Assignment-2E1-Nachiketh-nxp251

March 10, 2018

Plot the basis functions of a 16x16 discrete cosine transform (DCT)

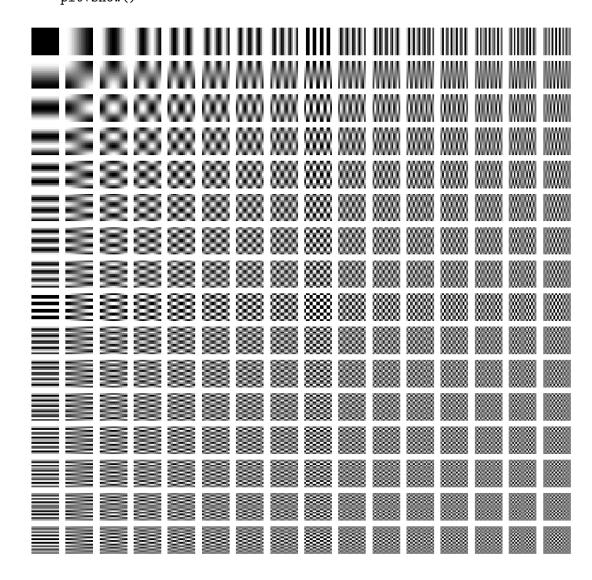
A Discrete Cosine Function express a finite set of datapoints in terms of a sum of cosine functions oscillating at different frequencies. It is a liner invertible function $f: \mathbb{R}^N \to \mathbb{R}^N$, or equivalently an invertible N X N square matrix. DCT is a Fourier-related transform similar to the Discrete Fourier Transform (DFT) but using only real numbers.

There are several DCT functions with slight modifications, for this assignment I have used the following one -

$$B_{u,v}(i,j) = C(u) * C(v) * cos(\frac{\pi(2i+1)u}{2N}) * cos(\frac{\pi(2j+1)v}{2N})$$

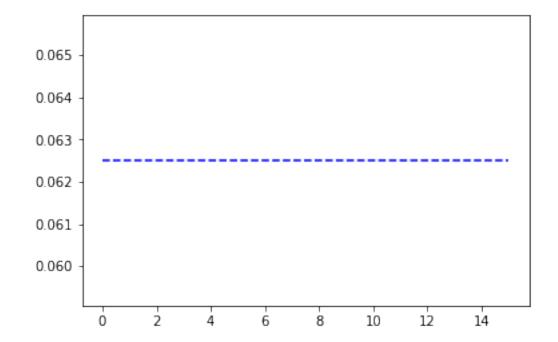
Where, u and v are the different frequencies. C(u) and C(v) are $\sqrt(1/N)$ when u and v are 0 and $\sqrt(2/N)$ otherwise.

```
In [52]: import math
         import numpy as np
         import matplotlib.pyplot as plt
In [53]: def C(x, N):
             if x == 0:
                 return math.sqrt(1/N)
             else:
                 return math.sqrt(2/N)
         def computeDCT(i, j, u, v, N):
             I = math.cos(((2*i+1)*(u*math.pi)) / (2*N))
             J = math.cos(((2*j+1)*(v*math.pi)) / (2*N))
             return C(u, N) * C(v, N) * I * J
In [83]: def DCT(N):
             maxU = N
             maxV = N
             DCTimages = []
             points = []
             for u in range(0, N):
                 for v in range(0, N):
```

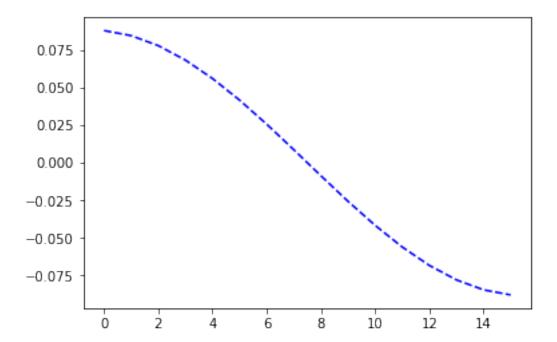


Below is the plot for the basis values

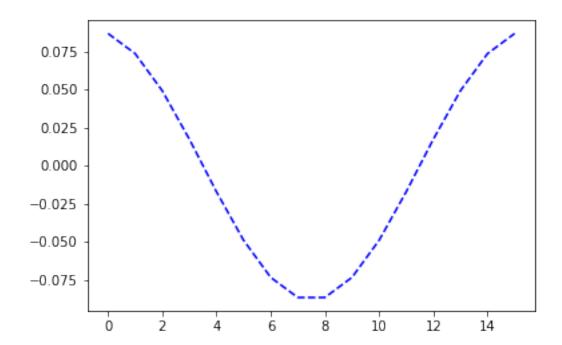
```
In [145]: first = points[0]
          plt.plot(first, 'b--')
          plt.show()
```



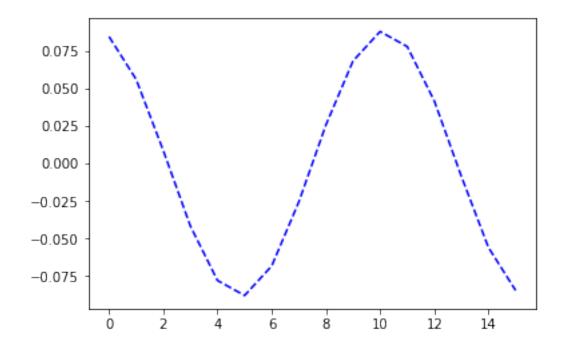
```
In [144]: first = points[1]
        plt.plot(first, 'b--')
        plt.show()
```

