

Introduction to Electromagnetism

1 Coulomb's Law



$$\vec{F}_1 = \frac{1}{4\pi\epsilon_0} \frac{q_1 Q}{r_1^2} \hat{r}_1$$

If there was another charge q_2 at \vec{r}_2 :



The force on Q due to q_2 is given by:

$$\vec{F}_2 = \frac{1}{4\pi\epsilon_0} \frac{q_2 Q}{r_2^2} \hat{r}_2$$

And the net force on Q is given by:

$$\begin{aligned} \vec{F} &= \vec{F}_1 + \vec{F}_2 \\ \vec{F} &= \frac{1}{4\pi\epsilon_0} \frac{q_1 Q}{r_1^2} \hat{r}_1 + \frac{1}{4\pi\epsilon_0} \frac{q_2 Q}{r_2^2} \hat{r}_2 \end{aligned}$$

If there were n charges, the net force on Q would be:

$$\vec{F} = \sum_{i=1}^n \frac{1}{4\pi\epsilon_0} \frac{q_i Q}{r_i^2} \hat{r}_i$$

$$\vec{F} = Q \sum_{i=1}^n \frac{1}{4\pi\epsilon_0} \frac{q_i}{r_i^2} \hat{r}_i$$

where $\sum_{i=1}^n \frac{1}{4\pi\epsilon_0} \frac{q_i}{r_i^2} \hat{r}_i$ is the electric field \vec{E} at \vec{R} due to the n charges.

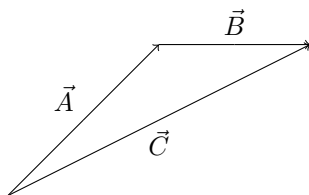
Field: A value, vector or tensor, that is defined for every point in space and time.

2 Vector Calculus

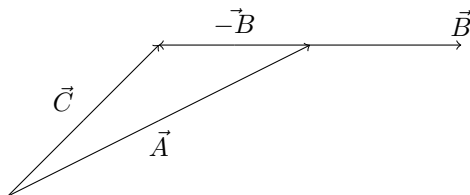
Vectors A vector is a quantity that is said to transform like a displacement.

Operations on Vectors

- **Addition:** $\vec{A} + \vec{B} = \vec{C}$



- **Subtraction:** $\vec{A} - \vec{B} = \vec{C}$



- **Multiplication by a scalar:** $c\vec{A} = \vec{C}$
- **Dot Product:** $\vec{A} \cdot \vec{B} = AB \cos(\theta)$. Dot product is a scalar. It is commutative and distributive.
- **Cross Product:** $\vec{A} \times \vec{B} = AB \sin(\theta) \hat{n}$ where \hat{n} is the unit vector perpendicular to the plane containing \vec{A} and \vec{B} .

Cross product is a vector. It is anti-commutative and distributive.

Component form of a Vector:

A vector \vec{A} can be written as:

$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

where $\hat{i}, \hat{j}, \hat{k}$ are unit vectors along the x, y, z axes respectively.

Given that $\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$ and $\vec{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$, we can perform the following operations:

- **Addition (and Subtraction):** $\vec{A} + \vec{B} = (A_x + B_x)\hat{i} + (A_y + B_y)\hat{j} + (A_z + B_z)\hat{k}$
- **Multiplication by a scalar:** $c\vec{A} = cA_x\hat{i} + cA_y\hat{j} + cA_z\hat{k}$, where c is a scalar.
- **Dot Product:** $\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$
- **Modulus:** $|\vec{A}| = \sqrt{A_x^2 + A_y^2 + A_z^2}$
- **Cross Product:** $\vec{A} \times \vec{B} = (A_y B_z - A_z B_y)\hat{i} + (A_z B_x - A_x B_z)\hat{j} + (A_x B_y - A_y B_x)\hat{k}$ This can also be written in a determinant form:

$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

Triple Product:

Scalar Triple Product: $\vec{A} \cdot (\vec{B} \times \vec{C}) = \vec{B} \cdot (\vec{C} \times \vec{A}) = \vec{C} \cdot (\vec{A} \times \vec{B})$ Geometrically the scalar triple product is the volume of the parallelepiped formed by the three vectors.

Vector Triple Product: $\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B}(\vec{A} \cdot \vec{C}) - \vec{C}(\vec{A} \cdot \vec{B})$