Command to run before each code:

Cd devel

Source setup.bash

Command to open gazebo:

$ export TURTLEBOT3\_MODEL=burger

$ roslaunch turtlebot3\_gazebo turtlebot3\_empty\_world.launch

Commands to open turtlesim:

Rosrun turtlesim turtlesim\_node

Rosrun pkg1 name.py (in a new terminal)