

MT3244 - Calculus on Manifolds

Nachiketa Kulkarni

Contents

1	Parameterized Curves and Surfaces (in \mathbb{R}^n)	1
1.1	Paramterized Curves	1
1.1.1	Examples	1
1.1.2	Differentiation Curves:	1
1.2	Paramterized Surfaces	2
1.2.1	Examples	2
1.2.2	Differentiable Surfaces	2

Chapter 1

Parameterized Curves and Surfaces (in \mathbb{R}^n)

1.1 Parameterized Curves

Definition A parameterized curve is a continuous function

$$f : I \rightarrow \mathbb{R}^n$$

where I is an open set in \mathbb{R} .

1.1.1 Examples

1. Straight line: $f : \mathbb{R} \rightarrow \mathbb{R}^2$ defined as $f(\alpha) = (\alpha, m\alpha + c)$ where m and c are constants.
2. Parabola: $f : \mathbb{R} \rightarrow \mathbb{R}^2$ defined as $f(\alpha) = (\alpha, m\alpha^2)$ where m is a constant.
3. Circle: $f : \mathbb{R} \rightarrow \mathbb{R}^2$ defined as $f(\alpha) = (\cos \alpha, \sin \alpha)$.

- Function is bounded.
- There is no polynomial parameterization of this curve.
- Rational Parameterizations exists:

$$f(t) = \left(\frac{t^2 - 1}{t + 1}, \frac{2t}{t + 1} \right)$$

4. Not involving Modulus: $f : \mathbb{R} \rightarrow \mathbb{R}^2$ defined as $f(\alpha) = (\alpha^3, \alpha^2)$.

1.1.2 Differentiation Curves:

A function f which is differentiable for all $t \in I$ is called a Parameterized Differentiable Curves [for all possible parameterizations]. Let $f(t) = (f_1(t), f_2(t), \dots, f_n(t))$, then its derivative is defined as: $f'(t) = (f'_1(t), f'_2(t), \dots, f'_n(t))$. This is used to define the direction of the tangent at a point $f(t)$ as $f'(t)$.

Regular Curve: A differentiable curve such that the tangent vector is non-zero for all $t \in I$

1.2 Parameterized Surfaces

Definition A parameterized curve is a continuous function

$$f : I \rightarrow \mathbb{R}^n$$

where I is an open set in \mathbb{R}^2 . In our case, $n = 3$.

1.2.1 Examples

1. **Affine Linear Transformation:** $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined as $f(u, v) = (p_1 + q_1 u + r_1 v, p_2 + q_2 u + r_2 v, p_3 + q_3 u + r_3 v)$. Let $q = (q_1, q_2, q_3)$ and $r = (r_1, r_2, r_3)$ are:

- 0: The space is a fixed point.
- Linearly Dependent: The space is a line.
- Linearly Independent: The space is a plane.

2. **Sphere:** $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined as $f(u, v) = (\cos u \cos v, \cos u \sin v, \sin u)$. There is no polynomial parameterization to a sphere.

3. **Cone:** $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined as $f(u, v) = (v \cos u, v \sin u, v)$. Polynomial Parameterization exists as follows:

$$(u, v) \rightarrow (u^2 - v^2, 2v, u^2 + v^2)$$

1.2.2 Differentiable Surfaces