

Numerical Simulations of Ideal Chain Model of Polymer using the Freely Jointed Chain (FJC)

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1 Introduction

- General introduction about physics of polymer. Discrete models. Examples
- Theory of FJC model.
- Presentation of measure of extent (metrics). Relationship with experimental measurement.
- Goal of the practical work

Polymer physics deals with complex substances through a simple approach. Understanding the properties of polymers from a molecular point of view is key to unveil their complexity.

Given an ensemble of polymers, we can use tools from statistics to derive some properties that apply to the ensemble at any given instant. To do so we model each polymer as a (continuous or discrete) ideal chain of monomers along with some constraints. Some examples of these models include the Freely Jointed Chain, the Freely Rotating Chain, the wormlike chain, the hindered rotating chain, the rotational isometric state model, among others⁷.

The first, most straightforward (yet illustrating) approach is the Freely Jointed Chain model. The FJC is a chain consisting of N links, each of length b and able to point in any direction independently of each other (thus the simplicity).

To characterize the spatial extent of the polymers, two standard measures of extent are introduced: the end-to-end vector \mathbf{Q} and the radius of gyration R_g . The end-to-end vector is defined as $\mathbf{Q} = \mathbf{r}_N - \mathbf{r}_0$, and provides a direct measure of the global elongation of a polymer chain. The statistical quantity derived from it, $\langle Q^2 \rangle$, is directly related to experimental observables obtained from single-molecule techniques, including force-extension measurements using optical tweezers, as well as from scattering experiments through their connection to the structure factor.

The radius of gyration R_g quantifies the spatial distribution of monomers around the center of mass of the chain and is defined as the mean squared distance of the monomers from this center. It provides a global measure of the polymer size and compactness that is less sensitive to instantaneous end-to-end fluctuations than \mathbf{Q} . Experimentally, R_g is commonly accessed via small-angle neutron or X-ray scattering (SANS/SAXS), where it determines the low- k behavior of the scattering intensity. Taken together, \mathbf{Q} and R_g offer complementary descriptions of polymer extent, allowing for a consistent comparison between numerical simulations and experimental measurements.

The goal of this practical work is to analyze the conformational statistics of a freely jointed polymer chain using numerical simulations and to connect microscopic configurations with measurable macroscopic observables.

2 Methods

- Numerical simulations: Parameters + Brief description of the algorithm
- Examples of structures generated
- Time series + mean square and distributions statistical tools (theory) + Monte-Carlo
- Summary of data produced (ex: Table)

2.1 Analysis of FJC polymer configurations

The first script analyzes the simulation data of a 3D FJC polymer for different chain lengths N . The parameters are the bond length b , the N values we wish to test for, and the number of configurations T we wish to analyze. An XYZ file containing T polymer configurations is read, and for every configuration the end-to-end distance Q and the radius of gyration R_g is computed. Finally both quantities are squared and averaged over all configurations yielding $\langle Q^2 \rangle$ and $\langle R_g^2 \rangle$. This algorithm is looped over for every N .

Algorithm 1 Analysis of FJC Polymer Configurations: $\langle Q^2 \rangle$ and $\langle R_g^2 \rangle$

