



Reliable weight measurement with the use of F/T sensor for objects carried in motion by 6DOF robotic manipulator

Master of Science Thesis

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1 Introduction

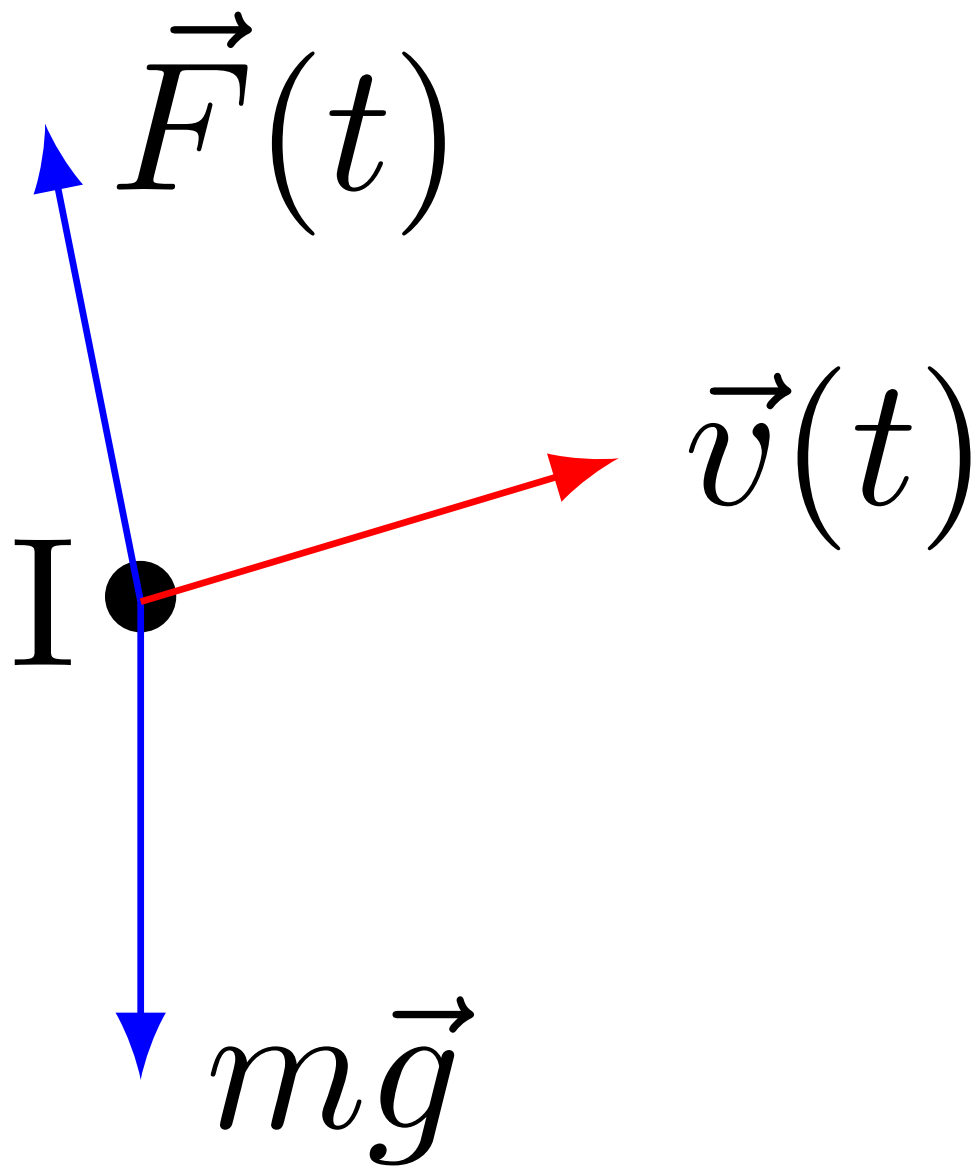


Figure 1: My TikZ picture

Bla

[1]

References

[1] NoMagic. *Graphs of the sensor*, 2019.