Summary

The homework is to identify handwriting figures with Single-layer Linear Perceptron, Single-layer Perceptron, Multi-layer Perceptron, and Convolutional Neural Network:

mini batch x, mini batch y = get mini batch(im train, label train, batch size)

Training images are separated into small batches. The whole data samples are divided into (length / batch size) parts, and images are taken from these parts (one part one image) to form a mini batch.

2. y = fc(x, w, b)

Simply,
$$y = X * W + b$$
.

3. dl dx, dl dw, dl db = fc backward(dl dy, x, w, b, y)

With the back-propagation formula, dl dx = dl dy * w, dl dw = dl dy * x, dl db = dl dy.

4. l, dl dy = loss euclidean(y tilde, y)

The l is the Euclidean distance of y tilde to y, dl dy is the derivative of l.

5. w, b = train slp linear(mini batch x, mini batch y)

In this Single-layer Linear Perceptron, the learning rate is 0.016 while the decay rate is 0.5 and the iteration time for the training is 5000. The accuracy obtained is 58.2% (FIG.1).



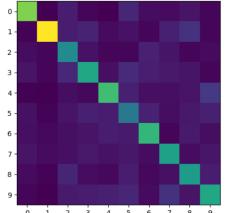


FIG.1 Single-layer Linear Perceptron

Single-layer Perceptron Confusion Matrix, accuracy = 0.882

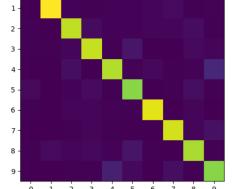


FIG.2 Single-layer Perceptron

6. l, dl dy = loss cross entropy softmax(x, y)

Loss cross entropy with softmax is defined as the -1 * the sum of [y * ln(y prediction)], and dl dy in this cross entropy is y prediction – y.

7. w, b = train slp(mini batch x, mini batch y)

In this Single-layer Perceptron, the learning rate is 0.32 while the decay rate is 0.5 and the iteration time for the training is 5000. The accuracy obtained is 88.2% (FIG.2), higher than Single-layer Linear Perceptron.

8. y = relu(x)

In this function, e, 0.01, is set as the leaky ReLU parameter. Leaky ReLU performs better than ReLU in CNN.

9. dl dx = relu backward(dl dy, x, y)

When using leaky ReLU, the derivation is 1 when $y \ge 0$ and e when y < 0 (e = 0.01 in the code).

10. w1, b1, w2, b2 = train mlp(mini batch x, mini batch y)

In this Multi-layer Perceptron, the learning rate is 0.64 while the decay rate is 0.9 and the iteration time for the training is 5000. The accuracy obtained is 91.3% (FIG.3).

11. im col = im2col(im, f h, f w, stride=1, pad=1)

I defined a function im2col. For the input, im is the image, f h and f w is the size of the filter, stride is the stride for the convolution, pad is the size of the zeros around the original images. Im2col function can help increase the speed of the CNN training.

12. y = conv(x, w conv, b conv)

With the input x, x new is obtained with im2col(x...), w conv is reshaped to fit the size of x new and y is obtained by the equation y = w conv * x new + b.

- 13. dl_dw, dl_db = conv_backward(dl_dy, x, w_conv, b_conv, y)
 With the reshaping and im2col methods, dl_dw = dl_dy * x, dl_db = dl_dy.
- 14. y = pool2x2(x)

With a 2x2 window and stride 2, the largest pixel is kept in the window.

15. dl dx = pool2x2 backward(dl dy, x, y)

This function is to move pixels in dl_dy into corresponding dl_dx coordinates, it's the reverse method of max pooling.

- 16. y = flattening(x)
 - Flatten x into a long single line vector.
- 17. dl_dx = flattening_backward(dl_dy, x, y)
 Reverse what we did in function flattening.
- 18. w conv, b conv, w fc, b fc = train cnn(mini batch x, mini batch y)

In CNN, the learning rate is 3.2 while the decay rate is 0.8 and the iteration time for the training is 12500. The accuracy obtained is 92.2% (**FIG.4**). In my case, the training speed of CNN is slow, so once I got good W and B, I saved them and put them into the model again with other learning rates or decay rates to expect a higher accuracy. The processes are shown in TABLE.1 below.

TABLE.1 Processes for increasing the accuracy of CNN prediction

	Learning	Decay	iterations	Iterations	Accuracy
	rate	rate		to decay	obtained
1	3.2	0.8	10000	1000	0.916
2	3.2	0.8	1000	100	0.917
3	3.2	0.5	500	100	0.919
4	3.2	0.1	500	100	0.920
5	3.2	0.1	500	100	0.922



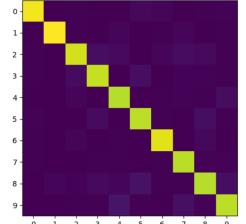


FIG.3 Multi-layer Perceptron

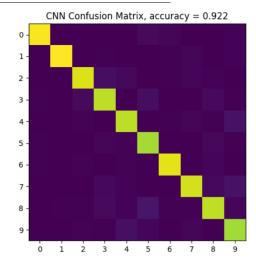


FIG.4 Convolutional Neural Network