

src/position_service.cpp

```
graph TD; A[src/position_service.cpp] --> B[ros/ros.h]; A --> C[rt2_assignment2/RandomPosition.h];
```

The diagram illustrates the dependencies of the file `src/position_service.cpp`. It is represented as a box at the top with two arrows pointing downwards to two other boxes. The left box is `ros/ros.h` and the right box is `rt2_assignment2/RandomPosition.h`.

ros/ros.h

rt2_assignment2/RandomPosition.h