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1: Set bond length  $b$  and list of chain lengths  $\{N\}$ 
2: Set number of configurations  $T$ 
3: Initialize arrays  $\langle Q^2 \rangle_{\text{sim}}$  and  $\langle R_g^2 \rangle_{\text{sim}}$ 
4: for each chain length  $N$  do
5:   Initialize position arrays  $\{X, Y, Z\}$  of size  $T \times (N + 1)$ 
6:   Open trajectory file
7:   for  $t = 1$  to  $T$  do
8:     for  $i = 1$  to  $N + 1$  do
9:       Read monomer coordinates  $(x_i, y_i, z_i)$ 
10:      Store coordinates in  $X(t, i), Y(t, i), Z(t, i)$ 
11:    end for
12:   end for
13:   Initialize arrays  $Q(t)$  and  $R_g(t)$ 
14:   for  $t = 1$  to  $T$  do
15:     Compute end-to-end distance
16:     Compute center of mass
17:     Compute radius of gyration
18:   end for
19:   Compute ensemble averages
20: end for

```

2.2 Statistical analysis of Q

The second script is built over the first one. The only extra parameter needed are the number of bins for the histogram. After computing the end-to-end distance Q , the algorithm builds a histogram out of these values, treating them as samples from a probability distribution. The histogram is then normalized so that it can be directly compared to the gaussian distribution.

Algorithm 2 Statistical analysis of Q

- 1: Replicate Algorithm No.1
- 2: Set the number of bins
- 3: Construct normalized histogram of Q values to estimate $P(Q)$
- 4: Evaluate theoretical distribution:

$$P(Q) = 4\pi Q^2 \left(\frac{3}{2\pi Nb^2} \right)^{3/2} \exp\left(-\frac{3Q^2}{2Nb^2}\right)$$

- 5: Compare simulated and theoretical distributions
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2.3 Structure Factor

The third simulation focuses on computing the structure factor for a polymer of $N = 100$ and $b = 3$. An array k is introduced, spanning values from 0 to 1 (in our case, sampling every 0.01 steps). One of the files containing the simulated polymers is held in memory. Then, we use the formula

$$I(k) = \sum_{i=0}^N \sum_{j=0}^N \left\langle \frac{\sin(k|\mathbf{R}_i - \mathbf{R}_j|)}{k|\mathbf{R}_i - \mathbf{R}_j|} \right\rangle \quad (1)$$

where $\mathbf{R}_i, \mathbf{R}_j$ are coordinates of the monomers in 3D space obtained from the simulated polymer.

