiltonian cycle (impossible w/ celebrity)

Same as the Eulerian case, in order to visit every node without "lifting the pen off the paper" would require one to reach the celebrity (end) node from the starting node then go back and visit certain nodes again to reach the rest of the unvisited nodes.

3) weight  $w(p)$  of path  $(p) = \text{sum of weights of its constituents}$

$$w(p) = \sum_{i=1}^k w(v_{i-1}, v_i)$$

Shortest path weight  $\delta(u, v)$  from  $u$  to  $v$  is

$$\delta(u, v) = \begin{cases} \min \{w(p) : u \rightsquigarrow v\} & \text{if there is a path from } u \text{ to } v \\ \infty & \text{otherwise} \end{cases}$$

Dijkstra  $(G, w, s)$

Initialize single-source  $(G, s)$

$S = \emptyset$

$Q = G.V$

While  $Q \neq \emptyset \wedge O(V)$

$u = \text{extract-min}(Q) \rightarrow O(V)$  // once per vertex // for linked list

$S = S \cup \{u\}$

for each vertex  $v \in G.V \setminus S$  //  $E$  times

Relax  $(u, v, w)$   $O(1)$

$O(V)$  inside  $O(V)$  gives  $O(V^2) + O(EV)$  would determine lower bound  
So  $O(V^2)$  over all