

Nafis Abeer EC 330 HW 7

- 1) In order for a graph to be bipartite, the graph $G(V, E)$ has its vertex (V) set divided into $V = L \cup R$ where L and R are disjoint and all Edges (E) go between L and R . Any element of L does not have an edge connecting to another element in L . Pseudo code to check for a bipartite:

- will be using a similar idea

- as breadth first search

- will color every vertex white to indicate that they have not been visited.

- $G.adj[u]$ $u \in V$, is

used to indicate all adjacent vertices of vertex u .

- color Red refers to partition 1

- color Blue refers to partition 2

- Run through every vertex and if it contains neighbors that has already been assigned the same color as itself, return false.

- If end of function is reached, return true because no adjacent vertices of any given vertex was the same color as itself.

- Using an adjacency list will give a runtime of $O(V+E)$.

```
bool Bipartite(G, s) { // s is starting node
```

```
    for (each vertex  $u \in G.V$ )
```

```
         $u.color = white;$ 
```

```
     $s.color = RED;$  // source is red as in partition 1,
```

```
     $Q = \emptyset;$  Enqueue( $Q, s$ );
```

```
    while ( $Q \neq \emptyset$ ) {
```

```
         $u = Dequeue(Q);$  // this empties queue everytime
```

```
        if ( $\exists v \in G.adj[u] \text{ s.t. } v == u$ ) // if there is a self loop.
```

```
            return false;
```

```
        for (each  $v \in G.adj[u]$ ) { // loop through every neighbor
```

```
            if ( $v.color == white \ \&\& \ u.color == RED$ ) {
```

```
                 $v.color = blue;$  // assign the opposite
```

```
                Enqueue( $Q, v$ ); } // color
```

```
            else if ( $v.color == white \ \&\& \ u.color == Blue$ ) {
```

```
                 $v.color = RED;$  // assign the opp. color
```

```
                Enqueue( $Q, v$ ); } // store in queue
```

```
            else if ( $v.color == u.color$ ) // same partition
```

```
                return false;
```

```
        }
```

```
    }
```

```
    return true;
```

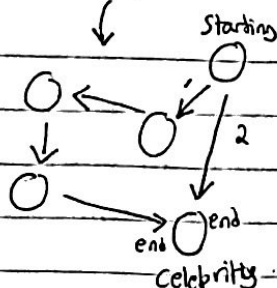
```
}
```

// in the case v is already the opposite color, the

// for loop just continues

visiting every edge will require 1 to trace back on every edge in a given path

2)

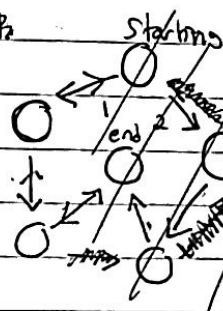


Eulerian cycle (impossible w/ celebrity)

In order to have a Eulerian cycle, the starting node must also be the end node. In the case where a celebrity is present, the celebrity node is always the end node since no edge leads out from it. For this reason it will be impossible to visit

every edge because say we go down path 1 from starting node in the case above. We stop at the celebrity and we never get to visit path 2. The same is true for the path 2, as we never visit any edge in path 1.

3)



Hamiltonian cycle (impossible w/ celebrity)

Some as the Eulerian case, in order to visit every node without "lifting the pen off the paper" would require one to reach the celebrity (end) node from the starting node then go back and visit certain nodes again to reach the rest of the unvisited nodes.

3) weight $w(p)$ of $\text{Path}(p)$ = sum of weights of its constituents

$$w(p) = \sum_{i=1}^k w(v_{i-1}, v_i)$$

Shortest path weight $\delta(u, v)$ from u to v is

$$\delta(u, v) = \begin{cases} \min \{w(p) : u \rightarrow v\} & \text{if there is a path from } u \text{ to } v \\ \infty & \text{otherwise} \end{cases}$$

Dijkstra (G, w, s)

Initialize single-source (G, s)

$$S = \emptyset$$

$$Q = G.V$$

$O(V)$ inside $O(V)$ gives $O(V^2)$

While $Q \neq \emptyset$ // $O(V)$

$u = \text{extract-min}(Q) \rightarrow O(V)$ // once per vertex // for (inlined list

+E for for loop but overall

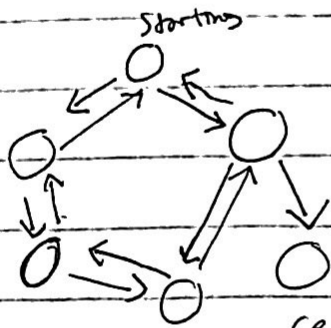
$O(V^2)$

$$S = S \cup \{u\}$$

for each vertex $v \in G \text{ adj}[u]$ // E times

Relax (u, v, w) $O(1)$

2b)



In the hamiltonian case, it is possible to visit every node just once. The process would be to start at a node that will allow one to visit every other node before finally visiting the celebrity node