Then, the Guinier approximation is computed on the same k array to compare them side by side.

Algorithm 3 Structure Factor and Guinier approximation

- 1: Set bond length b , chain length N , and number of configurations T
 - 2: Define a range of scattering wave vectors k
 - 3: **for** each value of k **do**
 - 4: **for** each pair of monomers (i, j) **do**
 - 5: Compute distance between monomers i and j
 - 6: **if** distance is zero **then**
 - 7: Assign unit contribution
 - 8: **else**
 - 9: Assign sinc-like contribution depending on distance and k
 - 10: **end if**
 - 11: **end for**
 - 12: **end for**
 - 13: Sum contributions over all monomer pairs to obtain the structure factor
 - 14: Compute the radius of gyration from model parameters
 - 15: Evaluate the Guinier approximation using the computed R_g
 - 16: Compare numerical structure factor with the Guinier approximation in the low- k regime
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2.4 Polymer Extension

A considerable amount of attention has been driven toward the physical manipulation of polymers that are not large to be in thermodynamic equilibrium, the extension of a polymer by the stretching of a cantilever is a recurrent example⁷ in this regard, an expression for the force - extension relationship has been found by⁷.

$$|\vec{Q} \cdot \vec{u}_x| = Nb \left[\coth \alpha - \frac{1}{\alpha} \right]; \alpha = \frac{Fb}{K_B T} \quad (2)$$

In order to test this analytical formula with experimental data, a simulation was performed, where one polymer of 100 monomers was exposed to a range of constant forces from 0 to 10 pN. The polymer is modeled as a chain of fixed-length bonds, and its configuration is updated by randomly perturbing individual bond orientations.

Each trial move changes the end-to-end vector and the associated potential energy due to the applied force. The acceptance of these moves follows a Boltzmann-like (Metropolis) criterion, which ensures that configurations are sampled according to thermal equilibrium at temperature T . This energy-based acceptance allows the algorithm to capture thermal fluctuations and generate physically meaningful polymer conformations under force. For the details of the algorithm look to Algorithm 1.

