

# Fine Grained Classification

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**Abstract**—In this project I have defined a multi-class classification model using the Deep Learning model with the imbalanced image instances of the classes varying from 1-80, using PyTorch

**Index Terms**—Deep Learning, Classification, Imbalanced Dataset, Confusion-Matrix, Overfitting, Fine Tuning, Dropout, Data Augmentation

## I. INTRODUCTION

Classification problems having multiple classes with an imbalanced dataset present a different challenge than a binary classification problem. The skewed distribution makes many conventional machine learning algorithms less effective, especially in predicting minority class examples.

### A. Multiclass Classification:

Image classification using deep learning algorithm is considered the state-of-the-art in computer vision researches.[1] In the deep learning algorithm, the object feature extracted engineering is done by the algorithm automatically.

### B. Imbalanced Dataset:

Imbalanced data typically refers to a problem with classification problems where the classes are not represented equally. For example, you may have a 3-class classification problem of a set of fruits to classify as oranges, apples, or pears with a total of 100 instances. A total of 80 instances are labeled with Class-1 (Oranges), 10 instances with Class-2 (Apples), and the remaining 10 instances are labeled with Class-3 (Pears). This is an imbalanced dataset and the ratio of 8:1:1. Most classification data sets do not have an exactly equal number of instances in each class, but a small difference often does not matter. There are problems where a class imbalance is not just common, it is expected. For example, datasets like those that characterize fraudulent transactions are imbalanced. The vast majority of the transactions will be in the “Not-Fraud” class, and a tiny minority will be in the “Fraud” class.

## II. EXPERIMENTATION

### A. Dataset:

For the task of training and validation for classification, in the dataset, we have 258 classes having a total of 12,607 images, which is divided into the train(10,000) and test(2,607) using the random distribution `randomsplit()`.

### B. Preprocessing:

Building an effective neural network model requires careful consideration of the network architecture as well as the input data format.

1) *Uniform Aspect Ratio*:: One of the first steps is to ensure that the images have the same size and aspect ratio.

2) *Image Scaling*:: In order to feed a dataset of images to a convolutional network, they must all be the same size. Once we’ve ensured that all images are square (or have some predetermined aspect ratio), it’s time to scale each image appropriately. I’ve decided to have images with a width and height of 128 pixels.

3) *Data augmentation*:: To expose the neural network to a wide variety of variations. the existing data-set with perturbed versions of the existing images. Scaling, rotations, and other affine transformations are typical. This makes it less likely that the neural network recognizes unwanted characteristics in the data-set.

4) *Mean, Standard Deviation of input data*:: We might want to normalize the dataset such that the mean value of each data sample would be equal to the mean given below. It’s useful to look at the ‘mean image’ obtained by taking the mean values for each pixel across all training examples. Observing this could give us insight into some underlying structure in the images. For this to ensure I have calculated the mean and std of the dataset.

a) *DataSet’s Mean*: `tensor([0.4829, 0.4329, 0.3960])`

b) *Std*:: `tensor([0.2112, 0.1898, 0.1821])`

5) *Normalizing image inputs*:: This makes convergence faster while training the network. Data normalization is done by subtracting the mean from each pixel and then dividing the result by the standard deviation. The distribution of such data would resemble a Gaussian curve centered at zero.

### C. Cross Entropy Loss:

Cross entropy loss function (CEL) is a popular loss function for training DCNNs in the image classification task. This is because it measures the difference between target class distribution and predicted class distribution and can be reduced by stochastic gradient descent (SGD) methods. In multi-class classification tasks, the binary cross-entropy loss function can be extended to categorical cross entropy (CCE) loss for one-hot encoding.[2]

### D. Optimizer

The Adam optimizer is super easy to use and tends to settle at a good learning rate all on its own. SGD on the other hand usually gets you a nice 1–2 percent boost over Adam but is much harder to tune. Stochastic Gradient Descent(used): To overcome the shortcomings of BGD, stochastic gradient

descent (SGD) was introduced. SGD allows updating the network weights per each training image. SGD with momentum renders some speed to the optimization and also helps escape local minima better.