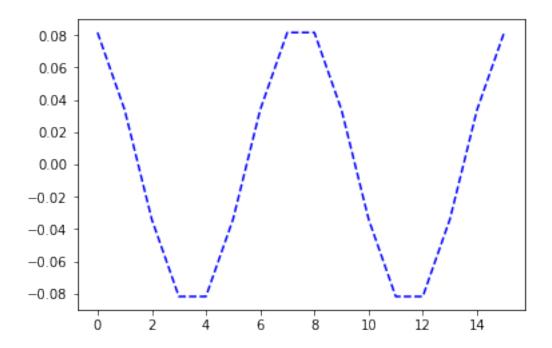


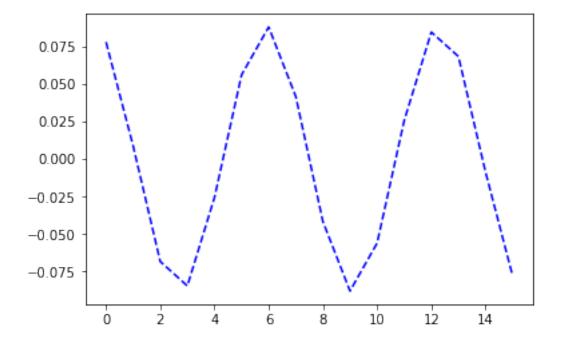
In [146]: first = points[2]
 plt.plot(first, 'b--')
 plt.show()

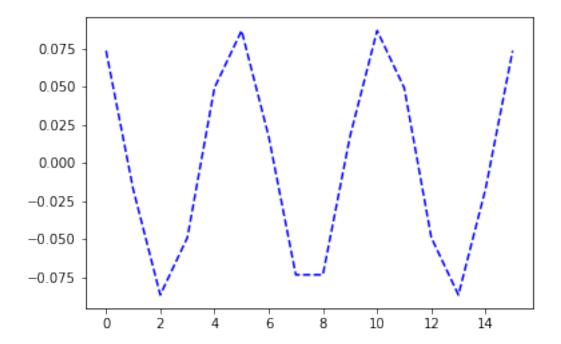


```
In [147]: first = points[3]
        plt.plot(first, 'b--')
        plt.show()
```

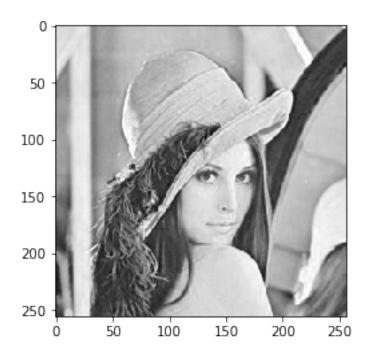




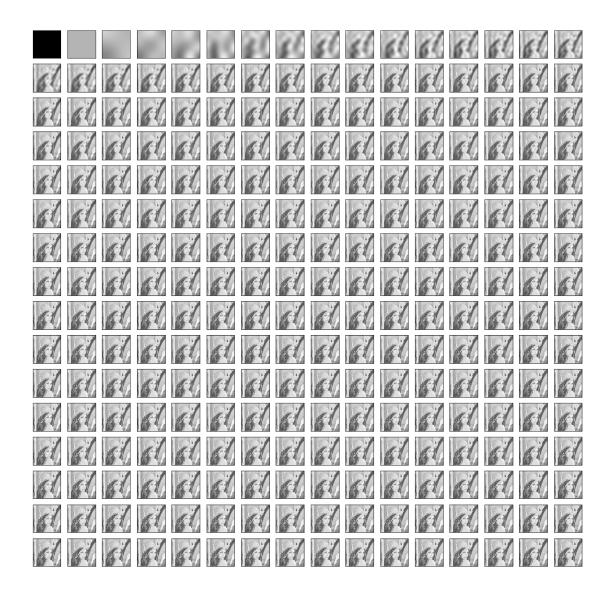




Applying DCT and IDCT to an Image Here I have used the scipy built in functions dct and idct from fftpack package.



```
In [128]: dct_size = image.shape[0]
          dct = fftpack.dct(fftpack.dct(image.T, norm='ortho').T, norm='ortho')
          reconstructed_images = []
          for i in range(dct_size):
              dct_copy = dct.copy()
              dct_copy[i:, :] = 0
              dct_copy[:, i:] = 0
              #Reconstruct Image
              r_image = fftpack.idct(fftpack.idct(dct_copy.T, norm='ortho').T, norm='ortho')
              clipped_img = r_image.clip(0, 255)
              img = Image.fromarray(clipped_img)
              reconstructed_images.append(img)
In [136]: fig = plt.figure(figsize=(16, 16))
          for i in range(256):
              plt.subplot(16, 16, i+1)
              plt.imshow(reconstructed_images[i], cmap='gray')
              plt.grid(False)
              plt.xticks([])
              plt.yticks([])
          plt.show()
```



From above we can see that the first 40 - 50 dct coefficients could capture most of the image. If we use these coefficients to reconstruct the image we do not loose much image quality in the process. The first coefficients are mostly color and hue differences, then it reconstructs a coarse, very approximate image. Then, with high frequency components, we could get a high quality image. This is a nice way to think about the compression in general.

DCT is good for compression of natural images, even with few coefficients you can construct the image well.