Algorithm 4 Monte Carlo Polymer Extension Under Force

- 1: Initialize N bond vectors uniformly on the unit sphere, scaled by bond length b
 - 2: Compute monomer positions and end-to-end vector \mathbf{Q}
 - 3: Set external force $\mathbf{F} = (F_x, 0, 0)$ and energy $U = -\mathbf{F} \cdot \mathbf{Q}$
 - 4: **for** step = 1 to n_{steps} **do**
 - 5: Randomly select bond index i
 - 6: Propose new bond direction \hat{u} and bond $\mathbf{b}'_i = b\hat{u}$
 - 7: Compute proposed \mathbf{Q}' and U'
 - 8: $\Delta U \leftarrow U' - U$
 - 9: **if** $\Delta U < 0$ **or** rand $< e^{-\Delta U/k_B T}$ **then**
 - 10: Accept move: update bonds, $\mathbf{Q} \leftarrow \mathbf{Q}'$, $U \leftarrow U'$
 - 11: Recompute monomer positions
 - 12: **end if**
 - 13: Store \mathbf{Q} and U
 - 14: **if** step mod $n_{\text{skip}} = 0$ **then**
 - 15: Save polymer configuration to file
 - 16: **end if**
 - 17: **end for**
 - 18: Combine saved frames into a trajectory file
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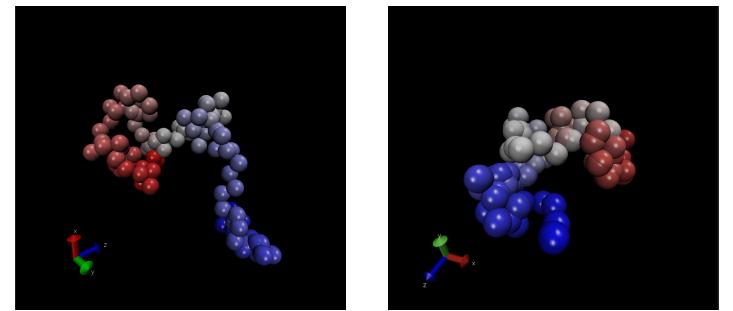


Fig. 1 Two polymer structures generated from FJC model simulations for $N = 100$ and $b = 3.0$.

3 Results and Discussion

- Description of the numerical results (Parts 1 to 4)
- Comparison with theoretical results (qualitatively and quantitatively)
- Discussion

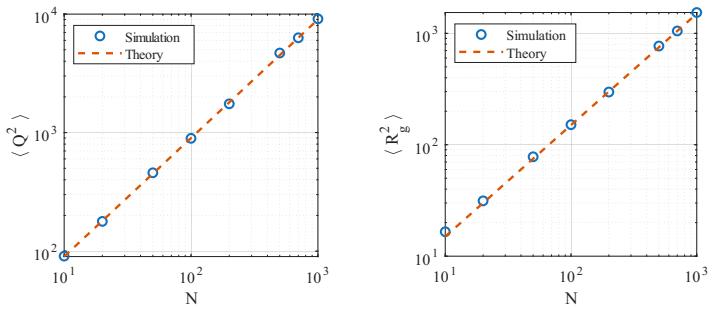


Fig. 2 $\langle Q^2 \rangle$ (left) and $\langle R_g^2 \rangle$ (right)

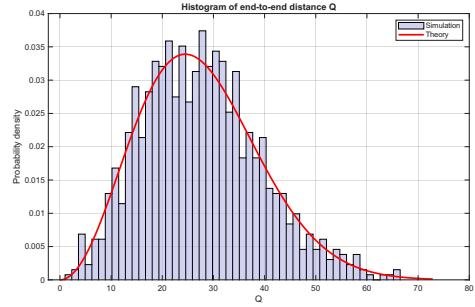


Fig. 3 Probability distribution

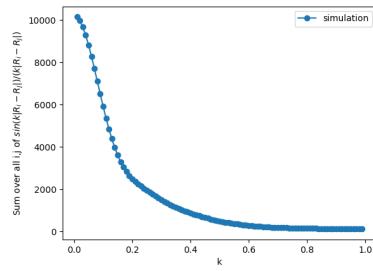


Fig. 4 Structure factor (simulated)

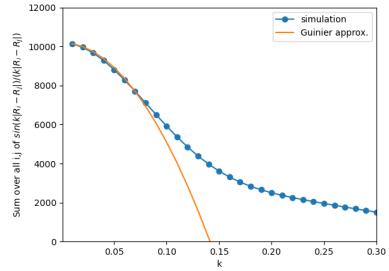


Fig. 5 Structure factor comparison (simulation and Guinier approximation)

4 Conclusion

- General conclusion about FJC model
- Summary of the main results

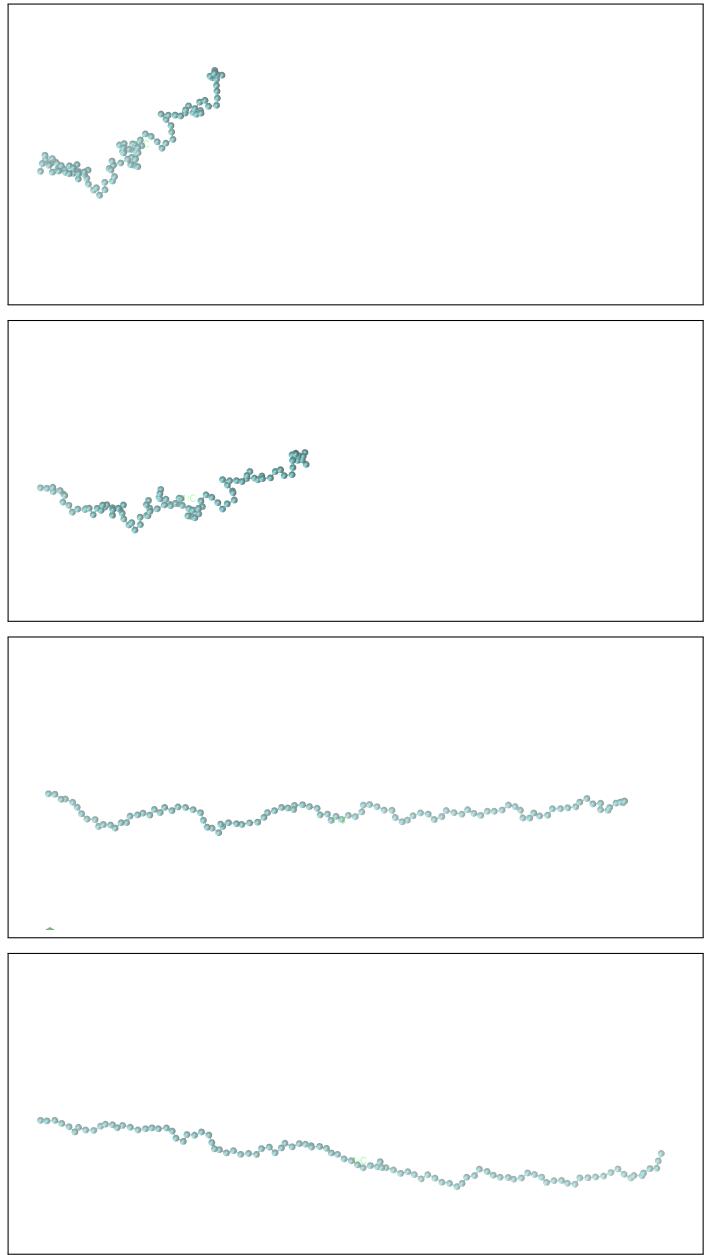


Fig. 6 Extension of the polymer using Monte-Carlo simulation

- Perspectives

5 References

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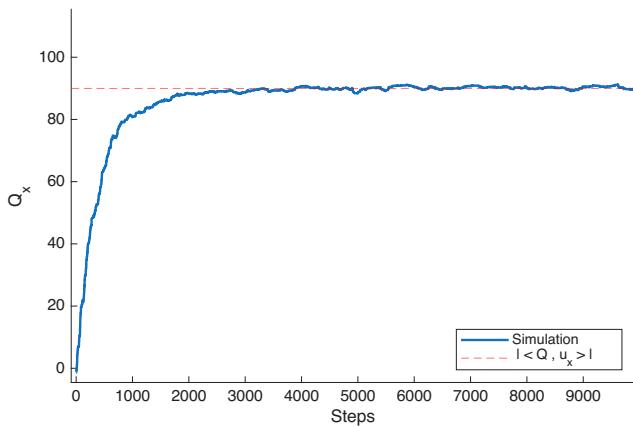


Fig. 7 Extension evolution of the polymer, saturating to the theoretical value

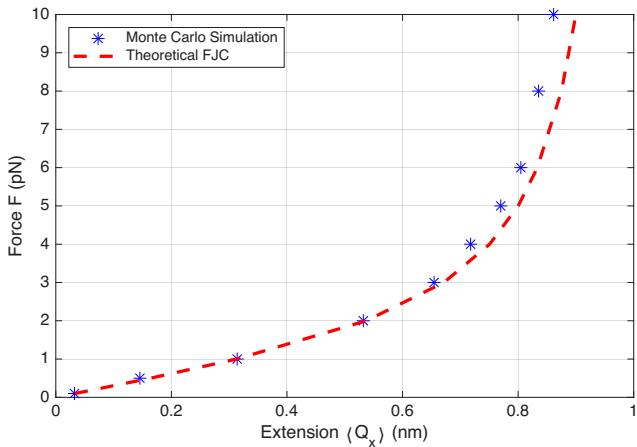


Fig. 8 Extension - Force curve