AdaGrad: The learning rate is tuned automatically, by dividing the learning rate by the sum of squares of all previous gradients. To scale the learning rate for each weight.

Adam Optimizer: To combine the benefits of Nesterov momentum, AdaGrad, and RMSProp algorithms.

#### E. Deep Learning Model:

Deep Models Matter.

For the baseline, I directly run the constructed 5-layer CNNs classifier as an optimizer without any dropout or data augmentation to be compared with the following models as a shallow model. The baseline perform not well that has only about 70 percent test accuracy and there exists string overfitting since training accuracy is much better than validation accuracy and validation loss value is greater than training loss value.

InceptionResNet[3]: Inspired by the performance of ResNet, Google presents InceptionResNet. Residual is added to the output of the convolution operation of the inception module. After convolution, the depth is increased and this model achieves top-5 error on the ImageNet classification. InceptionResNet takes the idea of an inception network and a deep residual network. It accelerates the speed of training and improves the accuracy with about 467 layers in total. It shows the power of deep layers as well.

#### F. Performance Evaluation:

Classification is one of the two sections of supervised learning, and it deals with data from different categories. The training dataset trains the model to predict the unknown labels of population data. [4]

Measuring the area under the ROC curve is also a very useful method for evaluating a model.

Measurements on Confusion Matrix.

#### G. Confusion-Matrix(Conflicting Classes):

With imbalanced classes, it's easy to get a high accuracy without actually making useful predictions. So, accuracy as an evaluation metrics makes sense only if the class labels are uniformly distributed. In the case of imbalanced classes, confusion-matrix is a good technique for summarizing the performance of a classification algorithm.

When we closely look at the confusion matrix, we see that the classes which have very few samples are indeed having very few scores as compared to the classes with a higher number of samples. Thus looking at the confusion matrix one can clearly see how the model is performing on classifying various classes. We have a large no of classes(258) which makes it difficult to find the conflicting classes.

Confusion matrix is at the end of 'finegrained-logQ298700txt' in the folder of output files.

### III. RESULTS

I have trained the Resnet50[5] Deep Learning model.

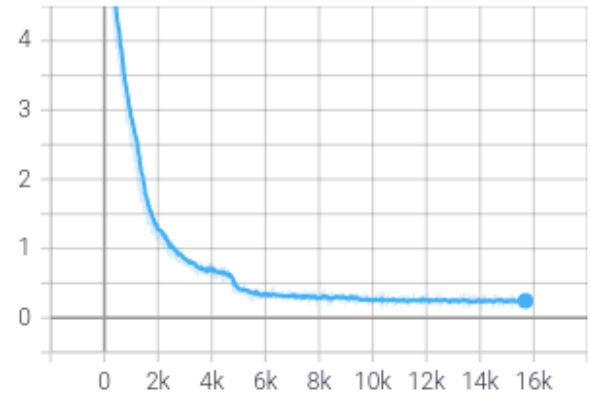
The classwise accuracy of the classes and the accuracy for the classes with images less than 20 is in the result(output) file "finegrainedlogQ298550txt".

In the table below there is the accuracy of the test and train with top1, top5, avg( for the 10000 and 2607 images)

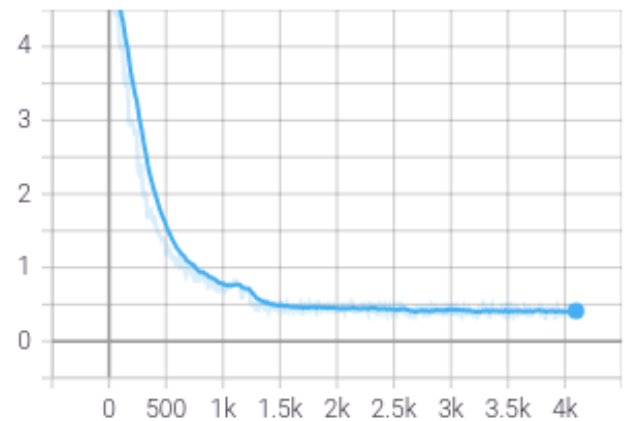
The loss for the Train and Test is shownn in fig(a), fig(b) below respectively.

acc	top1	top5	avg.
train	95	99	95
test	91	95	92

training loss



(a) train loss



(b) test loss

### IV. CONCLUSION

The objective of this project is to show how deep models like VGG16, VGG19, Inception V3, InceptionResNet V2 can be used on very small size data with a total of 12,607 images including 10,000 training data, 2,607 validation data, without severe overfitting and with great performance. All of the models are without pre-trained on Resnet50. According to the experiments, all of the models perform well. Specifically, I

apply data augmentation, dropout, and fine-tune these models. It turns out it barely has any overfitting.

As proved from experiments, very deep models can be used to fit a tiny dataset as long as the good model is chosen and proper modifications are applied. The key to adopting the deep models on the very small dataset is data augmentation with dropout and fine-tuning.

Choosing proper deep models to fit in very small datasets is crucial to determine the performance. However, overfitting is reduced a lot during the process of the experiment, underfitting occurs for some models. The reason why this happens maybe that too many weights are dropped. Overall, the experiments prove that deep models can be used to fit in very small datasets with proper modifications without severe overfitting.

## V. FUTURE WORK

Experiments on different models with proper modifications can be carried on in the future. For example, the issue like why fine-tuning these models leads to the increase of validation loss and how underfitting/Overfitting happens in the models.

Modifying more models to better fit in very small datasets and comparing them is meaningful to work on in the future.

Data augmentation, dropout, and fine-tune the these models for the dataset to minimized the overfitting and improve the accuracy for class with very few image instances.

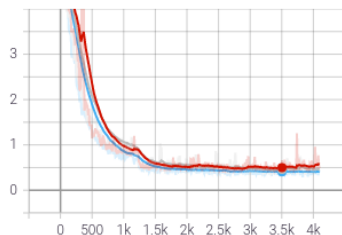
We can use the Transfer learning/ pre-trained model which will decrease the training time of the models.

## REFERENCES

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	Name	Smoothed	Value	Step	Time	Relative
<input checked="" type="radio"/>	lmz_size_256_e_100	0.4991	0.6592	3.504k	Wed Jan 13, 03:32:55	1h 15m 21s
<input type="radio"/>	Inception_v3	0.4585	0.5148	3.504k	Thu Jan 14, 00:48:13	27m 26s
<input type="radio"/>	new_resnet50	0.4056	0.3322	3.504k	Wed Jan 13, 05:15:54	26m 2s

validation loss



(c) test loss

top1



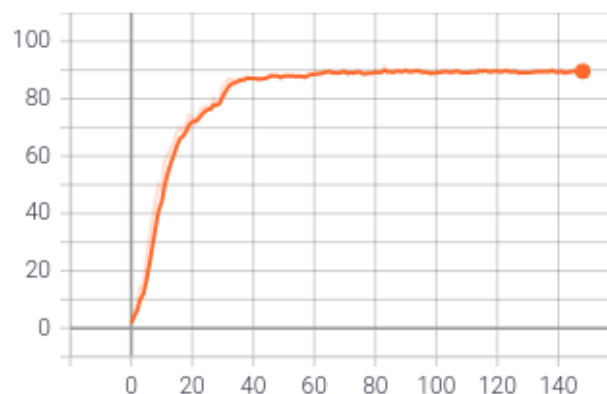
(d) test acc top1

top5



(e) test acc top5

top1\_acc



(f) train acc top1